

Carlson Software Inc. 33 E Second Street Maysville, KY USA 41056 (p) +1-606-564-5028 www.carlsonsw.com

SurvCE

User Manual





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2 Installation

This chapter describes the system requirements and installation instructions for Carlson SurvCE.

2.1 Using the Manual

This manual is designed as a reference guide. It contains a complete description of all commands in the Carlson SurvCE product.

The chapters are organized by program menus, and they are arranged in the order that the menus typically appear in Carlson SurvCE. Some commands are only applicable to either GPS or total station use and may not appear in your menu.

Look for the icons for either GPS mode and/or total station mode, found at the start of certain chapters. These icons will be located at the top (header) of these pages, or at the start of a chapter.



For some commands both icons will be shown, indicating that the SurvCE command can be used in both GPS and total station modes.

Many of the figures / images have been modified for proper formatting, please be aware your screenshots may differ slightly.

2.2 System Requirements

The information below describes the system requirements and installation instructions for Carlson SurvCE.

Software

- Windows CE® or Windows Mobile version 4.0 or later. Handheld PC.
- Microsoft Windows Mobile Device Center

RAM and Hard Disk Space Requirements

- 64 MB of RAM (recommended)
- 16 MB of hard disk space (minimum)



Hardware (Required)

• StrongARM, XScale or compatible processor (hardware must be supported by the Microsoft operating system being used)

Hardware (Optional)

• Serial cable for uploading and downloading data.

2.3 Windows Mobile Device Center

If you use Windows XP or an earlier version of the Windows Operating System on your computer, Microsoft® ActiveSync® provides support for synchronizing data between a Windows-based desktop computer and Microsoft® Windows® CE or Windows® Mobile based portable devices. ActiveSync is only compatible with Windows XP or earlier. If you are running Windows Vista or Windows 7, you will need to download and install Windows Mobile Device Center from Microsoft.

You should have a USB cable or 9-pin null modem cable that was included with your mobile device. Attach this cable from your desktop PC to the mobile device. Before you can install Carlson SurvCE, your desktop PC must have Microsoft ActiveSync or Windows Mobile Device Center installed and running depending on what version of Windows is running on your computer. If you have ActiveSync on your desktop PC, you should see the ActiveSync icon in your system tray. If you do not see this icon in the tray, choose the Windows Start button, choose Programs and then choose Microsoft ActiveSync. If you do not have ActiveSync installed, insert the Carlson SurvCE CD-ROM and choose "Install ActiveSync". You may also choose to download the latest version from Microsoft. After the ActiveSync installation starts, follow the prompts. If you need more assistance to install ActiveSync, visit Microsoft's web site for the latest install details.

Auto Connection

If the default settings are correct, ActiveSync should automatically connect to the mobile device. When you see a dialog on the mobile device that asks you if you want to connect, press Yes.

Manual Connection

If nothing happens when you connect the cable, check to see if you have the ActiveSync icon in your system tray. If you see this icon, right click on it and choose "Connection Settings". You should see the following dialog:



Connection Settings		?	×
Waiting for device to connect			
Allow USB connections			
Allow connections to one of the following:			
Bluetooth \checkmark			
This computer is connected to:			
Automatic \checkmark			
Allow automatic device authentication			
Allow data connections on device when connected to P	PC .		
	ОК	Cance	el

Be sure that you have selected the appropriate COM port or USB options. Upon connection of the mobile device (Surveyor 2 or other Windows Mobile Device), the program will recognize and begin the connection process. Sometimes however, this does not automatically happen and a disconnect / reconnect procedure may be needed. To ensure the mobile device is connected and recognized by the PC, a user may need to investigate the connection (Device Manager – COM Ports).



One the connection procedure is completed; the icon will indicate 'Connected'.





Troubleshooting

If you cannot get connected, make sure that no other program is using the COM port. Programs to check for include any Fax/Modem software and other data transfer software. If you see anything you think may be using the COM port, shut it down and retry the connection with ActiveSync.

2.4 Windows Active Sync (older PC's)

Enabling COM Port Communication for ActiveSync on Allegro, Panasonic Toughbook 01 and other CE devices

In older versions of Windows, PCs may use Microsoft Active Sync. In order for ActiveSync to communicate, it may be necessary to direct the CE device to utilize the COM port as a default. Some may come set default to USB. Go to Start (on Allegro, blue key and Start button), then Settings, and open the Control Panel. Next choose the Communications icon, then PC Connection. Choose COM1 at a high baud rate, such as 57,600 baud. This will download programs and files at a high rate of speed. On the Allegro, use PC Link to connect to PC with ActiveSync. On the Panasonic Toughbook, do Start, Run, and in the Open window, type in "autosync –go" (autosync then spacebar then "minus" go). Then go to Start, then Settings, and open the Control Panel. Choose the Communications icon, then PC Connection. Change Connection to Serial Port @ 115K. Make sure "Enable direct connections to the desktop computer" is checked.

Note: When using SurvCE's Data Transfer option, you will need to disable Serial Port Connection (uncheck Allow Serial Cable). This is done in the Connection Settings in ActiveSync. This option must be enabled again in order to use ActiveSync.



2.5 Installing SurvCE

Before you install Carlson SurvCE, close all running applications on the mobile device.

1. Connect the mobile device to the desktop PC and ensure a connection.



- 2. Insert the CD into the CD-ROM drive on the desktop PC or double click on the exe file (if downloaded to PC).
 - If using a CD and Autorun is enabled, the startup program begins. The startup program lets you choose the version of SurvCE to install. To start the installation process without using Autorun, choose Run from the Windows Start Menu. Enter the CD-ROM drive letter, and setup. For example, enter d:\setup (where d is your CD-ROM drive letter).
 - If using a downloaded .exe file, double-click on the file to begin installation
- 3. On the PC, a Welcome dialog will appear. Click Next.





4. On the next dialog, you must read and accept the Carlson SurvCE End-User License Agreement (EULA). If you agree with the EULA, click "I accept ..." and then select Install. If you do not agree with the EULA, click "I do not accept ..." and the installation program will quit.

	License Agreement	
Carlson	Please review the license terms before installing SurvCE 6. $\!$	¢
Press Page Down to see the	rest of the agreement.	
CAUTION! READ THIS NOTI	n Software All Rights Reserved CE BEFORE USING SOFTWARE ftware License Agreement before using the SOFTWARE.	^
Using this SOFTWARE indica	ites that you have accepted its terms and conditions. IFINT FOR CARLSON SOFTWARE	¥
If you accept the terms of the agreement, select the first option below. You must accept the agreement to install SurvCE 6.xx. Click Next to continue.		
● I accept the terms of the ○ I do not accept the terms	-	
ullsoft Install System v2.46 —		
	< Back Next > Canc	el

 The next dialog asks for components, or geoids, to install. A Required component is SurvCE, and a selection of geoids (US or Canada) may be checked and installed as well.

	Choose Components		
Carlson	Choose which features of SurvCE 6. \pmb{xx} you want to install.		
Check the components you want to install and uncheck the components you don't want to install. Click Install to start the installation.			
Select components to install	Continental US Geoid		
Space required: 97.6MB	All-Canada Geoids		
Nullsoft Install System v2.46 –			
	< Back Install Cancel		

6. SurvCE will begin the file extraction and installation process. Be sure to keep the mobile device connected to the PC during this process as it will be using both the PC and the mobile device.

Carlson	Installing Please wait while SurvCE 6.xx is being installed.
Extract: Canadian_cgg2013.	gsb
Extract: WIDOT.fd 100 Extract: Registrar.exe 1 Extract: SurvCE_Intro.exe Extract: startup_splash.dll	
Nullsoft Install System v2,46 —	<back next=""> Cancel</back>



7. If a previous version of SurvCE is identified, the user may need to verify this installation is preferred. Once confirmed, the extracted files will begin installing.

Installing Applications		
Installing Carlson Software SurvCE		
Cancel		

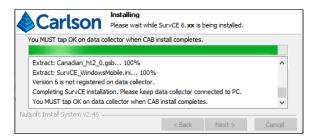
8. A notification will show on the PC for the user to check the mobile device.

Application Downloading Complete	×
Please check your mobile device screen to see if additional steps are necessary to complete this installation.	
	ОК

9. SurvCE will now begin to install on the mobile device, this process will take 5-10 minutes.

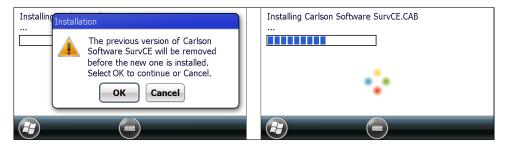
Installing Carlson Software SurvCE.CAB		
•		

10. While the installation on the mobile device is installing, the PC will have a window similar to below. Leave both windows open until the installation is completed. Files are being transferred between the PC and the mobile device at this point.

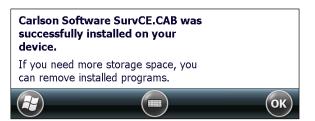




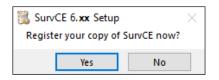
11. If a previous version of SurvCE is recognized on the mobile device, the user will need to again confirm the installation. Once confirmed the install will progress.



12. Once installation is completed, the mobile device will inform the user.



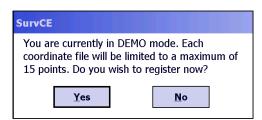
13. On the PC, a registration window will appear. The user can choose to register the software by clicking 'OK'.



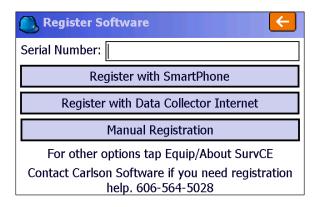


2.6 Registering SurvCE

The first time you start SurvCE, you are prompted to register your license of the software. If you do not register, SurvCE will remain in demo mode, limiting each job file to a maximum of 15 points.



If you open SurvCE and it says you are in "Demo Mode", tap Yes to register now. If you are at the Main menu of SurvCE already you can tap the File tab / About SurvCE and tap Change Registration to access this screen.



Type in your SurvCE Serial number into the Serial Number box at the top

Select one of the following two (2) choices: Register with Smartphone, Register with Data Collector Internet, or Manual Registration. Each selection will be further explained below.



Register with Smartphone: This option is perhaps the most widely used. Start by clicking on the Register with Smartphone button. The user will be presented with a QR Code for their phone to scan, as shown below:



Using your Smartphone, scan the code. Once scanned, the phone's default browser will open on the SurvCE website Registration page, as shown below. Fill out the necessary information and click Submit Registration on the bottom.

SurvCE 6.X	Phone Number
Registration	Account Number
User Name	
Mr. Smith	Reason for Install
	New Handheld Hardware (major component repair 🔹
Company Name	
Carlson Software	✓ I have read and agree to the terms of the
Serial Number	End User License Agreement
Email Address	CLEAR



The Change key will be provided once a successful registration has been submitted, as shown below:



This Change Key can now be used in SurvCE to complete the registration process. Enter in the Change Key and click the green check to continue. A notification informing the user of a Successful Registration will be presented; click the OK button to complete the registration process.

💽 Change Key 🛛 🛃	
Enter Change Key from SurvCE Registration	
webpage	Successful
	Successful SurvCE 6.X Registration!
Change Key XXXXXX	<u>O</u> K
1	



Register with Data Collector Internet: Ensure the data collector is connected to the internet for this process to be successful. To begin, click on the Register with Data Collector Internet button. The user will be presented with a notification as shown below. Click OK to continue.

SurvCE
Complete registration in browser window that appears. Note the change key and return here to enter it.
<u>O</u> K

SurvCE will automatically close and the data collector's browser will open on the SurvCE Registration webpage as shown below. Fill out the necessary information and click Submit Registration on the bottom.

SurvCE 6.X Registration	Phone Number
-	1.555.555.5555
User Name	
Mr. Smith	Account Number
Company Name	
Carlson Software	Reason for Install
	Reinstall on same device
Serial Number	I have read and agree to the terms of the
123456 - ABC78 - 901234 - 567890	End User License Agreement
Email Address	Submit Registration
APerun@AnEmail.com	Clear

A warning about network security may appear to the user. Click YES to continue the registration process. The Change key will be provided once a successful registration has been submitted, as shown below:

SurvCE 6.X Registration successful
Change key XXXXX
User: Mr. Smith
Company: Carlson Software
Email:
Phone:
Fax:
Account Number:
SurvCE 6.X Serial Number:



This Change Key can now be used in SurvCE to complete the registration process. Enter in the Change Key and click the green check to continue. A notification informing the user of a Successful Registration will be presented; click the OK button to complete the registration process.

🚺 Change Key 🛛 🔽 🗙	
Enter Change Key from SurvCE Registration webpage	Successful
	Successful SurvCE 6.X Registration!
	<u>о</u> к
Change Key XXXXXX	
,	

Register using Manual Registration

In a rare case that none of the previous registration methods are available, manual registration may be required. For users running on a Carlson model data collector, a 'Manual Registration' button is available and registration can be completed at <u>survce.com</u>. For other devices, please contact Carlson Software for further assistance with registration.



2.7 Hardware Notes

If SurvCE quits responding, you can reset the hardware by following the applicable procedures described in the hardware documentation. For the Carlson Mini, Surveyor and Surveyor+, if the data collector locks up, or is unresponsive, a hard reset can be performed by holding down the on/off button for two seconds. A menu will appear on the screen. Choose "Reset" to reset the data collector. If the menu does not appear, or the data collector does not respond to screen taps, continue holding down the power button. After about 7 seconds, the amber light will turn on, and the data collector will reset automatically.

A full list of data collector hardware compatible with SurvCE 6.0 is found at http://www.carlsonsw.com/products/data-collection/survce/#hardware

2.8 Color Screens

SurvCE 1.21 or greater enables viewing of color. Any red, green, blue or other colored entities in DXF files will retain their color when viewed within SurvCE. Points will appear with black point numbers, green descriptions and blue elevations. Dialogs and prompting will utilize color throughout SurvCE.

2.9 Battery Status

Battery Status of Data Collector: The black icon that appears at the top of every screen is designed to indicate battery status of the data collector itself. Full black should indicate full battery. As battery levels decrease the black recedes to nothing (out of battery).

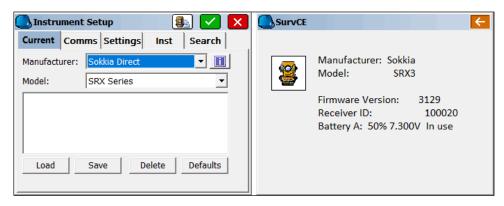


Most Windows Mobile devices show an accurate battery status. If you tap the battery icon, it will display the exact battery percent available, as in 73% (for example). On some CE devices, there is no way to detect battery status, so the battery icon does not change. On other devices, such as the Jett CE, a partial indication of battery status is detected as follows:

- Good 100%
- Low 50%
- Critical 10%



Battery Status of Instrument (some models): For many instruments including Sokkia and Topcon, you can select the "i" (for information) button within Instrument Setup (Current tab) and see details on the instrument including battery status. This is also useful for verifying the firmware version of the instrument. Battery status is also reported for many GPS systems such as Altus APS-3, where both the A and B battery status is displayed. For the Carlson Surveyor+ GPS system, clicking "i" for information will also show the A and B battery status.



2.10 Carlson Technical Support

Contact information for Tech Support for SurvCE is provided below:

Carlson Software, Inc.	Carlson EMEA, BV
Corporate Headquarters Maysville, KY,	Corporate Headquarters Almere,
USA	Netherlands
Tel (606) 564-5028 Fax (606) 564-6422	Tel: +31 36 750 1781
www.carlsonsw.com	www.carlsonemea.com
support@carlsonsw.com	support@carlsonsw.com

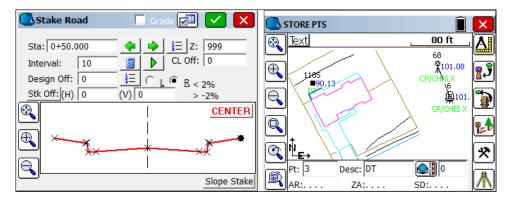
2.11 Customer Service, Technical Support, Repair:

If you need assistance with your Carlson Software products, please call by telephone, or send an email to the address above. U.S. support hours are Monday through Friday, 8:00 A.M. to 6:00 P.M. (EST, GMT -5 hours). EMEA support hours are Monday through Friday, 8:00 A.M. to 6:00 P.M. (GMT +1).



3 User Interface

This chapter describes the general user interface features of SurvCE.





3.1 Graphic Mode

ICONS

SurvCE can be configured to show either the traditional letter Icons or graphical icons for several functions. To set this option, go to the Equip tab, select Configure and toggle the 'Use Graphic Icons' check box.

Letter	Graphical	
icons	icons	Description
R		This icon will Read a measurement (ALT-R).
Τ		Total Station Only. This icon will Traverse to the measured point by advancing your setup (ALT-T).
S	د ۽	This icon will Store a point. This function is also performed via the Enter key. (ALT-S).
Α	Σ'n	This icon will lead to a dialog where the user can Average up to 999 epochs of GPS readings (ALT-A).
Ο		This icon leads to Offset reading screens with options for keyed-in offsets as well as offsets taken by laser and hydrographic devices that measure distance only, or distance and azimuth (ALT-O).
С	*	This icon will take you to the Configure dialog, also found on the EQUIP tab. Here you set many preferences in SurvPC such as the number of readings to average, function of the Store icon, and whether to display the Hgt/Desc prompt on Save (ALT-C).
\mathbf{N}		This icon will advance stake location incrementally to the Next point or station (ALT-N).
M	*	This icon returns to the previous stakeout settings dialog where you can Modify the current design stake data.
El		This icon allows the user to override the design Elevation (ALT-E).
	\checkmark	OK : This icon will accept the dialog.
	←	Back: This icon will return you to the previous dialog.
	×	Exit : This icon will return you to the main menu and dismiss any changes (ALT-X).
[A	Standby/Search : Robotics only. This status icon shows the instrument is in standby and when pressed, puts the instrument in search mode when then leads to lock mode when the prism is found.
		Locked : Robotics only. This icon shows that the instrument is locked on the prism, and when pressed, places the robotic total station in Standby mode, meaning it will suspend tracking mode (e.g. allows you to place the pole down, drive a stake, then resume work).
	ال ا	EDM is On : Robotics only. This icon shows that the instrument is continuously measuring distances and when pressed will stop the EDM.
	*7 XI	EDM is Off : Robotics only. This icon shows that the instrument is NOT continuously measuring distances (not tracking) and when



	pressed will start tracking and enable the EDM on the total station.
	When in reflectorless mode, pressing this icon will begin continuous
	reflectorless measurements.
\sim	Prism Mode: This icon shows that the instrument is currently
	configured to read a prism and when pressed will switch the instrument
	to reflectorless mode.
	Reflectorless Mode : This icon shows that the instrument is currently in
	reflectorless mode and when pressed will switch the instrument to
	prism mode.
\frown	Laser Pointer Off: This icon shows that the Laser Pointer is Off.
	Laser Pointer On: This icon shows that the Laser Pointer in On. It is
*	often used when doing reflectorless work and makes a red mark on the
	wall, floor or object being surveyed.
	Stop/Go: This icon, inside of Auto by Interval, begins and pauses the
	action of recording points (ALT-G).
	Monitor/SkyPlot: This icon will take you to the Monitor/SkyPlot
<u>#</u>	screen for GPS status and Coordinate and Lat/Long display (ALT-D).
	Tripod: This will take you to the Instrument Setup dialog. This dialog
<u>/1\</u>	contains Backsight, Setup, Robotics and Remote Benchmark (ALT B).
E	Zoom Extents: This zooms the entire drawing to fit the screen.
E	Zoom In: Zooms in 25%.
	Zoom Out: Zooms out 25%
	Zoom Window: Zooms into a rectangular area that you pick on the
<u> </u>	map screen.
6	Zoom Previous: Zooms to the previous view. SurvPC remembers up
	to 50 views.
	View Options: Displays the View Options dialog box, where you can
	control aspects of points such as the symbol, the style of the plot and
	the freezing or thawing of attributes such as descriptions and
	elevations. To avoid "point clutter", you can even set it to show only
	the last stored point along with setup and BS. See the View Options
	section of this manual.
	Settings: This icon leads to settings associated with the current
	command or option.

Pan

You can also pan the screen simply by touching it, then holding and dragging your finger or stylus along the screen surface. Pan is automatic and needs no prior command.

View/Edit Points by Touch



You can edit or delete any point by simply clicking on it graphically. In the Store Points command, clicking on a point also allows you to Re-Measure a point location or Delete a point, both in GPS and Total Station mode.

Text Mode

The Text screen uses a large character size for easy viewing, and limits options to Monitor/Skyplot, Offset and Store. Select the Text mode by clicking on the Helmet in the upper left of the screen, in most active survey commands, choosing Text. You can return to the Graph view by tapping the Helmet icon and choosing Graph. You can also temporarily view your points on the screen by tapping the Map (upper right globe icon), then tap Back (Red X) to return to the text-based data collection screen. Note that the program will remember which screen you were in last (Graph or Text) and return to that mode of data collection automatically.



3.2 View Options

The graphic view has all of the standard zoom icons as well as a View Setting Icon in the lower left. This icon allows you to change the way the graphical items will be displayed. The View Setting Icon will show more options such as the "Alt-F" (store last point only) option when clicked during commands such as Store Points and Stake Points (active survey commands).

💽 View O	ptions						X
Graphics	Data	Disp	olay				
Point La	bel Setti						
Fre	eeze All		✓ <u>Pt</u> ID ✓ <u>Eleva</u>		7	Zoroc	
Set Attr	ibute Co	ors		ription		Zeros	
-Font Si	ze	Sy	mbol —	~	~	~	
🗌 🕛 <u>L</u> ar			_		-	0+	
🔍 💽 🖻	nall		Use	Deci <u>n</u>	<u>n</u> al as	s Pt Loo	
			>	UCS Scale			

- **Freeze All**: This toggle will freeze (hide from view) the point attributes (e.g. Point ID, Elevation and Description). Each attribute can be toggled off separately as well.
- Font Size: Points can be small (default setting) or large and bold for easier readability.
- Use Decimal as Point Location: This toggle will adjust the text location so that the point location is the decimal point of the elevation. It applies if the "dot" symbol is used.
- Set Attribute Colors: This button will allow users to specify the colors of the point text (color units only).
- ----- The following options appear only when in active survey mode (e.g. Store Points, Stake Points) -----
- UCS Icon: This shows the N/E icon on the graphic screen, for orientation.
- Scale Bar: This shows the Scale Bar on the graphic screen, for use if preferred.



The Data tab goes to a secondary screen which normally shows only the Intelligent Zoom option, but when selected from the Map screen (globe icon), also includes Traverse Defaults:

💽 View Options 🔽 🗙	💽 Traverse Defaults 🛛 🖌
Graphics Data Display	Prompt for: Instrument & Rod Height
Intelligent Zoom	Vertical Angle Prompt:
	C 0 Degrees Level 90 Degrees Level
	C Elevation Difference
Traverse Defaults	C On Off

- Intelligent Zoom: When selecting points "From Map" in commands such as Inverse or Stake Points, the "Intelligent Zoom" allows you to pick the point from the screen in a condensed area of points, and the program will auto-zoom allowing you to pick again and obtain the precise point that you want. If Intelligent Zoom is off, you would instead see a list of points and must pick from the list or return to the Map screen and zoom in closer using the Zoom + or Zoom Window options.
- **Traverse Defaults**: The T for Traverse and S for Sideshot commands, within the Map screen, will prompt for instrument height, rod height and zenith angles as set in this dialog, and will optionally store to the raw file for processing. This allows for very fast manual entry of raw field data.



3.3 Hot Keys & Hot list

The ALT key commands take the form ALT-C (Configure Reading) or ALT-N (Next Point). The ALT key and the subsequent "Hot Key" ("C" or "N", as mentioned here) can be entered at nearly the same time or with any delay desired. If you press ALT and delay the entry of the hot key, you will see a text instruction: "Waiting for HotKey... Press Alt again to return". A second ALT returns to the previous position in the program without executing any command. If in the main menu, use the first letter of the tabbed commands (E for Equip, S for Survey, etc.) to go directly to those commands as an option to tapping the screen.

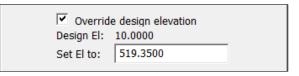
List of Hot Key Commands Activated by ALT

Many of the hot keys work only within related data gathering commands, as opposed to working from the main menus. Hot Keys vary by command. For example, in the Store Points screen, the hot keys are as follows.

- ALT-R: Read (Total Station Only)
- ALT-S: Store (or Shot/Store)
- ALT-O: Offset
- ALT-C: Configure Reading
- ALT-B: Backsight (Total Station Only)

Here is a list of other common hot keys:

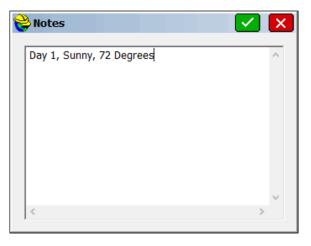
• ALT-E: Target Elevation — From the stakeout screen in any Stakeout Line/Arc command, Offset Stakeout, Elevation Difference and virtually all stakeout commands except Stakeout Points, ALT-E will allow the user to enter an alternate design elevation different from the computed current design elevation. The screen prompt appears below:



- ALT-F: Foresight Only Toggle. When in the Store Points graphic screen and taking new shots, ALT-F will freeze all but the setup point number, backsight point number and current foresight shot. This is helpful when points are densely located. Alt F again returns to the full point plot. Linework remains. In GPS Mode, Alt-F hides (freezes) all points, but shows a solid square symbol for the last GPS-measured point.
- ALT-H: Help. Takes you to the Help menu, where available.
- ALT-I: Inverse. Does a quick inverse, and upon exit, returns you to the command you were in. Inverse is also accessible from the Helmet in the upper left of the screen, in many commands including Store Points.



- ALT-J: Joystick. Applies only to robotic total station. Takes you to the Settings option. ALT-J typically only functions if you are configured for a robotic total station. ALT-J will work from within data gathering commands, most stakeout commands (e.g. Stake Points) and from the main menus.
- ALT-L: List, as in Feature Code List. When entered in any Description field, this will recall the Feature Code List, which displays the characteristics (layer/linework) of the feature code. This serves not only as a way to select the code and apply it to the description, but it also serves as a handy reminder of the code's properties. Helmet-Codes also goes to the Feature Code List.
- ALT-M: Map Screen. ALT-M will switch to the map screen.
- ALT-N: Next. Moves you to the Next point or station in the Stakeout commands.
- ALT-T: Traverse. Takes a reading and advances the setup to the measured point. The instrument setup dialog is presented for verification. Applies when in the Store Points routine.
- ALT-V: Shortcut to View the Raw Data, Point Data, Feature Codes and Cutsheets.
- ALT-W: Write a Note anytime with this command. Notes store to the Raw File.



- ALT-X: Shortcut to Exit most commands. Similar to Esc (escape key).
- ?: The '?' character can be used in any field that requires a numerical entry to access the Calculator. (The Sokkia SDR8100 is an exception. This device uses the '=' symbol.)



In most measurement screens, you can also select the SurvPC Helmet icon at the top left to access the hot list of shortcuts to other routines. Depending on what commands you are in, or if a Bluetooth device is involved (Reconnect option), the Helmet options appear as shown:

🚬 🧔 View Data	Alt+H Alt+V Alt+P	re 🚺 🛃 💽	● Help ↓ View Data]= Points	Alt+H Alt+V Alt+P		× S
👘 🔧 Inverse	Alt+I	.1- 1- 1	🛁 🐾 Inverse	Alt+I	ľ	2
1 J 🧪 Write Note	Alt+W	5 Data Transfer 🛛 😣 🚱	🕀 🧪 Write Note	Alt+W	2	A
Eeature Codes	Alt+L		Feature Codes	Alt+L	· 328.08	<u>a</u>
2 J 📓 Calculator	Alt+K	<u>7</u> Import/Export 🛛 🔒	🔄 👩 Мар	Alt+M		
🔚 💕 Reconnect			Calculator	Alt+K	Å328.07	U]
3 P 💍 Carlson Cloud		3 Delete Job 🛛 🗟	🖳 🥵 Reconnect		Point 1	$ \subseteq $
Advanced Setting	gs	Albert Com CE	🕝 🥘 Freeze Points	Alt+F		\mathbf{C}
4 F Scale App UI		2 About SurvCE	🔁 🖬 Text	Alt+Y		_
<u>5</u> F 🔄 Minimize		2 Exit 🧏	🛐 🗖 Minimize		91.2> Z:328.0678)P:2.37 GDOP:3.10 TDOF	

While in any Topo (Store Points) or Stakeout routine, a number of features are accessible by pressing ALT, followed by the corresponding Hot Key. Below is a list of Hot Keys arranged by routine and equipment type.



Action in Topo Mode Summary

Key	GNSS	Conventional TS	Robotic TS
A	Take Average Reading	Read and Store (All)	Read and Store (All)
В		Total Station Setup	Setup and Robotics
С	Configure Reading	Configure Reading	Configure Reading, Sets, Settings and Search
D	Monitor GNSS	Manual Read	Leica: Toggle EDM; Others: Manual Read
E			
F	Freeze Points	Freeze Points	Freeze Points
G	Start/Stop Interval Recording		Start/Stop Interval Recording
Н	Help	Help	Help
Ι	Inverse	Inverse	Inverse
J		Sokkia Motorized: Joystick	Joystick
K	Calculator	Calculator	Calculator
L	Feature Code List	Feature Code List	Feature Code List
М	View Map	View Map	View Map
Ν		-	-
0	Offset Point Collection	Offset Point Collection	Offset Point Collection
Р	List Points	List Points	List Points
Q	Toggle Prompt for Hgt/Desc	Toggle Prompt for Hgt/Desc On and Off	Toggle Prompt for Hgt/Desc On and Off
R		Read	Read and Store
S	Store	Store	Store
Т		Traverse	Traverse
U			
V	View Raw File	View Raw File	View Raw File
W	Write Job Notes	Write Job Notes	Write Job Notes
Х	Exit to Main Menu	Exit to Main Menu	Exit to Main Menu
Y	Toggle Graphics/Text Mode	Toggle Graphics/Text Mode (Helmet-Graph to return)	Toggle Graphics/Text Mode (Helmet-Graph to return)
Z	Zoom to Point	Zoom to Point	Zoom to Point



Key	GNSS	Conventional TS	Robotic TS
А			
В		Total Station Setup	Total Station Setup
С	Configure Reading	Configure Reading	Configure Reading
D	Monitor GNSS		Leica: Toggle EDM
Е	Set Target	Set Target Elevation	Set Target Elevation
F	Freeze Points	Freeze Points	Freeze Points
G			
Н	Help	Help	Help
Ι	Inverse	Inverse	Inverse
J		Sokkia Motorized: Joystick	Joystick
Κ	Calculator	Calculator	Calculator
L	Feature Code List	Feature Code List	Feature Code List
М	View Map	View Map	View Map
Ν	Next Point/Station	Next Point/Station to Stake	Next Point/Station to Stake
0			
Р	List Points	List Points	List Points
Q			
R		Read	Read and Store
S	Store	Store	Store
Т			
U			
V	View Raw File	View Raw File	View Raw File
W	Write Job Notes	Write Job Notes	Write Job Notes
Х	Exit to Main Menu	Exit to Main Menu	Exit to Main Menu
Y	Toggle	Toggle Graphics/Text Mode	Toggle Graphics/Text Mode
Ζ	Zoom to Point	Zoom to Point	Zoom to Point



3.4 Quick Calculator

From virtually any dialog entry line in the program, the '?' command will go to the Calculator routines and allow copying and pasting of any selected calculation result back into the dialog entry line.

Elev Difference	🔽 🔽						
Select Type of Surface Grid Triangulation Elevation Set Elevation:	 Road Design Section From Alignments 						
Voff: ?	ft						
Use Horizontal Alignment for Sta-Off report Stakeout Pattern							
Light Bar Settings							

For example, grading a site that had 4 subgrades with a modeled top surface, you need to grade to the lowest subgrade surface with a vertical offset of (0.12+0.15+0.33+0.25). Quickly obtain the value by entering '?' in the Vertical Offset field within the Elevation Difference dialog, as shown above.

	>						B 🖪 🗙				
St	Standard Scientific Conversion Generic										
	0	1	2	3	%	sqrt	e				
	•	-				sqre					
	4	5	6	7	1/x	+/-	CE				
	8	9	+	-	*	1	с				
	MR	MS	мс	M+		•	=				

This leads immediately to the Calculator dialog, with its four tabs, or options, many with suboptions. Using the Standard tab, we can enter 0.12+0.15+0.33+0.25 and then "=". Then select the Copy button, which places the value in the banner line at the very top of the screen. Then choose Paste to paste the value back into the Vertical Offset dialog edit box. Change the sign to "-" for negative, as needed. Calculations can also be done directly from the edit box within the Vertical



Offset dialog. You could enter "19.5 in" for inches, which would auto-convert to feet or the current units setting. In this same edit box, you could also enter 19.5/12, which would do the division directly in the edit box.



3.5 Carlson Cloud

Features of Carlson Cloud

The Cloud feature is accessible in the Helmet of SurvCE and SurvPC. It offers the following capabilities.

- Messaging from Office to Field Staff and Peer-to-Peer
- File Transfer from Office to Field Staff and Peer-to-Peer
- "Crew View"--viewing of Rover Positions in particular when using GNSS equipment on Grid Coordinates
- For SurvPC only, Data Storage into the Same Job File (CRD File) by multiple Survey Crews

Setting up a Company Account

For each company, an account can be established using the option New User. The first user in a company needs to establish the company key word, ideally something unique so there is little or no potential for other companies to log into the same name. Each user within the company should have their own name and password, as shown below:

Cloud Login	Create new account
Username: Password: Log In New User Forgot User Name	Username: Password: Retype Password: Phone: Email: Create Company Key
Forgot Password	Use Existing Company Key
Delete User	

If you create a new account within the same company and don't match the name, you will get this screen:





Once successfully logged in, you can select any other company member to message, and you can exchange files. Click the paper clip to attach a file and then tap Send. The recipient will obtain a notice and can download or discard the file.

🚺 Mike, Carlson 🛛 🛛 🔀	File Transfer
JobShare CrewView Log off Send To: Ken - 04/30/13 11:18:09 Mike: Did you get the latest loc	You have been sent file Kentucky.crd by Ken
04/30/13 11:19:15 Ken: No, please send. 04/30/13 11:20:06 Mike: LOC file attached File: C:\Data\ACESurvCE.loc	Download File
Sęnd 🖉	Discard File

Tapping Crew View can lead to viewing of other crew members as shown below. They appear as Point ID's which you can calculate distance to (Inverse command) or navigate to, if needed. The positions of crew members update about once every 5 minutes.

CrewView	🖲 STORE PTS	×
	Fixed I+114	S
	KEN X	A
☑Allow others to view my position.		อี
Show others within (km)		പ
	Pt: 10 I Desc: HT: 5	<u> </u>
	E:5292.1764 N:5250.0203 Z:501.0048 HRMS:0.014 VRMS:0.026	M



3.6 Instrument Selection

The user can switch between current instruments using the Instrument Selection flyout on the top bar of the SurvCE.





3.7 Input Box Controls

When point IDs are used to determine a value, the program will search for the point IDs in the current job. If not found it will then search in the control job, if active.

Formatted Distance/Height Entries

Entries for distances or heights that include certain special or commonly understood measurement extensions are automatically interpreted as a unit of measurement and converted to the working units as chosen in job setup. For example, a target height entry of 2m is converted to 6.5617 feet if units are configured for feet. The extension can appear after the number, separated by a space (2 m), or can be directly appended to the number (2m). For feet and inch conversion, the second decimal point informs the software that the user is entering fractions (See Below). Recognized text and their corresponding units are shown below:

- f or ft: US Feet
- i or ift: International Feet
- " or in: Inches
- cm: Centimeters
- m: Meters
- #.##.#: Feet and Inches (e.g. 1.5.3.8 = 1'5 3/8" either entry format is supported)

These extensions are automatically recognized for target heights and instrument heights, and within certain distance entry dialogs. Entries are not case sensitive. An entry of 1.5" or 1.5in would convert to 0.038 feet, for example.

Formatted Bearing/Azimuth Entries

Most directional commands within SurvCE allow for the entry of both azimuths and bearings. Azimuth entries are in the form 350.2531 (DDD.MMSS), representing 350 degrees, 25 minutes and 31 seconds. But that same direction could be entered as N9.3429W or alternately as NW9.3429. SurvCE will accept both formats. Additional directional entry options, which might apply to commands such as Intersection under Cogo, are outlined below:

If options in Job Settings are set to Bearing and Degrees (360 circle), the user can enter the quadrant number before the angle value.

Example 120.1234 --The result is N20°12'34''E.

Quadrants

- 1 NE
- 2 SE
- 3 SW
- 4 NW



In the case where Job Settings have been set for Bearing, and the user would like to enter an Azimuth, the letter A can be placed before the azimuth value and the program will convert it to a Bearing.

Example A20.1234 --The result is N20°12'34''E.

In the case where Job Settings is set to Azimuth and the user would like to enter a bearing, the quadrant letters can be used before the bearing value.

Example NW45.0000 --The result is 315°00'00".

Formatted Angle Entries

Interior Angle: The user can compute an angle defined by three points by entering the point IDs as <Point ID>, <Point ID>, Point ID>. The program will return the interior angle created by the three points using the AT-FROM-TO logic. Such entries might apply to the Angle Right input box in Store Points when configured to Manual Total Station.

Example 1,2,3

Using the coordinates below, the result is 90°00'00". Point 2 would be the vertex point.

Pt.	North	East
1	5500	5000
2	5000	5000
3	5000	5500

Mathematical Expressions

Mathematical expressions can be used in nearly all angle and distance edit boxes. For example, within the Intersection routine, an azimuth can be entered in the form 255.35-90, which means 255 degrees, 35 minutes minus 90 degrees. Additionally, point-defined distances and directions can be entered with a comma as separator, as in 4,5. If point 4 to point 5 has an azimuth of 255 degrees, 35 minutes, then the same expression above could be entered as 4,5-90. For math, the program handles "/", "*", "-"and "+". To go half the distance from 103 to 10, enter 103,10/2.

Point Ranges

When ranges of points are involved, such as in stakeout lists, a dash is used. You can enter ranges in reverse (e.g. 75-50), which would create a list of points from 75 down to 50 in reverse order. For example, in Stake Points, you could enter 75-50 for the point to stake, click "Add to List", then starting at point 75, stake 74, then 73, etc. by clicking N for Next.

Survey Data Display Controls ANGLE

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The angle control will display the angle as defined by the current settings in Job Settings. Options are available for Azimuth (North or South) or Bearing combined with the option of Degrees or Grads.

Format

The display format of degrees uses the degree, minute, and second symbols. For the case of a bearing we display the quadrant using the characters N, S, W, E.

Example Bearing N7°09'59"E Example Azimuth 7°09'59"

All angular values entered by the user should be in the DD.MMSS format.

Example 7.0959 --*The result is* 7°09'59".

Formulas

Formulas can be entered for working with angles. The format must have the operator after the angle value.

Example 90.0000 * 0.5 --The result would be 45°00'00"

DISTANCE

The distance control will display the value using the current Job Settings unit. You can enter a formula using the mathematical operators as described above.

Inverse

You can compute a distance from a point-to-point inverse by entering <Point ID>,<Point ID>. Example

Exam

Using the coordinates listed below, the result is 500'.

Pt.	North	East
1	5500	5000
2	5000	5000

STATION

The station control will display the value using the current Job Settings format.

The same options described above for distance input boxes apply.

SLOPE

The slope control will display the value using the current Job Settings format.

3.8 Keyboard Operation

Carlson SurvCE allows the user to operate the interface entirely from keyboard navigation, as well as touch screen navigation. The rules for keyboard navigation are outlined below: **Controls**



- Button (Radio Buttons, Check Boxes and Standard Buttons)
 - Enter: Select the button.
 - **Right/Left Arrows**: Move to the next tab stop.
 - Right [Tab]
 - Left [Shift+Tab]
 - Up/Down arrows: Move to the next tab stop.
 - **Down** [Tab]
 - Up [Shift+Tab]
 - **Tab**: Move to the next tab stop.

In Menus like Job Settings, Tab Right and Tab Left move through the tab headings (New Job, System, Format, Options, Stake) along the top of the dialog, while the right and left arrows move up and down through the options within each tab.

Drop List

0

- Enter: Selects the highlighted option within each drop list.
- **Right/Left Arrows**: Move to the next tab stop.
 - Right [Tab]
 - Left [Shift+Tab]
- Up/Down arrows: Move through the list items.
- **Tab**: Move to the next tab stop.
- Edit Box
 - **Enter**: Move to the next tab stop. For any measurement screen, if focus is in the description edit box, take a reading. For all other edit boxes, ENTER moves through the tab stops.
 - Right/Left Arrows: Move through the text like standard windows.
 - **Up/Down arrows**: Move to the next tab stop.
 - Down [Tab]
 - Up [Shift+Tab]
 - **Tab**: Move to the next tab stop.
- Tab
 - Enter: Move to the next tab stop.
 - **Right/Left Arrows**: Move through the tabs.
 - **Right** Next Tab
 - Left Previous Tab
 - Up/Down arrows: Move to the next tab stop.
 - Down [Tab]
 - Up [Shift+Tab]
 - **Tab**: Move to the next tab stop.



3.9 Abbreviations

Adr: Address AR: Angle Right Avg: Average Az: Azimuth Bk: Back Calc: Calculate Char: Character Chk: Check cm: Centimeter Coord(s): Coordinate(s) Ctrl: Control Desc: Description Dev: Deviation Diff: Difference Dist: Distance El: Elevation Fst: Fast ft: Foot Fwd: Forward HD: Horizontal Distance HI: Height of Instrument. Horiz: Horizontal Ht: Height or Height of Antenna with GNSS. HT: Height of Target. ID: Identifier ift: International Foot in: Inch Inst: Instrument Int: Interval L: Left m: Meter No: Number OS: Offset Prev: Previous Pt: Point ID Pts: Points R: Right Rdg: Reading SD: Slope Distance Sta: Station Std: Standard Vert: Vertical ZE: Zenith



4 File

This chapter provides information on using the commands from the File menu.

🖲 <u>न</u> Job:CSW					& 😣
<u>F</u> ile	Equip	Sur	vey	COGO	Road
<u>1</u> Job		2	<u>6</u> Da	ta Transfe	r 😝
2 Job Sett	ings	ه	Z Import/Export		
<u>3</u> Points		ŧΞ	<u>8</u> De	lete Job	9
4 Raw Dat	ta	5	<u>9</u> Ab	out SurvCl	E 🔳
<u>5</u> Feature	Code List		<u>0</u> Ex	it	1



4.1 Job



This command allows you to select an existing coordinate file for your job or to create a new coordinate file. The standard file selection dialog box appears for choosing a coordinate file, as shown in the next figure. Buttons for moving up the directory structure, creating a new folder, listing file names and listing file details appear in the upper right corner of the dialog box.

🚺 Coordinate Files 🛛 🚯 💽 🗙
Type: CRD/CRDB 🕶 Drive: C 💌 🎓 📂 💷 🔲
C:\Program Files (x86)\SurvCEDemo\Data\
🔁 Backup
DOTCodes
L NewJob.crd
Name: LongIDs1.crdb

All data points you collect are stored in the coordinate (.crd) file you select or create. The .crd file extension will automatically be appended to the file name. If you add a "b" to the "crd", you will select the database format of the crdb file, which enables Point IDs up to 255 characters and Point Descriptions up to 255 characters. Then future jobs will default to the ".crdb" format. If you return to the "crd" format (standard), point IDs are limited to 9 characters and descriptions to 31 characters. Once in any format (crd versus crdb), that particular format becomes the default on new jobs, until changed. Point ranges in a crdb file are presented to the user from highest number to lowest (e.g. 10, 9, ..., 1). SurvPC, the PC version of SurvCE, additionally permits the direct loading of ArcMap doc files (.mxd extension) and Microstation drawing files (.dgn extension). With SurvPC, these alternate file types are loaded by selecting the options under "Type" in the upper left.

Select Existing Job

To select an existing job, browse to and select an existing file, then select OK (the green check icon).

Create a New Job

To create a new job, simply enter a new name and select OK. You can control where your job is saved by browsing to the desired folder where the job is to be created before entering the new name and selecting OK. You can also create a new folder for this new file name. Following job creation, you will be asked to enter in Job Attribute information. This feature lets you set up prompting for each new job with job-related attributes like Client, Jurisdiction, Weather Conditions and the like. The information is stored in the raw file. This is discussed in detail in the Job Setting section.

Copy and Paste Job



The Copy icon at the top of the dialog allows you copy an existing file and then paste it with the Paste icon into a different directory, as selected.

Note: If you key in a coordinate file that already exists, it will load the file instead of overwriting it with a new file. The benefit of this feature is that you cannot accidentally overwrite an existing coordinate file from within Carlson SurvCE.



4.2 Job Settings (New Job)



This tab allows you to configure how all new jobs will be created.

🖲 Job Se	ttings	🗾 🔽
New Job	System	Format Options Stake
Pt ID:	npt for Firs	t Pt 🔽 Prompt for Units Use Last Job Localization Use Last Control File Cutsheets:
East:	5000 5000 100	Auto-Save By Job Use Template .dxf Select File
Desc:	Start	None Define Job Attributes

- **Prompt for First Pt**: This option specifies whether or not SurvCE will prompt you to specify a starting point when starting a new job. If enabled, you specify the default starting point coordinates in the left column. This applies for total station use only.
- **Prompt for Units**: This option specifies whether or not SurvCE will prompt you to set the units when you start a new job.
- Use Last Job Localization: If this feature is enabled, each new job will use the previous job's localization file and project scale. If this feature is disabled, each new job will start out with no localization and a project scale of 1.0. The default value is off.
- Attach Last Control Data: This allows the user to use the same control file on all new jobs. With this option off, the control file will automatically be deactivated during new job creation.
- **Cutsheets**: Cutsheets are reports of cuts and fills based on stakeout (setout) commands. Auto-Save by job will automatically create cutsheet files (in the last format used) for each new job. If your job was named Macon1.crd, then the first 3 cutsheet files created would be Macon1-Pt.txt (for non-alignment, point-only stakeout), Macon1-CL.txt (for stakeout involving alignments) and Macon1-Sl.txt (for slope staking). Auto-Save by Job & Date will include the date in the job name. Recall Previous will allow the user to use the same cutsheets on all new jobs. With Manual, the control file will automatically be deactivated during new job creation and you will need to create cutsheet files within the Stake tab of Job



Settings. Cutsheets normally store in ASCII (*.txt) format but can store in EXCEL (*.csv) format if selected within Job Settings, Options.

- Use Template DXF: This allows users to create an empty DXF file that contains all of the layers and colors that will be used and displayed in the field. The feature works well with use of Feature Codes for linework. If you designate code 201, for example, as a pavement edge in the layer BitPav, you could make a blank DXF drawing with BitPav layer created, set to color blue. Then using that "template dxf" file, everytime you code a 201, you will see the blue linework as an extra confirmation of correct coding. This color-coding could be repeated for other often used layers.
- **Define Job Attributes**: This lets you set up prompting, for each new job, for job-related attributes like Client, Jurisdiction, Weather Conditions, Party Chief and other notes. These will prompt when each new job is started, and the attributes and entries will appear in the raw file (.rw5) file. Select Add to enter new attributes.





4.3 Job Settings (System)



This tab allows you to define the units for the current job.

😂 Job Se	ttings				X		
New Job	System	Format	Options	Stake			
Distance	US Surv	,		•			
Angle:	Degree	Degrees, Minutes, Seconds					
Lat/Lon:	Degree	Degrees, Minutes, Seconds					
Zero Azimuth:	North	•	Edit Proj	jection Lis	t		
Projectio	n:				_		
USA/NA	D83/KY No	rth		-	·		
	DOS/KT NO	i ui					

- **Distance**: Select the units that you want to use. Choices include US Feet, International Feet, and Metric. If US Feet or International Feet is selected, you have the option to display distances as decimal feet (Dec Ft) or Feet and Inches (Inches). This is a display property only and will not change the format of the data recorded to the raw file. Once distance units are selected for a new job (meters vs feet), they cannot be changed, except for selection of decimal feet versus feet and inches in the case of measurement in feet. If you want to select another unit of measurement, create a new job and if necessary, import the coordinates, linework and symbols as desired. Convert entities and points between meters and feet using options within Cogo, Transformation, Scale or Align.
- Angle: This offers the option of degrees (360 circle, 60 minutes to a degree and 60 seconds to a minute), decimal degrees and gons (also refered to as grads- 400 circle and fully decimal). An angle of 397.9809 gons is equivalent to 358 degrees, 10 minutes and 58 seconds. (Note: you can verify this in Cogo, Calculator, Conversion tab). Angle measurement in Mils is also provided for military applications, where each mil represents 1/6400 of a circle (standard in NATO countries). The Angle Unit configuration impacts commands such as Inverse, Traverse, Sideshot, Input-Edit Centerline and other commands where a direction is displayed or entered.
- Lat/Long: Options are for degrees, minutes, seconds and decimal degrees, impacting all latitude and longitude displays and entries, such as in Equip, Localization.
- Zero Azimuth Setting: Allows you to specify the direction for zero azimuth, North or South.



• Edit Projection List: You can create a short list of commonly used projections that appear in the pulldown list. This is done by selecting projections from Predefined choices, per the menu option below. Predefined choices include NAD 27 and NAD 83 for the United States and UTM for projections around the globe, as well as individual country projections. Although UTM selections include every UTM zone spanning the globe, one advantage of the UTM Automatic Zone Selection is that your local Latitude and Longitude will be used to automatically set the zone, in case you do not know which UTM zone to use. You can also Add User Defined projection systems, where you enter the New System name, choose the Projection type from an extensive list, then enter all the information requested such as False Northing, False Easting, and the items within "New Datum".

8	Coordinate Projection	on		裬 New Syste	em	🗈 🔽 🖡	×
	Name USA/NAD83/KY North Delete	Add Predefine Add User Defin		System: Projection: Datum: Load Scale Factor C. Meridian: Zone Width: Lat. of Origin	: 1 0 6	User Defined False Northing: 0 m False Easting: 0 m	
	Delete		ed	Projection: Datum: Load Scale Factor C. Meridian: Zone Width:	File	User Defined False Northi 0 False Eastin	ng: m g:

Note: The Projection selection applies primarily to GPS work and your localization file. It enables automatic calculation of scale factors for grid to ground and ground to grid, for example (See Localization). However, the Projection can also apply to total station work. When you do any processing of your data within the Raw Data option (File Menu), there is an option "Reduce to Grid Coordinates". If this option is turned on, then the position on the projection is calculated for each point in the traverse and for each sideshot and leads to a specific grid factor. The grid factor, combined with the elevation factor, leads to computation of the combined factor, which is applied to each traverse and sideshot. The program then calculates the fieldwork at sea level on the projection (ground to grid). This can improve your closures especially when traversing from one known grid system monument to another. Selecting and applying the correct projection is also useful when trying to match total station measurements (often located on the ground) to GPS-based survey work (typically located on the grid, at sea level).



4.4 Job Settings (Format)



This tab allows you to select the viewing format of the data displayed and entered in the current job.

裬 Job Set	ttings			X		
New Job	System	Format	Opt	ions	Stake	
Coordinat	te Display	Order:		North	,East	_
Angle Ent	try and Dis	play:		Azimuth 💌		
Horizonta	l Observat	tion Display	r:	Angle Right 💌		
Vertical C)bservatio	n Display:		Zenith Angle 💌		
Distance	Observatio	on Display:		Slope		-
Slope Entry and Display:			Percent 💌		•	
Station Display: (e.g. 1+00.000)				+00.0	00	•
				-		

- **Coordinate Display Order:** This option allows you to display coordinates with the order of North *then* East or East *then* North.
- Angle Entry and Display: Options are Bearing or Azimuth. This applies to numerous commands, such as prompting and displays in Sideshot, Traverse (the backsight as azimuth or bearing), Intersections, and Inverse.
- Vertical Observation Display: Allows you to set the default prompting to Zenith (0 degrees up, 90 degrees level), Vertical Angle (90 degrees up, 0 degrees level) or Elevation Difference (up is positive in absolute units, down is negative). Normally combine Elevation Difference with Horizontal Distance. If combined with Slope Distance, the non-zero Elevation Difference will be used to compute the equivalent zenith angle and will reduce the Slope Distance to a lesser Horizontal Distance. (Applies to entries in Manual Total Station mode).
- **Distance Observation Display**: Options are Slope or Horizontal. This applies to the values displayed from total station readings.
- Slope Entry and Display: Whenever slopes are reported or prompted, you have the option to specify the default in Percent, Degrees or Ratio. Some commands such as 3D Inverse will automatically report both slope and ratio and are unaffected.



Station Display: This option impacts the display of centerline stationing, sometimes referred to as "chainage". In the U.S., for example, roads designed in feet are "stationed" by every 100 feet, so that a road at linear position 14280.5 is given a station of 142+80.50. Metric roads in the U.S. are often stationed by kilometers, where the same road position has a station of 14+280.500. You can configure the placement of the "+" as desired, independent of your configuration for metric vs feet units. You can also configure for a purely decimal display of stationing/chainage, as in 14280.500. This display form shows up in such commands as Input-Edit Centerline, within the Start Station dialog box. Please note that you should still input the stationing in purely numeric form, without the "+" convention. Only the display is impacted by this option. Note how the example within parentheses changes with each selection.



4.5 Job Settings (Options)



This tab allows you to set configuration options for the current job.

误 Job Set	tings			🔽 🗙
New Job	System	Format	Options	Stake
Use (Control File	<u>م</u>		
Select	1			
Store Store Use C Recal	GPS Vect	uracy in Ra ors in Raw e for Descr	/ File when	availabl

- Use Control File: The control file is used for selecting and using points that don't exist in your current working file.
- Select File: Select the control file to use. The chosen file appears, and will remain as the default control file, even when the control file option is disabled (in which case it is grayed out).

General Rule: Carlson SurvCE will always look for the defined point in the current working file first, and then the control file. If the point is not found in either file, a warning that the point does not exist will be displayed. You can force a point to come from the control file or the current file, regardless of settings, by using the List icon to the right of the point ID input box. While in the point list selection window, select the Control file button prior to selecting the desired point.

Stakeout Option: Control files work similarly in stakeout. However, you can go to the STAKEOUT tab in Job Settings and set the program to give priority to the control file points when duplicate points exist. If this option is turned on, and the selected point is found in both files, you will actually be staking out the point from the control file.

Coordinate File Rule: At no time, will a point be automatically copied from the control file into the current file. This allows users to avoid large gaps in coordinate files and eliminates the potential for conflicting points.

Raw Data File Rule: Any time a point is occupied, the occupation record (OC) is written to the raw file for processing purposes. There will not be an SP record written for control file points, only an OC record. Note that if the raw file is reprocessed, the point will be written to the current coordinate file.



💝 Job Settings 🛛 🔽 🗙	Options Available	
New Job System Format Options Stake Use Control File Store GPS Accuracy in Raw File Store GPS Vectors in Raw File Use Code Table for Descriptions Recall Job Road Files	Time Stamp Each Point Store GFS Accuracy in Raw File Store GFS Vectors in Raw File when available Use Code Table for Descriptions Recall Job Road Files Auto Save Map Recall World Image Allow Import. ddf./dwg/Esri Options Default Cutsheets to EXCEL(*.esy) files Use Finnish NLS Store Points Style Use SWC Store Points Style Valiow Stake Nearest Pt from Pts List	Skip confirmation screen in NEXT STK Pts Allow 'Navigate To' in Store Points dy Show TEXT/VEW Buttos dy Show TEXT/VEW Buttos dy Show TEXT/VEW Buttos dy Store Fort to display Positions/Measurements in the bottom bar Apply 'GNSSAnalysis' to average identical GPS Pts: IDs or IDs+DESCs duto Store Fick Points Store Rod Height as Notes Inducé Pt blocks in the crt DXF, on Save Allow GIS Data prompting for STK Pts Allow GIS Data to be Skipped(Hgt/Desc) Write MG(Units Record) to RWS As a Note

• **Time Stamp Each Point**: When enabled, a date and time stamp will be noted in the raw file beside each point. Raw files in Carlson SurvCE have a .RW5 extension and are nearly identical to the TDS .RW5 format. See the image below for simple SurvCE .RW5 file.

😂 Edit Rawfile: NewJob2.rw5 🛛 🗔 🔚 🧲
Scale Point not used
Base Configuration by Reading GPS Position
DT01-17-2017
TM10:40:54
Entered Base HR: 0.0000 ft, Vertical
Antenna Type: [],RA0.0000m,SHMP0.0000m,L10.00
BP,PN0,LA38.385172913148,LN-83.454407864440,E
GS,PN0,N 418323.4479,E 1779719.7669,EL397.2842
GT,PN0,SW-522,ST-259183000,EW-522,ET-259183 -
Add Edit Remove Find

• Store GPS Accuracy in Raw File: This option is available when configured to any GPS equipment. If enabled, the horizontal and vertical quality as reported by the GPS will be stored to the raw file with each point. The terms may vary by receiver type: (e.g. HRMS/VRMS, HSIG/VSIG or CEP/SEP typically).



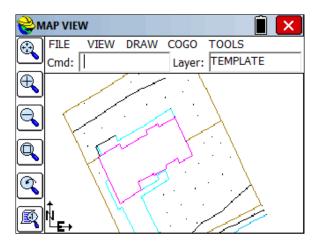
- Store GPS Vectors in Raw File: The GPS vectors option is a form of raw data for GPS measurements, similar to angle and distance data for total stations. The vectors refer to the distance and azimuth from the base receiver or virtual reference station base to the rover. These vectors can then be used by any Network Least Squares program such as Carlson SurvNet, which is part of Carlson Survey office software. They may also be utilized optionally in Post Processing, such as in the Carlson SurveyGNSS program. Finally, vectors are essential to utilize the GNSS Analysis feature within the Cogo Menu, Point Average. The vector option is available on most GNSS receivers, but not all. Many manufacturers are in the process, however, of adding access to the GNSS vectors allowing Carlson SurvCE to store the vectors in the raw file. Examples of receivers that provide access to the vectors include Altus, the Carlson Surveyor+ GPS, Topcon, Leica, Stonex S8 Plus, S9III, Trimble Promark SP80, Geomax Zenith 20, CHC and Satlab.
- Use Code Table for Descriptions: This feature activates feature code usage. If on, feature codes can be used to draw symbols and linework within specific layers. Special code icons also appear when "Hgt/Desc Prompt on Save" is on (within Equip-Configure). If "Use Code Table" is clicked off, use of feature codes is disabled and no linework or symbol drawing will occur. When clicked off, only the current descriptions used in the current job will appear. Most users will turn on the "Use Code Table" option and access the power of the feature codes. Only users who do not want linework and symbols and only wish to see the specific descriptions in their current, active job will benefit from turning off "Use Code Table". When clicked off, only the previously used descriptions within the active job appear for reuse by picking.

铃 Sto	re Poin	it	Γ	Set H	T2	\checkmark	X	
Pt ID: 2	20	HT:	6.562		1.07			
🗆 Repe	at Store	э						
N:4999.	3678	HRM	S:0.044					
E:5290.9	9050	VRM	S:0.074				2	المعاد
Z:509.1	701	PDOF	P:3.200				8	ℰ^
Desc: 🚺	CP							
Categor						•	2	<u>'</u>
▲ BLD	Building	3				^		וניייזו
₫ [∿] CB	Curb						Ľ	
₫℃L	Center	line					1,2.,	n – n
СР						~	L I	ا•••ار

- **Recall Job Road Files**: This command only applies to Stakeout Centerline, Offset Stakeout, and Point Projection in the non-roading version of Carlson SurvCE. When enabled, this option will recall the last roading files (centerlines, profiles, templates, superelevation files, etc.) used in road stakeout. Routines in the Road menu such as Stake Road and Slope Staking will automatically recall the last-used roading files.
- Auto Load Map and Auto Save Map: Maps can be viewed in the MAP and Graphic views within Carlson SurvCE. These maps can be created by using the command IDXF which imports a DXF drawing file. AutoCad DXF formats 12 through 2010 are fully compatible



and will import. Microstation DXF files and DXF files from other CAD programs will also work. Linework (referred to as polylines) can be produced within the MAP view by using the PL (polyline) command, or other commands such as Offset (O2 and O3). In addition, use of Feature Codes, where linework is associated with field codes such as EP for edge-ofpavement, will lead to the drawing of polylines in the Map view. These maps can then be auto-saved whenever you exit a coordinate file, and auto-loaded whenever you load a particular coordinate file. The maps are saved in DXF format. It is typical to enable both Auto Load Map and Auto Save Map if you want to auto-recall your latest map. If Auto Load Map is on and Auto Save Map is turned off, you will recall the map that was saved previously—when Auto Save Map was on. If you want to start your map from a clean slate (from the point plot only—which always appears in map view), you can turn off Auto Load Map and re-enter the program. Then add polylines, use IDXF to import maps (polylines), then click on Auto Save Map and Auto Load Map and you will store and recall only the new linework.



Note: The above graphic display is default. In the Map screen, the normal display includes pull - down menus. These can be disabled by selecting Preferences under the File menu, which expands the map area. The Preferences screen below shows the display options. The pull-down menu format is recommended.



😂 Preferences	🗾 🔽 🔀
Command Bar style:	Menus ON C Menus OFF
Graphic Screen style:	Sketch Option erse One Tap Zoom
1 ×0.000 Start	

- **Recall World Image (Image Database)**: Similar to the DXF file used for new jobs, this option would recall and place an image database background screen, such as an aerial photo, on each new job or existing job. Whatever image is actively displayed when the option is selected will be displayed when other jobs are loaded. If no image is active when the option is selected, then it has no effect. This would be useful for repeated new jobs where a particular aerial photo graphic is needed for reference. The actual graphic used is set within the Map screen, Tools menu, option Image Overlays, Use Image Database.
- Allow Import .dxf/.dwg/Esri Options: This creates additional options within the Map Screen, Import of .dxf and .dwg files. If .dwg files are created by the ArcMap command "Export to CAD", these files can be imported with attribute data using Import .dwg, if this option is turned on. For both .dxf and .dwg files, AutoCAD point entities can be detected and imported as point entities, and even stored to SurvCE point IDs as an option. New since SurvCE 3.0, blocks and inserts can be imported from .dxf and .dwg files, allowing accurate surveying and stakeout using the "center" point snap. SurvCE 4.0 and higher allows the importing of Text. Be aware that all of these special Import options can add dramatically to the drawing size if activated. The dialog below does not appear unless this Job Settings option is clicked on, and only lines and polylines will import in that case.



Warning: Importing additional data will increase the memory used and could lead to slow performance. ✓ Import .dwg Blocks/Inserts Entities ✓ Import .dwg TEXT Entities Import .dwg POINT Entities Store Points Current Job: Current Job: Curent Job: Current Job: Current Job: C	Hamport .dwg Options
	the memory used and could lead to slow performance. Import .dwg Blocks/Inserts Entities Import .dwg TEXT Entities Import .dwg POINT Entities Store Points Overwrite Existing Point IDs

- Default Cutsheets to EXCEL (*.csv) Files: Stores Cutsheets in *.csv (EXCEL) format.
- Use Finnish NLS Store Points Style: Applies specifically to file formats used in Finland.
- Use SWC Store Points Style: This special style, although designed for particular companies, may have some general application. This option is designed for numeric field codes (eg, 10, 11, 101, 102, etc.). Although the screen appearance of the points is not altered, with this option clicked on, two preset GIS attributes are established.

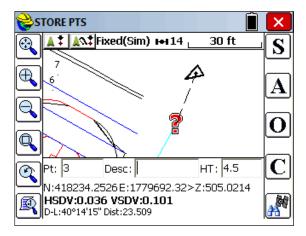
💝 Cod	de List: NC	DOT					<mark>ề</mark> SWC Fe	ature				←	😂 Edit at	tribute		X
Categ	ory: ALL			•	Set		SWLS						Name:	PTCLASS		Codes
Code	Linework	Line Type	Layer N	lame	Full Text		Attribute	Туре	Req.	Editable	Select-Only		Prompt:	MEAS		
2000	Yes	2D	ROAD	E	Edge of F	1	PTNOTES	Char	No	Allow	No		Default Vi	alue: MEAS		Set Default
2940	No	2D	SUE	G	Gas Test		PTCLASS	Char	No	Allow	Yes		Type: Ch	nar 🔻 Reg	.: No 🔻	Clear Default
2941	Yes	2D	SUE	Ģ	Gas U/G I									Mode: Allow		
2950	No	2D	SUE	F	Power Te									1	<u> </u>	Use List Only
2951	Yes	2D	SUE	F	Power U/ 🗸	(L							List Value	s:		Add
4					► F	1							MEAS			Remove
	Add Load	Edit Save			emove ial Codes		Point	R	emove Edit	U Ad			CTRL AVG TPS			Up Down

A special icon appears as shown above left within Feature Codes command, which when clicked, leads to the 2 preset attributes for each point. Preset as well, within PTCLASS, are 4 selectable class values (measured, control, average and TPS). All of these attributes can be edited or added to. The attribute prompting applies only to field-measured points, not points created in the Map Screen with the Create Points command. If "Time Stamp Each Point" is on within Job Settings (described above), then use of the "SWC Style" leads to a specially formatted point list when Export ASCII file is used. There, the SWC option leads to the format below:



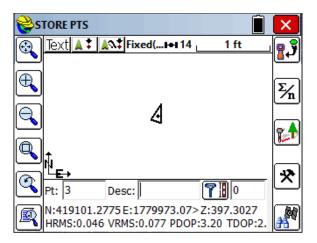
Pt ID, Northing, Easting, Elevation, Feature Code, Action Code, Description, Date, Time, HRMS, VRMS, PtCLass, Measurement Code /Backsight Prism Offset/Foresight Prism Offset The prism offsets in the ASCII Export file apply only to the "TPS" point class or total station measurements.

- Allow Stake Nearest Pt from Points List: Within Stake Points, points can be selected and added into a "stakeout list". With "Allow Stake Nearest.." on, as each point from the list is staked out, the nearest point to the last one staked will be selected next. This reduces the distance to move with each stakeout. However, by targeting the next nearest point, you may move in a direction where the last few to stake are behind you and relatively far away.
- Skip Confirmation Screen in NEXT STK Pts: Within Stake Points and other commands that allow "N for Next" (to move to Next point in order or to move to Next alignment point to stake), the screen confirming the point or station to stake is omitted for faster field stakeout.
- Allow "Navigate to" in Store Points: Selecting this option brings up two icons in the upper left of the Store Points screen, which allows Navigate to a picked point and Navigate along a path defined by a series of picked points. This enables simultaneous navigation and storing of points within the Store Points command. Shown below is use of the left-most icon (Navigate to Point) within Store Points. Note that an effective "View" Method within Configure is Deflection/Distance. A deflection left as shown would put you on line towards the selected point. When selecting a point to navigate to, by snapping, the ? snap allows you to pick a point in blank space, anywhere.





• Show TEXT/VIEW Buttons: When clicked on, Store Points will show a TEXT button in the upper left to allow clicking into the Text screen for storing (no graphics, just large print data) and Stakeout screens will offer the View button in the upper left leading to a special large text stakeout screen (shown below). Once in Text mode, the normal graphic screen mode can be selected using the Helmet options (icon in upper left) by selecting "Graph". Text mode itself can always be chosen using the Helmet in addition to the configurable "Text" button.

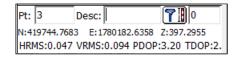


• Auto-Fit Positions/Measurements displayed in the bottom bar: With this option turned on, the number of decimals shown for either the Northing or Easting (depending which number is larger), or both, are reduced in order to fit the North, East and Elevation data on one line underneath the graphic display, within Store Points and the stakeout commands. In the example below, the Easting is reduced to 2 decimal places, from the standard 4 decimal places. With this option set to off, some clipping or overwriting of the numbers may occur as the program tries to display all data to 4 decimal places.

Pt: 3	Desc:	0				
	N:419101.2775 E:1779973.07>Z:397.3027 HRMS:0.046 VRMS:0.077 PDOP:3.20 TDOP:2.					



• Use smaller font to display Postions/Measurements in the bottom bar: Instead of reducing the number of displayed decimal places to fit all N,E,Z data, the program reduces the font size to fit the data:

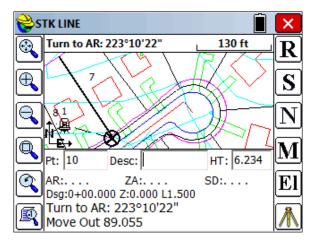


- Apply "GNSS Analysis" to Average GPS Points with Identical IDs: Within the command Point Average in the Cogo (coordinate geometry) menu, this option introduces a distinct averaging method for GPS measurements that applies a Chi Square analysis using vector data to the identical points, as read from the raw file, and includes blunder detection and blunder point removal. Points collected individually within Store Points, or by A for average within Store Points, sharing the same point ID, will be averaged by statistical methods including estimates of accuracy, which under most conditions of measurement will exceed normal RTK accuracy. This option can be viewed as a form of post-processing in the field, leading to greater accuracies. Be sure that "Store Vectors in Raw Data" is turned on (above, in Job Settings). Your GNSS equipment needs to have the vector storage option available. Furthermore, it is advisable to turn on, within the Hgt/Description prompt, "Avg Same Pt ID". Once this is clicked on, the Hgt/Description prompt itself can be turned off (to reduce prompts in the field) using the Configure command (C for Config or Equip-Config).
- Auto Store Pick Points: With this option turned off, when you select line or polyline endpoints when defining alignments using the Map button selection (highlighted below), no new point IDs are created. Selections are referred to as "picked point 1" (PP,1) and "picked point 2" (PP,2) temporarily and then discarded.

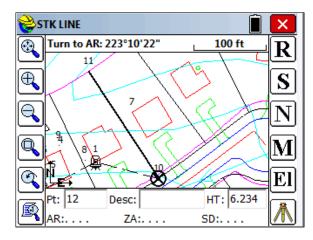
误 Define Line		🔽 🔽
First Point ID: (from Current Second Point (from Current	ID: 2	
North Azimut	45°00'00"	Use Points
Slope:	0.00%	
Method	2 Point	C <u>A</u> zimuth
Start Sta: End:	0+00.000 0+02.828	Confirm NEZ



Similarly, with Auto Store Pick Points off, no new points are created in the screen view or in the file when selecting line elements for stakeout.



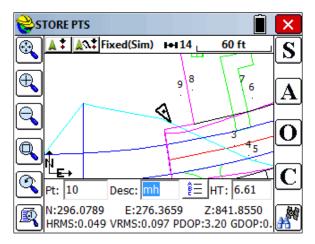
But with this option on, new points are associated with the screen-selected alignment when picked using the "from Map" snaps. Note that the "down - arrow" option was used to expand the graphic screen viewing area. The "angle right" instructions are still seen at the top of the screen.



• Store Rod Height as Notes: With this option on, the Rod Height is stored in the note file associated with the job in addition to being stored in the RW5 file.



• Show Code List when DESC Used: This very useful setting allows faster field operation by eliminating the need for Prompt for Height/Description on (in Equip, Config, or set by C button for Configuration). The Height/Description prompts is preferred by many surveyors to double-check the rod height and to pick the default feature code and same-day used descriptions from a list. But this involves an extra screen to appear. If you turn off Prompt for Height/Description, you can save a screen, and with "Show Code List when DESC used" On, you can get the description field in the single point measurement screen. For example, with this option off, a description would need to be entered (see graphic above). But with this opion on, you get a "From List" icon and can select the description with a single pick (see below). This appears not only in Store Points but in Stake Points (when storing points) and in any command where points are stored.



• Include Pt Blocks in the current DXF on Save: It is recommended to keep this option clicked off, unless you want to DXFIN the point blocks themselves into an external CAD program. This feature, new with SurvCE 4.0, can drastically reduce the time to save and load jobs. If a job has 2000 points, not only the linework and blocks (symbols) on the screen are saved to the DXF file, but also the point graphics can be saved to the DXF file, making it larger and slower. But since the point graphics, in effect, duplicate the points themselves in the CRD file, they are redundant and typically unnecessary to be saved in the DXF drawing when using SurvCE. So, click this option OFF to speed up saving and recalling jobs, since the points will load quickly and display on their own directly from the CRD file itself.



• Allow GIS Data Prompting for STK Points: With this option clicked on, you get an extra prompt when staking out to select GIS attributes to associate with the staked points. Then whatever the GIS prompts are for the feature code, they follow on the next screen(s). Here is how this appears:

💝 Stakeout Report	X	😝 Add GIS Data	RM	X
Northing Easting Staked: 344.920 304.400 Design: 344.918 304.378 Move: In 0.016 ft Left 0.016 ft VOff 1: Elv: Elv: VOff 2: Elv: Elv:	Elevation 841.861 841.841	10 (Char) Status Found	[Point]	Save <u>V</u> alues
HRMS:0.047 VRMS:0.082 PDOF Store Point Point ID: 10 Set GIS	:3.200 Ê=	Del Recall	Nex	t Prev Store



4.6 Job Settings (Stake)



This tab allows you to set configuration options for the stakeout routines.

💝 Job Settings 🛛 🔽								
New Job	System	Format	Options	Stake				
Men Co Use	▼ Te Data to M	Pts for St lave Priorit Desc	k Increme y (Up Alignment	O Down				
Auto Descriptions Cutsheets								

- Precision: Use this to control the decimal precision reported during stakeout routines.
- Store Data to Note File: This option specifies whether or not to store the stakeout data in the note file (.NOT) for the current job. At the end of staking out a point, there is an option to store the staked coordinates in the current job. Note (.NOT) files are associated with points, so you must store the point to also store the cutsheet note. This additional data includes the target coordinates for reference. Keep in mind that the cut and fill data is also stored in the raw file. You can also store an ASCII cutsheet file using the button at the bottom of the dialog, so storing into the note file is somewhat redundant. SurvCE does not show the cutsheet note within List Points (notes turned on), since this feature only shows notes that begin with "Note:" The one advantage of the note file is that notes are viewable in association with points using Carlson Software office products such as Carlson Survey. See command Cutsheet Report, option Note File.
- **Control File Points have Priority for Stakeout**: This option, which applies to both total stations and GPS, will give priority to the control file point during stakeout, when the point requested exists in both the current file and the control file. *Note: Use this option with care. You may not realize that this option is enabled and will discover that directions to your expected stakeout point of 10 are really based on a point 10 from another file altogether the control file.*
- Use Automatic Descriptions: This allows you to have descriptions automatically entered for staked locations based on the settings defined by the Auto Descriptions dialog.
- Increment ID UP/Increment ID Down: Within the Stake Points command, you may need to stake points in decreasing order (see below). In this case, you can preset to Increment ID Down, so prompting would be 87, then 86, then 85, etc.



s N	1AP VIE	w					X
\odot	FILE	VIEW	DRAW	COGO			
<u> </u>	Cmd:			Layer:	TEMPLA	TE	
E			37				
			86				
Q			85				
			84				
R	ĺ ₩ ■ E + *		82				

Stake Offset Description This allows you to define what the ID is called for each offset location in the Stake Offset routine (Surv Menu).

裬 Default De	escriptions 🔽 🔀
Description	Alias
LCurb	LCurb
LDitch	LDitch
LEOP	LEOP
CL	CL
REOP	REOP
RDitch	RDitch
RCurb	RCurb
Alias:	LCurb Update Item



Auto Descriptions

This button allows you to configure the point description when you store points in stakeout. The very act of storing a staked point is optional. You can stake a point or a station and offset, but must click Store Point within the stakeout screens to actually store a point. If you do choose to store the point, the description is configurable. See image below.

Stake De	scription	1	- 🔽 🚺	
Item	On/Off	Prefix		
Stake Pt ID	ON	STK		
Station	ON	STA		
Stake Desc	ON			
Offset Left	ON	L		
Offset Right	ON	R		
Cut	ON	CUT	-	
Off All	On All	Move Down	Move Up	
Prefix:	STK	On/Off	Update Item	
STK1317 CB#22 CUT 2.1 STA1+00.000 CL L10 CUT 2.1				

A user in Australia or Great Britain might want to change the STA for "Station" to CH for "Chainage". An example of a typical stake description, based on your configuration settings, is shown at the bottom left of the screen. The first line (STK1317 CB#22 CUT 2.100) represents a typical Stake Point description, where CB#22 is the description you would enter, and the rest is governed by your Stake Description settings. Similarly, if centerline-based stakeout is being conducted, then the lower line would apply. The description (CL in this case) is the only aspect entered by the user in the field during stakeout. All the rest is reported based on your Stake Description. The "+" in the station can also be configured to appear or not appear, but this is set globally within the Format Tab of Job Settings. The behavior of the On/Off, Up/Down and Update buttons is identical to that discussed in the Cutsheet section.

Other routines, particularly Cross-section Survey and Slope Staking (part of the Roading features), have their own settings for descriptions. When any automatic description for stakeout is turned on, the program will no longer default to the last-entered description such as "EP"; it will use the "automatic" description instead. If you type a new description, you will turn off the "automatic" stakeout description. If you delete the default (new) description, the program will return to using the automatic stakeout description. To delete, you can simply place the cursor in the description field and hit the delete key — there is no need to first highlight the description.



Alignment Settings

This dialog allows the user to define how all alignments and roads are staked.

😂 Settings				
Alignment	Road			
 ☐ Increment from Starting Station ✓ Extend Alignments ✓ Stake Start and End Stations ✓ Stake CL Alignment Points □ Stake Profile Points 				
0+00.000	ta. Range: to 3+08.327	Select File Edit File		

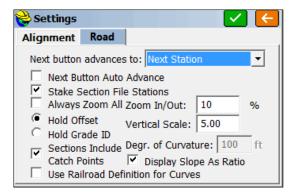
Alignment Tab (Applies to N for Next Station and all auto-incrementing of stations)

- Increment from Starting Station: For centerlines that start on an "odd" station such as 1020 (10+20 in U.S. stationing format), this option would conduct stakeout by interval measured from station 1020. So a 50 interval stakeout, instead of being 1050, 1100, 1150 would be 1020, 1070, 1120, etc.
- **Extend Alignments**: This projects a tangent line off of the first and last segments of the alignment for extending them beyond their defined limits.
- Stake Start and End Stations: This instructs the software to start and increment to these critical locations even when they do not fall on the even station.
- Stake CL Alignment Points: This instructs the software to stop at these critical locations (e.g. PC, PT, curve-to-spiral, etc.) even when they do not fall on the even station.
- Stake Profile Points: This instructs the software to stop at these critical locations (e.g. PVC, PVT) even when they do not fall on the even station.
- Stake High and Low Points: This instructs the software to increment to these critical locations even when they do not fall on the even station.
- **Template Series Station**: If a Template Series File (*.tsf) file is used, which is a series of templates applied to ranges of stations and transitioning between templates, then all stations entered in the *.tsf file for starting and ending a particular template will appear in the incrementing list of stations.
- Combine Station Equations: This allows the user to overlap the station equations.
- Apply Station Equations: If turned off, this allows the user to ignore the station equations so that the station reflects the length of the alignment.
- Offset Gap Type: Fillet: This allows the user to define the offset gap type used when defining offsets within Stakeout Line/Arc routine at straight corners as: radius fillet or radius zero fillet. If turned off, the offset to the outside has fillet radius=0 and comes to a point. If turned on, the radius equals the offset and the outer intersecting offset contains an arc with radius equal to the offset.



- Allow Reference Centerline: With this option clicked On, a "Reference Centerline" (sometimes called "Master Centerline") icon appears in Stake Line/Arc and other alignment-based roading routines. This allows stakeout to a target alignment referencing a "master centerline" for forward-back instructions, and for reporting.
- **Remove Sta Eq when Loading SCT File**: Special feature to remove reference to station equations on loaded cross-sections. Applies to Input-Edit Section File and Section File Conversion, within Road Menu, Utilities. For example, if you had 4 stations, 0+00, 0+50, 1+00 and 1+50, but had a station equation where 0+75 forward = 0+50 back, the equation is removed, and the 4 stations become 0+00, 0+50, 1+25 and 1+75.
- **Remove Sta Eq when Loading PRO File**: Special feature to remove reference to station equations on loaded profiles.
- Limit Station Range: When selected, the program will not automatically advance beyond the natural start and end of a given centerline.
- Use Station and Offset List: Use this option to load a predefined list of stations and offsets. This allows the Stake Offset routine to use a pre-defined list of station, offset, and elevation information as defined by the user. This is sometimes referred to as "Cutsheet" list. An ASCII file with a .CUT file extension is required. The file format is shown below:

```
Station, Offset, Elevation, Description, as in 20100, -11.5, 102.34, 20109.23, -11.5, 102.35, PC
```





Road Tab

- Next icon advances to: This defines how the "Next" icon will behave. It can advance to the next station or the next offset location.
- Stake Section File Stations: When ".sct" cross-section files are involved, this instructs the software to stop at the stations within the ".sct" file along the alignment even when they do not fall on the even station. or other selected alignment station. If you had a cross-section at station 178, the program would stake station 178 and increment to it even if that station was not a "critical" station, not a start, end, PC or other special station.
- Sections Include Catch Points: This instructs the software whether or not the design sections were extracted/stored to the shoulder/back-of-ditch point or all the way to the design catch location. If the design catch location is included in the section, the software will automatically determine the pivot point at the next interior section point for slope staking purposes. The design slope ratio will be determined by the last two points in the section. This applies within the command Road Menu, Stake Slope, Section File option.
- Always Zoom All: This zooms the preview window automatically to fit the extents of the current section.
- Hold Offset/Hold Grade ID: If Hold Offset is selected, the zoom holds the actual numerical offset of 12, for example, for a 12' roadway width but if Grade ID is selected, the zoom holds the calculated position of the Grade ID and factors in widening of the lane. This applies to cross-section viewing within Stake Road.
- Zoom In/Out: This determines the zoom increment of the preview window.
- Vertical Scale: This allows the user to exaggerate the scale vertically.
- **Display Slope as Ratio**: Instructs the program to display ratio instead of slopes--useful for cut and fill slope display.
- **Degree of Curvature**: This allows the user to define the degree of curve base value when metric: 100 ft is the default value used for US Feet or US International Feet.
- Use Railroad Type Curves: This allows the user to define the use of railroad definition for the curves present within the alignment used inside the Stakeout Line/Arc routine.



Cutsheets

There can be as many as five cutsheet files active at one time, one for point staking cutsheets, one for centerline staking cutsheets, one for slope stake cutsheets, one for "grade stake" style cutsheets and finally one for the "story stake" cutsheets. The latter two (grade stake and story stake) cutsheets are described in some detail within the Stake Road command. All cutsheet files can be given distinct names, and any of them can be turned on or off for purposes of storing. And finally, if cutsheets are reported from the raw file, a distinct new name can be assigned prior to recalling the raw file and creating the cutsheet file. All cutsheet files are ASCII and can be viewed in a text editor or an Excel Spreadsheet.

The Cutsheets button leads to the following options:

😂 Cutsheets	(zii 🔽 💌
Point Stakes	Format	Edit File
Select File None		
Alignment Stakes	Format	Edit File
Select File None		
Slope Stakes	Format	Edit File
Select File None		
Grade Stakes	Format	Edit File
Select File None		
Story Stakes	Format	Edit File
Select File None		

- **Point Stakes**: Toggling this option on enables writing to the selected cutsheet file. The buttons allow the user to select the file, customize the Point Cutsheet report format as well as edit and view the current point cutsheet file. This applies to the command Stake Points.
- Alignment Stakes: Toggling this option on enables writing to the selected cutsheet file. The buttons allow the user to select the file, customize the Alignment Cutsheet report format, and edit and view the current alignment cutsheet file. This applies to commands within Stake Line/Arc, and to Offset Stakeout, Point Projection and Stake Road (in Roading) and includes station and offset options in the stored file, as well as cut/fill. A special "centerline-style" cutsheet file, containing station and offset information, can be named and saved within the Roading command, Cross-section Survey. This file is viewable in the editor within Set Cl Cutsheet Format, but has no cut/fill values, just "as-built" data. Centerline-based cutsheets have more configurable options in the report, such as Stake Station, Staked Offset, Design Station and Design Offset. The Design Point ID is one of the configurable items to report, and since commands such as Offset Stakeout, Point Projection and Stake Road do not stake out Point IDs, the program uses either the command name (CL for Stake Centerline, PP for Point Projection), offset reference, or template ID as the "design point name". "RCurb", for example, would be the name given to the design point in Offset Stakeout for top of curb, right side. This might lead to a variety of ID names for the design point.



- Slope Stakes: Toggling this option on enables writing to the selected cutsheet file. The buttons allow the user to select the file, customize the Slope Stake Cutsheet report format as well as edit and view the current slope stake cutsheet file. This applies only to the commands Stake Slope and Stake Road available within Roading. Slope Stake Cutsheets have an extra option to "Include progressive offsets report", and also have different options such as "Pivot Offset", "Slope Ratio" and "Elevation: PP/CP" (Elevation of Pivot Point and/or Offset Point). Note that columns can serve a dual purpose in the slope stake report. If progressive offsets are enabled, the header lines (such as Design Station) are ignored for the additional information, and you obtain the incremental, delta distance and elevation from each point on the section or template from the offset stake to the catch and then all the way into centerline. These last three options allow you to customize the respective output report. To change an item label, highlight the item, change the Header Label field, then tap Update Item. You can select an item in the list and turn it ON or OFF (no reporting). You can also control the order of the report items by using the Move Down and Move Up buttons. Changes must be made prior to starting a new cutsheet file.
- **Grade Stakes**: With this option on, even the Grade Stake method used for stakeout, within Stake Road, will output a specific format.
- Story Stakes: This will output a "story stake" cutsheet if "Story Stake" is clicked on within the Stake Road command. Cutsheets for both grade stakes and story stakes (all points in the cross-section) are discussed in the Stake Road portion of the manual.
- Select File: Tap this button to select the output file. The file name is shown below this button.



Format

Select the format button to configure each cutsheet to your liking. Column order and column headers are completely user-defined and any column can be turned off if not useful.

Settings		Image:	×
C:\Carlson F	Projects\[Data\File.txt	
Item	On/Off	Header Label]
Design Pt#	ON	Design Pt ID	l
Design Nor	ON	Design North	L
Design Eas	ON	Design East	
Stake Nor	ON	Stake North	
Stake Eas	ON	Stake East	
Stake Elv	ON	Stake Elev	
Cut	ON	Cut 👻	·
, Header Labe	el: Desi	gn Pt ID Update Item	
Cutsheet f	from Rav	v On/Off Down Up	

- Header Label: You can substitute header text of your own choice for the defaults. Here, the text Pt ID was substituted for Design Pt#. Tap Update Item after changing a Header Label. These changes should be done prior to starting a new cutsheet file—they cannot be applied retroactively to a file that already contains information. However, the header line in that file (e.g. Market.txt) can always be edited using Notepad or any text editor to accomplish the change.
- **Down-Up**: Items in the list can be moved up and down to change their order. For example, if you prefer Fill *before* Cut in the report, just move Cut down below Fill.
- Cutsheet from Raw: SurvCE automatically stores cutsheet data and header information to the raw file for the job. You can capture and report the cutsheet information directly from the raw file. Before doing this, it is recommended that you start a new cutsheet file, configure the header lines, and order of information as desired, then run "Cutsheet from Raw". This option is very useful if no cutsheet file was established in advance of field work. This enables a cut and fill report by reading the raw file directly.



Edit File

Select this option to edit and review the cutsheet file. Shown below is an alignment cutsheet file as viewed in the Edit File option. Notice that the vertical bars of the spreadsheet can be moved left and right to condense the display. Just pick them in the title line and move them. The Cutsheet editor also includes the ability to insert and delete lines. If you insert a line and enter a Design Elevation and a Stake Elevation, the program will compute the cut or fill. Using the Special button, you can increase or decrease the Pt ID, Design Elevation or Stake Elevation by any desired amount, and the cut or fill will be computed. Do not use the Special button to directly modify the cut or fill. If a second vertical offset is entered during stakeout, then two cut and fill results will appear for each point (useful, for example, for top and bottom of curb).

Edit CutSheet File File.txt					
Design Pt ID	Stake Pt ID	Delta X	Delta		
1	7	6197.56	454.26		
2	8	6202.43	470.20		
3	9	4.153	13.444		
5	10	2.596	8.402		
Insert Up Down Delete Special					





Select this for additional format controls for the cut and fill report.

😂 Cutsheet Settings 🛛 🔽 📕	×
Stored Story Stake Report	7
Slope Stake: Progressive Total Combo	
Stake Road: Progressive Total	
Store Grade ID Only Add Off Value Show Report Up to CENTER	
☑ Include Slope Stake Report as Notes	
Offset Prefix: Left: Right:	

For the "Story Stake Report", which is a report of all cut/fill and distance information to each break point on the target cross-section, options for the slope stake report within Stake Road include "Progressive" or individual distance between break points, Total distance from the staked point to each break point and Combo. The "Combo" option shows a "progressive", incremental slope ratio for each segment (last column), combined with a total HDist and VDist measurement to each point. For the Slope Stake Option, if "Total" or

"Combo" are selected, the total distance reported can be from the Catch Point or from the Offset to the Catch Point. The normal Stake Road command also offers "Progressive" and "Total" options for the story stake report. Store Grade ID Only avoids storing a Point ID with each point. If you click on "Show Report Up to CENTER", you only get the cutsheet report for the Slope Stake and Story Stake break points on the same side of the alignment of your measured point. If this is turned off, you get a full report on both sides of the alignment. The Slope Stake Report can also be stored in the ".not" file associated with the job. The prefix for Left and Right of centerline is defined at the bottom of the dialog. "R" for Right would save space versus "Right", which was used in the example cutsheet file above. Various uses of these settings are explored within the examples found in Stake Road in the Road Menu portion of the manual.



4.7 Points



This command will list all of the points in the current coordinate (.crd) file. You can also edit any point in the list. If a Control File is active within Job Settings, Options, then you can also list and edit the Control File. The "From List" icon also allows you to recall points from both the current Job and the Control File job, if active.

裬 Pts:13= 18 💿 Job 🔍 Control 🔯 🗾 🧲					
Point ID	Northing	Eastir	ng	Elevation	Descr 🔺
10	3355.28	5038.4	13	838.995	EP
11	3404.53	5037.0)2	838.989	EP
12	3410.85	5089.3	35	838.995	EP OH
13	3388.95	5130.4	12	838.995	EP
14	3339.64	5139.7	79	838.986	EP OH
15	3370.03	5108.3	37	839.002	EP PC
16	3377.57	5085.9	95	838.995	EP
17	356.85	5070.7	77	838.988	EP PT
18	3321.96	5065.3	34	839.001	EP
4					• •
Edit	Ad	ld	Fir	nd	Delete

The above figure shows the Points dialog. The point list includes Point ID, Northing, Easting, Elevation, and Description. Columns can be shifted to condense the display, as desired. The new positions, however, are not stored.

• **Details**: The type of file (alphanumeric or numeric point IDs), number of points, unused points and highest point number in the file appear in the Details option.

Current Job	←
Point ID Report:	
Highest Point ID: 18	
Used Points:	
IDs: 1-3,9-18	
Number of used points: 13	
Unused Points:	
IDs: 4-8	
Number of unused points: 5	-



Settings: Select the Settings button to customize the List Points display. The next figure shows the Settings dialog for List Points.

裬 Settings			🗾 🔽 🔀
Field Name	Display N	ame	
Point ID	Point ID		
Northing	Northing		
Easting	Easting		
Flevation Show Poi			•
Add to Next F	* ID: 1		Use Highest Pt ID
Display Name	:	Elev Digits:	Nor/Eas Digits:
Point ID		0.000	▼ 0.00 ▼
Update	Item	Move Dov	vn Move Up

Show Point Notes: Notes can be placed in any order on the list, or can be disabled, as shown above. (Only notes entered in response to "Prompt for Point Notes" or "Edit Notes" within List Points itself will display. Notes for GPS accuracy, time stamps and cutsheets, for example, appear in the raw file but not within List Points.)

Add to Next Pt ID: This makes it possible to number sequentially using 1 or add 2 to every point to skip every other number.

Use Highest Pt ID: This defaults the next available point to the Highest Pt ID in the file after starting SurvCE.

Move Up/Down: To rearrange the order of the fields, highlight a field and use the Move Down and Move Up buttons.

Display Name: To rename a field, highlight it, enter a new name in the **Display Name** field and then tap **Update Item**. This feature allows customization so that, for instance, Northing and Easting could become X and Y as renamed.

Precision (Elevation Digits - North & East Digits): The decimal precision for each field can also be set in the **Options** dialog.

• Edit: To edit a point in the list, double tap on it or highlight the point and tap the Edit button. You may edit any aspect of the point. To edit, move the cursor into the field of the aspect to modify and enter the new value. Choose **OK** to enter the edited point into the coordinate file, or choose **Cancel** to negate your modifications. The Input/Edit Attributes button refers to GIS data attributes associated with a point. These GIS attributes will export in the form of shape files (Tools pull - down in the Map screen). These attribute features help link SurvCE to the ESRI world, just as the DXF output of linework links to the CAD world.



😂 Edit Point			
Point ID:	18		
Northing:	3321.9599	ft	
Easting:	5065.3397	ft	
Elevation:	839.0010	ft	
Description:	EP		î= 10
Input/Edit	Attributes	Edit No	tes

Note: If only the description value is edited, the raw data file will be updated without writing a store point record. If any other value that would change the point position is edited, the raw data file will record a store point record with the new position of the point.

- Add: To add a point, press the Add button. The Add Point dialog appears and you must enter the point ID, northing and easting. A store point record will be written to the raw data file. Data entered using the Add button may be edited (N,E,U or Lat,Long).
- Find: To find a point ID, tap the Find button. You can search for a point by Point ID or description, but not both at the same time. When searching by description, any part of the description can be used to find the point and the search "gs*" has the same effect as "gs" to find points beginning with gs. Both would find the description "gs Sta 1+00 L25".

😽 Find Point in List	🔽 🔽
SEARCH based on:	
Point ID:	
Point Description:	Ê

- **Delete**: To delete a point, highlight a point ID and tap the **Delete** button. You will be asked to confirm this choice before the point is actually deleted. To delete a range of points, use Keyboard Input within the Cogo Menu, option "Utilities".
- **Control File**: When a control file is specified, List Points offers the option to select the control file and to list the control file points. This feature enables the **From List** option found throughout SurvCE to access Control Points. The number of points and highest point number in the control file will now appear in the **Details** option.





4.8 Raw Data



Carlson SurvCE creates a raw file (.RW5) that contains various lines of survey data similar to a surveyors' field book. The data contained in the RW5 file will vary depending upon whether a total station, robotic total station, or GPS is used during the survey. The name of the RW5 file will default to the specified job name (jobname.RW5). This command enables viewing and editing of the raw survey data, as well as traverse closure and adjustment computations for the survey, for both total station and GPS raw data. If total station shots are involved, a graphical representation of the traverse can also be viewed using this command.

If the GPS receiver is logging raw data and tagging sites in the receiver's raw data file is supported, sites will automatically be tagged when they are stored in SurvCE.

Total Station and GPS Use

Total station adjustments are conducted differently from GPS adjustments (**Process GPS**). If you wish to adjust your GPS first for control, and then calculate your total station traverse, first select **Process GPS**. Then use **Process No Adjust**, or **Compass**, as desired. If the rw5 file contains only total station data, Process GPS will be "ghosted" and will not function. If the rw5 contains only GPS data, then only Process GPS and Edit/Export RW5 options will be available. If both data types appear in the rw5 file, all options are available.

≷ Raw File: newjob.rw5		
Process No Adjust	Compass	
Process GPS	Crandall	
Edit/Export RW5 File	Direct-Reverse Report	
Angle Balance	Draw Traverse Lines	
Transit	Triangulate	

Process Raw File Operations: Total Station, GPS, Reporting, Editing

SurvCE has made available four different types of raw file processing. You can process or draw your total station measurements, report out the Direct-Reverse measurements, Process GPS, and Review and Edit the RW5 file.

Note that for all processing where new coordinates are calculated, beginning with SurvCE 2.0, upon exit the program will prompt you whether or not to store the newly calculated points into the coordinate file. This provides the flexibility to experiment with different processing settings and options without impacting the actual stored coordinates, until you deliberately choose to do so.



Total Station Adjustments

If you wish to adjust or draw a total station traverse, you would choose any of the following: **Process No Adjust, Angle Balance, Transit, Compass, Crandall** or **Draw Traverse Lines**. All of these commands have the same four-tab menu system, outlined below.

😂 Process Ra	w File		
Total Station	Proj.	Redundancies	Other
R	educe to (Grid Coordinates	
Scale	: [1.0000000	
□ A	pply Curve	ature Refraction	
	ing Point: Ig Point:	1	

• **Total Station Tab**: Reduce to Grid Coordinates will perform a "ground to grid" calculation based on your GPS projection used, viewable in the projection tab. The Scale Factor for each leg of the traverse and for each sideshot will be independently calculated by averaging the combined grid/elevation scale factor for the start and end of the measurement. Apply Curvature and Refraction will compute curvature and refraction distinctly on all raw measurements and adjust accordingly.

😂 Process Ra	w File		🔽 🗙
Total Station	Proj.	Redundancies	Other
Projection: USA/NAD83 Projection lis		in Job Settings und	Jer GPS



• **GPS Projection Tab**: This tab, critical for GPS calculation, only applies for total station work when **Reduce to Grid Coordinates** is set on within the Total Station Tab. To change the active projection, go to the GPS tab under Job Settings.

😝 Process Ra	w File		🔽 🗙		
Total Station	Proj.	Redundancies	Other		
Multiple Me	asuremen	t Settings			
Method:	ſ	Use First	•		
Average T	уре: [Coordinate	-		
Backsight Recip: None 💌			•		
Horz Distance Tolerance: 0.50 Vert Distance Tolerance: 0.50					

• Redundancies Tab: This screen covers the handling of multiple measurements to the same point, known as redundancies. There are three options for Method: Use First, Use Last or Average. For example, if you shot point 10 a total of four times, you could choose to use the first reading, the last reading or average them all. If you select Average, then the Average Type option becomes available. Here you can choose from coordinate or distance measurement. If you shot point 10 four times, twice from two different setups, and then chose coordinate under the Average Options drop-down, then the 4 northings and eastings computed would be averaged. If you chose instead Distance Measurement, then the two measurements would first be averaged, and then the two distinct coordinates calculated for point 10 (using the averaged measurements) would themselves be averaged.

The **Backsight Reciprocal** option provides special treatment for reciprocals. A foresight to point 15 from a setup on 14, followed by a backsight from 15 to 14, makes a pair of "reciprocal" readings. The backsight reciprocal reading can be ignored (for its impact on recalculating the occupied point), or the Elevation component of the reciprocal measurements can be averaged, or both the Elevation and Distance can be averaged, to recalculate the setup (occupied point) coordinates. The program will calculate reciprocals for backsight direct (BD) records. First set Backsight Reciprocals to Average Elevation. Then if you foresight from 2 to 3, for example, then occupy 3 and backsight 2, the stored BD record will lead to an averaged delta Z calculation for point 3 within Process No Adjust or any of the other adjustment options. If the Tolerances entered above are exceeded, then warning screens appear during the processing.

Note: If there are significant redundancies in a traverse (reciprocal readings, D&R sets, multiple measurements to the same point from different setups, multiple tie shots into control) then it is recommended that the raw file be processed in a Network Least Squares program back at the office, such as SurvNet which is an add-on to Carlson Survey or Carlson Civil.



😂 Process Ra	w File		X			
Total Station	Proj.	Redundancies	Other			
Direct-Reve Direct-		gs ertical Angles:				
Ba	ance Dire	ct-Reverse	•			
Foresig	ht-Backsig	ht measurements	5:			
Balance Foresight-Backsight 💌						
Angle Tolerance (sec): 30.0"						
Distanc	e Toleran	ce: 0.2	2000			

• Other Tab (for D&R Measurements): This tab contains settings for how to use direct and reverse (D&R) measurements. For the vertical angles, you can balance the direct and reverse measurements or use Direct-Only. When you have Foresight measurements and Backsight measurements (e.g. slope distance/zenith angles) between the same points (e.g. reciprocals) in Direct and Reverse surveys, you can Balance Foresight-Backsight measurements (apply reciprocals) or use the Foresight data only. For purposes of warning screens, you can also set the Angle Tolerance and Distance Tolerance for Direct and Reverse measurement processing.



Process No Adjust

This command processes the RW5 file and computes coordinate values for the surveyed data. No angle balance or traverse adjustment is applied. The **Process Raw Data Options** dialog shown below appears after selecting Process No Adjust and then the green check.

💝 Proces	ss Raw Data Options	
	ort Sideshots ort Closure	
Reference	ce Closing Point ID:	2
North:	5002.0000	
East:	5002.0000	
Elv:	10.00000	

You can report the traverse only or compute all measurements by clicking on **Report Sideshots**. If you click on **Report Closure**, then you need to specify a **Reference Closing Point ID**, which is the point that the last traverse point is closing to, or trying to match. The **Reference Closing Point ID** is not a point in the traverse—it is the point the traverse is trying to close on. It can be entered as a point ID or a coordinate.

Note: To preserve coordinate values of the initial setup and backsight, particularly with D&R measurements involved, it is recommended that Redundancies be set to Average by Distance Measurement, if averaging is used.

Pressing OK leads to the calculation and the report screen for Process No Adjust.

ę	Review File	←
	Azimuth Error : 153º07'55"	•
	North Error : -0.04214	
	East Error : 0.02135	
	Vertical Error: -0.20224	
	Hz Dist Error : 0.04724	
	SI Dist Error : 0.20769	
	Traverse Lines> 9	
	SideShots> 40	
	Horiz Dist Traversed: 846.830	
	Slope Dist Traversed: 861.660	-
	<u>۱</u>	



Angle Balance

This method of processing applies an angle balance to the traverse lines when calculating the coordinates. The angle balance takes the angular error divided by the number of traverse lines and adjusts the angle of each traverse line by the calculated amount. The angular error is the difference between the angle balance shot and a reference angle. The program will prompt you to enter the traverse shot to use as the angle balance shot. The measured direction between the occupied point and the foresight point in the specified angle balance shot is then compared to a reference angle. The reference angle is specified as a bearing, azimuth or by a traverse line defined by entering a **From Point** and a **To Point**. The angle balance process is initiated by selecting the angle balance option from the process raw file menu.



The Angle Balance Measurement dialog appears in the figure. Suppose a given traverse started at 24, traversed up to 25, then around a loop and back to 24 (point 45). If point 45 was the end point or closing shot, the traverse leg from 45 to 46 could be the angle balance shot. It is very common, for example, in closed-loop traversing to take a closing angle shot from the closing point (45) by measuring the angle along the first traverse leg (24 to 25). That is what occurred in the case of this sample traverse.

		X
ance Reading:		
Foresight Pt.		
38		
39		
40		
41		
42		
43		
		_
46		
	Foresight Pt. 38 39 40 41 41 42	Foresight Pt. 38 39 40 41 42 43 44 45



Next, the **Reference Closing Angle** dialog appears. Enter the bearing or azimuth of the reference angle or define the reference angle with points by entering in the desired point numbers in the **From Point** and **To Point** fields. If using bearing or azimuth, enter the bearing in DD.MMSS format and then select the correct quadrant from the format field located at the bottom of the dialog. Once the reference angle has been defined, then the angular error display will update with the calculated angular error. The measured closing bearing and measured closing azimuth is displayed at the top of the dialog box. If the reference angle has been defined by point numbers, then the reference closing angle field will update and display the defined angle. There is no need to select a format from the format field if point numbers are used.

Reference Closing Angle	<u>o</u> k	<u>C</u> ancel
Measured Closing Bearing:	N45°00'06	"W
Measured Closing Azimuth:	314°59'54	u
Angular Error: -0.00060000	D	
From Point: 24 To P	oint: 25	
Reference Closing Angle (dd.mi	mss): 45.	0000
Format		
ONE OSE OSW	ONW (0 az

Pressing the **OK** button, or the enter key, will execute the angle balance process, and the process results will be displayed. The results display shows the closure results before angle balance and after angle balance.

Review File Close	Review File Close
East Error : 0.31194	Ending Coordinates: N 10000.373
Vertical Error: 0.00000	Azimuth Error : 37°02'17"
Hz Dist Error : 0.49576	North Error : 0.37267
S1 Dist Error : 0.49576	East Error : 0.28122
Traverse Lines> 21	Vertical Error: 0.00000
Sideshot Traverses> 1	Hz Dist Error : 0.46687
SideShots> 0	S1 Dist Error : 0.46687
Horiz Dist Traversed: 10257.250	Total Hz Dist Traversed: 10257.250
Slope Dist Traversed: 10257.250	Total S1 Dist Traversed: 10257.250
Closure Precision: 1 in 20690	Closure Precision: 1 in 21970

The angular adjustment applied to each traverse leg is also displayed, along with unadjusted angles and adjusted angles for each traverse le.g. The adjusted coordinates are written to the coordinate file replacing the unadjusted coordinate values.



Transit, Compass, Crandall Adjustments

These methods apply the selected rule to the traverse lines when calculating the coordinates. After adjusting the traverse points, the sideshots can also be recalculated. The closure error is calculated as the difference between the specified ending point and a reference point. The ending point is specified in the initial dialog.

😂 Process Ra	w File			×
Total Station	Proj.	Redundancies	Other	
Scale	e: [Grid Coordinates 1.00000000 ature Refraction		
	ing Point: ng Point:	15 26		

You can change the ending point to correspond to the point in the traverse that closes back to the existing reference point. In the current example, point 26 is the final shot, and is closing to an existing point, 10.

The reference point is specified by point ID or by entering the northing, easting and elevation of the reference point.

😂 Proce	ess Raw Data Options	- I I I I I I I I I I I I I I I I I I I	×
🔽 Rep	oort Sideshots		
Referen	nce Closing Point ID:	2	
North:	5002.0000 C Apply Ar	igle Balance	
East:	5002.0000 🗹 Vertical	Error Adjustment	
Elv:	10.00000	oint Adjustments Inadjusted Points	

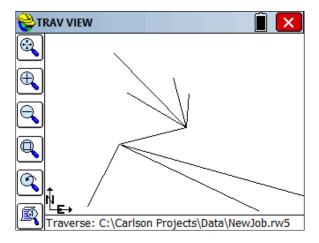


The process results show varying information depending on selected options from the Process Raw Data Options dialog box.

- **Reference Closing Point ID**: The desired closing point number must be entered into this field. If the closing point does not exist in the coordinate file, the known coordinates can be entered into the North, East and Elevation fields on the dialog box.
- Apply Angle Balance: This option performs an angle balance on the traverse lines before the selected adjustment routine is processed. With this option enabled, the Angle Balance Shot must be chosen from the Angle Balance Measurement Dialog box. The adjustment method is applied without angle balance computations.
- Vertical Error Adjustment: The vertical error between the starting and ending points will be calculated and displayed in the results screen. An adjustment value is determined and applied to the traverse points proportional to their measured distance.
- **Report Point Adjustment**: The adjusted point coordinates and the original point coordinates will be displayed in the results display under the adjusted point comparison section.
- Report Unadjusted Points: Displays points not impacted by the adjustment routines.

Draw Traverse Lines

This button will process total station data and show the traverse and sideshots graphically. The example below shows 2 traverse legs and a total of 6 sideshots.





Process GPS

This option is available when GPS data is detected. The opening screen appears below:

😂 Proce	ss Raw	File			X X	
GPS	Proj.	Redund	lancies	Types		
Scale:	1.0	0000000				
Lo	calizatio	n File	Geoid	Separatio	on File	
Locali Geoid	zation Fil File:	e: None None				
Transf	formation	:				
Plane	Similarit	у			Ψ.	
One P	oint Loca	lization Az	imuth:			
State	Plane Gr	id			Ŧ	

If a virtual reference station is used, then the Projection tab will govern and there will be no Localization File, which typically applies to a base-rover setup with UHF radio communication. Clicking the Projection Tab reveals the active projection. Similar to total station adjustment, the Redundancies tab allows selection of the First measurement, Last Measurement or Average of all measurements when duplicate ID measurements are detected. A set of GPS (Lat/Long) measurements can be re-calculated based on new, distinct localization files. For example, if your very last measurement was a control point, you could add that to your localization file (Equip, Localization) and then go to Process GPS to recalculate all GPS measurement taken that day.



4.9 Feature Code List



This command allows you to define default, ready-to-use descriptions. These descriptions lead to linework drawn within SurvCE as well as point symbols. It is important to point out that the drawing of linework and point symbols must be "activated" within Job Settings, Options, by clicking on "Use Code Table for Descriptions". If this is clicked off, linework and symbols will not be drawn. SurvCE ships with "Use Code Table" on. In addition, within Configure, the option "Show Line Details" will automatically redraw the linework whenever any revision occurs or whenever the Map screen is selected. So, if you had a line drawn from points 101 to 105, but then you edited or resurveyed point 102, "Show Line Details" will lead to the automatic redrawing of the line whenever the graphics are shown. If this is clicked off, then you would need to go to the Map screen and select Tools, Field-to-Finish, to update linework.

💝 Job Settings 🛛 🔽 🗙	💝 Configure 🔽 🔀
New Job System Format Options Stake	General View Sets
 ✓ Use Control File Select File C:\CarProjects\Data\NewJob2.crd Store GPS Vectors in Raw File when available ✓ Use Code Table for Descriptions ✓ Recall Job Road Files ✓ Auto Load Map 	✓ Use Line Details ▲ □ Use Layerized Points by Feature Code ↓ □ Use Ctrl Pts for Map Selection ▼ ▲ ▶ No. of Readings to Avg - TS: 1 GPS: Enter/Store Icon - TS: Read & Store

Both lines and points can have attributes describing aspects such as material type, quality, age and date installed. You can create multiple feature code lists and each list can contain an unlimited number of codes. Each feature code consists of a short code, a longer description, a polyline toggle, and a polyline type setting. Point-type features can have symbols. All features can have associated prompting for GIS attributes. Feature codes can be organized into categories, which is useful to sort through large code tables using shorter lists picked by category. The initial dialog is shown below.

Category: ALL Set							
Code Linework Line Type Layer Name							
BLD	Yes		2D		BUILDING		
CB	Yes		3D		ROAD		
CL	Yes		3D		ROAD		
•					Þ		
Ado	i l		Edit		Remove		
Loa	d		Save As Special Codes		Save As		pecial Codes



Add a Feature Code Category

• Set Button: You can add a new category and then within Add or Edit Code, assign each code to a category. Clicking "Set" takes you to the Category Manager. Enter New Categories beside "New Name" and click New. This adds to the Category List within View Category. Then when selecting "All" categories, you can select one or more codes and assign them to the category selected at the bottom of the dialog, by clicking "Move To".

裬 Category	Manag	jer					F
Category:	NO CATEGORY Rename Delete New						•
View C	Categor ategorie	· .	LL				•
Move To Clear All Select All	Code BLD	Linewo No	rk	L	ine T. 20		

Add a Feature Code

• Add: To add a code to the list, select this button. The Add Code dialog will appear.

Select a Feature Code File

• Load: The Load button allows you to select a file to open or edit. Choose an existing file or enter a new file name to create a new Feature Code List. Feature Code List files have a *.FCL file extension.

Edit an Existing Code

• Edit: If you wish to edit an existing code, double tap on the code or highlight it and tap Edit. It will appear in the Edit Code dialog.

Saving the Feature Code List

• Save As: Select the Save As button to save the file. Choose an existing file or enter a new file name to create a new feature code list.

Remove an Existing Code

• **Remove**: To remove a code from the list, highlight an existing code and press the **Remove** button. SurvCE will ask you to confirm deletion of the code.

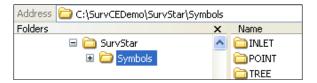
The Add / Edit Code dialog is shown below. Below the figure is a description list of the various options and buttons available in the dialog.



邊 Edit Code				X
Code: MH Category: NO CA Set Symbol Nai Layer: UTILITY Full Text: Manh	me: POIN	▼ T\spt5.Ł	omp Select	Color:
Entity Type: Point 2D Polyline 3D Polyline			New Fe	eature Notes

Code: Enter the name of the Feature Code. For example, you might use EP for edge of pavement. **Category**: If categories have been established (set) within the main Feature Code List screen, then individual codes can be assigned to a category. The very appearance of categories can be removed by clicking off the "Use Categories" option within Special Codes, Settings. This creates more space for the list of codes if there is no intention to use categories.

Set Symbol: For Point entity types, symbols can be assigned, as an option. Symbols plot on the screen for quick reference and will export by .Dwg or DXF using the Map Screen, provided "Include Symbols" is clicked on. Symbols are stored as bitmaps or ".bmp" files, along with ".dxf" files, on subdirectories of the "SurvStar\Symbols" directory created by the install of SurvCE and SurvPC. Three subdirectory "libraries" are typically provided: "Point", "Inlet" and "Trees" as shown below:



Within SurvCE, you can load the any symbol from any selected library by clicking the library, such as "Point" and selecting the symbol to use for the feature code.

8	Select Sy	ymbol		💽 💽	
	POINT	•	•		
		0	•	0	
	spt1	spt2	spt3	spt4	
			\diamond	Δ	
	spt5	spt6	spt7	spt8	

You can create your own symbol library, such as "DDC" shown below, by first creating the additional subdirectory within "Symbols" on your data collector, then adding to that subdirectory both a unit-sized symbol and bitmap for display and viewing, for each symbol. If the "DDC"



subdirectory is selected, for example, an additional manhole symbol could be added as shown below:

Address 🛅 C:\SurvCEDemo\SurvStar\Symbols\DDC						
Folders	×	Name				
 □ □ SurvStar □ InstConfig □ nadconv □ □ Symbols □ DDC 	^	₩HS.dxf				

The bitmap for this "MHS" symbol appears as shown here:

If MHS is entered as a new feature code, this symbol can be selected as follows:

📚 Edit Code 🔽 🗙	📚 Select Symbol 🛛 📝 🔽 🗙
Code: MHS	DDC
Category: NO CATEGORY 💽	
Set Symbol Name: ddc\mhs.bmp	MHS
Layer: UTILITY Select Color:	
Full Text: Manhole Type S	
Entity Type: New Feature	
Point Notes	
C 2D Polyline	

Then when locating MHS features in the field using the command Store Points, the newly defined symbol will plot, as shown below:

<mark> Store Point</mark> 📃 Se	et HT2 🗸 🔀	😂 STORE PTS	🗎 🔀
Pt ID: 1 HT: 4.5	1	Fixed(Sim) ➡14	S
🔲 Repeat Store 🗖 Avg Same Pt ID	_		
N:5034.2751 HSDV:0.045			
E:9942.0116 VSDV:0.083	MG		A
Z:1552.5052 PDOP:3.200	<u> </u>		
Desc: mhs			
Category: ALL	- <u>"</u> (~		
● LP Light Pole			
MH Manhole		Pt: 2 Desc: mhs	HT: 4.5
MHS Manhole Type S	1,2,	N:5029.5133 E:9947.7122	Z:1552.5030
● PK	Ĭ_Ĭ ● ∙.	HSDV:0.050 VSDV:0.102	<u>#8</u> ~

Layer: Symbols and linework can be assigned to layers, and will export to DXF or .Dwg files in the assigned layer. Even if office software is used to conduct field-to-finish, layers and distinct colors are useful for viewing points and linework while in the field.

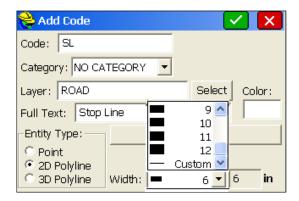


Color: The color of the layer will be applied to the symbol or line. But if you click on the Color box, you can assign a different color than the one associated with the layer.

Full Text: Enter a description for the code. This is only for your information. It will not be added to the point description. It is particularly helpful when using numeric codes, to remind you of what they refer to.

Entity Type: There are 3 entity types: point, 2D polyline and 3D polyline.

Polyline 2D vs 3D: Choose whether the polyline should be 3D or 2D. If you choose **3D**, then each polyline vertex is located at the elevation of the point. If you choose **2D**, then the entire polyline is constructed on elevation 0, regardless of each point's elevation. If 2D is selected, you can change the width of the polyline (in inches or centimeters if metric), as shown below. Selecting "Custom" allows entry of a user-defined width. An example of use might be a painted "stop line" at a road intersection.



Notes: Allows the association of a user-entered Note with any feature code. Since notes have no character limit, large descriptions can be entered as notes and applied to each instance of the feature code, avoiding the need to enter or select the note in the field. Also, for options like "TR" for Tree, you can preset Notes such as the type of tree (oak, maple, etc.) and choose from a list of notes. "Prompt for Point Notes" should be turned on within Configure to access the Notes option. If Settings within "Special Codes" is selected, you can limit the list of notes to choose from, to just the list associated with the Feature Code, by clicking on "Use Code Notes Only When Storing Point".

New Feature (GIS Attributes): This option leads to GIS type attributing, where you can further describe the code (e.g. MH for Manhole) with additional attributes. If GIS attributes are entered for a code, then the "New Feature" button becomes "Edit Feature". SurvCE allows use of the identical, "preferred" names for features as outlined in the ESRI Geodatabase Schema enabling direct uploading in ESRI products and Carlson office products, where the data is auto-linked to screen elements. The link to ESRI and the Carlson GIS office products is accomplished through the Shape File Export command in the Map screen. Then use Import Shapefiles in ESRI or Carlson GIS or other GIS products. An alternative is to save what is known as the MSC extension data into the .Dwg file within SurvCE, and then export to .DWG within the Map Screen. This imports seamlessly into ESRI products.

For example, consider a manhole survey where 4 distinct attributes are to be entered for each manhole surveyed: Lid Diameter, Wall Material, Depth to Flow Line, Number of Inlets. The setup process begins by clicking on "New Feature". If you click "Set", you see that the "Feature Class Name" for the code defaults to the code name "MH". The Feature Class is a GIS term which assists in the database linkages within GIS software such as ESRI and Carlson GIS. A



typical "Feature Class" as named by the "Set" option, might be SWManhole representing "Storm Sewer Manhole". Do not use a colon (:), semicolon (;) or forward slash (/) in the Feature Class name. Clicking Set establishes the Feature Class, and the same Feature Class name can be assigned to different codes. For example, Pine, Spruce and Deciduous trees can all be placed in Feature Class "Trees". In this case, you would enter SWManhole and click OK.

😂 Feature	🗹 In Use	🗲 📚 Poin	t Feature	🗹 🗙
Set MH		CANOPY		
Attribute Type Req. Ed	itable Select-Only			
Point v Remove	Up Do	wn		
			our teste te	
Load Edit	AddSa	ave New Nar	ne: SWManhole	Select

Then for this new Feature Class (SWManhole), you can enter the 4 attributes. The result is shown below at left, with a typical attribute entry (use Add to create new entry) shown at below right. If you click "Add" in the "New Attribute" screen (below right), you can create a list of values to select from while in the field. For an attribute such as depth (to flow line), a real number entry can be specified (as opposed to a character entry involving letters), and no default values would be entered since depths are variable. If you click "Use List Only", then you are restricted from entering an attribute in the field except what is in the list. If you click off "In Use" at the top of the Feature dialog, then you will not be prompted for attributes for this code when working in the field.

癸 Feature			🗹 In Use 🛛 🧲	<mark>ஜ</mark> Edit attribute	
Set St	WMANHOLE			Name: INLETS	Codes
Attribute	Type Red	. Editable	Select-Only	Prompt: Number of Inlets	
COVERDIAM	Char No	Allow	No	Default Value: 1	Set Default
MATERIAL DEPTH	Char No	Allow	No	Type: Char 🔻 Req.: No 💌	Clear Default
	Real No Char No	Allow	No No		
					Jse List Only
				List Values:	Add
				1	Remove
				2	Tremove
Point 📃 💌	Remove	Up	Down	3	Up
Load	Edit	Add	Save	4	Down

When "MH" is coded in the field, the attribute options would then appear. If there are more than 3 options (as above), the Next and Previous buttons become active:



😂 Add GIS Data	SWMANHOLE 💽 🗙
12	[Point] 🔲 Save <u>V</u> alues
(Char) Lid Diameter	
30"	•
(Char) Wall Material	
Precast Concrete	•
(Real) Depth to Invert (Flow	w Line)
Last Values <u>N</u> ext Pr	revious <u>D</u> elete Store

The same system applies to linework. For the fence line code "FL", an attribute called Fence Type might be used, and there may be 6 options, with a default option. These can be set up, one time, by using the **Add** option within New Attributes. Once setup, whenever a fence is chosen, the attributes can be selected from a list. These attributes will be stored in the raw file and most importantly, will output to an ESRI Shape file (Map Screen, File pull - down, Export SHP File). You can even control the prompt and what the default attribute is (in this example, "Chain Link") and if you wanted Chain Link to be first in the list, you could highlight it and click "Up". You can choose whether each attribute entry is required, or just optional. In "Field Edit Mode", the "Hidden" option lets you hide individual attributes on specific jobs so that prompted options are limited to only what you need. The "Read-Only" option ghosts the attribute and does not allow entry or editing, but still displays it in the field and specifically stores the default value shown. The setup screen for new attributes is shown below.

😪 Feature			In Use 🛛 🧲	Edit attri	bute	X
SetST	RUCTURES			Name: F	ENCE TYPE	Codes
Attribute	Type Req.	Editable Se	elect-Only	Prompt: T	уре	
FENCE TYPE	Char No	Hidden No		Default Value	: Chain Link	Set Default
				Type: Char	Req.: No	Clear Default
				Field Edit Mod	ie: Allow 🔽	Use List Only
				List Values:	Allow	Add
				Woven Wire	Read-Only	Remove
				Chain Link	Hidden	Kemove
Line 💌	Remove	Up	Down	Barbed Wire		Up Up
Load	Edit	Add	Save	Wood Rail Stone		🕑 🗾 Down

Fence type is a user-defined attribute. But many attributes of the feature are known by Carlson SurvCE (e.g. the current instrument being used, the date and time, etc.). These types of known attributes appear in a list of special codes, selectable above by tapping "Codes", and shown in the figure below.



📚 Special codes	🔽 🔀
NORTHING	^
EASTING	
ELEVATION	
DESCRIPTION	
DATE	
TIME	
LATITUDE	
Selected code:	
NORTHING	

When you are collecting the points with an "FL" code, and the program detects that you have shot a "point-only" feature, or if you are shooting a line, that you have ended the line (e.g. FL END), then you will be prompted for the attributes. If, however, you select the Point option (lower left) for codes that involve linework, you will get prompted for attributes at each vertex, and then once for the line as a whole. In this way, you can be prompted for attributes of each pole on a power line, and then once for the entire power line (separate set of attributes).

<mark>癸 Feature 🛛 🗖</mark> In Use 🧲					se 🧲		
Set STRUCTURES							
Attribute	Туре	Req.	Editable	Select	-Only		
FENCE TYPE	Char	No	Allow	No			
Line 💌	Rem	ove	Up		Down		
Line Point	Edit		Add		Save		

Note in the dialog below, you can set when you are prompted for the line attributes (start vs end of line). This screen is found within Special Codes, Settings (button at top of screen in Special Codes). The "Use FCL Path to Store *.GIS" means that the folder used for the Feature Code File will also be the folder used for the *.GIS files that are made for each description with attributes. (This applies only to pre-SurvCE 2.51 versions). For example, if MH has attributes, a file MH.GIS will be created. If FH has attributes, a file FH.GIS will be created. These *.GIS files normally store in the current job data directory, in a subdirectory called \CSGIS\FCLFileName (name of the feature code list file). Beginning in SurvCE 2.51, only one GIS file is made, and it always goes in the standard data subdirectory that contains the FCL file. Even this single file protocol is an option in SurvCE 2.51 or later, set by clicking on "Use Single Carlson GIS Features File" at the bottom of Settings within Special Codes. SurvCE 2.51 or later is backward compatible for use with earlier FCL files, and will continue to use the coding system for attributes for FCL files set up by earlier versions, including file location protocols. The GIS file location protocol is shown below, based on a data folder called c:\data and an FCL file name called FieldCodes.fcl:



Prior to SurvCE 2.51

C:\Data\CSGIS\FieldCodes\MH.GIS C:\Data\CSGIS\FieldCodes\FL.GIS, etc.

SurvCE 2.51 and After ("Use Single Carlson GIs Feature File" clicked on)

C:\Data\FieldCodes.GIS

SurvCE also creates an *.VTT file which contains the actual user-entered attributes. This file is associated with the CRD file. The combination of the CRD and VTT files are used to export the shapefiles under the Map Screen, Fill pulldown. If you wish to store the same attribute data on all vertices on a line, you can click on "Store GIS Line Data to All Vertices", as shown below.

😂 Settings	X
☑ Use FCL Path to Store *.GIS	Prompt At:
Store GIS Line Data to All Vertices	End 💌
Use FCL Only Save Only One GIS Feature to the S Store Attribute(AT) to RW5 File Use Code Notes Only, when Storing Use Unique COLORs for Linework	_
T Auto-Detect Code Pattern	

The "Save Only One GIS Feature to the Stored Pt" is a rarely used item which applies to field measurements with 2 or more codes (e.g. MH FH) where MH for Manhole and FH for Fire Hydrant both have GIS prompting associated with them. With this "Store Only One" clicked on, you would be prompted in the field for which item (MH or FH) to assign GIS coding to, and only one set of attributes are associated with the single point surveyed. If "Store Attribute(AT) to RW5 File" is on, then the attribute data also stores to the raw file, and can be viewed using FILE ® Raw Data ® Edit RW5 File.



Special Code Suffixes

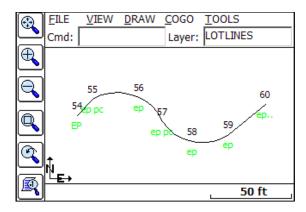
• **Special Codes**: In addition to the codes that you add to the Feature Code List, there are some predefined code suffixes that you may use to end lines or start curves. For example, FL END could end the fence line, with "END" being a predefined special code. The need to append codes is one reason that the "END" button on your data collector is useful, to move to the END of the existing description so you can append a special code. You can substitute new codes for default codes, such that "..." can be substituted for "END" to end a line. To substitute a code, highlight it and enter the substitution characters at the bottom of the screen, in the "Code" entry box. The special code suffixes can also be entered as prefixes, as in PC EP (for start curve) rather than EP PC. Special Codes should be separated from your actual feature codes by a space. However, the alias of "..." can go right up against the feature code as in "FL..". The special codes are described below.

💝 Spe	ecial Codes 🛛 🗾 🔽 🚦	×
Code	Action	^
Space	Code Separator	
None	String Designator	
ST	Begin Line	
END	End Line	
PC	Arc PC	
PT	Arc PT	
CLO	Close Figure	
SMO	Smooth Line	
JPN	Join Point	
RECT	Close Rectangular	
OH	Offset Horizontal	¥
Carlsor	n Code: ST Accep	t

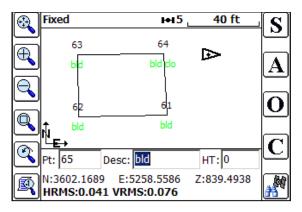
ST & END: Start and End Line. Some users prefer codes such as BL for Begin Line and EL for End Line, and ".." is another example of an "end line" code. You only need either to start or end lines to get new lines. You don't need to use both the start and end line coding. If you code 3 EP points as EP ST, EP, EP then the next new line can be EP ST again. Or you could just end the line as in EP, EP, EP END, then start again with EP. Another separate technique to generate unique lines is to add a number to the code, as in EP1, EP1, EP1. Then if you code EP2, EP2, EP2 a separate line will be drawn. In this case, you don't even need to use the start or end special codes. This allows you to mix the codes up as in EP1, EP2, EP2, EP1. In this case, the EP1 codes will connect and the EP2 codes will connect. See also the discussion below on "Auto-Detect Code Pattern" for techniques of cross-sectioning roads and other linear features. Within Configure, the option "Use Unique IDs for Linework" makes use of the EP1, EP2, EP3 concept by incrementing the appended number each time a new line is started using the line start code (e.g. ST) or the line start icon. With "Use Unique" on, the EP code becomes EP1 when you start a line, and if you use EP again and start another line, the code becomes EP2, etc. In this case, the ST code is retained (redundant but harmless) as in EP2 ST, EP2, EP2.



PC & PT: Used to specify the point of curvature (PC) and point of tangency (PT) of a curve. If you are taking shots on a curve, use PC to specify the beginning of the curve and PT to specify the end of the curve. The PC special code will activate a 3-point arc automatically, so use of the PT code in a 3-point arc is redundant and therefore it is not necessary. You can even do a reverse curve by entering the PT instead as PC. However, if you are picking up a meandering stream or tree line, PT is useful to end the curving feature, and the program will "best fit" a curve through all the surveyed points between the PC and PT codes.

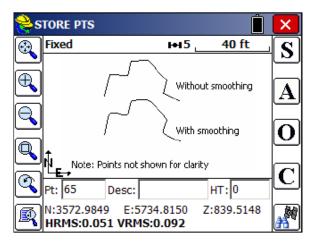


• CLO: Use this code to close a figure. This tells the software to close from the last point coded as CLO back to the first point of the figure. Note that after using a special code such as "CLO", appended with a space to the description code "BLD", that the program automatically removes the special code as it defaults the next description to "BLD". The "CLO" code also has the effect of ending the line and starting a new line. It only works with codes defined as 2D or 3D polylines.

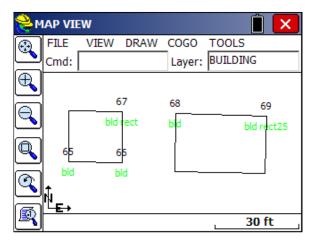




• **SMO**: Use this code to smooth the line through all of the points. This code must occur on the first point of the line.



- JPN: Use this code followed by a point ID to create a new line segment between the current point and the entered point ID.
- **RECT**: This special code can be used in 2 different ways. You can take measurements to 3 sides of a building and on the third side, add the special code RECT, and the program will create a 4-sided building. Or you can measure two sides of a building and enter the distance right (RECT25) or distance left (RECT-20) to create the other, parallel sides. Both methods are illustrated below.

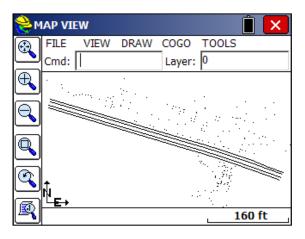


• **OH and OV**: You can also create horizontal offset lines and you can offset these same lines vertically as well by combining OH and OV as in EP OH0.5 OV0.5 (which might create a 6" over, 6" up back of curb parallel 3D polyline). You can even do multiple offset lines as shown below:



😂	9) Job 🔍 C	control 🤯		÷
	Elevation	Descriptio	n	Pt ID	
.27	109.629	tr oh-5 o	h-12.5 oh-17.	5 120	
.97	109.673	tr		121	
.12	109.733	tr		122	
.92	109.808	tr		123	
.96	109.819	tr		124	
.29	109.837	tr		125	
.08	109.780	tr		126	
.18	103.966	tw		127	
.89	104.159	tw		128	-
•					•
<u>E</u> dit		<u>A</u> dd	<u>F</u> ind	De <u>l</u> e	te

This example here leads to a series of 4 parallel lines (for railroad tracks in this case), all offset to the left (negative) of the direction of the points 120 through 126.



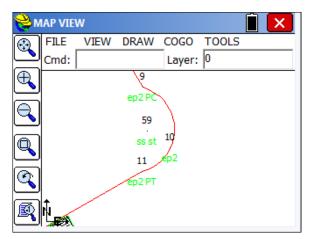
The OH and companion OV commands are flexible in that they can be entered after the first point measured, such as on point 121 or 122.

- NE: No Elevation. When a point is coded NE, it will not be used inside SurvCE for contouring or use in volumes. However, if a 3D Polyline is drawn connecting between points, the elevation will be used.
- JOG: This powerful option allows you to hand-enter right-angle extensions of the last line segment. So if you have just measured 2 BLD points from 14 to 15, you can enter 15 as BLD JOG 12 20 -5 10 17. Minus means left. This represents R12, R20, L-5, R10, R17. The effect is shown below:



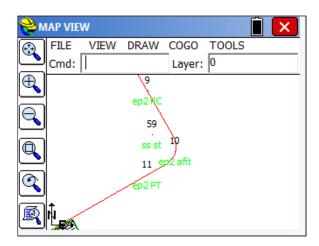
📚 Store Point 🗾 Set HT2 🗸 🗙				
Pt ID: 15 HT: 5.75 👬	FILE VIEW DRAW COGO TOOLS			
Repeat Store				
N:5165.2977 AR:0°00'00" E:5463.6995 ZA:90°00'00"				
Z:504.6028 HD:230.0000	BLD Jog 12 20 -5 10 17			
Desc: BLD Jog 12 20 -5 10 17				
Category: ALL				
	■ bld ST			
BLD Building				

- **ZO**: Elevation Only. This is just a way of coding points as being important only for elevation, for processing typically in other software. It can be viewed as reference information on the point--only the elevation matters.
- **AFIT**: This code stands for "Arc Fit". It is used with 3-point arcs to avoid bulges caused by not picking the PC (start) and PT (end) of a true tangent curve accurately, in the field. When measuring curbs, it is common to get a bulging curve as shown below by picking point 9 too soon, still within the tangent, straight portion of the curb. Note that the EP2 PT description on point 11 is not necessary--the "PT" portion is assumed on a 3-point arc. Only the "PC" code on point 9 is necessary to initiate and draw this arc.

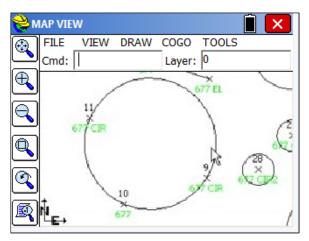


To remove the bulge in the arc and make it tangent, add code "AFIT" to point 10. If Line Details are clicked on within Configuration, the moment you add the text (click 10 directly in map screen and edit it), the line will redraw as shown below. In the field, if you add AFIT ahead of time, anticipating a bulging arc, it will draw correctly in the field.



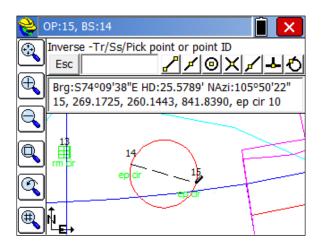


• **CIR**: The Close Circular special code works 3 ways. First, with a single, measured point including a radius distance, it will draw a circle, as in CIR2 for a 2-meter or 2-foot radius (depending on units).



Secondly, if 2 points are used, then the radius becomes the mid-point of the 2 points and a circle will be drawn through both points with the entered radius:





Third, if 3 points are entered as in 9 code CIR, then 10 code, then 11 code CIR, the third point defines a unique circle without user entry of the radius. This is shown in the above graphic. The code used must be a linework code (like EP for edge-of-pavement), not a point code, for the circle to be drawn.

Using Short-Cut Icons to Append Special Codes

With the Prompt for Height and Description turned on within Configure, you have the opportunity to choose from your existing descriptions saved in your Feature Code List, whenever you store points. You also have the ability to select icons for the special codes as shown here:

😂 Store Point 🛛 🗖 Set HT2 🗹 🗙	<mark>📚 Store Point</mark> 🗖 Set HT2 ✔ 🗙
Pt ID: 20 HT: 5.75 🔜	Pt ID: 20 HT: 5.75
🗆 Repeat Store	Repeat Store
N:4969.1425 AR:174°35'19"	N:4969.1425 AR:174°35'19"
E:5130.5037 ZA:91°55'14"	E:5130.5037 ZA:91°55'14"
Z:499.3360 HD:157.0637 🖌 🧭	Z:499.3360 HD:157.0637
Desc: 📴	Desc: 🔝
Category: ALL	Category: ALL
🔨 BLD Building	🕆 BLD Building
	📲 CB Curb 🔤 🖳 🛄
The centerline I.2	Z CL Centerline
🔪 EP 🛛 Edge of Pavement 🛛 🔽 🖌 💽	🔨 EP 🛛 Edge of Pavement 🛛 🚽 🚺 🐽

On the first page, these codes going from top to bottom, starting at the left, represent start line, end line, close line, select active line (when multiple lines are being drawn with the same code), start curve, end curve, rectangle, and "more". When you pick more, the options are offset horizontal, offset vertical, smooth curve, select active line, join to point ID, no elevation, jog and more (return to first set of icons).



Pre-Formatted Special Codes

SurvCE has several pre-made files of codes used by certain highway departments and others. These can be selected from the drop list by selecting Special Codes within the Feature Code command. The actual DOT code files (at right below) can be loaded from the Knowledge Base on the Carlson website, as outlined below.

📚 Sp	ecial Codes 🛛 🗾 🔽 🗙		췆 Coc	le List: Mo	DOT		←	
Code			Categor	ry: ALL			▼ Set	
-	Code Separator		Code	Linework	Line Type	Layer	Full Text 🔼	
l÷.	String Designator		95	Yes	2D	95	Guard Cab	
BS	Begin Line		100	Yes	3D	100	Centerline	
ES	End Line	l l	100	Yes	3D 3D	100	Edge of Co	
С	Arc PC	l li	101	Yes	3D 3D	102	Concrete C	
EC	Arc PT	l l	102	Yes	3D	102		
CL	Close Figure	l l			3D 3D	103	Top Concre	
CLR	Close Rectangular	l k	104	Yes	30	104	Edge of Co	
OH	OH Offset Horizontal		<				>	
OV	OV Offset Vertical						- 1	
J			/	Add	Edit		Remove	
Geopa	Geopak (MO DOT) 🔽 Code: - Accept		Load		Save As		Special Codes	
Geopak (MO DOT) InRoads (MD SHA) Geopak (NC DOT) Geopak (MDOT) TMOSS (CO DOT) Geopak (MDOT) Geopak (OH DOT) Geopak (MB DOT) InRoads (WA DOT) Geopak (IA DOT) Geopak (SC DOT) Geopak (IA DOT) InRoads (NV DOT) InRoads (NYS DOT)								

When a specified format is selected such as Geopak (MO DOT), the standard codes all change, including the separator code. Whereas for normal coding, a space is used to separate a description from a special code (e.g. EP PC), with MO DOT coding, a "-" (dash) would be used as the separator, as in EP-EC. The users of these systems need to be familiar with the required coding. For example, with Geopak (MO DOT) coding, a typical edge of bituminous survey might be coded: 201-BS, 201, 201, 201-C, 201-C, 201-EC, 201, 201-ES. Note that Geopak requires a start line and end line and requires coding on all arc points (C or EC). This coding will process correctly in SurvCE, but SurvCE will also process this coding if the "-BS" is omitted on the first measurement. Use of the special icons within the Hgt/Description prompt screen will append the correct special codes that are active. Geopak also requires points to process linework, so it will not respond to the OH feature and the CLR feature, unless "Create Points for All Linework Elements" is turned on within Settings. (This option appears only if the program detects coding systems requiring the option). Otherwise, OH will create offset lines, for example, with no associated points.



😂 Settings 🛛 🔽 🚦	×	<mark>ஜ</mark> े Settings	\checkmark	X
✓ Use FCL Path to Store *.GIS Prompt At: Store GIS Line Data to All Vertices End Store GIS Line Data to All Vertices	:		Prompt End	At:
Use FCL Only Save Only One GIS Feature to the Stored Pt Store Attribute(AT) to RW5 File Use Code Notes Only, when Storing Points Create Points for All Linework Elements Use Use Use Col One for Linework	<	 ✓ Save Last Point Note ✓ Use Code Categories Linework Layer: <code>_<layer></layer></code> ✓ Allow Carlson FLD File Import ✓ Use New Carlson GIS Features File 		
C Auto-Detect Code Pattern		Auto-Detect Code Pattern		

The various coding systems used by different state highway departments can be loaded at the following locations:

The DOT FCL files are all available at www.carlsonsw.com - here.

Category: SurvCE Topic ID: 388 Title: DOT Feature Code Lists Also, the following link will open the Knowledge Base 388 article. http://update.carlsonsw.com/kbase_main.php?action=display_topic&topic_id=38 8

Other Settings

Store GIS Line Data to All Vertices: When lines are created by field coding, points at the vertices are also created (except for features created by RECT and OH). In addition to associating attribute data with the linework itself, you can click this option to store the GIS attribute data to each point on the line that was surveyed.

Add New Descriptions to FC List: If this option is selected, the Height/Description prompt screen shows only the feature codes in the list and will not display others descriptions used in the current job. This simplifies the code selection process when the goal is to more strictly limit codes to those in the list. New descriptions can be typed and added to the FC List.

Save Only One GIS Feature to the Stored Pt: When two codes are entered for the same point, separated by a space, and both codes lead to GIS prompting, only the first code will be used for the GIS prompts and stored attributes.

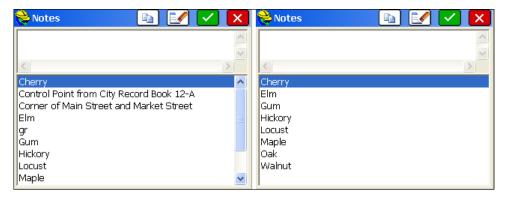
Store Attributes (AT) to RW5 File: All attribute data will store at "AT" records in the raw file. For example, multiple attributes entered for a manhole might appear as shown below. The name of the attribute is identified with a "TN" prefix and the value of the attribute is identified with a "TN" prefix.



Ś	<mark>è</mark> Edit Ra	wfile: A	CESur	vCE.rw5			÷	
	OcPt 0°00'00"	BsPt	BkAz	imuth Se	etAzi		^	
l	OCPt FsPt HorzAngle SlopeDist Zenith							
l	SS 1	27	AR 16	2°00'00"	180.0	1000 ZE	91	
l	SS 1 28 AR 162°00'00" 220.0000 ZE 9 Note							
I	AT, TNCOVERDIAM, TV30" AT, TNMATERIAL, TVConcrete							
I	AT, TNDEPTH, TV4.5							
I	AT, TNINI	LETS, TV		1			<u> </u>	
1	<u> </u>	1	_		- 1		•	
	<u>A</u> dd	E	dit	<u>R</u> emo	ve	Eino	1	

Use Code Notes Only, when Storing Points: This is a method that allows storing more than 31 characters for point descriptions (the normal limit for CRD files). First, you must turn on "Prompt for Point Notes" within Configure. Then, a code such as "CP" can be associated with a long note, such as "Control Point from City Record Book 12-A". You would then select that single note each time and save typing of notes. The notes can then be exported with the points using File, Import/Export. Using File Export, one technique is to set the delimiter on the coordinate values (Pt ID, N, E, Z, Description) to comma and on "Other" (e.g. the note) to Space. In this way, within File Export, you can append the long note to the description as a single field to be imported and used by any office software.

Another use of this option is to limit the list of notes that appear to just those associated with the Feature Code. For example, if you want to use Notes to describe the type of tree just measured in association with code "TR", then you can use the "Notes" option within Feature Codes, option Add or Edit to establish the list of trees as Notes, and then only that list would appear if "Use Code Notes Only" is clicked on. Shown below at left would be all recent notes, then the more limited list with "Use Code Notes Only" turned on.



The 4 buttons along the top of the dialog represent Select Note, Clear Note, OK and Cancel.



Auto-Increment Colors for Linework: Produces different colors, increasing sequentially from 1 to 7 (Autocad (r) color conventions), for each new version of the same feature code (e.g. EP). After color 7, it goes to other distinct colors.

Auto-Increment Layers for Linework: This appends numbers to the linework layer as you make new lines for the same feature code. So, if EP makes lines in the ROAD layer, then the first EP line goes to ROAD1, the next line to ROAD 2, the third line to ROAD3, etc.

Recall Last Point Note: Recalls and applies to the newly stored point whatever point note was used last.

Save Last Point Note to Point List: With this On, all notes that are entered are saved to a file of notes making a Note List (see above graphic). Then users can select previously entered notes from the list, to save typing in the field.

Auto-Create Linework Layer: <CODE>_<LAYER>: This option changes the layer dynamically by appending the code to the layer. So, if both FH (fire hydrant) and MH (Manhole) are defined to be in the Utility Layer, this option will place them in the FH_Utility and MH_Utility layers.

Force Code Separator Between Code and Value: It forces in HGT/Desc to add the separator value (usually "space character") if not present. If you tap, EP, you end use with EP<space> and then you could type, "2" string 2.

Store GIS Line to RW5 as FC (Feature Name): Adds an entry as FC record (usually processed by Bentley Office software). To the RW5 file. FC,PN4,FNfence (Feature code, Key, Feature name).

Force Single Linework if only OV's are used: It allows to, set each vertex to have a different Elevation. Usually, we create individual new lines using the OV, every time we change the values. If on we create one single line with different elevations per each vertex.

Automatic Recall Last GIS Values: This allows the GIS attribute table to be recalled from the last stored point. If only small changes are needed to editable

Apply F2F to Elevation Difference: This will enable Field to Finish during the Elevation difference command.

Warn on Repeated Code: This option allows SurvPC to warn the user that a code used has been repeated.

Use PC (no PT) Arc, F2F Style: Style of no PT. Usually requires a PC, one extra point and the end of the arc (no PT note). Need it for Office software which is not Carlson. Power Survey, InRoads, etc.

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Storing GIS Attrib. Time HH:MM (No Seconds): This option allows for feature codes with time-related attributes to be stored in Hours:Minutes format, thereby eliminated the seconds field.

Auto-Detect Code Pattern: With the option selected, the program will look for patterns of crosssection style coding, particularly applicable to roads and ditches. In the most simple example, consider a ditch or stream being surveying to 3 points: (TB for Top of Bank, DL for Ditch Line and TB for Top of Bank on the opposite side). So consider the Left-to-Right pattern of surveying below:

TB1, DL, TB2

TB1

Right at the point of entering TB1, the program will detect a pattern and will assume the next point is DL and the point after that is TB2 and will default to prompting for that coding. Similarly, consider a L to R then R to L survey:

TB1, DL, TB2

TB2

In this case, with **Auto-Detect On**, the program will prompt next for DL and then for TB1, and then TB1 again, DL and TB2. This same pattern recognition applies to 5-point cross-sections such as CB1, EP1, CL, CB2, EP2 and any number of pattern-based cross-section examples. When a new pattern is detected and the program is about to launch into auto-assignment of descriptions, you will be prompted:



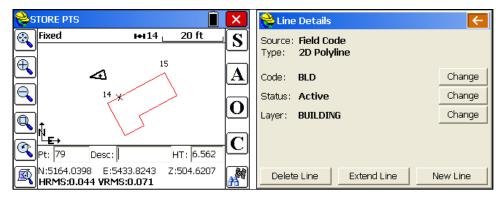
You can survey points outside the pattern by simply entering a different code. The program will then resume auto-assigning the code based on the recognized pattern. Whenever Auto-Detect is on, it is advisable to review the automated code to be certain it matches what is intended. The button: "1.2.." in the HGT/Desc dialog gives you the option to:

- turn ON/OFF auto-detect pattern.
- check the codes that are making the pattern.
- skip a code.
- clear the codes that are making the pattern.

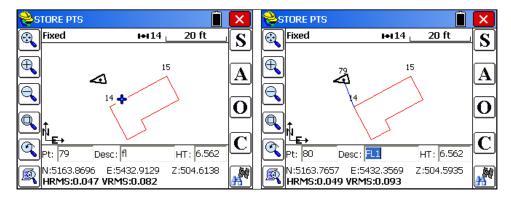


Line Details

When conducting field measurements in the command Store Points, if an existing line created by Field Codes is clicked, on the line but away from the corner points (to avoid Point Details), then an advanced "Line Details" option appears as shown:



The line from 15 to 14 is picked near the X shown at left. Because the picked position is sufficiently distant from the corner point, the program recognizes that a line has been selected and "Line Details" options appear. If the line is extended, it will extend from point 15 based on the next measured point. If the line is deleted, it will be erased. Codes, status and layers can be changed. If the goal is to start a new line from the nearest endpoint (14) to the next measured position, then the "New Line" option would be selected. The new line could be a fence line in a completely new layer, as shown below:





In this way, new lines can start from end points of existing lines without the need to re-survey them (which saves time and is particularly beneficial in high-traffic areas). Even though only one new measurement was taken in this example, a 2-point line is drawn, and the code for point 14 is updated to include the original text as well as the new text. The program cautiously uses both the start code (ST) and the concept of the numerical version of the code (FL becomes FL1, first fence line) to start the line, even though the combination of FL1 and ST is redundant. If point 79 is the end of the line, and "END" is the special code to end a line, then point 79 is coded FL1 END.

8	💿 Job 🔍 Control 🐲 🕞	7 (
ation	Description	Pt ID 🔼
j03	mh	11
500	mh COVERDIAM:30" MATERIAL:Preca	12
.00	MH NE COVERDIAM:30" MATERIAL:Pr	13
603	BLD ST FL1 ST	14
603	BLD Jog 12 20 -5 10 17	15
36	CB	20
603	ep	21
603	ep	22
603	ep	23
603	ep END	24
j03	ep	25 💌
<	III	>
E	Edit <u>A</u> dd Eind	De <u>l</u> ete

Even though point 79 was the newly measured point, point 14 is auto-updated to include BLD ST FL1 ST (start building, the original code and start fence line, the new code). The Line Details process therefore saves field measurement time and field coding time. Line Details, like Point Details, is a transparent or "context-sensitive" command. Simply pick the line or point, without issuing any command, and the options appear. If you do so within the Store Points "context", additional prompting occurs as discussed above. This also applies to Point Details, as described below.

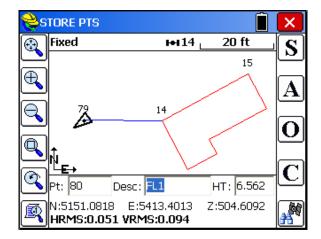
Point Details

When conducting Store Points and using Field Codes, the picking of a point on the screen, in this context, allows for the re-measuring of the point, to correct the field-to-finish linework and symbol placement. (Even if field codes are not being used, picking any point within Store Points allows for re-measurement of the point.) So in the example above, picking point 79 leads to the screen shown below, and the new result if re-surveyed. The original field code will be the default description, but you have the option to change it.



<mark>ऐ</mark> Point Details	←	📚 STORE PTS	Î 🔀
Point ID: 79 Northing: 5163,7772 ft Easting: 5432,4186 ft Elevation: 504,6112 ft Description: FL1 END			14 20 ft S 15 A 0
Edit	Delete	Pt: 79 Desc:	FL1 END HT: 6.562
Re-Meas	ure Point	N:5151.6971 E:5 HRMS:0.041 VRM	5414.2943 Z:504.6138

The result of the new measurement is shown below:



Reprocessing the Field Codes

Using the command **Field to Finish**, found under the Tools pulldown menu in the Map screen, you can reprocess your field codes after editing any aspect of your point data. So if you left off an "end line" command, you can edit the point, change the description, and re-process the linework. In the example using the code RECT25 above, if you edited that point and changed it to RECT50, it would draw a twice as large building when you run **Field to Finish**, and RECT-25 would draw the same building but instead in the opposite direction. If you click on Show Line Details under Configure, this reprocessing is fully automatic whenever a graphic screen is displayed, whether in active survey commands or by going to the Map screen.



4.10 Data Transfer



This command prepares Carlson SurvCE for transferring data to and from a desktop PC or to a USB stick (thumb drive). For Data Transfer to a PC, a program on the PC must be running to receive and send files. SurvCE, using the Data Transfer option, must "handshake" with the program on the PC in order for the transfer to be successful. A serial cable must connect the PC to the handheld device running SurvCE. COM ports must be identified correctly, as well as baud rates. For data collectors with a standard USB port (such as the Carlson Surveyor and Surveyor+), it is only necessary to insert the USB thumb drive into the port. The USB transfer option is part of the "Copy to Storage" feature.

Ê	Data Transfer				X	
[- 1	
	Carlson/C&G Tran	sfer	Manua	l Transfer		
	TDS Transfer		SDR	Transfer		
	Kermit Transfe	r				
	COM Port:	COM1		-		
	None					
	Copy Current	Job to	Folder	Set Folde	er	
	Copy Job to Folder Include Images					

- **Carlson/C&G Transfer:** This option is designed to work with Carlson Software and C&G office products (Carlson Civil, Carlson Survey, Carlson Survey Desktop, Carlson Connect in older Autodesk products, X-Port, CG Survey and SurvNET). It also works with the standalone SurvCom program that is included with the purchase of SurvCE. The handshake is designed for simplicity and robustness. Carlson Software products use the same native file formats as SurvCE, so no file conversion occurs only transfer.
- **TDS Transfer:** This command is used to transfer data from SurvCE to TDS Foresight or other programs that have a TDS Link routine.



- **SDR Transfer:** This command is designed to work with existing programs that communicate with the SDR. For example, if you have LDD, Intergraph, SurvCADD/Carlson Civil, SelectCAD or other software that contains an SDR33 transfer routine, then this option is designed to mimic that protocol. When an RW5 file is selected, it is automatically converted to a Sokkia RAW file and downloaded to the PC. When a CRD file is selected, it is automatically converted to a Sokkia RAW file and Braw file with "08" records for points. This allows you to use and process the data in SurvCE similarly to the data in the SDR33. You can also upload into the SurvCE field computer Sokkia RAW files that contain point records. All the points will be stored in a CRD file on SurvCE.
- **Kermit Transfer:** This command leads to a send and receive screen that works with the Kermit program on the PC. This is a readily available data transfer program.
- Infrared Transfer: Only available on data collectors with infrared capability. This command leads to a send and receive screen that works with the Window Socket IrDA server/client objects only between two CE mobile devices. This is a readily available data transfer program. It works, for example, from Ranger to Ranger. Please make sure you align your devices so that the infrared transceivers are within one meter of each other, and the transceivers are pointing at each other. For an easy connection, it is preferable to start first the server (the device that will receive the data file) and after that the client (the device from which the data file will be sent).
- **Manual Transfer:** This option opens a SurvCE File Transfer Tool. This tool can be used to manually transfer any file to any location.

😔 SurvCE File Trans	fer Tool		×
C:	+	C:	• +
Carlson Projects Intel Manuals PerfLogs Program Files Program Files (x86)	F L L N X	 Carlson Projects Intel Manuals PerfLogs Program Files Program Files (x86) 	(2000 R (2000 U (2000 V (2000 R) (2000
<	>	<	>
File:			



• Set Folder: This option should be selected prior to choosing "Copy Current Job to Folder" or "Copy Job to Folder". The "Set Folder" option allows you to set where the "Copy to Storage" commands will place the files. Where USB output is available, the USB (thumb drive) port is designated as "Hard Disk". You can also store to the CF Card, which is the "Storage" option, and you can store to the SD Card. On the Carlson Surveyor and Surveyor+, the USB thumb device (Hard Disk option) is the default.

误 Select Folder	🔽 🔽
Drive: C 💌	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
🗁 C:\	
🚞 Carlson Projects	🚞 Windows
🚞 Intel	
🚞 Manuals	
PerfLogs	
Program Files	
Program Files (x86)	
Recovery	
🚞 User Manual	
🚞 Users	

- **Copy Current Job to Folder:** This copies the entire current Job, all files associated with the current coordinate file (CRD file), to the selected storage option. This would include th RW5 file, the DXF file (drawing portion), the VTT file (containing GIS data), basically every file sharing the same name as the CRD file.
- **Copy Job to Folder:** This copies the selected Job or CRD file to storage, which can be different from the current file. When the current job or selected job files are copied, the program displays: "Process Done".
- Include Images: This allows the user to copy images associated with job attributes.



Sending data to a computer using the Carlson Transfer Option

- Connect your serial cable to your PC. Select Data Transfer from the File menu. Choose Carlson Xport Transfer. This leads to a File Transfer screen on SurvCE, which prompts "Awaiting Connection". All further action takes place on the PC side. There is no time delay in this handshake. SurvCEwill wait for the PC program to catch up. When you connect the cable from SurvCE to the PC, Microsoft ActiveSync may interfere and display "Connect to PC?" If you get this question, select No and on your PC, disable the Microsoft ActiveSync serial linkage if it is on.
- Execute SurvCom, or for Carlson Survey users (July, 2001 build or later), choose Survey, Data Collectors, Carlson SurvCE option. If you get "Failed to open COM 1 error code -3", the most likely errors are lack of cable connection or interference by Microsoft ActiveSync. If connection is automatically established, SurvCE will display, "Connected to PC".

Local PC Total Files: 83 Bytes: 14280K Bytes Tree: 59970M Local Patr: C Bies/Cerlson software 2006/Data					Remote Total Files: 111 Bytes: 3949K Bytes Free: 18514K Remote Path: \Syst	emcf\Data	1		
Name	Size	Modified	File Type	-	Name	Size	Modified	File Type	
Drawing1.LOT			LOT File		road2-bak.dd	2149	07/07/05 20:42		
Drawing1.co1	67584	05/23/05 13:54	Microsoft Offi		road2.CRD		07/07/05 20:41	CRD File	
Drawing1.PDD	0	07/11/05 21:03	PDD File		road2.dd	5281	07/12/05 19:15	AutoCAD Dr	
Drawing122.CL	261	07/06/05 18:22	CL File		road2.inf	1785	07/12/05 19:48	Setup Inform	
Drewing1bb.P	0	07/06/05 18:26	PDD File		road2 RW5	610	07/07/05 20:41	RW5 File	
DRAWING1_0	5388		XML Docum		road3.CRD	434	07/07/05 20:47	CRD File	
Drawing2.CRD	56	07/11/05 12:52	CRD File		road3.dd	2078	07/07/05 20:51	AutoCAD Dr	
Drawing2 LOT	0	11/16/05 18:40	LOT File		road3.inf	1785	07/07/05 20:51	Setup Inform	
drawing2.TIN	16713	02/01/06 21:37	TIN File		road3.RW5	610	07/07/05 20:47	RW5 File	1
Drawing221.P	0	07/06/05 18:25	PDD File		road4.CRD	896	07/07/05 21:01	CRD File	
Drawing222.C	112	01/18/06 21:44	CRD File		road4.dxf	6116	07/12/05 16:58	AutoCAD Dr	
Drawing222.P.	0	01/18/06 21:09	PRJ File		road4.inf	1785	07/12/05 16:58	Setup Inform	
Drawing3.CRD	280	10/13/05 17:46	CRD File		road4.RWS	1368	07/07/05 21:01	RW5 File	
Drawing3.RW5	31	10/13/05 17:49	RW5 File	_ X	road5.CRD	434	07/08/05 14:57	CRD File	z
•				<u> </u>	•			· ·	J.
File: **		Tag	ged REMOTE	Files: 1			Bytes: 0		
Status: Connected to remote machine Image: Status: Connected to remote machine Image: Status: Connect of the status: Connect									



- 3. If only the left side of the screen on the PC displays data, then you do not have a connection yet. Press the Connect button located at the bottom left of the file transfer dialog. The transfer program will respond with "Retrieving File List". Once the file list has been retrieved, the left side of the dialog box will show files located in the specified path on the PC, and the right side of the dialog will show the files located in the designated path on the remote. You can change directories by scrolling to the top of the file list and choosing Up One Level (just like in Windows). In the above dialog, a filter is applied so that only files in the form of *.crd are displayed. Filters such as this can be set up using the Options button.
- 4. To transfer one or more files, simply select or highlight the desired files and select the Transfer button. More than one file can be transferred from the remote to the PC or from the PC to the remote during the transfer process. Standard Windows selection options apply. For example, selecting one file and then, while pressing the shift key on the PC, selecting another file deeper on the list, will select all the files in between the first and last selected. You can also select the first file to transfer and press and hold down the shift key and use the down arrow to specify the range of files to transfer. Pressing and holding the control key on the keyboard allows for the selection of multiple files in any selection order, by picking the files with the left mouse button.
- 5. After the files, have been selected, press the Transfer button. When the transfer is complete, the program will display the "Transfer Complete" message and will then proceed to update the file lists on the PC and the Remote.

Note: The process of importing points to the data collector mimics the process of exporting points to the office computer, but in reverse. If a point is found to already exist on the data collector, options appear to Overwrite All (Yes All) or Cancel All (No All).

SurvCom Commands

These commands are found and can be seen in the SurvCom dialog box shown above.

- **Connect**: After selecting Data Transfer from the File menu, press this button to connect to the PC. Once connection is made, the status line on the file transfer utility dialog box will show "Connected to the remote machine".
- **Transfer**: Pressing this button transfers selected files from either the Remote to the PC, or the PC to the Remote.
- Set Path: This option allows for the specification of the desired source and destination drives and folders for both the PC and the Remote device. For example, if you were downloading, or copying files from the Remote device to the PC, to specify a source path on the remote device, select the Remote Machine toggle and then type in the desired path in the path field. To specify a destination path on the PC, select the Local PC toggle and type in the desired path the path field. When a change to either path is made, the transfer utility will retrieve a new file list from the specified paths.
- Make Dir: This option allows for creation of directories on both the PC and the Remote device. Specify the machine to create the directory on and then enter the directory name.
- **Delete**: This option allows you to delete the tagged files.
- **Rename**: Select a file and rename it.
- **Options**: This command allows you to set various options for data transfer. The dialog shown in the figure below will appear.



Options	×
COM Port	ActiveSync 💌
File Mask	**
Directory Sort	BY NAME
Display Special Files	NO
Confirm Overwrite	YES
Confirm Delete	YES
Baud Rate	38400
Protect Remote Files	YES
Archive RW5 Files	YES
ОК	Cancel

Com Port: You must select which com port on the PC to use.

File Mask: You must select a file filtering syntax.

Directory Sort: You must select how to sort the list of files.

Display Special Files: Toggle whether or not you should see special files.

Confirm Overwrite: Check this to confirm before overwriting files.

Baud Rate: You must choose the baud rate for transferring data.

Protect Remote Files: Check this to protect files on the mobile device.

Archive RW5 Files: Toggle YES or NO.

• **Geoid**: This command will carve out a portion of the Geoid 99, EGM96, Canadian CGG2000, Canadian HT2.0, Canadian HT1.01, Australian GDA94 and Great Britain OSG-MO2 grid files and send it to SurvCE. Since these geoid grids are very large, the program carves out a precise portion of it and avoids overloading the memory on the remote device running SurvCE. You will be prompted for the directory, on the PC, of the source Geoid grid file, and the approximate latitude and longitude of the job, and the size of the area desired in miles, kilometers or degrees of latitude and longitude.

Set Geoid Area				×
Geoid Grid Files Dir	C:\Carlson So	ftware 2006\DATA		Select
Geoid Type		Geoid 99		¥
Enter Lat/Lon near cente	er of job.			
Latitude(dd.mmss)			€N	C S
Longitude (dd.mmss)			C E	€ W
Grid size	25	C miles	€ km	C deg
Grid Name		geoid	_	
	<u>Q</u> K	<u>C</u> ancel		

- **F2F Conversion**: This converts the more thorough and detailed Carlson Survey field code file (for field-to-finish work) to the more simplified Feature Code List that runs in SurvCE. The Feature Code List in SurvCE handles Linework (on or off), Line Type (2D or 3D), Layer (= Code) and Full Text (Description).
- Send Points: The command allows for the sending of a range of points.
- Exit: This command will exit the File Transfer Utility
- **Bluetooth Transfer**: If the mobile device has a Bluetooth emulated serial COM port, the user will be able to select it from the list, and transfer data from/to another device that has Bluetooth available.



4.11 Import / Export



This command allows you to import an ASCII file to job data or export job data to an ASCII file. When you choose this command, you will see a secondary dialog in which you will be prompted to choose to Import or Export.

🤗 1	mport/Export	×
	Import Ascii File	
		1
	Export Ascii File	
		1

Import ASCII File

This command converts point data from an ASCII text file into the SurvCE format. The source ASCII file can contain any combination of point number, northing, easting, elevation, and description. You may select any of the predefined formats or create your own custom format. Since some of these source file formats (like Carlson CRD and TDS CR5) are not ASCII but are actually binary, Import ASCII file can be used to import points from certain non-ASCII type files. This next figure shows the Import ASCII dialog box.

😂 Import Ascii	🗾 🔽 🔀
	✓ Select File
File Type: User Defined	Select File
C:\Carlson Projects\Data\File.txt	Details
Enter/Select Format: P,Y,X,Z,D	 P,Y,X,Z,D
P-Pt ID, Y-North, X-East, Z-Elv, D-Des	sc, S-Skip
#1#Design Pt#,Design Nor,Design E #Design Pt ID,Design North,Design E	
<	>
Header Lines: 0 Set Add to P	t ID's: 0
Pt's to Import: ALL	Pt Protect



• Source File Format: You must choose the format of the source file. The choices include User Defined: For importing most .TXT and .ASC files. The coordinate order in the Choice field is used.

Traverse PC: For importing Traverse PC .TRV files.

TDS: For importing TDS .CR5 files. Note that CR5 files can contain point numbers in excess of 32760. If point IDs exceed that value, it is best to set **Alphanumeric** as the point ID type under **New Job** in **Job Settings** prior to importing.

Geodimeter: For importing Geodimeter .OBS files.

Trimble POS: For importing Trimble .POS files.

CRD / **CRDB File:** Allows you to import a SurvCE CRD / CRDB file into the current, active CRD / CRDB file, and set the range of points to import. Note that this method can be used to move a subset of points from one CRD file over to another file, as shown below. You can import "All" points or just points 101 to 110, as needed.

Import Ascii	X
File Type: CRD/CRDB Files	Select File Details
Add to Pt ID	s: 0
Pt's to Import: ALL	Pt Protect

SDR File: For importing point data within Sokkia SDR files.

MMH File *.360, MOSS, SDMS, CAICE: Other formats that can be imported. SDMS, for example, is a format for both points and raw survey data that was developed by AASHTO.

- Select File: Type in or browse for the name of the file to import.
- **Details:** Only after a file has been selected, Details can be clicked to show the range of points detected in the file.
- Enter/Select Format: If your Source File Format is set to User Defined, choosing one of these settings copies the contents into the Choice field, which will be used to import the file.
- Choice Field: If you are importing an ASCII file with a special form (e.g. A,Survey,1254552.123,498135.12,1109.23,iron pin,54) then you want a format that skips the first two columns (A and Survey) and does Easting (X), Northing (Y), Elevation (Z), Description (D) and Point ID (P), so your format will be: S,S,X,Y,Z,D,P. If there is no point ID in the ASCII file, you simply omit the P in the entered format, and the program will prompt for a starting point number or ID and will number each subsequent point sequentially.



- **Preview:** Shows you a preview of the first line of the ASCII file. This is helpful in determining the correct coordinate order format.
- Header Lines: Specifies the number of header lines to skip in the ASCII file.
- Set: First highlight the last of the lines in the "Preview" that you want to skip, and then clicking this button sets that specific number of header lines to skip. If all the display lines are valid coordinates, you would not use the "Set" option and would enter "0" header lines to skip.
- Add to Pt ID's: Specifies a value to be added to each point ID during the import process. If you added a value of 100, then point 1 would become 101, point 2 would become 102, etc.
- **Pt Protect:** Specifies whether or not to check each point ID to see if it already exists in the current CRD file. If this is toggled ON and you attempt to import point ID's that already exist, you will then be prompted to overwrite each existing point or to cancel the operation.
- Settings: Notes can also be imported and will associate with point IDs. Settings allows control of the separator used between the point ID information and Note on the ASCII Import (comma, tab, space or "other" as specified).

Export ASCII File

This command converts SurvCE point data to an ASCII text file. The next figure shows the Export ASCII dialog box. Choose a coordinate order, type of delimiter, range of points and precision. After choosing the settings in this dialog box, press OK. A standard file dialog will appear. In this dialog, choose a name for your ASCII file and then press OK. After the file is written, a dialog will appear telling you that the conversion if finished.

😂 Export As	cii				X
File Type: Coordinate O	User D	efined	_		•
Delimiter-	East,Elev,Des		ַד Othe	Config er	
Precision: 0	-19 .0000	Export Other:	P	oint Noto oint Info ttributes	



- File Type: The user may specify the File Type. Selections for File Type are: User Defined, MMH File *.360, MML ETRS File *.mml, KML/KMZ File *.kml/z, SWC File *.swc, JUPEM TXT File *.txt, SDR Raw File *.sdr, SDR Point File *.sdr, TDS File *.rw5, and Pregeo *.dat.
- **Coordinate Order**: You must specify the output format for the ASCII file. There are seven different formats to choose from. The last field is always the description. The fields can be space, comma or tab delimited, and you can also separate the fields by a user-defined delimiter. Two of the options include quotes around the description field so that your descriptions can include spaces and/or commas. An additional option, "Custom", appears at the bottom of the drop list. If this option is selected, the "Config" button becomes active.
- **Config**: With Custom selected for Coordinate Order, Click "Config" to see the dialog options below. Note that if Latitude and Longitude is included in the output, the "Format Geodetic" option in the dialog also becomes active.

Custom		X
Preview:		
ID,NORTHING,EASTING,E	LEVATION	
Available:		Used:
GEOCENTRIC X ^		ID
GEOCENTRIC Y		NORTHING
GEOCENTRIC Z	>	EASTING
DEPTH		ELEVATION
SEAFLOOR Z		
DEPTH_QUALITY	<	
*		
Write "DESCRIPTION"		Up Down
	A	
Justification:	🖲 Right	0 O Left

- **Type of Delimiter:** You must specify the character used for delimiting the fields in the output ASCII file. You may choose either a space, comma, tab or user-defined delimiter.
- **Coords vs Other:** As shown in the first graphic above, you can use one delimiter for the coordinates and another for the "other" information such as notes and GIS attribute data. If, for example, you had notes that were types of trees associated with the "TR" description, then the tree type could be appended to the code TR with a space, as in TR OAK, and export as a single field. You can control whether or not you choose to export notes, point info and point attributes.
- **Range:** You must specify the range of points to output. Ranges can be separated with commas, as in 1-40,101-199,A1-A44.
- **Export Notes:** When this option is enabled, any point notes associated with the current job will be exported to a .NOT file. These files are used with SurvCADD (and other Carlson office software products).
- **Export Point Info:** This exports any "known" information about the point, such as HRMS and VRMS values that have been included automatically in the Note file.



- **Export Attributes:** GIS attributes can be assigned to points that are stored based on settings in the Feature Code List. If a point that is shot is a manhole (e.g. MH) and attributes such as concrete, 5 rungs, 2 inlets are entered for this point, these attributes will be exported to an ASCII file for use by external programs when this option is enabled.
- **Precision:** You must specify the output precision for northings, eastings, and elevations. This setting does not affect point IDs or descriptions. After choosing the settings in this dialog box, press OK. A standard file dialog will appear. In this dialog; choose a name for your ASCII file and then press **OK**. After the file is written, a dialog will appear to let you know that the process is finished.
- Format Geodetic: Based on setting of Custom for Coordinate Order and use of Latitude and Longitude in the export "used" list, the Format Geodetic button becomes active. You can select from many Geodetic formats for the Lat and Long, plus control notation and location of the notation, as shown below.

💝 Format		×
Geodetic Format:	DDD.MMSSSSSS	•
	DDD.MMSSSSSS DDD° MM' SS.SSSS" DDD MM SS.SSSS DDDMM.MMMMMM DDD° MM.MMMMMMM'	* *
Notation:	Sign (+/-)	•
	Sign (+/-) Cardinal (N/S/E/W)	
Location:	Before Angle	-
	Before Angle After Angle	

• This next figure shows the result of exporting a job to an ASCII file.

<u>File E</u> dit <u>H</u> elp	×
📗 🗅 🚅 🔚 🐰 🖦 💼 🎒 💡	
101,3121284.38,882181.92,128.00, 102,3121277.99,882267.69,127.30,	
103,3121275.35,882375.23,126.50,	
104,3121272.52,882482.87,126.40, 105,3121262.36,882580.85,126.40,	



4.12 Delete Job



This command allows you to remove any existing file from any directory to free up memory. This figure below shows the standard file selection dialog, where you can choose the file name to delete.

Note: It is always a good idea to back-up your data by transferring it to a PC before deleting files. Carlson SurvCE does not require you to back-up your data before deleting.

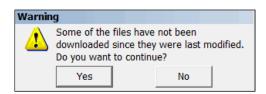
😂 File to Delete 🛛 🗈 💽 🔀
Type: CRD Files 💌 Drive: C 💌 🎓 📂 📖
C:\Carlson Projects\Data\ Backup CSGIS DOTCodes geoids NewJob.crd NewJob2.crd
Name:

Select the file you wish to delete from the standard file selection dialog box and pick **OK**. SurvCE will ask if you want to delete all files associated with the job (e.g. the .dxf file, the .rw5 file, etc.).

Warnin	g			
2	Do you want associated w C:\CARLSON PROJECTS\D	vith this jo I	b?	S
	Yes		No	

Press Yes, if you wish to continue. SurvCE will then warn you if the file or files to be deleted have never been downloaded before.





Press Yes, if you wish to continue. You will be asked to confirm your file selection once more. Press Yes to accept the deletion of the file or files, or No to cancel the selection.



4.13 About SurvCE

This command allows you to view information about Carlson SurvCE and your registration.

😂 About	SurvCE			
\	SurvCE Versio Registered O Carlson Soft	wner:	X/XX/XX	
TS: ON GPS: OI			Char Regist	
ROBOT ROADS	ics: On : On		Char Langu	
Carlson	Software	Copyri	ight (C) 200	1-2017

Change Registration

The Change Registration button will open the SurvCE product registration dialog box. This dialog will allow the user to register SurvCE.

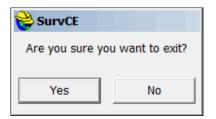
Change Language

The Change Language button will allow you to select the preferred language used in SurvCE.

4.14 Exit



This command will exit the Carlson SurvCE program. The software presents the confirmation dialog.



If you choose Yes, SurvCE will exit and your data files are saved. If you choose No, SurvCE does not exit.



5 Equip

This chapter provides information on using the commands from the Equip menu.

		1	0	😂 JOB:NEWERJOB1		1	0
<u>F</u> ile Equip	<u>S</u> urv	rey <u>C</u> OGO <u>R</u> oa	d	<u>F</u> ile Equip	<u>S</u> urv	/ey <u>C</u> OGO <u>R</u> oa	d
1 Total Station		6 Localization	•	1 Total Station	B	<u>6</u> Localization	
2 GPS Base	3	7 Monitor/Skyplot	\$	2 GPS Base	×	7 Check Level	•
3 GPS Rover	2	8 Tolerances	IP)	<u>3</u> GPS Rover	7	8 Tolerances	P
4 GPS Utilities	ø	9 Peripherals	tà)	4 TS Utilities	V	9 Peripherals	tė)
5 Configure	℀	<u>O</u> About SurvCE		5 Configure	Ŷ	<u>O</u> About SurvCE	



5.1 Total Station



The Total Station routine allows the user to configure their total station communication and operation settings. The tabs shown are configured based on the selected instrument (see specific instrument for details). It is recommended to go left to right through the tabs, from Current to Comms to Settings to Search, to ensure that all settings are correct, especially when first configuring a new instrument. Click the green check mark (not the red X) to accept all changes and continue. Some models of equipment do not have Settings or Search.

Current Tab

Select first the manufacturer and then the model. The routine also provides an instrument recall feature that allows the user to store and recall all instrument-related settings as a user named configuration. Configure all of the settings as desired and select the save button to name and store the custom configuration. Settings that will be retained are as follows:

- Instrument Settings
- Communication Settings
- Configure Settings
- Stakeout Reference Settings

😂 Instrumer	t Setup 🛛 🚯 🔽 🗙	
Current Co	nms Settings Search	
Manufacturer:	Leica Robotic 🔹 🔟	
Model:	TPS 1200 🔽	
Load	Save Delete Defaults	

- Load: This button will load all settings defined by the selected icon.
- Save: This button will save the current settings and allows the user to enter the name of new icons that will be created to represent the instrument settings.
- **Rename**: This button will allow the user to rename the selected icon.
- **Delete**: This button will remove the selected icon.



Comms Tab

There are 5 Comms options: Cable, Bluetooth, Radio, Radio (Bluetooth), and USB. The Comms tab allows you to specify communication parameters for the data collector. For most total stations, communication is by cable. For many newer total stations, there is a Bluetooth option. The user can detect if there is any Bluetooth emulated serial COM port available on the Windows Mobile data collector by looking for the Bluetooth icon or application. Typically, COM 1 and COM 2 are reserved for serial cable connection, so Windows Mobile will use higher COM ports to emulate the connection by Bluetooth. It is recommended to choose COM4 or higher for the Bluetooth COM port. This is done outside of SurvCE, using features of the Windows Mobile device. If the Generic Bluetooth method is selected, then the user can choose the COM port for Bluetooth as prompted within SurvCE. SurvCE can use Bluetooth to communicate only with instruments that have Bluetooth capability. Some total stations have Bluetooth passwords (PIN #) such as "0000". The user can find the Bluetooth device and can change the name and the password for the Bluetooth present on the instrument by using the "Bluetooth Settings" button (the tool icon). In many commands, such as Store Points and Stake Points (in the Survey Menu), there is a Bluetooth "Reconnect" option found under the Helmet icon (upper left), for quick reconnection if Bluetooth linkage is lost. For robotic total stations, there may be a Radio option that resembles the Cable option, except that an extensive list of radio types is available.

裬 Instrur	nent Setup 🚯 🔽 🔀	😂 Instrument Setup 🛛 🚯 🔽 🗙
Current	Comms Settings	Current Comms Settings
Type:	Bluetooth	Type: Radio 💌
	Cable Bluetooth	Radio: Satel 3AS 💽 🗶
BT Type:	Radio Radio (Bluetooth) USB	Defaults
Port:	COM I	Port: COM 1
		Baud: 1200 Parity: Even
		Data Bits: 7 🔹 Stop Bits: 1 💌

- **Port Number:** You must select the COM port to use. This is the COM port of the data collector.
- Instrument (Bluetooth): SurvCE can use Bluetooth to communicate only with instruments that have Bluetooth incorporated on them. The Instrument name is displayed when a Bluetooth connection is made.
- Baud Rate: Baud rate for data transfer by serial cable or radio.
- **Parity:** Parity setting is None, Odd or Even.
- **Data Bits:** You must select the character length setting.
- Stop Bits: You must select the stop bits setting.
- **Defaults:** Clicking Defaults will utilize the standard default settings for the configured instrument.

Bluetooth Wireless



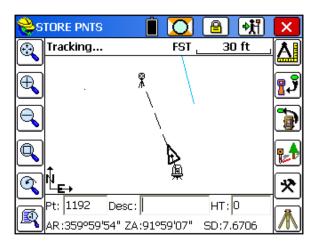
Bluetooth is automatically detected on the Windows Mobile data collector, if available. The com port settings to use Bluetooth vary from unit to unit. For example, Com 3 is typical for the Compaq Ipaq and Com 5 is typical for the Topcon FC1000, though it may use any of Com 4, 5 or 6. On the Allegro, the Bluetooth port is typically Com 4, 5, 8 or 9. The Bluetooth serial com port settings can be found in the "My Bluetooth Device" menu selection.

Settings/Search Tabs

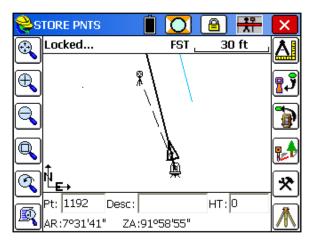
😂 Instrument Setup	💽 🛃 🔽	😂 Instrument Setup	🗈 🔽 🔝
Current Comms Setting	gs Search	Current Comms Settin	gs Search
EDM Mode	Standard 💌	Power Search	Power Search Settings
FS Target	Leica 360 🔹 🛠	Joystick Speed	High
BS Target	Leica 360 🔹 🛠	Search On Read	ATR Search 🔹
Guidelights	Off 🔹	Horiz. Range 4º00'00"	Vert. Range 4º00'00"
Guidelights Intensity	Medium	Turn to Pt. in Stakeout	Horiz. 🗌 Turn Vertical
Laser Pointer	Off 🔹	GPS Search	Settings
Compensator	Enable		

- **EDM Mode:** Options may vary based on the total station selected. Note that EDM mode in these tabs refers to the reading method when using the read button within live survey screens. When the instrument is tracking and the store button is pressed, all readings will be taken at the fastest possible EDM mode.
- On the Leica 1200 total stations, for example, available methods are Standard (1.5 to 2 seconds), Fast, Reflectorless, and User Defined. Referring to the graphic below, when storing points or staking points, your current mode of operation is displayed on the top line (e.g. prism mode, locked on and tracking the target, measuring distances). Clicking the "little man" or distance tracking icon takes the program to the "No Distance" or "Tracking Only Mode" (no distance measurements, locked on and tracking target). Avoiding taking distance measurements will save battery usage. On large topo jobs or as-built surveys, many field surveyors prefer to turn off distance tracking, but leave the instrument locked on the target for quick measurements. On Leica instruments, this will show a beam or line in the direction of the prism, which will move as you walk between measurements. While locked on and tracking distances (as shown below), the store icon (data collector icon) will always take a "Tracking" shot (last shot in memory), and pressing enter will take a Tracking shot if Enter is configured to Store only (to mimic the store icon). Pressing the read icon (measure icon) will always cause a new, fresh reading to be taken, as will Enter when configured to Read and Store (normal). The figure below shows the Tracking/Distance mode, which follows the movement of the prism by taking rapid distance measurements, much like RTK GPS.





Note that in the above figure we are in "Fast" read mode for a configured reading, and in "Tracking/Distance" mode for display and quick readings by S. Changing to "No Dist" mode leads to display of direction only, as shown in this figure:





- Foresight/Backsight Prism Offset: This drop-down menu provides a list of standard prism offsets. Whenever a prism constant is changed, a note is written to the raw (RW5) file. When you select one of the prisms from the list (Circle, Mini, etc), the value that is shown in parenthesis is the actual value sent to the instrument. i.e. 0.0 for Circular, 17.5 for Mini. If you select "30mm" or "40mm", we send 4.4 and 5.6 respectively (30-34.4 and 40- 34.4). The user may also type in any value they choose. In this case, we will send that value exactly, unmodified, to the instrument.
 - o (360) (23.1): Prism offset of 23.1 (Leica model).
 - \circ Circle (0.0): Standard Leica round prism.
 - Mini (17.5): Leica mini prism.
 - ReflTape (34.4): Equates to zero offset (wall, surface).
 - o 30mm: Other manufactures (Sokkia, Seco).
 - 40mm: Other manufacturers.
- **Guidelights**: When available, guidelights can be turned on or off and their intensity set by the user. They are seen from the prism viewpoint, and are valuable when running robotically from the prism, looking at the instrument. The field surveyor can see when he is lined up with the instrument by the appearance of the guidelights.
- Laser Pointer: On *K* / Off *L* Ideal for indoor or dark evening surveying, this feature causes the instrument to emit a red beam. It is often used when doing reflectorless work and makes a red mark on the wall, floor or object being surveyed. This is useful for confirming the position prior to the shot. The beam should not be directed into someone's vision or eye.
- Compensator: Settings are On or Off.
- **Power Search Enabled**: The Power Search option may be available with motorized total stations. This option activates the "Power Search" button in the "banner line" at the top of the survey and stakeout screens. When Power Search is pressed, the total station will typically find the prism in 10 seconds regardless of the direction it is initially pointed. If it has found one prism and you hit "Power Search" again, it will leave that prism and find the next one. If you have only two prisms on the job (foresight and backsight), it will conveniently rotate from the foresight to the backsight and back again each time it is pressed. An option to ignore the backsight is available as well, if preferred.
- Use ATR: When this feature is enabled, ATR (Auto Target Recognition) will be used when configured to standard or fast reading. When running the robotic in remote mode with ATR turned on, and when performing a "Set Angle and Read" in the backsight screen (a standard measured backsight), the ATR connection will be taken into consideration, so that the angle set is relative to the center of the prism, not necessarily the crosshairs of the instrument. The "Set Angle" and "Check Angle" functions will still be relative to the crosshairs. With ATR set on a robotic total station such as a Leica 1200, the prism can be found even if the instrument is not pointed exactly at the prism. The ATR feature is strong enough to shift the instrument onto the exact center of the prism even if sighting slightly outside the prism circle itself.
- Horizontal Range/Vertical Range: This is the range that will be used in a Standard Search. When lock is lost, and the "binoculars" icon appears, tapping the binoculars or "search" icon will conduct a standard search for the prism through the range of horizontal and vertical



angles set, based on the current centering of the instrument. This feature applies to all robotic total stations.

• Power Search (Work Area Settings):

🔍 Work Area Settings	🔽 🗙
● No window (full 360) ○ Ignore Backsight ○ Define Window	
Work Area	Define
Hz Left: 0°00'00"	
Hz Right: 0°00'00"	Center
V Upper: 0°00'00"	
V Lower: 0°00'00"	Show
Min Dist: 0.0000 Max Dist: 0	0.0000

No window (full 360):

This will define an unlimited area for searching, allowing for a full 360-degree search area.

Ignore Backsight:

This option allows for the instrument to ignore backsight when searching points in the field.

Define Window

This will define a limiting area for searching. This can speed up both the standard ATR Search and the PowerSearch. The Work area angle ranges apply to both searches.

- Show will show the two positions of the search window, first by moving immediately to Position 1. You will be prompted to press OK to see Position 2.
- **Center** will move the search window to a new center position. You will be prompted to "Sight on Centered Position and Press OK".
- **Define** will prompt you to shoot the lower left and upper right positions, which are then displayed above under "Work Area". If the Work Area is set to start at 0.0000 horizontal, for example, searching would send the instrument to the backsight point.
- Search When Lost Lock: This feature will auto-search whenever a measurement is taken, if the instrument is not currently locked on target.
- **Turn to Point in Stakeout Horizontal/Turn in Vertical:** These options are useful only in stakeout with motorized total stations, and the effect is to turn to where the stakeout point or position is calculated to be. If Turn to Vertical is off and only Turn to Horizontal is on, the instrument will retain the current vertical position of theodolite.



5.2 Total Station Prism Search by GPS



This feature utilizes NMEA GPS to help the motorized or robotic total station find the prism. Often the NMEA GPS is the one built into the data collector itself. For example, with the Carlson Mini2 or the Hi-Target Qmini, both of which have built-in L1 GPS, the SurvCE software can access this GPS and guide the instrument to the prism. You can also link to an external GPS like a Garmin 10, if your data collector has no built-in GPS capability. This feature is not designed for full RTK GPS, but only for NMEA or any GPS sending the "GGA" message, which is typical of NMEA GPS. This feature is particularly useful with the Focus 30 robotic total station from Spectra, the Focus 10 (former Geodimeter 600 and Trimble 5600), Topcon and Sokkia robotic total stations all of which in certain situations may be interrupted by leaves, fog, reflective surfaces, even the sun in some cases. With Prism Search by GPS, the instrument turns in the direction of the GPS position and can often sight close enough to allow target recognition features to take over and locate the prism.

Grid Coordinates and Local Coordinates: There are 3 ways for the feature to work:

- 1. Fully automatic if the job is on grid coordinates as defined in Job Settings, System Tab.
- 2. Fully automatic if the job is on local coordinates and a GPS localization file is referenced.
- 3. Functional after 3 points due to an internal localization and improving in accuracy until 20 total station field points are measured, after which the program statistically uses the "best" 20 points and removes outliers. Any new point is checked to see if it improves the localization by comparing total station and GPS distances. You can also block the program from considering new points for a tighter localization (such as to avoid points near canopy). The localization for Prism Search by GPS can be stored and re-used in subsequent days.



In the graphic below, GPS Search, using the NMEA GGA message built into the Mini2 data collector, can be used to find the prism if there are many interfering reflecting objects in the vicinity.



The features are found within the Search Tab for any robotic total station driver.

😂 Instrument Setup	🗈 🔽 🛃	
Current Comms Settin	gs Search	
Power Search	Power Search Settings	
Joystick Speed	High 💌	
Search On Read	ATR Search 💌	
Horiz. Range 4.00 Vert. Range 4.00 Turn to Pt. in Stakeout Horiz. Turn Vertical		
GPS Search	Settings	



For any robotic or motorized total station, the Search tab will contain the GPS Search option. Select this and then choose Settings:

😂 Settings 🛛 🗹 🗙
Comm Setup Status: Insufficient Points
Num. Points: 0
 Auto Localization Use Current GPS Transformations Lock Localization Ignore Elevations GPS elevation (relative to prism): 0 ft
Load Loc. Reset Loc.

The Settings dialog shows the 3 methods of GPS Search. Method 1 is Auto Localization which uses the measured field points "on-the-fly". If you have less than 3 field measurements with total station and GPS data in common, Status will indicate "Insufficient Points". If you use Auto Localization from field measurement points, you can lock the localization and not use additional points for the calculation. You can also Ignore Elevations.

If you set "Use Current GPS Transformations", you have 2 options, to work with a loaded localization file or to use no localization file and use only the direct grid coordinates for the selected projection as configured in Job Settings, System. When an existing localization file is loaded, the geoid separation information will be compared against current user settings. Current user settings for geoid separation will override geoid separation data in the localization file. A note regarding the change will be logged in the rw5 file. Any specified Geoid file will also be used in locating the prism from the GPS reading.

The GPS elevation (relative to prism) option allows the user to define an offset between the prism and the GPS in order to get more accurate elevations in GPS Search.

The Comm Setup option refers to the communication with your handheld data collector to obtain the NMEA GPS position. The Mini2, for example, can communicate through Com 8 at 115,200 baud based on an internal connection. You select "Cable" but it is using an internal cable to the motherboard. Clicking the GPS icon at the top of the dialog will verify the connection.



<mark> C</mark> onfigu	re	🖹 🔽 🔀
Туре:	Cable Cable Bluetooth	•
Port: Baud: Data Bits:	COM 8 115200 • 8 •	Defaults Parity: None Stop Bits: 1

It should be noted that you can also use a completely external separate GPS unit for the NMEA message and link to that unit with your data collector (which may lack the GPS NMEA feature). For example, a little Garmin 10 GPS can be the source of the NMEA GPS position, linked by Bluetooth to your field data collector.



5.3 GPS Setup

T

Both Base and Rover GPS are configured with Receiver and RTK in the same manner. Base GPS requires additional setup and is covered in the GPS Base section. GPS Rovers section covers the configuration of GPS networks and internet corrections. This section covers the common portion of the process, selecting the GPS equipment doing basic configuration. In the dialog below, it is recommended to work left to right across the menu structure. Here are two examples (Altus and Ashtech, near the top of the alphabet). The recommended procedure is to work left to right across the tab items, from Current to RTK and then within tab options, verify the items from top to bottom. Note that configurations, including settings in Comms, Receiver and RTK tabs, can be given names, saved and recalled using the Load option.

😂 GPS Base	🗹 🗙	😂 GPS Rover 🛛 🗸
Current Rec	eiver	Current Receiver
Manufacturer:	GPS Simulation	Manufacturer: GPS Simulation
Model:	GPS Simulation Acnovo AD Navigation Altus C4M Carlson Champion Instruments	Model: GPS Simulation Acnovo AD Navigation Altus C4M Carlson Champion Instruments
Load	Save Delete Defaults	Load Save Delete Defaults

Current Tab

Select first the manufacturer and then the model for the GPS equipment to be used. Do this distinctly in the GPS Base and GPS Rover command if different brands and models of GPS equipment are used. The blue 'i' will show receiver, IMEI, and ISDN information when possible; when this is clicked on, SurvCE will refresh the model information.

Comms Tab

Typical connection is by cable, but in more recent GPS models, Bluetooth connection is available, for example, with Ashtech ZMax, ProMark 500, ProFlex 500, Topcon Hiper and GR3, Altus APS-3 and other models. The Blueooth Com port comes from the data collector and can be any number from 3 to over 40. In a few cases such as the Ashtech ZMax, the Bluetooth Com port should be set to the baud rate in Comms Setup to match the baud rate set for Port C on the ZMax receiver which is typically used for Bluetooth communication. For Topcon, set the baud rate in Comm Setup to match the baud rate for Port B on the Hiper receiver, which is typically used for Bluetooth.

Find Receiver

Clicking the tools icon next to the right of Device proceeds to the Bluetooth Manager screen. This screen gives you the option to choose which GPS receiver you would like to connect to via



Bluetooth. If you click Cancel, no Bluetooth connection will be established. Select a receiver and click the Bluetooth icon at the top of the screen, to connect.

📚 Bluetooth Devices 🛛			X
Select Rover BT Device			
Receiver Name		Receiver ID)
DataGrid DataCollector 0 TopconPS	2100039	DataGrid D TopconPS	ataCo
Eind Receiver	Delete Receiver		
Set Receiver PIN	iver <u>P</u> IN Set Receiver <u>N</u> ame		

First time into this routine, no receivers will be listed. Select Find Receiver and you can add the connected receiver to the list. (You may also find ALL Bluetooth devices in the vicinity, which may include cell phones and computers. Find Receiver will "ghost" if. Find Receiver will only work on ARM processor devices, which includes the Allegro and Symbol 8100.

On the Allegro CX and on data collectors with the Socket Bluetooth driver, a search window appears as shown below:

Bluetooth Device Search	😤 Bluetooth Devices 🛛 🔽
Looking for Bluetooth device(s)	Please select from these available devices:
Time remaining;	DataGrid DataCollector 02100039 TopconPS
	<u> ۱</u>

Name:		<u>0</u> K	<u>C</u> ancel
Name:	P	MAXPROT	01020

Delete Receiver

Highlight a Bluetooth Receiver and click Delete Receiver button to remove the device. You will be prompted before removing the device.

Set Receiver PIN

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You can enter the receiver PIN by clicking "Set Receiver PIN", and you can change the receiver name by clicking "Set Receiver Name".

The default PIN is different for each manufacturer and examples for PINs are below. Please see your equipment manuals for your equipment PINS. Topcon 11111 Leica 00000 Thales 12345

Bluetooth Manager

The Bluetooth Manager will appear in many places: entry into the program, clicking OK from Comm Setup, Configure Base, and Configure Rover (it works the same from all of them). After making a successful connection, the software will let the user know. If the connection fails, there will be a warning.

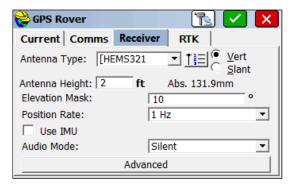
SurvCE	SurvCE
Connection established to receiver: Z-Max 1020.	Receiver Not Found! Check Power and Cabling!

Trouble-shooting Note: Be sure the GPS receiver is turned on before trying to connect, and that you are within 30 feet of the receiver. If the user can't see the device from the Bluetooth Devices program, it is not going to work in SurvCE. The Bluetooth Manager works somewhat better with a passkey but it is not strictly necessary. Sometimes the Bluetooth registry settings don't work correctly with an empty passkey. A pass key is the name the Bluetooth driver uses for a password. This is always used on Thales/Ashtech and can be used on Topcon. It makes the Bluetooth connection more reliable.



Receiver Tab

This tab is used to Configure the receivers Antenna, set the elevation mask and for some gps position rates.



- **Receiver Model**: SurvCE will auto-detect the receiver model and display it in this list. It will also auto-detect the port setting for data and the port baud.
- Antenna Type: The entire list of NGS supported antennas is available for selection. To select an antenna, press the "List" button and search the list by manufacturer. In this dialog, the user can also verify the antenna offset values or create custom antenna types.
- Antenna Height: Entered as either "vertical" or "slant" height in the current job units. The slant height is the distance from the base of the pole or from the "hub and tack" up to a mark or defined slant measurement point on the edge of the antenna (See NGS for more details). The vertical height is measured plumb, straight down from the base (where it screws into the antenna) of the antenna to the ground.
- Use Internal Antenna: Many GPS units now have internal antennas. Select this option if not using an external antenna.
- **Elevation Mask**: This specifies the cutoff vertical angle above the horizon. Any satellites below this angle will be left out of calculations.
- **Position Update Rate**: This option allows the user to set the position update rate for the GPS readings. 1 Hz will display one reading per second, while 5 Hz is 5 times per second.
- Use IMU: This option utilizes the IMU on the internal GNSS Receiver, if applicable for that model. Here, using a Carlson BRx6 the option is available.



- Advanced: This option will allow the user to:
 - Tag Stored Points in Log File using a given duration. SurvCE will ask the user to open a log file if one is not already open.
 - Configure NMEA output (Varying options depending on the receiver type Carlson BRx6 shown below)
 - Configure NMEA Output: Allows for a stream of NMEA data to be enabled and sent / stored at a desired location
 - Configure Constellations button: Allows for enabling / disabling of receiver permitted satellite constellations.

Sdvanced	🔽 🔀		Onfigure NMEA Out	put 🗹	X
			GGA	OFF	•
Log Raw Data to Receiver			GLL	OFF	-
Site Duration:	1 s	_	GSV	OFF	•
Send file after config	No File Selected		GSA	OFF	•
			ZDA	OFF	•
Configure NMEA Output	Configure Constellations		LLQ	OFF	-
			LLK	OFF	•

SAdvanced	🔽 🔀		🖲 Advanced	\checkmark	X
Log Raw Data to Receiver			Use SBAS (WAAS,EGNOS,etc.)		
Site Duration:	1 s		Use Beidou		
Send file after config	No File Selected!	1	Use GLONASS		
Configure NMEA Output	Configure Constellations		✓ Use Galileo		
-					



RTK Tab

The RTK tab is used to configure the GPS RTK communications.

😂 GPS Rover 🛛 🔂 📈	😂 GPS Rover 🛛 🔂 🔽
Current Comms Receiver RTK	Current Comms Receiver RTK
Device: Cable or Generic Device Network: None RTK Port: COM 1 Baud: 115200	Device: Internal UHF Network: None RTK Port: Internal ¥ Baud: 115200 ¥
Message Type: Auto Base ID (0-1023): Use Any Base ID	Message Type: Auto Base ID (0-1023): Vise Any Base ID
😂 GPS Rover 🛛 🔂 📈	😂 GPS Rover 🛛 🔀 🔽
GPS Rover The Comms Receiver RTK	GPS Rover Table GPS Rover Table GPS Rover
Current Comms Receiver RTK	Current Comms Receiver RTK
Current Comms Receiver RTK Device: Internal GSM	Current Comms Receiver RTK Device: Data Collector Internet

Device: This list contains the supported devices that deliver or receive RTK messages, such as a radio or IP modem. If an External Radio is selected, the user will need to specify the Port, Baud, Parity and Stop Bits that the radio manufacturer requires. For internal radios, SurvCE will detect the proper settings.

Network: This list allows you to configure and connect to various networks (e.g. NTRIP).

Message Type: You must select the RTK message type that you wish to broadcast and receive.

This is the format of the RTK message that is either sent from the base and received by the rover. **Base ID**: This is typically used to isolate paired devices. The user specifies that the base is "ID 1", then the rover should be set to only listen for "ID 1" so that other base stations that might be in the area do not interfere.

Send Rover Position to Network: This will output a NMEA GGA message for NTRIP networks that require it – This is located in the configure menu when the **Device** is Internal GSM.



Listen – Listen: Listen – Listen is an RTK mode where the base sends RTK corrections to an online server via IP. The rover(s) will then connect to this online server via IP to obtain RTK corrections in the field. Both the base and rover(s) must have valid SIM cards installed and Listen – Listen service enabled. Please contact your local sales representative if you are interested in more information. Some receivers are capable of the Carlson Listen – Listen mode, notably the Carlson BRx6.

Base Setup: The base receiver can be setup easily in the Equip – GPS Base screen, under the RTK tab. Select Internal GSM for the device, Listen – Listen for the network, and preferred Message Type. Click on the Configuration ICON to the right of Listen – Listen to configure the IP Port and Message Type as shown below.

📚 GPS Base 🛛 🔂 🔀	😂 Configure Listen-Listen 🛛 🔽 🗙
Current Comms Receiver RTK	
Device: Internal GSM 💽 🛠	
Network: Listen-Listen	
RTK Port: Internal V Baud: 115200 V	Name: Listen-Listen 💌
, _ ,	Port:
Message Type: RTCM V3.0 -	RTK Message Type: RTCM V3.0
Listen-Listen	
,	

Rover Setup: The rover receiver can be setup in a similar fashion. Select Internal GSM for the device, Listen – Listen for network, and Message Type (same as base setup). Click on the Configuration ICON to the right of Listen – Listen to configure the proper IP Port and Message Type as shown below.

😂 GPS Rover 🛛 🔂 🔀	😂 Configure Listen-Listen 🛛 🔽 🔀
Current Comms Receiver RTK	
Device: Internal GSM	
Network: Listen-Listen	
RTK Port: Internal V Baud: 115200 V	Name: Listen-Listen 💌
	Port:
Message Type: RTCM V3.0 - Use 1021-102	RTK Message Type: RTCM V3.0
Listen-Listen 💽 🖈	



5.4 GPS Base

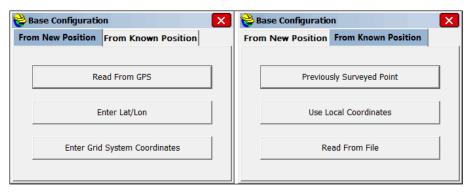


For GPS equipment, it is necessary to set up the base antenna and record the correct antenna height, the antenna type (for certain equipment), and the methods used for localizing (obtaining the desired coordinates).

Much of GPS Base is common to most instruments. For example, the Base Ant. Height would be entered in feet or meters, depending on the setting specified in Units within Job Settings. Vertical or Slant height refers to the method used to measure the height of the base antenna. Vertical refers to the distance from the ground point to the antenna disk, measured plumb. Slant refers to the distance from the edge of the antenna disk down to the ground point directly beneath the center of the antenna. Elevation Mask refers to the degrees above the horizon above which satellites will be used for GPS "correction" calculations, and below which satellites will be ignored. Keep in mind that it is not always better to lower the elevation mask below 10 or 15 degrees. Satellites closer to the horizon than 10 degrees will often degrade the calculation of coordinates.

The "alternative" to GPS Base is GPS Rover. GPS receivers can usually function as either type but must be "configured" for the role they will serve. You will be warned when you switch receiver configuration from Base to Rover and vice versa, to confirm that is what is intended.

With all RTK GPS Equipment selections (except GPS Simulation), GPS Base will first bring up settings and then proceed to the 6-option GPS Base screen which "locates" the base position. After completing the GPS communications setup and clicking on the Ok button the Base Configure dialog will be presented. These button options "locate" the base position. The 6-button GPS Base options (3 buttons per "tab"), common to all, are discussed first, followed by equipment-specific settings.





GPS Base for All RTK GPS Brands

For all brands of GPS, the GPS Base button is the command that configures the base receiver for broadcasting GPS corrections to the rover. You must click the GPS Base button in while you are connected to the base receiver. The base needs a set of coordinates to use as its stationary position. Given that you are configured for a particular coordinate system, there are two "types" of localizations: (1) Enter an Accurate Base Position and work from that point outward on the scale and "true north" of that system (no rover localization), (2) Enter an Accurate or Semi-Accurate (Read from GPS) Base Position and then localize to known rover points that transform to the local coordinate system (required if the local system is not true GPS north). There is also a "mixed" base-rover approach. To use the base in the localization, you should configure the base with the "Use Local Coordinates" option under "From Known Position". Here, you configure the base by entering the local point (5000, 5000,100) and start a new localization file (or use an existing one if it applies). Then, at your rover, you can add more points to the localization as necessary. In this case, a single rover point within Localization will produce a scale factor and best fit to the local coordinates.

There are six methods to set the stationary base position, organized into two categories:

From New Position includes

- Read from GPS
- Enter Lat/Long
- Enter Grid System Coordinates.

From Known Position includes

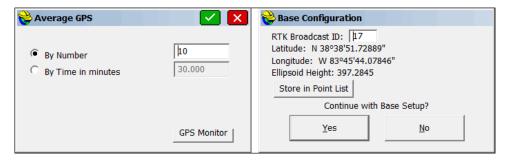
- Previously Surveyed Point
- Use Local Coordinates
- Read From File

When you are starting a new job (no information in the raw RW5 file yet), always use the options in From New Position.



From New Position Options

• **Read from GPS** - This method takes a specified number of GPS readings from the base receiver's autonomous position and uses it as its "true" position. The autonomous position can be off of the actual position by 150 feet. The base will calculate corrections based on this autonomous position. If you set up the base with this method, the rover points must be used for localization since the corrections they are using are based on the approximate position of the base antenna. Read GPS, combined with rover-based localization, is one of the most common methods used to start a GPS survey. When Read from GPS is used, the program will present the current position, as shown:



After the Average GPS routine, the user is presented with a results dialog. Here the user can enter in a Broadcast ID (used for rovers to verify correction stream), store base point in point list, and continue with Base Setup. Answering Yes to the 'Continue with Base Setup' query will bring up an entry screen for the reference file name. Reference files are stored with a ".ref" extension. It is important to save a reference file if you plan to return to the job at another date. Without relocalizing to control points, you can set up over the same base position, recall the reference file, and enter the new antenna height for the base position, and start working.

The Read from GPS option is sometimes referred to as "Find Me". This option is accurate to Autonomous specifications, and it enables the corrections to broadcast with enough accuracy to permit localization and sub-centimeter real-time work. Be sure that your GPS zone in Job Settings is set correctly before using this option. Also, give the base enough time to find itself. When first set up, the base receiver has to "collect" satellites and "resolve ambiguities". If you Read from GPS too early, you may find a position, but one that is not fully resolved and ends up slowing down the speed at which the rover fixes.

• Enter Lat/Lon - Requires you to enter the latitude and longitude for the position of the base antenna. This is useful if you are setting up over a monument whose latitude and longitude is known. It can also be used over a control point whose position is known from GPS post-processing. This will put you on the NAD83, NAD27, UTM or other coordinate system specified in Job Settings, GPS Tab. You can still do a rover-based alignment to transform to a local system. Rover-based localizations are always improved by more accurate base positioning. If the GPS detects that your entered Lat/Long is not near the current GPS readings, the program will warn the user.



😂 Enter Lat/I	Lon	
Use dd.mmss	ss format.	
Latitude:	N 42°21'41.76909"	
<u>N</u> orth	South	
Longitude:	W 71°09'53.44863'	
West	○ <u>E</u> ast	
Height:	33	ft
Ellipsoid	O <u>O</u> rthometric	

This method should be used if you are reasonably sure of the accuracy of the latitude and longitude—it should be at least as accurate as the "Read from GPS" option, or otherwise you will have difficulty getting a "fix" on the rover. If it is a very accurate latitude and longitude, you will get the best results. Pressing OK leads to the option of store the base position as a reference file, similar to Read from GPS.

• Enter Grid System Coordinates: Requires you to enter the grid system northing and easting for the point that the base is occupying. This applies to any projection that you have configured, including U.S. state plane, worldwide UTM or any individual country or user-defined grid system. This is useful if you are setting up over a monument whose coordinates you know. An accurate base position, either by entry of Lat/Long or Grid System Coordinates, will enable immediate data collection without rover-based localization, but also will improve rover-based localization.

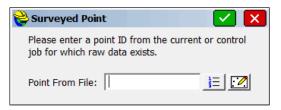
😂 Grid Coordinate		😂 Point	t Details			街 🔽 🖡	÷
		Point ID	Northing	Easting	Elevation	Description	Po
		9 1	5000.00	5000.00	10.000	First Point	1
Point From File:		<mark>-⊕</mark> 2	5002.00	5002.00	10.000	Point 2	2
KY North							
Northing:	ft						
Easting:	ft						
Elevation:	ft						
● Ellipsoid ○ Orthometric							
							•



The Coordinate method is similar to the Lat/Lon method, since Lat/Longs convert to Grid Coordinates based on the current coordinate system set in Job Settings, GPS option. The Grid Coordinates will convert back to the Lat/Long coordinates needed by SurvCE to configure the base.

From Known Position Options

• **Previously Surveyed Point**: This requires you to enter the coordinates, on the configured coordinate system, of a known, surveyed point. This will transform and localize to the local coordinate system, and optionally can be followed by rover-based localization. The known point must be found in the RW5 file in a form that includes its Lat/Long (a previous GPS measurement). This Lat/Long, just as with New Position options, is used to establish the base position. This method requires that you are working within an existing job that has a raw file including Lat/Long positions for the points being used. This next figure is an example of the prompting.



Like the other options, this continues on by showing the corresponding Lat/Long for the coordinate and allowing the user to save the result in a reference file.

• Use Local Coordinates: If you have "localized" using option 5 (Localization) within the Equip menu, you obtain a "dat" file. This localization file is used to convert any Lat/Long reading into a local coordinate. By the same token, you can take a local coordinate, run it back through the dat file and obtain a Lat/Long for the base receiver setup. That is the procedure used in this option.

When OK is pressed, you will be asked to load the associated ".dat" file, in a dialog similar to below:

📚 Local Point 🔽 🔀	😂 Localization File 🛛 🗈 🔽 🔀
Please enter local coordinate values. You may use a point ID from the current or control job.	Type: LOC Files Drive: C
Point From File:	C:\Carlson Projects\Data\
Local Northing: ft	CSGIS
Local Easting: ft	DEMO.loc
Local Elevation: ft	
	Name: NewerJob1.loc



• **Read From File** - Reads a previously saved base position file. All of the other methods of setting up the base let you save the base position at the end of setup. If you return to a site, set up the base in exactly the same position, use Read From File to use the same base position and you don't have to re-align the rover: the old alignment is still valid.

This option recalls a reference file in a dialog similar to that above. Then you will receive the standard prompting.

😂 Base Configuration	
RTK Broadcast ID: 1 Latitude: N 38°38'51.72958" Longitude: W 83°45'44.07860" Ellipsoid Height: 397.2844	
Store in Point List	
Continue with Base Setup?	
Yes No	

This is the Reference Station ID prompt (showing the default ID). A message is displayed after successful configuration from a file. Only if you set the base antenna on the same horizontal and vertical position each day would the base antenna height remain fixed. If the base antenna height and x,y position is the same from day to day, then you do not need to do GPS Base each day. You would simply power up the base, power up the rover and start working in that case. Keep in mind that in certain power surge conditions, receivers can lose their settings, and a re-configuration may be necessary, even if the base receiver antenna has not been moved. The option 'Store in Point List' allows the user to store the base location to the point list of the job.



If the user clicks 'OK', a notification window will be presented. This asks the user if the settings just ascertained should be saved to file. Use this option if the setup will be repeated in the future or preferred.

SurvCE		
Base C to File		Successful. Save Settings
	Yes	No

Note: In SurvCE 1.50.006 or later, a "quick connect" is performed when you exit and re-enter the SurvCE program. In earlier versions of SurvCE (before August 20, 2004) and after the release of SurvCE 1.50 in May, 2004, it was necessary to conduct a fresh GPS Base after exiting SurvCE.

Note: One method of obtaining Latitude/Longitude and state plane coordinates in the U.S. is to occupy a point, any point, for two hours or more, logging the static data, then submit the Rinex file to the NGS "OPUS" program accessible on the web. You must log the data with dual frequency equipment. The OPUS program is fully automated, and will return the x,y,z, lat, long, ellipsoidal height and orthometric height. This data can then be entered in during base localization. Though most post-processing programs (Trimble Geomatics Office, Leica SKI-Pro) use proprietary post-processing file formats, they will output the ASCII "Rinex" format needed by OPUS.



5.5 GPS Rover



For many brands of GPS, receiver perform differently depending on whether they are set as base or rover. Even though the receivers are identical, they perform differently depending on whether they are configured as a base or a rover. Multiple rover receivers can communicate with a single base receiver. The GPS Rover command is used to set the rover receiver to the correct parameters and to instruct the receiver that it is, in fact, a rover.

Connecting a GPS Rover to a Modem or Base Network

There are several methods for connecting to an available network. The RTK tab in the GPS Rover dialog configures the modems and network settings.

😂 GPS Rover		- 🔁 🔽 関
Current	Comms Receiver	RTK
Device:	Internal GSM	- *
Network:	NTRIP	- *
RTK Port:	Internal 💌 Baud:	115200 🔻
Message T	ype: Auto 💌	
NtripInfoCa	ster:	•

The dialog is designed to be filled out from the top to bottom, and from left to right. First select the device you will use to connect to the remote modem or network.

Device:	Internal GSM 🔹	*
Network:	Internal UHF]
	Internal GSM	
	Data Collector Internet	
	Cable or Generic Device	



If a particular receiver model supports an internal modem or radio, meaning it is integrated into the receiver; those devices are shown first in the list. When an internal device is shown in the list, it means that model could have the device inside, but does not guarantee it. The user will have to know if the receiver was purchased with an integrated radio or modem.

External radios and modems are shown next and then one of the last options is "Data Collector Internet", which is a special case explained below where the data collector provides access to the internet instead of a modem inside the receiver or connected to the receiver.

Once a device that is capable of connecting to the internet is selected, the Network combo box is enabled. Select the type of network connection you will use.

裬 GPS Rov	/er	- 🔁 🔽	<mark>/</mark> 🗙
Current	Comms Receiver	RTK	
Device:	Internal GSM	-	*
Network:	NTRIP	-	*
RTK Port:	None TCP/IP Direct		-
	NTRIP		
Message T	SpiderNet Listen-Listen		
NtripInfoCa	ster:	•	

Here is a brief summary of the different network types available:

TCP Direct: For connecting to a single modem at a base or to a VRS network or another network that doesn't require a special login. The configure button for TCP Direct brings up this window:

😂 GPS Rover 🛛 🔁 🔀	😂 Configure TCP/IP Direct 🛛 🔽
Current Comms Receiver RTK	
Device: Internal GSM Network: TCP/IP Direct RTK Port: Internal Baud: 115200 Message Type: Auto Base ID:	Name: Delete IP Address or Host Name: Port: 0 RTK Message Type: Auto Send Rover Position to Network



To add a new base or network address, select <New> in the Name field and replace the "<New>" text with what you want to call the connection and fill out the Address and Port fields. Most modems support either an IP address (Ex: 192.202.228.252) or a URL address (Ex: www.basenetwork.com).

UDP Direct: This works exactly like the TCP Direct option but uses UDP protocol instead of TCP. Most networks use TCP.

NTRIP: This option is for base networks that support NTRIP protocol. Pressing the Configure button shows the NTRIP Broadcasters (Also called Casters) that have been previously connected to.

😂 GPS Rover 🛛 🔂 📈	😂 NTRIP Broadcasters 🛛 🔽 🗙
Current Comms Receiver RTK	Name: NtripInfoCaster New Delete
Device: Internal GSM 🔹 🛠	IP addr: rtcm-ntrip.org Port: 2101
Network: NTRIP	User: Pwd:
RTK Port: Internal <u>Baud</u> : 115200 <u>V</u>	Broadcaster Information Identifier:
Message Type: Auto	Operator: Position 0.00S 0.00W , Misc:
	NMEA: Rover position not needed.

The default is for rtcm-ntrip.org which if connected to will download information about many Broadcasters (casters) all over the world. They will be shown the next time NTRIP Configure is selected. Select an existing caster or select <New> in the Name combo box and replace with a different name and fill out the other information. If the Default User and Password fields are filled out, they will be used as the default user name and password for all the bases at that caster.

When the green checkbox is selected, SurvCE will have the modem connect to the address of the Broadcaster and establish a connection. The Broadcaster then supplies a table of bases (also known as mountpoints) available at that Broadcaster. SurvCE puts the table of bases into the next window that comes up.



裬 Bases fo	r NtripInfoCaster 🛛 🔽 🗙	癸 Bases fo	r NtripInfoCaster 🛛 🔽 🗙
Name:	PRSNVRSCMR New Delete	Name:	PRSNVRSCMR New Delete
User	Password:	User	PRSNVRSCMR word:
Identifier:	PRSNVRSCMR	Identifier:	PRSNVRSRTCM
Short Id:	PRSNVRS	Short Id:	NTRIP_SKMA
Type:	GPS L1L2 Trimble GPS Net WSRN	Type:	GPS LILZ TIMDIE GPS Net WSRN
Format:	CMR+ 1(1), 3(10), 18(1), 19(1)	Format:	CMR+ 1(1), 3(10), 18(1), 19(1)
Position:	47.68N 237.67E USA	Position:	47.68N 237.67E USA
Misc:	WSRN Subnet for Puget Sound	Misc:	WSRN Subnet for Puget Sound
Send Rover Position to Network		Send R	Rover Position to Network

If you don't like the name of the base supplied by the Broadcaster, you can change it to something else you prefer and SurvCE will remember your preference but still ask the Broadcaster for the correct base.

Select the base you want to use and press the green check box. You are brought back to the RTK tab with the base you selected as the current Base ID. You can change the Base ID in the RTK tab without going back to the NTRIP Configure button.

裬 GPS Rov	ver 🔂 🔀
Current	Comms Receiver RTK
Device:	Internal GSM 💽 🗶
Network:	NTRIP 🛃 🔀
RTK Port:	Internal - Baud: 115200 -
Message Ty NtripInfoCa	ype: CMR + 💌 ster: PRSNVRSCMR 💌 🔟

Note that with NTRIP, SurvCE already knows if the base wants the rover position sent and what type of corrections are being sent. Those settings are shown in the RTK tab and are grayed out to guarantee that they stay on the correct setting.



SpiderNet: Networks that require that a GPUID message be sent to the network should use the SpiderNet option. The SpiderNet Configure window comes up when the Configure button to the right of the SpiderNet option is pressed.

😂 GPS Rover 🛛 🔂 📈	😂 Configure SpiderNet 🛛 🔽 🗙
Current Comms Receiver RTK	
Device: Internal GSM 💽 🔀	Name: Delete
Network: SpiderNet	IP Address or Host Name:
RTK Port: Internal - Baud: 115200 -	Port: 0
,	User Name:
	Password:
Message Type: Auto	RTK Message Type: Auto
Base ID:	Send Rover Position to Network

Add a new network by selecting <New> in the Name combo box and typing in the name of the network and filling out the other fields. If the User Name and Password fields are left empty, the GPUID message is not sent to the network.

Just like when using a radio, the RTK Port combo box is to identify which port on the receiver should be configured to accept RTK corrections. The Baud, Parity, and Stop Bits combo boxes specify the settings for the RTK port. Message Type identifies what type of RTK correction message the receiver should be expecting.

Base ID when using a network is a combo box to select the name of the network or base the modem should connect to. Use the Network Configure button to change the bases available in this list.

"Send Rover Position to Network" if turned on will cause the receiver to periodically send GGA messages out of the RTK port to the base or network.



Connecting a Data Collector to the Internet

There are several ways of connecting a data collector to the internet – Cell phone cards inserted into the data collector, connections to a cell phone with a data plan, etc. These instructions assume that an internet connection has already been established to the data collector. One way to tell that the data collector is connected to the internet is to browse the internet using Internet Explorer. For information about how to connect a data collector to the internet using an Enfora cell card in an Explorer 600+, search Carlson Knowledge Base for "Enfora".

Once the connection to the internet has been established, start SurvCE and select Configure Rover in the Equip tab.

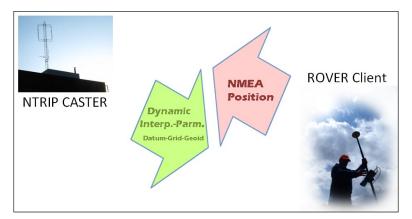
😂 GPS Rover 🛛 🔂 🔀	😂 Configure Data Collector Internet 🛛 🔽 🔀
Current Comms Receiver RTK	
Device: Data Collector Internet	ISP:
RTK Port: Data	Connected Disconnect
Message Type: Auto	RTK and position data will both use the Comms port.

Press the Configure button to the right of the Data Collector Internet option. Select the COM port on the data collector that is connected to the RTK port of the GPS rover receiver. It cannot be the same port that is used to control the receiver and is selected in the GPS Rover Comms tab. It may be a serial port or a BT port with a connection that has already been established.

After selecting the port and pressing the green check to accept the input, select the network type in the RTK tab. Other settings are just like using the other modem selections as explained in the section "Connecting a GPS Rover to a Modem or Base Network".



RTCM 3.1 Message String (for automated Grid Position and Geoid Adjustments)



Certain NTRIP casters (virtual reference systems) send out the RTCM 3.1 message format. A subset of these casters will send out the 1021 to 1027 messages within the RTCM 3.1 formatted messages. When these 1021 to 1027 messages are available, they contain grid system adjustments, sometimes for the x,y position, and sometimes additionally for the geoidal seperation or "Z" elevation adjustment. When these added messages are parsed and applied to the x,y,z position of the RTK reading, greater accuracy is obtained.

Germany, Austria and Croatia are countries where NTRIP casters adopted the RTCM 3.1 message format very early, and included the 1021-1027 message strings for x,y and z adjustments. The example below shows the sequence of operations to capture this message string as broadcast in the Bavarian region of southern Germany. First, confirm you have the correct grid system set. It is recommended not to rely fully on the RTCM 3.1 1021-1027 information for the grid source, but have the correct grid zone loaded within SurvCE itself (Job Settings, System or Localization, System tab).

ݢ Localization 🛛 🗹 🗙	📚 NTRIP Broadcasters 🛛 🗸 🗙
System TS GPS Points By Helmert	Name: SAPOS-BY - Delete
Projection: Edit Projection List	IP Address: 195.200.71.81 Port: 2101 User Name: I Password:
Projection: Transverse_Mercator Datum: DHDN2011_NN2007_Bayern Ellipsoid: Bessel 1841 Convert WGS84 to NAD83	Broadcaster Information Identifier: Operator: Position 0.00S 0.00W , Misc: NMEA: Rover position not needed.



Now go to GPS Rover, RTK tab, select NTRIP for the Network, and click Configure to the right of the NTRIP option. Then load the correct network and IP Address and also enter your user name and password. The network selected above was an early adopter of RTCM 3.1 messages containing the 1021-1027 message strings. Usually you pay for access to most NTRIP service providers to obtain a user name and password.

Then when you click OK, back in the RTK tab, pick Tools/Configure opposite the Sapos-By Ntrip network, and choose the appropriate mount point table or "base" that broadcasts the RTCM 3.1 message string, as confirmed in the dialog below: Note that the format is RTCM 3.1.

📚 Bases for SAPOS-BY 🛛 🖌	😂 GPS Rover 🛛 🚹 🔽
Name: VRS_3_BY Delete	Current Receiver RTK
User Name: VRS_3_BY VRS_BY	Device: Data Collector Internet 🔄 🛠
Identifier: SNET_3_BY	Network: NTRIP
Short Id: RTKMon	RTK Port: Data
Type: G <new> SAPOS-BY</new>	۶
Format: RTCM 3.1 1004(1),1005/1007/1033(10 -	Message Type: RTCM V3.1 USe 1021-1027
Position: 49.00N 11.50E DEU	
Misc:	SAPOS-BY: VRS_3_BY
Send Rover Position to Network	Send Rover rosition to network

If the caster provides the RTCM 3.1 message string for 1021 to 1027, then the option "Use 1021-1027" appears. Check this on. Not every provider that offers RTCM 3.1 will support the 1021-1027 messages.

😂 Alert	🗸 🔽	😂 Alert	🔽 🔽
Projection:	GERMANY/DHDN/Gauss-Kruger zone 4	Projection:	GERMANY/DHDN/Gauss-Kruger zone 4
Datum:	DHDN2011_NN2007_Bayern (RTCM 10	Datum:	DHDN2011_NN2007_Bayern (current)
Horizontal Grid:	SAPOS-BY_VRS_3_BY_13 (RTCM 1023	Horizontal Grid:	None 🗟
Vertical Grid:	SAPOS-BY_VRS_3_BY_13 (RTCM 1023	Vertical Grid:	SAPOS-BY_VRS_3_BY_13 (RTCM 1023
Geoid:	None	Geoid:	None
Use RTCM Projection & Horizontal Grid		Use RTCM Proje	ection & Horizontal Grid
Use RTCM Verti	cal Reverse Vertical	Use RTCM Vertic	cal Reverse Vertical
Datum, Horizontal Grid, Vertical Grid will be saved as		Vertical Grid will	be saved as SAPOS-BY_VRS_3_BY_13



When you continue, you see this Alert screen which allows you to use selected portions of the available adjustments within the 1021-1027 message string. For example, you can choose to use both the horizontal and vertical adjustments or just the vertical to obtain the geoidal shift automatically. The "Reverse Vertical" is a rare option that applied, at least at one time, to a caster that reversed the sign on the geoidal shift. Rather than adding the geoidal shift, it would subtract it. Also, note that if you turn off the horizontal grid adjustment, then the program would revert to your Job Settings, System tab setting for the grid zone, which is why setting that zone initially is important. Where 1021-1027 message data is loaded, and imported by the above method, it is referenced in the software in other commands. For example, using another German NTRIP mount point as shown below, the 1021-1027 data are imported directly into the geoid file selection and Position tab information in Monitor/Skyplot.

Localization	🖌 🔨	🐣 Monitor/Skyplo	t			
ystem TS GPS Points By Helmert		Quality Position S	SATView SATInfo			
Base Translation by Rover Readings		Latitude: Longitude: Ellipsoid Elevation:		N 52°24'36.00000" E 9°48'00.00000" 100.0000		
Multi Point Method: Plane Similarity		Geographic Shift:		Lat:0.00000" Lon:0.0000	0" H:42.592m	
One Point Azimuth: State Plane Grid		Shift File: Localization:	None	None Base Shift:	None	
Geoid File: VRS_3_NI_1.gsf		Local Easting: Local Northing:		32554416.8311 5806942.2153		
Geoid Interpolation Method: Bilinear	•	Local Elevation:		57.4082		
Use Grid to Ground: 1.00000000000		Projection:	VRS_3_NI_1			

Here is another example of use of the RTCM 3.1 1021-1027 message string applying to Croatia:

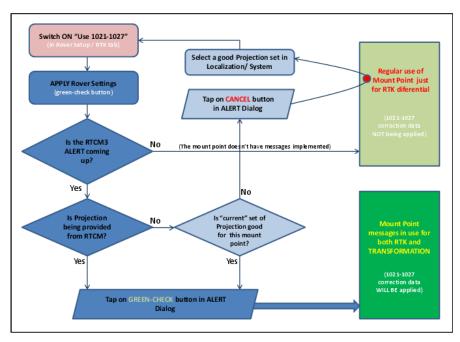
🐣 GPS Rover 🛛 🔂	
Current Receiver RTK	
Device: Data Collector Internet	• 🔀
Network: NTRIP	. 🔀
RTK Port: Data -	
Message Type:	
CROPOS: CROPOS_VRS_HDKS	• 🔀
Send Rover Position to Network	

\checkmark

Localization		× 💽	lonitor/Skyp	lot				
ystem TS GPS Points By He	elmert	Qui	lity Position	SATView	SATInfo			
Base Translation by Rover Readings		-	atitude: ongitude:		N 45°45'30. E 15°54'19.			
Multi Point Method:	Plane Similarity	. E	lipsoid Elevation: eographic Shift:		100.0000		75" H:45.374m	.
One Point Azimuth:	State Plane Grid	- s	hift File: ocalization:	None	C:\Sur083		_Testing\CROPOS_ None	VRS_HDKS
Geoid File: CROPOS_VRS	5_HDKS_2.gsf		ocal Easting: ocal Northing:		5570815.93 5068633.19			
Geoid Interpolation Method:	Bilinear		ocal Elevation:		54.6260			
Use Grid to Ground:	1.00000000000 (📷)	9 P	rojection:	CROPO	S_VRS_HDKS	2		

Current implementation in SurvCE is based in a new RTCM decoder that is compatible with the following RTK methods and devices:

- Any GNSS receiver compatible with SurvCE DCI (Data Collector Internet) RTK method. This mean for those able to make an NTRIP connection using a network device in the Data Collector, like internal GPRS modem, Ethernet, WiFi, etc
- Using the Internal GSM Modem in ALTUS APS 3 or PENTAX SMT888 (both on v2 versions) GNSS rover receivers
- Using the Internal GSM modem in Stonex S8 and S9III receivers





5.6 GPS Raw Only



GPS Raw Only allows the user to configure the receiver to log data internally. This data can be used in post-processing applications. There are three logging methods of GPS Raw Only:

- Static: This method assumes the logging receiver will not be moving (static) during the GPS Raw Only dataset.
- Stop and Go: The method assumes the logging receiver will be moving and storing points (stop and go) during the GPS Raw Only dataset.
- **Fully Kinematic**: This method assumes the logging receiver will be moving continuously (fully kinematic) during the GPS Raw Only dataset.

Once one of these methods is configured, the operation mode will update to show GPS Raw Only is active. In the top bar of the Menu screen(s), the GPS Raw Only Icon will appear.



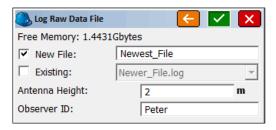
The GPS Raw Only mode can be excited by switching mode within the Quick switch dropdown.

GPS Raw Only – Static Logging

Static logging is categorized as a GPS Base option. Thus, this option can be initialized by either the GPS Raw Only or GPS Base routines. The GPS Raw Only routine allows the user to tag a point.

- Equip GPS Raw Only Settings tab Static selection
- Equip GPS Base Advanced Enable Log Raw Data to Receiver

Certain parameters are assumed when initiating the command via the GPS Base routine, such as logging interval, and stationary as the logging method. Using either routine to initiate the command will navigate the user to the Log Raw Data File screen.



In the Log Raw Data File screen, the user may start a new log file or append an existing log file. The above image is attained through Equip - GPS Raw Only - Settings tab - Static selection, where the user may select data logging parameters in the Settings tab. Alternatively, the user may initiate data logging through Equip - GPS Base - Advanced - Enable Log Raw Data to Receiver. The GPS Base setup routine will allow users to select data logging parameters (receiver specific) from the Log Raw Data File screen, thus a settings icon is shown in place of the back arrow and opens the Raw Data Settings screen (shown below).



🔍 Log Raw Data File			*	\checkmark	×
Free Memory: 1.43120	Gbytes	5			
New File:	New	est_File	9		
Existing:	Newer_File.log				-
Antenna Height:		0			m
Observer ID:					
Settings				\checkmark	X
Log Interval:		1.00 s	econds		•
Include diagnostic	data				

Note: Options available on the Start New File screen will be receiver – specific.

The Antenna Height and Observer ID may be set from this screen as well. The Log Raw Data File screen allows for the initial parameters of the log file to be activated. Clicking on the Back arrow will go back one screen (Equip – GPS Raw Only). Clicking on the Settings Icon will open the Raw Data Settings screen (Equip – GPS Base). Clicking on the Red 'X' will exit out of the logging routine. Clicking on the Green check will:

- Activate the logging file (Equip GPS Base).
- Activate the logging file and continue to the Tag New Site screen (Equip GPS Raw Only).

🖲 Tag New Site				X
Free Mem on R	eceiver: 1.4	308Gbytes		
File: 201	180604_GPS	_Raw.log		
Site Name: 🔽	est1			
Close Site Tag:				
Manually	After	1.00	minutes	

The Tag New Site screen allows for a Site Name to be entered as well as options for how and when to close the Site tag.

Note: Closing the Site Tag will not close or stop the logging file.

Clicking on the Red 'X' will exit the logging command. Clicking on the Green check will continue to the Recording Site screen. We have named our Site Name 'Test1' and selected the Site Tag to be closed in 1 minute.



Recording site 'Test1'	
Site Duration: 00:00:02	
Time Remaining: 00:00:58	
Antenna Height: 2.000 (Vertical)	
Antenna Type: 'Unknown'	
Monitor/Skyplot	
Close File	
Exit - Continue Logging	

The Recording site 'XXXX' screen allows the user to see the current status of the logging file.

The Monitor Skyplot button will allow monitoring options during the logging period. The Site Duration and Time Remaining will show on the top bar of Monitor Skyplot screens.

Site Duration: 00:00:23 Time Remaining: 00:00:37				
Quality	Position	SATView	SATInfo	
Status: Latency			tellites: cal Elev:	16/17 97.9921
Local No	orthing:	4281252.73	861	06/04/2018
Local Ea	asting:	259537.947	78	11:10:46.1
HDOP:	1.10	VDOP:	2.10	
TDOP:	2.00	PDOP:	2.37	
GDOP:	3.10			
HRMS:	0.016			
VRMS:	0.032			

The Close File button will allow the user to close the file immediately. This will prompt the user with a confirmation screen to confirm closing the log file is the preferred operation.

۵.		
	File closed!	

If either the Yes button in the Stop logging data for this point confirmation window or the file completes, the user will see a logging complete notification screen.





By clicking the OK button, the user has finished collecting data for the site.

The Exit - Continue Logging button will allow for the user to disconnect from the receiver.

SurvCE		
	d you like to a lation now?	lisconnect from GPS
	Yes	No

This allows for data logging to be setup on multiple receivers simultaneously. Note however, that logging cannot be stopped automatically when disconnected from the receiver. To stop data logging when using several receivers, a reconnection needs to be made and the close file command ran (Equip – GPS Raw Utilities – Close File).

🔍 GPS I	Raw Utilities	
File:	20180604_GPS_Raw.log(logging)	
	Close File	
	close the	
	File Manager	
Free	Mem on Receiver: 1.3975Gbytes	



GPS Raw Only - Stop and Go Logging

Stop and Go logging is categorized as a GPS Rover option. Thus, this option can be initialized by either the GPS Raw Only or GPS Rover routines. The GPS Raw Only method allows the user to tag points right away by taking the user directly to the Store PTS screen.

- Equip GPS Raw Only Settings tab Stop & Go selection
- Equip GPS Rover Advanced Enable Log Raw Data to Receiver

Certain parameters are assumed when initiating the command via the GPS Rover routine, such as logging interval, and stop and go as the logging method.

🔍 GPS Raw Only	🗾 🔽 🔀	Advanced	🔽 🔀
Current Receiver	Settings		
Mode:	Stop & Go 🔽		
Readings Per Point:	1	Log Raw Data to Receiv	er
Log Interval:	1.00 seconds 🔹	Readings Per Point:	10
🔲 Include diagnosti	c data	Send file after config	No File Selected!
		Configure NMEA Output	Configure Constellations

Reading Per Point is an option allowing the user to select the number of readings to average prior to storing a point. The selection made here (10 in our example) will be part of the GPS Raw Only profile. The number selected for in the GPS Raw Only profile for Reading Per Point will override any setting within the Store Point configuration routine. Using either routine (GPS Raw Only or GPS Rover) to initiate the command will navigate the user

to the Log Raw Data File screen.

🔔 Log Raw Data File		×	
Free Memory: 1.4431	Gbytes		
New File:	Newest_File		
Existing:	Newer_File.log	-	
Antenna Height:	2	m	
Observer ID:	Peter		

In the Log Raw Data File screen, the user may start a new log file or append an existing log file. The above image is attained through Equip - GPS Raw Only - Settings tab - Stop and Go selection, where the user may select data logging parameters in the Settings tab. Alternatively, the user may initiate data logging through <math>Equip - GPS Rover - Advanced - Enable Log Raw Data to Receiver. The GPS Rover setup routine will allow users to select data logging parameters (receiver specific) from the Log Raw Data File screen, thus a settings icon is shown in place of the back arrow and opens the Raw Data Settings screen (shown below).

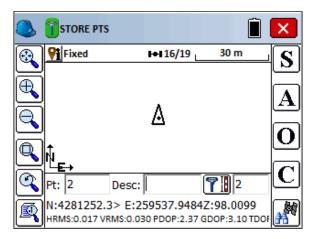


选 Log Raw Data File	🗶 🔽	X		
Free Memory: 1.4312Gbytes				
New File:	Newest_File			
Existing:	Newer_File.log	-		
Antenna Height:	0	m		
Observer ID:				
C and				
Settings	\checkmark	X		
Log Interval:	1.00 seconds	-		
Include diagnostic	data			

Note: Options available on the Start New File screen will be receiver - specific.

The Antenna Height and Observer ID may be set from this screen as well. The Start New File screen allows for the initial parameters of the log file to be activated. Clicking on the Back arrow will go back one screen (Equip - GPS Raw Only). Clicking on the Settings Icon will open the GPS Raw Only Settings screen (Equip - GPS Rover). Clicking on the Red 'X' will exit out of the logging routine. Clicking on the Green check will:

- Activate the Logging File (Equip GPS Rover).
- Activate the Logging File and Continue to the Store PTS screen (Equip GPS Raw Only).



Storing a point will automatically set the user to the Average screen where the Readings Per Point will be initiated and averaged.

An Average Results screen will appear when complete.

Average GPS	🔍 Avera	ge Results		
aking Reading #8 of 10	Valid Re	eadings:	10/10	
Valid readings recorded.	Fixed:		10/10]
		Average		StdDev
North: 0.0022	North:	428125	2.471m	0.0035m
Elev: 0.0049	East:	259537.	946m	0.0028m
	Elev:	97.999n	ı	0.0052m
SATS:16/17 STATUS:FIXED				
HRMS:0.012 VRMS:0.033		Min		Max
Stop Averaging and Store Cancel Averaging	North:	428125	2.466m	4281252.477m

Clicking on the Green check will allow the user to continue storing more points. Clicking on the Red 'X' will cancel the GPS reading.

When the storing points operation is complete, the user may exit to the main menu. However, the logging function is still active. Closing the logging file is shown at the end of this section.

GPS Raw Only – Fully Kinematic Logging

Fully Kinematic Logging is considered a standalone operation. Thus, Fully Kinematic Logging can only be initiated by the GPS Raw Only command. Click on Equip – GPS Raw Only to begin. This will take the user to the GPS Raw Only screen, select the Settings tab.

🔍 GPS Raw Only			X	
Current Receiver	Settings			
Mode:	Fu	lly Kinematic	•	
Readings Per Point:	1			
Log Interval:	1.0	00 seconds	-	
Include diagnostic data				

Select the Fully Kinematic option from the Mode dropdown along with a Log Interval. The red 'X' will exit the logging initialization. The Green check will continue to the Log Raw Data File screen.

🔔 Log Raw Data File		×	
Free Memory: 1.44310	Sbytes		
New File:	Newest_File		
Existing:	Newer_File.log		
Antenna Height:	2	m	
Observer ID:	Peter		

In the Start New File screen the user may start a new log file or append an existing log file.



Note: Options available on the Start New File screen will be receiver – specific.

The Antenna Height and Observer ID may be set from this screen as well. The Start New File screen allows for the initial parameters of the log file to be activated. Clicking on the Back arrow will go back one screen. Clicking on the Red 'X' will exit out of the logging routine.

Clicking on the Green check will continue to the Monitor/Skyplot screen.

🚴 Monito	r/Skyplot			←
Quality	Position	SATView	SATInfo	
Status: Latency:			tellites: cal Elev:	16/17 98.0017
Local No	orthing:	4281252.48	318	06/04/2018
Local Ea	sting:	259537.934	12	11:45:49.3
HDOP:	1.10	VDOP:	2.10	
TDOP:	2.00	PDOP:	2.37	
GDOP:	3.10			
HRMS:	0.015			
VRMS:	0.038			

The user may view any of the tabs within the Monitor Skyplot screen during the logging session. Since the mode is Fully Kinematic, the software assumes the user would only like to log data continuously and the logging function will remain active.



GPS Raw Only - Closing the Logging File

The logging file can be closed in any of three ways:

- Start a new file
- Close File button / Close a Site Tag
- Equip GPS Utilities GPS Raw Utilities Close File
- Exit the software

Starting a new file follows the same procedure as outlined in this section. Exiting the software via File – Exit will prompt the user to close the current log file. Selecting Equip – GPS Utilities – GPS Raw Utilities will offer receiver specific options, including the Close File option.

🔍 GPS I	Raw Utilities	
File:	20180604_GPS_Raw.log(logging)	
	Close File	
	File Manager	
Free	Mem on Receiver: 1.3975Gbytes	

Selecting Close file will close the current logging file.

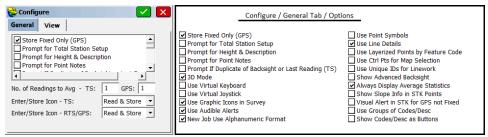




5.7 Configure (General)



This tab allows you to select settings and preferences that apply to observations taken in the field. These options remain set from job to job. If an option is not applicable, it is grayed out. Configure is accessible from within any routine where the C or Configure Icon is present. These options can also be accessed by pressing ALT-C on the keyboard.



- Store Fixed Only (GPS): When enabled, only data gathered in the fixed (locked) status will be stored to the point file. If you attempt to store data when the receiver is not fixed, a message will appear stating, "Position is not fixed! Continue storing?" The program will prompt to store the point anyway. This allows for overwriting the Store Fixed Only option without having to go back to the Configure menu.
- **Prompt for Total Station Setup**: This option determines whether or not the software will display the current setup and orientation values each time the user enters a survey routine.
- **Prompt for Height and Description**: When this option is enabled, you will be prompted after each shot to enter the target height, description, and the option to attach photographs to points/lines. Though this adds an extra prompt screen to each shot, it can reduce errors, as you no longer have to anticipate the shot and get the correct information entered ahead of time. This prompt screen is shown in the figure below. Two additional icons, for tangent curves ("AFIT") and elevation only ("ZO") appear on a third screen. The elevation only option will allow use of a line code such as "EP" for elevation only but will not draw linework through that point. The triple dot icon in the lower right cycles through the icon options, all of which can be entered by hand. When this screen appears, you will have the option to enter a point description and change the point number and the target height. Note that all the field codes identified in the Feature Code List under File are available for touch or arrow key selection, provided this option is activated in Job Settings (Use Code Table for Descriptions). Also, if you enter the first character of a code (for example, "I" for IP), the first field code starting with that character will be highlighted, allowing you to arrow key to the one you want, or accept the highlighted option. This entry is not case-sensitive. Disable the Prompt For Height and Description option to save time while storing points, or if you are certain that your height and description will not change from shot to shot. If the option is disabled, you must be sure that the correct target height and description have already been entered.



😂 Store Point	🔲 Set HT2 🗸 🗙	😂 Store Point	🔲 Set HT2 🗸 🗙
Pt ID: 96 HT: 1.4		Pt ID: 96 HT: 1.4	
Repeat Store N:5057.0997 HSDV:0.046		Repeat Store N:5052.6071 HSDV:0.039	
E:5011.8733 VSDV:0.097 Z:99.6480 PDOP:3.200	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	E:5029.0813 VSDV:0.098 Z:99.6526 PDOP:3.200	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
Desc: E	- ? (?)	Desc:	
Category: ALL		Category: ALL	
▲FL fence line		≣ep2	⊢
● MH		🗐 ep 3	
<u>■</u> RP	1,2,-	FL fence line	1,2,
ZT sw Sidewalk			

Regarding heights, the **icon** will toggle between the current height of measurement (e.g. prism height, antenna height) and a list of previously stored heights. It is useful when switching between commonly used heights such as full pole extension and normal setting.

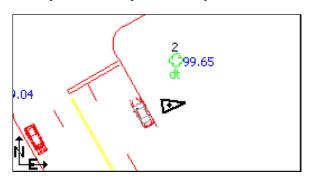
Note: In the Height/Description Prompt screen, you will see pre-defined Feature Code points indicated with a large dot. 2D polylines will show as a simple line, 3D polylines will show as a line with a "Z" indicator, and descriptions entered that are not found in the feature code list will appear with the "fieldbook" symbol above.

- **Prompt for Point Notes:** Point Notes are additional descriptions that can be stored with a point. A regular point consists of a point ID (number or alphanumeric), northing, easting, elevation, and description (up to 256 characters). Point Notes are a way to add an unlimited number of lines of text to a point. With this toggle enabled, you will be prompted for notes after collecting a point. The notes are stored in a file with the same name as the coordinate file, but with a .NOT extension. For example, a job called TOPO.CRD would have a note file called TOPO.NOT.
- **Prompt If Duplicate of Backsight or Last Reading (TS):** This option allows for the user to be alerted if a Backsight or Last reading is duplicated.
- **3D Mode**: This option allows you to toggle between 2D or 3D data. In 2D mode, all elevations will be stored as 0.0 and there are fewer prompts on many screens such as the backsight screen (no instrument height and target heights).
- Use Virtual Keyboard: This option provides a software keyboard for data collectors without keyboards. SurvCE offers a soft-button version of the arrow keys when the virtual keyboard is selected in the robotics screen. This allows some tablets and data collectors without arrows to use the total station joystick feature.
- Use Virtual Joystick: This option provides a software Joystick for data collectors without joysticks.
- Use Graphic Icons in Survey: This option toggles between the traditional letter icons (in versions prior to SurvCE 2.0) and the graphic icons for options like Store Points and Offset. Specifically, for Portrait View, it also organizes the main 5-tab menu items into icons so there is no scrolling of the main menu (see contrasting views below). Although the Store Points screen icons appear immediately when this option is on, the main menu icons in portrait view appear only after re-starting the program.



	: 🗎 法 😡	💝 Configure 🛛 🔽	😂 JOB:ACESURVCE 📋 法 💽
Survey CO	GO <u>R</u> oad	General View Sets	
Eile	<u>E</u> quip		
1 Job 🗳	<u>6</u> Data Transfer 😝	Use Virtual Keyboard	1 Job 🔓 🙆 Data Transfer 😽
2 Job Settings 😜	Z Import/ Export	No. Readings to Average -	2 Job Settings 韸 Z Import/ Export
<u>3</u> Points	<u>8</u> Delete Job 🔄	TS: 1 GPS: 1 Enter/Store Icon - TS:	3 Points 📜 8 Delete Job 💿
4 Raw Data 🛛 💐	9 Write Note 🧳	Read & Store Enter/Store Icon - RTS/GPS:	4 Raw Data 🛛 9 Write Note 🧳
5 Feature Code 👔 List	0 Exit 划	Read & Store 🔹	5 Feature Code 🛍 0 Exit 🖕 🧏

- Use Audible Alerts: Turn on or off data collector sound alarms.
- New Job Use Alphanumeric Format: When this option is enabled, SurvCE will allow alphanumeric point numbers such as 2A or T1105. When this option is disabled, SurvCE will only allow numeric point number entry. Note: this setting only affects new jobs, not existing ones. Using purely numeric files can increase operation speed in very large files, however, this option limits points to just over 32,000. An alphanumeric format will be necessary for files larger than 32,000 points. A comment will be added in the Rw5 file "—CRD: Alphanumeric" or "—CRD:Numeric", based on the format used.
- Use Point Symbols: When turned on, point symbols established for point-based codes in the Feature Code List command will draw on the screen. The value of this option is to distinguish features visually while working in the field, and the symbols stay in the dxf file and can be exported to a .dwg file. Shown below is a tree symbol defined by the code "dt" for "deciduous tree". Point do not have to have defined symbols in the Feature Code List, so even when clicked on, points can still plot without symbols.



• Use Line Details: This option has 2 effects. First, when clicked on, linework will "autodraw" any time a feature code is changed or new points with codes are added to an existing point list. Secondly, the option enables selecting of lines (by clicking on them), leading to options to edit the line, extend the line, or create new lines emanating from the vertices' near the clicked point.



😂 Line Details 🧲	📚 STORE PTS 📋 🗙
Source: Field Code Type: 3D Polyline	Fixed(Sim) I+I14 40 ft S 7 7 7 5
Code: EP1 Change	
Status: Active Change Change Change	1 3 99.57 6 RP 100.00 6p1 ST
View Attributes Delete Line	Pt: 3 Desc: dt HT: 1.4 Image: N:5020.0900 E:4997.3693 Z:99.6493 Z:99.6493 HSDV:0.050 VSDV:0.097 Image: N:5020.097 Image: N:5020.097

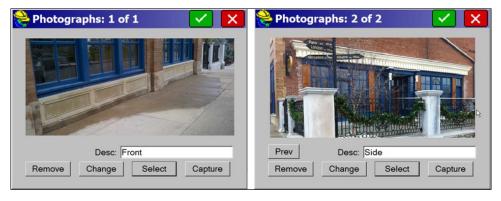
Reviewing the line from 3 through the curve from 4 to 6 and then to 7, this line can be clicked within the map screen without issuing any command, and the Line Details screen will appear at left. If you tap too close to a point ID, then Point Details will appear. But you can also click lines within the command Store Points. This provides additional options to Extend the Line and draw a New Line from the nearest vertice to the picked point. These options are discussed in detail in the section on Feature Code List found in the File menu.

- Use Layerized Points by Feature Code: This feature allows the user to use point layers.
- Use Ctrl Pts for Map Selection: This allows users to use Control Points for Map Selection.
- Use Unique IDs for Linework: This will impact the meaning of the "Start Line" special code, which is also appended using the green circle icon shown here: When clicked on, then start line will not only append the start line code (such as "ST") to the feature code, but will increment the code number by 1, as in EP2 ST. If the last line was EP2, then using the start line icon on another EP would create a code EP3 ST. In this way, there is no need for an end line code, since each distinct EP has its own numeric identifier (as in EP1, EP2, EP3).
- Attach Photographs to Points/Lines: This feature appears when the program detects a data collector operating system capable of using an external camera or built-in camera, such as with certain Getac, Hi-Target, Flint, the Nautiz X7 used with Navcom GNSS and other models. In Portrait mode, the option appears as shown below. Also turn on Height/Description Prompt in Configuration to use the Camera feature. Then when field measurements are taken by GNSS, total station or other means, you can tap the camera icon within the Height/Description prompt screen (middle below). Then you can select an image that is stored anywhere on the field data collector, or you can click "Capture" and take a photo. The images are associated with the point or line, and more than one image can be attached. Each individual image can be given a description. If multiple photographs are associated descriptions. You can Remove any if desired. Any single Photo can be Changed to better match the description (or removed and added again).



Configure	Store Point HT2 V X Pt ID: 2 HT: 0	Photographs: 1 of 2
Use Unique IDs for Linework	Repeat Store HSDV:0.104 N:127582.9589 HSDV:0.104 E:542072.0492 VSDV:0.133 Z:139.5274 PDOP:1.987	
TS: 1 GPS: 1 Enter/Store Icon - TS: Read & Store	Desc: Category: ALL	
Enter/Store Icon - RTS/GPS: Read & Store		Desc: > Downtown Maysville Select Remove Change Capture

When adding photos by "Select" or by "Capture", the Next and Prev buttons will appear in Landscape mode when more than 1 picture is attached.



The Camera feature, when activated here, also appears both in Line Details (when clicking a Line) and within Input-Edit GIS Data in Map, Tools menu.

Seman view	😂 Line Details	←	Ndd GIS Data	BLDGLN
FILE VIEW DRAW COGO TOOLS	Source: Drawing 3D Polyline		1367955700 (Char) Material:	[Line] Save Values
Cmd: Layer: PILLARS			Brick	
	Layer: ROAD	Change		
	View Attributes			
	Delete Line		Del Recall	Next Prev Save

In these commands, you can review photos and continue to Capture, Select, Change or Remove photos associated with the selected entities.

• Show Advanced Backsight: This option applies to total station work and allows for multiple reference backsight points, each one of which can be sighted and measured multiple times. Then, based on least squares analysis, the program will compute a "best fit" backsight for



purposes of zeroing the total station. The command can be likened to a special Resection for purposes of zeroing the instrument (or setting it to a backsight azimuth). This is a more commonly used in Europe. You can still obtain very accurate backsights to a single backsight point using direct and reverse methods, so most surveyors do not turn on this feature. The feature has some built-in error checking to prevent improper calculation if the coordinates for the backsight reference points are not correct or in proper relation to each other.

• Always Display Average Statistics: This option defaults on the "Always Display Average Statistics" option within Store Points, A for Average. An example of this average statistics display for a sample of 10 GPS readings appears here:

- Show STK Directions from Last Stored Point: Directions to the new point to stake will be in reference to the last stored point using the Point List option.
- Show Slope Info in Stake Points: This option will display slope information from your current reading to the target point to stake.
- Visual Alert in STK for GPS not Fixed: This will alert the user when in a Stakeout routine the current position mode is not Fixed.
- Use Groups of Codes / Descriptions: This will allow the user to use Groups of Codes and Descriptions for Stored Points.
- Show Codes / Descriptions as Buttons: This will allow the user to show the Codes and Descriptions as Buttons.

With both 'Use Groups of Codes / Descriptions' and 'Show Codes / Descriptions as Buttons' enabled, the user can quickly set the code and descriptions of stored points.



📚 Configure 🔽 🔀	💝 Description: 🔽 🔀
General View Sets Show Slope Info in STK Points 	Category: ALL ALL Desc:
 ✓ Use Groups of Codes/Desc ✓ Show Codes/Desc as Buttons 	2D * 2P * 4D * 4P * 6D * 2P * 4D * 4P * 6D
No. of Readings to Avg - TS: 1 GPS: 1	6P * 8D * 8P * 9P * 10D *
Enter/Store Icon - TS: Read & Store 💌	

No. of Readings to Avg (TS & GPS): Specifies the number of readings that will be taken and averaged on each observation. Values between 1 and 9 are accepted for Total Stations and 1-999 for GPS. If the tolerance is exceeded between readings, a warning screen will appear.

Note: The Num Dist Readings setting does not apply to Manual Total Station mode. In this mode, you can use the Calculator to average distances. When prompted for Slope Distance, enter "?" to bring up the calculator. Choose the Scientific Tab. Follow the tutorial below to average three values:

141.213 Enter 141.211 Enter 141.220 Enter

Now press + on the keyboard twice and with the first +, 141.220 is added to 141.211 to get 282.431, then with the second + you get 423.6440.

Then enter 3 and type "/" (backslash) for divide. This gives the result: 141.2147.

Choose the Copy button at the bottom of the screen, then Paste at the top.



Enter/Store Icon (TS & RTS/GPS): Since the Enter key is a convenient and popular way to take shots in the Store Points command, SurvCE allows you to specify the effects of this key. These different functions of the Enter key apply not only to Store Points but also to Elevation Difference. The function of the Enter key is set separately for Total Stations and GPS. The different options are described below. Note: Most users choose Read then Store.

- Store Then Read: This option similar to the effects of the Read key on the original SDR data collectors. After a backsight, the first time Enter is used, it will take the shot and display the results. Then when you foresight the next point, Enter will "Store Last, Read Next". This procedure is best used with the above Hgt/Desc Prompt on Save disabled. If that option is on, then when you turn to the new shot and press Enter, the new shot doesn't take right away, but instead, you are prompted for the target height and description of the previous shot. That could cause some confusion. But with Hgt/Desc Prompt turned off, this method can be very efficient. You press Enter and take your first shot. You see the results displayed and can alter descriptions or target heights or point numbers for that shot. You sight your next foresight, and press Enter and the previous shot is correctly stored and the next is taken. The information is displayed. You can review and alter it. You sight your next foresight, press Enter and shoot the next, etc.
- **Read then Store:** With this option, the Enter key takes the shot and stores the point. This option works very well with the Hgt/Desc Prompt on Save turned on, in which case Enter key takes the shot, then displays the results and provides an opportunity for editing as in the Store Point dialog shown above.
- **Read or Store:** The first Enter key takes the reading and the second Enter key stores the reading.



5.8 Configure (View)



These settings control the reporting appearance of the stakeout navigation information. The **Method** setting allows you to choose the stakeout information that is most appropriate for your situation and personal preference. The options for Method are described in detail below.

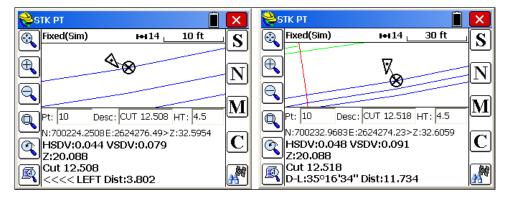
📚 Configure 🔽 🗙	😂 Configure 🔽 🗙
General View Sets	General View Sets
Method: Collapsed Report: In-Out & Left-Right to Ref Navigate Data Ref. Object: Point Move Relative To: Ref. Object Use CL for Ref. Object (when applicable) Use Horizontal Clock System	Method: Collapsed Report: Deflection L/R & Distance Navigate Data North-South & East-West Position Azimuth & Distance Navigate Data Direction L/R & Distance None Direction L/R & Distance None Deflection L/R & Distance Vise CL for Ref. Object (when applicable)

Method Options:

- In-Out, Left-Right: Nearly all surveyors choose this method with total stations, with instrument as reference object. Set to Reference Object as Instrument, if you are staking a point located 100 meters from the instrument, and take a measurement at 97 meters, the program will respond, "Out 3". If the In-Out, Left-Right method is selected, then the Ref. Object and Move Relative to: options become available to further define left-right. Although "Instrument" is the normal reference with a total station, the Ref. Object box allows you to choose a stationary point by which the directions will be referenced. This point can be either the instrument or a known point. If Ref. Object is set as instrument, then left is defined as left of the line between the point and the rod. Likewise, if Ref. Object is point then left is defined as left of the line between the directions are relative to the stationary point selected in Ref. Object or to the moving Rod.
- North-South, East-West: When total stations are used, the direction to go in stakeout can be North-South, East-West. For instance, the program might advise, "North 3.582, East 1.917." This method is better suited to GPS work and is subject to having a sense, in the field, of the north direction.
- **Direction to Point**—Azimuth, Distance: This directs you to the point for stakeout by the total distance and the azimuth, in either the 360-degree circle or a 400 degree circle if configured to grads.
- **Direction to Point--Bearing & Distance:** Similar to Azimuth and Distance except bearings referenced from North and South are used for the direction.
- Direction L/R & Distance: Available only in GPS mode, you are advised "Right", "Left" or "On-Line" as you move to the target point, along with a distance update.



• **Deflection L/R & Distance:** Available only in GPS mode, you are given precise advice in terms of the deflection angle left or right to turn, as you are walking, to move to the target point. Both Direction L/R and Deflection L/R (shown below) use the recent vector of your movement to determine the correction L/R instruction. Navigate mode in Store Points (an option made available in Job Settings) defaults to Deflection L/R & Distance.



- **CL In-Out, Forward-Back if Alignment available:** This option overrides the settings above, and if the stakeout involves a centerline, the program will direct the user by distance in to or out from the centerline and forward or back along the centerline. Note in the graphic below that the Method is set to North-South & East-West, but the actual report is "Out" and "Forward" because "Use CL for Ref. Object" is clicked on.
- The Use Horizontal Clock system option converts the 360 (or 400) circle into a 12-hour circle with 60 minutes per hour and is used in certain military applications. North is 12 o'clock.

Configure	🔽 🔽	📚 TPL STK	X
General View Sets		Plan Fixed(Sim) ++14 40 ft	S
Method:	Collapsed Report:		
North-South & East-West	None 🗾	221+18.05F	\mathbf{N}
	Position		
	Navigate Data None		\mathbf{M}
			\mathbf{C}
🔽 Use CL for Ref. Object (when applicable)	Pt: 10 Desc: DTA 22100.1HT: 4.5	
		OUT 7.674 FWD 0.323	n i

• Collapsed Report in the upper right of the View Tab of Configure applies to the various Stakeout commands and has 3 options: Position, Navigate Data and None. This option allows for more screen space in stakeout. Shown above is the most popular setting, Navigate Data. When the down - arrow is tapped in the field, the multiple lines of stakeout data (up to 6 as shown above) will collapse down to 1 or 2 lines. The "None" setting shows only one



line, the next Point line with Description and Height. The "Navigate Data" setting also shows the stakeout instruction (above right). The Position option shows the x,y,z position of the target point and also the next Point line. Pressing the up - arrow restores the larger screen. Using a PCDemo version of the software, F2 collapses the screen and F3 expands the screen. With a PC or field data collector, it is also possible to tap and hold the lower graphic horizontal line and drag down to collapse the text and enlarge the graphics, but since tap and hold also pans the screen, the sensitivity of this procedure makes it hard to use--you must tap and drag down just a few pixels of lower graphic window, precisely. It is easier to use the up and down - arrow keys, which are more convenient.



5.9 Configure (Sets)



This tab allows the user to define how the software will handle angle sets, reciprocals, and direct and reverse.

😂 Configure 🔽 🔀	💝 Configure 🔽 🔀
General View Sets	General View Sets
Backsight (Read D&R) Traverse (Read D&R) Resection (Read D&R) Topography (Read D&R) Stakeout (Read D&R)	Reverse Face - Angles Only Auto Turn Auto Read Calculate Reciprocals
Set Collection Routine Options Review Readings Review Sets Store Raw Data for Duplicate Points Set Order: BD-FD/FR-BR No. of Sets: 1	Set Collection Routine Options Review Readings Review Sets Store Raw Data for Duplicate Points Set Order: Robotic Set No. of Sets: 1

- **D&R**: The user can choose to measure direct and reverse readings for backsight, traverse, resection, topography, or stakeout routines. If the user measures direct and reverse for the backsight readings, all foresight readings that also are recorded direct and reverse will be recorded and computed as angle sets. If the backsight reading is only measured direct, then foresight points that are measured direct and reverse are then combined to produce an average observation record for the vertical circle, which is stored in the .rw5 file as a sideshot (SS) record. For calculation purposes, the routine only averages the distances using both vertical circle readings and uses the direct horizontal reading for the direction. Both the direct and reverse readings are stored in the .rw5 file as a note record. When disabled, (default setting) only the direct foresight shot will be taken. This option improves accuracy on elevation measurements and mimics a feature found on the SDR data collectors. The Resection D&R will also apply to Remote Benchmark.
- **Reciprocal Calc**: The Reciprocal Calculation option has three settings: No, Prompted, and Always. It governs the calculation of the elevation of foresight points taken with a total station, where a backsight measurement is also taken. When set to Always, the program will calculate the distance to the foresight point and delta elevation by combining the foresight and backsight measurements. When set to Prompted, the program will detect the backsight measurement and ask the user if the occupied point should be calculated using both previous foresight and current backsight. If set to No, the program calculates foresight points based only on the foresight, and then when you backsighted the difference was -1.0, the program would calculate the average difference (1.1) and would lower your occupied point by 0.1 "on-the-fly", prior to conducting foresights. This is useful for multi-setup topo work, in particular, where no further adjustment is anticipated. For closed traverse or high-precision work, it is recommended that you run with Reciprocals off and use the adjustment



options found in your office software or within Cogo, Process Raw File, in SurvCE. Reciprocals, because they re-calculate your occupied point by combining the backsight with the prior foresight information, should be used with care, because they will degrade the precision of the work if backsights are not precisely measured, with correct target heights.

- **Reverse Face Angles Only:** When taking Face 1 and Face 2 foresights, or when doing Set Collection, the program will use the distance from the direct reading only but will use the horizontal and vertical angles from both the direct and reverse face readings. This setting is repeated and displayed within Configure in Set Collection. Any change in either location controls the setting. (Note that in Manual Total Station, you will be prompted for reverse face distance, but the entry will not be used.) When using robotic total stations, which do not take distance measurements in reverse face, setting Reverse Face Angles Only is necessary to use motorized direct and reverse readings.
- Auto Turn: This option is for motorized instruments only and when enabled (by default) will automatically turn the instrument to the reverse face.
- Auto Read: This option will immediately take a reading after the instrument has turned to the reverse face. You must make sure that the auto targeting option is on. This is enabled by default.



5.10 Configure (IMU)

To use any IMU feature in SurvCE, it is first necessary to activate the sensors in the receiver. This is located in Equip – GPS Rover, and checking the box 'Use IMU' on the Receiver tab. Note that the position rate of 5Hz is required to use IMU features.

😂 GPS Rover		- 🔁 🕓	<mark>/</mark> 🗙	
Current Comms	Receiver	RTK		
Antenna Type:	MS321		ert lant	
Antenna Height: 0	ft	Abs. 131.9mm		
Elevation Mask:	10		•	
Position Rate:	5 H	z	-	
🔽 Use IMU				
Audio Mode:	Sile	nt	•	
Advanced				

Individual IMU features of SurvCE are controlled in Equip - Configure, on the IMU tab:

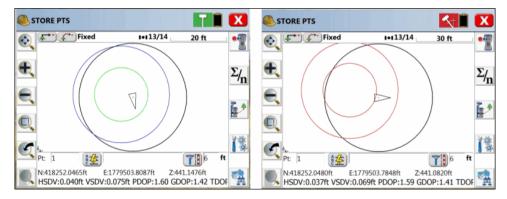
裬 Config	ure			\checkmark	×
General	View	IMU			
View	GNSS Lev	el			
Corre	ct Tilted P	ole]
Check	k for unit r	notion			

The internal Data Collector compass may be used for declination. This option will show if the Data Collector has a recognizable compass.



SurvCE allows the option to view the GNSS level on the live survey screen.

Check the box for View GNSS Level to view the GNSS level on the live survey screen. The digital level will let the user know visibly whether the receiver is level enough to store a reading. A green circle indicates a reading can be stored, and red indicates that the incline of the pole exceeds the user configured tolerances, blocking the reading. The digital level is aligned on the X/Y axis of the receiver. *The face of the receiver should be facing towards the operator for intuitive display.*



Users who wish to stay within level tolerance but do not like the appearance of the digital level can simply turn off View GNSS Level in the configure screen. As long as the IMU in enabled in the receiver configuration, SurvCE will still block reading which exceed the level tolerances. The Green or Red 'GPS Pole ICON', located in the top-right of the Screen, serves as an indicator of whether a reading can be stored.

Tolerances are configured from the main menu under Equip – Tolerances:

裬 Tolerances		×
HRMS Tolerance:	0.098 f	t
VRMS Tolerance:	0.197 f	t
PDOP Tolerance:	3.500	
Stakeout Tolerance:	0.328 f	t
"Navigate To" Tolerance:	16.404 f	t
Level Tolerance:	0.049 f	t

The Level Tolerance defines the amount of error that will be accepted when storing points. The tolerance is defined as the amount of distance error allowable on the ground and thus is a function of both the incline of the pole and the rod height.



Storing Measurements at an incline

Some receivers also include a compass, and by combining the heading of the instrument with the incline, the software can adjust for positional error due to the incline of the pole. To use this feature, go to Equip – Configure and check the box for 'Correct Tilted Pole'.

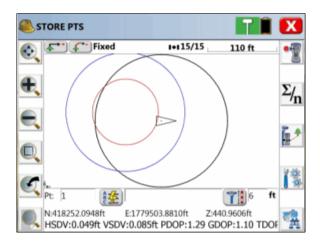
Config	ure		
General	View	IMU	
View	GNSS Lev	el	
Corre	ct Tilted F	ole	
Check	for unit r	notion	

The Incline Tolerance in the tolerances menu defines the maximum amount of tilt allowable. Most receivers begin to lose accuracy when tilted more than 20 degrees.

In the Store Points screen, the ICON in the top bar and the appearance of the digital level provide information to the user about whether a point can be stored.

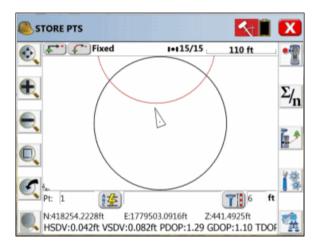
Please see the examples below:

Example 1: The red circle indicates the receiver is not within level tolerances, but the green icon in the top-right indicates that a reading can be stored, and the software will account for the incline of the receiver.

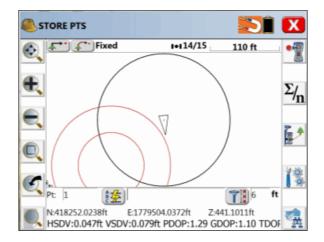




Example 2: The red icon in the top bar indicates that the receiver is tilted too far to correct for tilt, as configured in the tolerances dialog by the Incline Tolerance (for example, more than 20 degrees). The bubble level also shows that the receiver is very unlevel. No point can be stored.

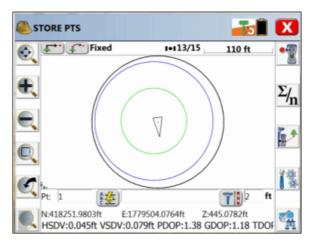


Example 3: Correcting for incline measurement can be unreliable in areas of magnetic noise. SurvCE will indicate this situation using a magnet symbol in the top bar. If magnetic noise is detected, SurvCE will block any reading outside of the level tolerance. No point can be stored in this state.

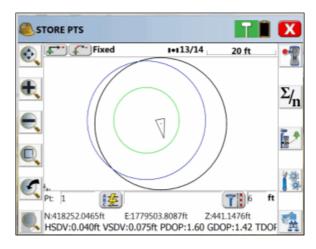




Example 4: To store a reading in areas of magnetic noise, simply level up the pole to within level tolerance. The icon now indicates that there is magnetic noise, but the receiver is level enough to store. Note that in this state, due to the magnetic noise, no adjustment will be made for incline.



Example 5: The digital level is green, indicating that the receiver is within level tolerance, and the icon is green, indicating that a point can be stored. When Correct For Tilt is enabled in this situation, corrections will still be applied for the small tilt of the pole.





ICON	Description
T	OK to store. Either within level tolerance, or if incline adjustment is being used, within incline tolerance.
	Magnetic interference detected, unsafe to store. Must level the receiver to within level tolerances to store.
T	Unit motion detected, possibly unsafe to store. If you press store in this state, SurvCE will wait up to 1 second for the compass to stabilize before storing the point.
15	Magnetic interference detected, but unit is within level tolerance, so it is OK to store. Tilt adjustments will not be made.
~	Out of tolerance. Either outside of level tolerance specifications, or outside of incline tolerance specification (if tilted pole is being utilized).
\bigcirc	Error State. This indicates that there is a delay between the sensor messages and the positions. Unsafe to store the point.



5.11 Hybrid+



Hybrid+ allows the use of a robotic total station and GPS receiver simultaneously to increase survey reliability and efficiency. The new Hybrid+ module is a paid addition to SurvCE/SurvPC which allows full simultaneous integration of total stations, GNSS, and all available sensors for the most flexible and efficient survey experience on the market. Users can mix and match any GNSS and RTS from the Carlson driver library for a custom setup.

The Hybrid+ setup wizard is designed to step you through configuration of Hybrid+, allowing multiple setup options based on user preference. We will walk through two methods of setup and explain the basics of Hybrid+.

Instrument Status Icon:

New instrument status icons are now available in most screens. The icon is a single panel for single instrument use, or a double panel when Hybrid+ is active.



Red: The instrument is not connected.

Vellow: The instrument is connected but an accurate position is unavailable.

- Yellow for GPS: Receiver mode is not Fixed RTK. (Receiver mode is Autonomous, DGPS, RTK Float, etc..).
- Yellow for Robotic Total Station: Standby or lost prism.

Green: The instrument is connected and an accurate position is available.

- Green for GPS: Receiver mode is Fixed RTK.
- Green for Robotic Total Station: Locked / Tracking.

Flexible Search Options for Total Station:

The search icon allows for instance access to all available search methods.



Press the right side of the icon (the down arrow) to see a list of available search types: General Search, Search Left, Search Right, GPS Search, RC Search, etc. The chosen search will begin when the selection is made. Press the left side of the icon to repeat the last user selected search. A STOP ALL option is also available in the drop-down list.



Laser Pointer Icon for TS:

Enable and disable the laser pointer from any live survey screen.



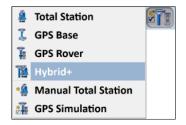
Setup Method 1: Hybrid+ Setup Using Grid Coordinates

Use this setup method if you run a GPS receiver on grid coordinates and would like to configure your robotic total station to run on grid coordinates.

Begin by configuring a GPS Receiver as you normally would, setting up RTK corrections and achieving a fixed position using either a radio or network connection.

👃 Monit	or/Skyplo	t			
Quality	Position	SATView	SATInfo	Ref	
Status	s: FI	XED		Satellites:	14/18
Latend	cy: 1.	0s		Local Elev:	97.2956ft
Base S	Selection:		VRS_RTCM3		
Local	Northing:		5003.2547ft		10/25/2017
Local	Easting:		4936.3075ft		08:53:15.0
HDOP:	:	1.30	VDOP:	1.82	
TDOP:		1.26	PDOP:	2.24	Reset RTK
GDOP:	:	2.57		Disconnect	Connect
HRMS:	:	0.041ft		Disconnect	
VRMS:		0.063ft	Connec	cted	

To enter Hybrid+ mode, tap the quick-switch instrument selector in the top bar of the main menu. Select Hybrid+. Click yes when prompted "Switch to Hybrid Survey Mode?" If you have not registered the Hybrid+ module, you will be prompted to temporarily enter demo mode to try Hybrid+. You can revert to your full registered copy at any time by exiting and reentering the software.





If you have not purchased the Hybrid+ module, you will be prompted to temporarily enter demo mode with the Hybrid+ module to try. Demo Mode will only allow a maximum of 15 points. You can revert to your full registered copy of the software by exiting and relaunching the software.

🔍 Hybrid+ 🛛 🔀	Hybrid+ Demo
Get even more out of SurvPC with the purchase of the Hybrid+ module. This allows you to connect to total station and GPS at the same time for added power and flexibility. Visit www.survce.com to purchase now, or contact a Carlson dealer to learn more. Try Hybrid+ Now	SurvPC is now in Demo Mode. Each coordinate file will be limited to a maximum of 15 points. Exit and re-enter the software to resume registered operation.
Cancel	

If this is the first time you have used Hybrid+, you will be prompted to use the wizard for configuration. Click on 'Yes' to continue.

SurvPC					
Would you	like to configu	re Hybrid+	using the	wizard?	
	Yes		No		

The first step of setup is to configure the Robotic Total Station (RTS) and GPS receiver. For this example, we have already configured the GPS (note the green check icon). Press 'Configure TS' to begin the configuration of the robotic total station.





Configure the robotic total station as you normally would.

Instrument S	etup		🌉 💭	X
Current Comm	s Settings Search			
Manufacturer:	Carlson Robotic			
Model:	CR+			
 tssimulation leicartslib5 topcondirectlib 				
Load	Save	Delete	Defaults	

Press the green check to connect and return to the wizard. Both buttons should now have a green check to indicate the instruments are configured. Press 'Next' to continue.

🔍 Hybrid+ Setup Wizard				X	
Configure your GPS Receiver a	and Robotic To	otal Station he	ere. Press N	ext to continue.	
Configure GPS	GPS Simulation				
Configure TS	CR+				
Monitor/Skyplot			Next		

Next, the wizard will guide you through setting your GPS and RTS heights. Measure the height of the prism (from the tip of the pole to the center of the prism) and measure the height of the GPS receiver (from the found to the reference mark on the antenna, slant or vertical). Enter in these values in the screen.

选 Hybrid+ Setup Wizard		
Measure prism height and gps rod heig press Next. From this point forward, ch automatically adjust the other.	· ·	U ,
TS Prism Height:	2.2000	ft
GPS Antenna Height:	2.3000	ft
GPS ARP:	🔘 Slant	Vertical
Hybrid Offset:	0.1000 ft	

The software will now calculate the fixed offset between the center of the prism and the GPS receiver. From this point forward, changing either height (GPS or RTS) will automatically adjust the other using this fixed offset value. Press 'Next' to continue.

To survey in Hybrid+ mode, it is necessary to ensure the robotic total station and GPS are measuring points on the same coordinate system. The next step in the wizard will address this. In this example, we will configure the robotic total station to use state plane grid coordinates using the Hybrid Resection procedure.

lybrid Survey Setup Wizard	
The next step is to ensure that your Total Station and establish grid coordinates for your job, choose Use Hyl job, choose Use Localization.	
Use Hybrid Resection	
O Use Localization	
Back	Next

In order for coordinates to match over long distances, it is necessary to scale either the robotic total station or GPS measurements, Select your scaling method. In this example, we are using 'Scale TS (Ground to Grid)'. Click 'Next' to continue.

Hybrid+ Setup Wizard	
ect Scaling Method	
Scale GPS (Grid to Ground)	
Scale TS (Ground to Grid)	
No Scaling	
Back	Next

The next screen will allow the Hybrid Resection procedure to begin. When ready, click on 'Perform Hybrid Resection' to continue.

🔍 Hybrid+ Setup Wizard	X
Perform a Hybrid Resection to setup your To necessary to have known points for this ope from GPS Receiver RTK Fixed measurement	ration. Known coordinates will be created
Perform Hyb	rid Resection
Back	Next



It is not necessary to have any known coordinates to perform a hybrid resection. The known points will be measured from the GPS receiver. Simply aim the total station to the prism and press 'Read Hybrid Position' to measure a resection point. The software will measure the total station position and the GPS position at the same time, synchronizing the readings automatically by time. You will be prompted to store the resection point if you desire. Move to a new location and repeat.

Resection [0]	
Press Enter or Read to take Reading #1	
Point ID:	Read Hybrid Position
	Calculate
Desc: N: E: Z:	Ignore Elev
۷.	Use GPS
Status: Standby Horizontal: 4°59'10"	Robotics (Alt+J)
Zenith: 93°37'40"	Configure
Inst Hgt: 0 m	2 m

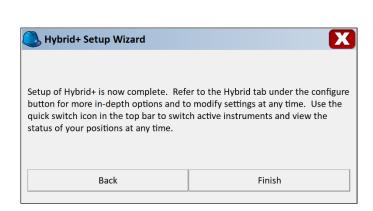
When you are satisfied with your resection, press 'Calculate' to view your results and store the calculated position of the robotic total station. The software will then set the orientation angle on the robotic total station and return to the wizard.

The next step is to 'Perform a Cross-Check'. Cross-check will measure a position simultaneously using the robotic total station and GPS receiver. It will then compare the coordinates match based on the displayed tolerances.

🔍 Hybrid+ Setup Wizard		
Coordinate systems are now synchronized. A that your GPS Receiver and Total Station coc		eck to confirm
Hybrid Pos. Tol.(SDist):	0.131	ft
Hybrid Pos. Tol.(Elv):	0.246	ft
Perform C	ross-Check	
Back	Next	

Cross-check tolerances can be augmented within this screen. Perform a Cross-check by pressing 'Perform Cross-Check'.

Once setup is complete, the software will use these tolerances to detect any unacceptable deviations between the RTS and GPS positions. If an unacceptable deviation is present, a warning screen will pop-up to warn the field engineer.



Setup is now complete. Press 'Finish' to exit the wizard and begin using Hybrid+.

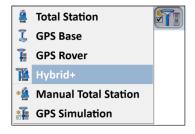
Setup Method 2: Hybrid+ Setup Using Known Local Coordinates

Use this method if you typically run a robotic total station on ground coordinates and want to localize the GPS receiver to ground coordinates.

Begin by configuring a robotic total station (RTS) normally, configuring the instrument and setting your backsight and orientation.

💽 Instrument Setup				A	\checkmark	X	
Current	Comms	Settings	Search				
Manufactur	er:	Carlson R	obotic			•	
Model:		CR+					·
 leicatslik leicartslik leicartslik leicartslik leicagsilik 	ib ib12	sokki leicar	raprecisior artslib tslib6 artslib47	ıtsli			
Load		Save		Delete	[Defaults	

To enter Hybrid+ mode, tap the quick-switch instrument selector in the top bar of the main menu. Select Hybrid+.





If you have not purchased the Hybrid+ module, you will be prompted to temporarily enter demo mode with the Hybrid+ module to try. Demo Mode will only allow a maximum of 15 points. You can revert to your full registered copy of the software by exiting and relaunching the software.

🔍 Hybrid+ 🛛 🗙	Hybrid+ Demo
Get even more out of SurvPC with the purchase of the Hybrid+ module. This allows you to connect to total station and GPS at the same time for added power and flexibility. Visit www.survce.com to purchase now, or contact a Carlson dealer to learn more.	SurvPC is now in Demo Mode. Each coordinate file will be limited to a maximum of 15 points. Exit and re-enter the software to resume registered operation.
Try Hybrid+ Now	UK
Cancel	

If this is the first time you have used Hybrid+, you will be prompted to use the wizard for configuration. Click on 'Yes' to continue.

SurvP	С						
Wou	uld you like	to configu	re Hyb	orid+ u	sing the	wizard	?
	Yes	5			No		

The first step of setup is to configure the Robotic Total Station (RTS) and GPS receiver. For this example, we have already configured the robotic total station (note the green check icon). Press 'Configure GPS' to begin the configuration of the GPS receiver.

🔍 Hybrid+ Setup Wizard								E	X
Configure your GPS Receiver a	nd Robotic	Total St	ation	here	. Press	Next to	continu	ue.	
Configure GPS	Not Config	ured							
Configure TS	CR+								
Monitor/Skyplot					Ne	xt			



Configure the GPS as you normally would, ensuring a valid RTK correction link. Once the GPS receiver is configured, both buttons will show green check icons. Press 'Next' to continue.

🔍 Hybrid+ Setup Wizard					X
Configure your GPS Receiver a	nd Robotic	: Total S	tation he	ere. Press N	ext to continue.
Configure GPS	GPS Simu	lation			
🝼 Configure TS	CR+				
Monitor/Skyplot				Nex	t

Next, the wizard will guide you through setting your GPS and RTS heights. Measure the height of the prism (from the tip of the pole to the center of the prism) and measure the height of the GPS receiver (from the ground to the reference mark on the antenna, slant or vertical). Enter in these values in the screen.

🔍 Hybrid+ Setup Wizard		
Measure prism height and gps rod height. press Next. From this point forward, chang automatically adjust the other.	•	U ,
TS Prism Height:	2.2000	ft
GPS Antenna Height:	2.3000	ft
GPS ARP:	⊖ Slant ● V	'ertical
Hybrid Offset:	0.1000 ft	
Back	Next	

The software will now calculate the fixed offset between the center of the prism and the GPS receiver. From this point forward, changing either height (GPS or RTS) will automatically adjust the other using this fixed offset value. Press 'Next' to continue.



To survey in Hybrid+ mode, it is necessary to ensure the robotic total station and GPS are measuring points on the same coordinate system. The next step in the wizard will address this. In this example, we will configure the GPS receiver to existing ground coordinates using the 'Use Localization' procedure. Select 'Use Localization' and click 'Next' to continue.

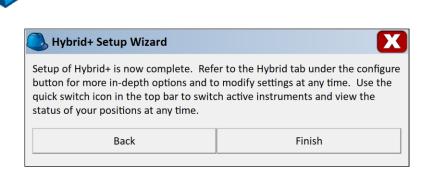
🔍 Hybrid+ Setup Wizard	X
The next step is to ensure that your Tot systems are synchronized. If you want to read from your GPS, choose Use Hybrid points read from your Total Station choo O Use Hybrid Resection	o setup your Total Station using points Resection. If you want setup GPS using
Back	Next

There are two methods of performing the localization for Hybrid+, localize manually and autolocalize. Localize Manually will proceed to the SurvCE localization screen where a localization may be created by measuring individual points and adding them to the localization. Auto-Localize will proceed to the Store Points screen and switch the active instrument to the robotic total station. The auto-localization will complete once enough points are measured.

We will run an example of the Auto-Localization method below. Select 'Auto Localize' and click 'Next' to continue.

🔍 Hybrid+ Setup Wizard	X
Select Localization Method: Continue setup without localizing. The GPS ground coordinates as you survey with your switch to GPS mode until the localization is a	Total Station. It will not be possible to
O Localize Manually	
Auto Localize	
Back	Next

The setup wizard will now complete. However, no points have been measured and a Cross-check has not been performed, so Hybrid+ is not yet fully active.

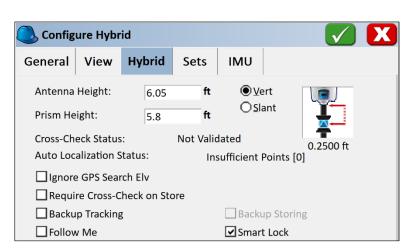


Click on 'Finish' to exit the Hybrid+ Setup Wizard. SurvCE will now automatically set the active instrument to the robotic total station. It will not be possible to switch to GPS mode until enough points are measured with the robotic total station to form a good auto localization. From the main menu, select Survey – Store Points. The Store points routine will be used to form an auto-localization.

		PTS		(X
	9j Tracking			120 ft	D
	10		397.19		Γ
E	405.17	9	2 397.86 GNSS Resection #1		S
		398.27	395.33		T
					0
	й <u>е</u> ,	-			
	Pt: 11	Desc:		5.8	ft 👗
	AR:46°10'21"		ZA:90°28'24"	SD:137.6543ft	

Within the Store Points screen, each time a point is stored with the robotic total station, the GPS measurement is collected at the same time. A localization will be formed in the background by analyzing all measurements pairs and selecting the best quality measurements.

The status of the auto localization can be viewed at any time by selecting Equip – Configure – Hybrid tab.



The screen shot above reflects the status of an Auto Localization routine before any points are stored. When enough points are stored the Auto Localization status will switch from 'Insufficient Points [0]'.

Before the Auto Localization is complete, an attempted switch to GPS mode will be blocked by the software with a warning message.

Use the robotic total station to store several points. An ideal localization will form a triangle around the robotic total station, but it is not necessary to intentionally form a localization. The software will calculate the best localization continuously. When an auto localization is calculated, features like Smart Lock, Follow Me, and GPS Search will be enabled, based on user settings. Once the auto localization is complete, a switch to GPS mode using the instrument status icon can be made. At that time, the auto localization will be finalized and no further localization points will be collected. Press the quick switch icon to switch to GPS Mode.

SurvPC		
	ching instruments, you r points. Finalize now?	need to review and finalize your
	Yes	No

Press 'Yes' to finalize. SurvCE will proceed to the Localization screen.

From this screen, you can review your localization points and quality as you would a manual localization.

Locali	Localization) (Ð7) (\checkmark	E
ystem	TS	G	iPS	Point	s	Ву Н	elme	ert			
Pt ID			North	ing(ft)	Eas	sting(f	t)	Elev	ation(ft)	H Res(
Auto-Loo	alization	Pt 5	4181	79.2762	17	79575.	.0007	403	.6775	0.029	
Auto-Loo	alization	Pt 6	41820)3.9331	17	79648.	9891	403	.6939	0.037	
Auto-Loo	alization	Pt 8	41812	24.3060	17	79598	.0156	401	8089	0.024 ►	•
Scale:1.0	00064					[2pt	Rota	ate Only		
Avg HRes	:0.0340 A	۹vg ۱	/Res:0	.0035							
Ad	d		Dele	ete			Edit		C	Dn/Off	
Loa	ad		Vie	w		M	onitor			Save	

Press the green check to finalize the auto localization routine. With the localization complete, the next step is to perform a Cross-Check. The software will direct the user to the cross-check procedure automatically.

			PTS			b i		X
	<u>9</u> i	Tracking	•		L	120 ft		D
	10			397.19				I
E	• 40	SurvPC		````	^			S
		Confirm	n Hybrid	Setup by per	forming a Cro	oss-Check?		T
Q			Yes		No			Ō
	E+							C
	Pt:	11	Desc:			5.8	ft	Ā
	AR:4	46°09'26"		ZA:90°28'27	" S	D:137.5361ft		

Click 'Yes' to perform a cross check. The Cross-check procedure will measure a position simultaneously using the robotic total station and GPS receiver and verify that the coordinates match. If the coordinates match within tolerances, the localization is good and the robotic total station and GPS receiver are on a matching coordinate system. Hybrid+ setup is complete.

Tolerances can be adjusted in the Hybrid tab of Equip – Configure. Once setup is complete, SurvCE will use these tolerances to detect unacceptable deviations between the robotic total station and GPS positions. Unacceptable deviations will be shown as a warning to the user throughout the survey session.

Nybrid+ Setup Wizard	
Setup of Hybrid+ is now comp	
button for more in-depth optic	te. Refer to the Hybrid tab under the cor is and to modify settings at any time. Use to switch active instruments and view the me.

Setup is now complete. Press 'Finish' to exit the wizard and begin using Hybrid+.



Using Hybrid+

Once Hybrid+ is active, SurvCE can be used normally. The new Instrument Status icon, shown on the upper-left of the screen, will indicate the status of the configured instruments at all times. The checkmark (shown below the instrument icon) will indicate the active instrument. While both the robotic total station and GPS receiver are connected and may be measuring at any time, the *active* instrument will control the options available in the main menu along with the display in active survey screens. The color on each side of the Instrument Status icon indicates the status of position quality.

Red: The instrument is not connected.

- **Vellow:** The instrument is connected but an accurate position is unavailable.
 - Yellow for GPS: Receiver mode is not Fixed RTK. (Receiver mode is Autonomous, DGPS, RTK Float, etc..).
 - Yellow for Robotic Total Station: Standby or lost prism.

Green: The instrument is connected and an accurate position is available.

- Green for GPS: Receiver mode is Fixed RTK.
- Green for Robotic Total Station: Locked / Tracking.



Note: The Instrument Status icon shown above is displaying the robotic total station as active. The yellow color indicates it is not currently tracking a prism. The GPS icon is green, indicating the current Fixed RTK status.

The instrument status icon can be selected from any screen to quickly switch active survey modes. When the GPS instrument is active, the menus and display of SurvCE will be in GPS mode. When the robotic total station instrument is active, the menus and display of SurvCE will be in total station mode.

د 🏹 🧶	IOB:			i 74	
Eile	Equip	Survey	COGO	Road	
1 Total Station	I	🌉 6	Localization		2
2 GPS Base		*I Z	Monitor/Skyplo	ot	
3 GPS Rover		8	Tolerances		7
4 GPS Raw On	ly	و 🖥	Peripherals		-
5 Configure		80	GPS Utilities		T¢.

Note: Menus shown in GPS mode.



L 🚺 🖉	OB:					74	
File	Equip	Survey	/	COGO	F	Road	
1 Total Station		2	6 Lo	calization			<u>^</u>
2 GPS Base		*	Z Ch	eck Level			
3 GPS Rover			8 To	erances			7
4 GPS Raw On	ly	Ъ	9 Pe	ripherals			
5 Configure		Ö	о тѕ	Utilities			Te

Note: Menus shown in Total Station mode. Check Level and TS Utilities are shown in the main menu.



Hybrid+ Features and Settings

Hybrid+ settings can be accessed from the main menu by selecting Equip – Configure and navigating to the Hybrid tab.

Config	ure Hybi	id				\checkmark	X
General	View	Hybrid					
Antenna Prism He	-	<mark>2.3</mark> 2.2			● <u>V</u> ert ○ Slant		
Cross-Cł	neck Statu	s:	Not Vali	dated		0.1000 ft	
🗌 Ignor	e GPS Sea	irch Elv					
🗌 Requ	ire Cross-	Check on St	ore				
🗹 Back	up Trackin	g			Backup Sto	oring	
✓ Follo	w Me			✓	Smart Lock	(

The Hybrid tab allows editing / viewing several settings.

- Antenna / Prism Height: The Antenna and Prism Heights can be viewed and/or edited. Updating either height elsewhere in the software will automatically adjust the other.
- **Cross-Check Status**: The Cross-Check Status is shown this will inform if any recently compared GPS and robotic total station points have been compared successfully. The screen shot above indicates Cross-Check has not yet completed. If localization has been used, the auto localization status and/or other localization information will be visible under the Cross-Check Status.
- **Ignore GPS Search Elv**: GPS Search is always available when Hybrid+ is active. To use it, select the down arrow to the right of the search icon from any active screen, and select 'GPS Search'.



In locations where the GPS cannot get a quality position and elevations are relatively flat, it may be useful to ignore the less accurate elevation measurement of the GPS receiver and still perform GPS searches using only the horizontal position to locate the prism. Enable 'Ignore GPS Search Elv' to do this.

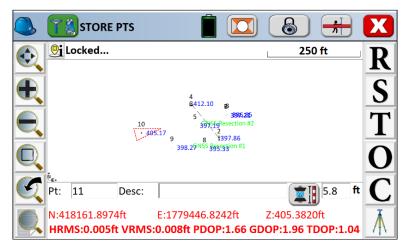


- **Require Cross-Check on Store**: Enable this option to force the software to calculate a crosscheck on every stored point. When enabled, this option will affect workflow based on mode.
 - **In GPS Mode**: If the robotic total station is not locked on the prism, a search will be performed.
 - In Robotic Total Station Mode: If the GPS is not Fixed RTK, the user will be warned.

Note: Only the active instrument's measurements will be stored in the RW5 file.

This option forces the software to check both instrument positions for each stored point, allowing the user to see a warning if either instrument's position is sub-optimal.

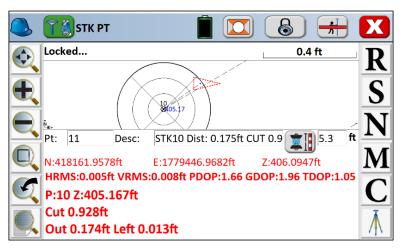
• **Backup Tracking**: When Backup Tracking is enabled, SurvCE will automatically display the backup (and inactive) instrument position on the screen when the primary (and active) instrument's position is unavailable. The backup instrument position will be displayed in red. This means if the robotic total station is active, and the E.D.M. is obstructed, the software will display the GPS position in the bottom bar as well as the GPS location triangle until the robotic total station position is restored.



Shown in the image above, the robotic total station is the active instrument, but is in a locked state (the E.D.M. is not firing). Since no position is available from the active instrument, and backup tracking is enabled, SurvCE is displaying the backup position of the GPS in red.

In the Stake Points screen, the stakeout directions will continue to be issued using the backup position if the active position is lost. If the 'Follow Me' option is enabled, the robotic total station will continue to follow the prism as it moves toward the field point. If the 'Smart Lock' option is enabled, the software will detect when the prism is within close proximity to the target point and automatically lock. This ensures final directions to the point are from the active instruments (in most cases where precise stakeout is needed, this will be the robotic total station).





Shown in the image above, the robotic total station is the active instrument, but it is in a locked state (the E.D.M. is not firing). Since no position is available from the active instrument, and backup tracking is enabled, SurvCE is displaying the backup stakeout directions from the GPS position in red.

- Follow Me: When the 'Follow Me' option is enabled, the robotic total station will automatically 'follow' the GPS receiver as it moves, turning every few seconds to the location of the GPS so that it is always ready to take a measurement at any time. The 'Follow Me' option causes a turn to the prism, but not a lock. This is sometimes called 'GPS Tracking', as the robotic total station is following the prism not by optical tracking, but by using the location of the GPS. Pressing the standby button in the top bar will put the instrument in manual standby mode and temporarily disable the 'Follow Me' option. 'Follow Me' will resume when a position is stored or lock is reacquired.
- **Backup Storing**: When the 'Backup Storing' option is enabled, the backup position will be stored when the primary (and active) instrument's position is unavailable. For more manual control, leave this option disabled, and simply tap the quick-switch icon in the top bar to switch to the active instrument and store the position.
- Smart Lock: When the 'Smart Lock' option is enabled, the software will monitor the motion of the GPS. When the movement of the GPS slows (i.e. the surveyor is slowing to take a measurement), the robotic total station will rotate to the prism and optically lock on to the prism. 'Smart Lock' can operate by itself, or in conjunction with 'Follow Me'. If the software detects further movements of the GPS while attempting to lock, the Smart Lock routine will cancel automatically in the background. Pressing the standby button in the top bar will put the instrument in manual standby mode and temporarily disable Smart Lock. Smart Lock will resume when a position is stored or lock is reacquired.
- IMU: Hybrid+ can take full advantage of tilt sensors on the GPS receiver by applying them to both the robotic total station and the GPS. When IMU is enabled during Hybrid+:



- The tilt sensors of the GPS receiver can be used to adjust the measurements of the robotic total station prism. This is true even when the GPS receiver is *not* Fixed RTK.
- The digital level bubble can display in active survey screens even when the robotic total station is the active instrument.
- SurvCE can warn the user when the robotic total station measurements are outside of level tolerance.

Exiting Hybrid+

Hybrid+ mode will end automatically when SurvCE is exited, or a new job is started.

Alternatively, a return to normal survey mode can be made by selecting any other survey mode using the quick switch icon in the main menu.



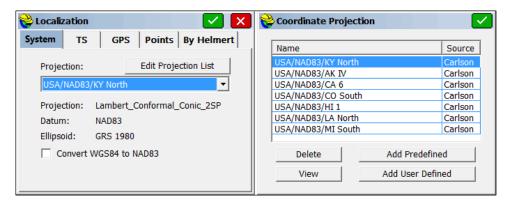
5.12 Localization



This command allows you to define the project coordinate system, geoid usage, and scale factors, as well as align on a local coordinate system for GPS.

System Tab

Click **Edit Projection List** to add to the list and to create user-defined projections. The user may select a predefined or create a user-defined coordinate projection system



- **Projection**: If you click the arrow to the right of the current projection, you can select from a list of projections that you have previously created. But to select a projection that you haven't previously used, choose **Edit Projection List**.
- **Convert WGS84 to NAD83**. Most base stations in North America broadcast NAD83 positions. Topcon Base Reference networks sometimes are configured to use WGS84. Turn this option on when a North American base station is transmitting WGS84 positions. Leave this option off for all other situations.
- Edit Projection List: Click this button to select a predefined projection or define a new projection.
- Add Predefined: If you click Add Predefined, you can set the country/projection to use at the top of the dialog, then choose the zone within the projection. For example, in the United States, State Plane 83 is a common projection, with various grids available covering all states. If Austria is selected, options for that country appear. Predefined coordinate systems are not editable.



Coordinat	oordinate Projection 🔽 🚺			
Country:	USA/NAD83	•		
AL East				
AL West				
AK I				
AK II				
AK III				
AK IV				
AK V				
AK VI				
AK VII		-		

• Country: A few of the projections available for selection in the Country category are discussed below:

NAD 27: When selecting this coordinate system, you will also need to specify a state plane zone. SurvCE will use data files to perform a NADCON datum shift from WGS84 to NAD27 coordinates. By default, only data files for the continental U.S. are loaded to the data collector. If you are working outside this region, please load the appropriate files from your CD to the SurvStar\NADConv directory. NAD27 uses the Clarke 1866 ellipsoid.
NAD 83: When selecting this coordinate system, you will also need to specify a state plane zone. NAD 83 uses the GRS80 ellipsoid. If you choose the option, another NAD83 Zone selection dialog will be shown to the user. The user may select the Find my Zone or Select State options to set the NAD83 zone correctly.

UTM: The ellipsoid used in the Universal Transverse Mercator calculation is determined by the Datum selection. If you choose the option, "WGS 84/Automatic Zone Selection", the zone is determined by the lat/lon values read in from the receiver. If you know your UTM zone, you can also select it. Whenever SurvCE does a reverse calculation (from UTM to WGS84) you will be prompted to enter a zone number.

3TM (Canada): This system is also referred to as "MTM". It is a 3 degree zone width Transverse Mercator calculation. You may select between the Clarke 1866 ellipsoid and the WGS84 ellipsoid.

New Zealand: You may select between "NZGD2000" and "NZGD49". Both use the Transverse Mercator calculation. NZGD2000 uses the GRS80 ellipsoid. NZGD49 uses the International 1924 ellipsoid. You may specify a Meridional Circuit with either datum. To select the circuit, press the Define button. You will see a pull-down list with all Meridional Circuits as well as the option to pick None.

RGF 93 (France): This system requires that you have the file named "Predef1.csl" in the SurvStar directory on the data collector. If this file is not found, please re-install SurvCE. **NTF (France)**: This system requires that you have the file named "Predef1.csl" in the SurvStar directory on the data collector. If this file is not found, please re-install SurvCE. NTF is an approximation of the NTF-GR3DF97A grid transformation.



NTF-GR3DF97A: This system is a grid transformation that requires the files "Predef1.csl" and "gr3df97a.bin" to be in the SurvStar directory on the data collector. The "Predef1.csl" file is part of the default installation. You will need to use Data Transfer to copy the "gr3df97a.bin" file from your CD to your data collector.

OSTN02 (UK): This system is a grid transformation that requires the files "Predef1.csl", "ostn02_x.bin" and "ostn02_y.bin". The "Predef1.csl" file is part of the default installation. You will need to use Data Transfer to copy the "ostn02_x.bin" and "ostn02_y.bin" files from your CD to your data collector.

RD2000: This is the RD NAP transformation for the Netherlands. This system is a grid transformation that requires the file "Predef1.csl", "X2C.grd" and "Y2C.grd". The "Predef1.csl" file is part of the default installation. You will need to use Data Transfer to copy the "X2C.grd" and "Y2C.grd" files from your CD to your data collector.

Denmark 34: Used for all cadastral mapping and for most technical mapping carried out in Denmark. System 34 is a two dimensional - horizontal - coordinate system. System 34 is based on the National Geodetic Reference Network and is divided into two different zones, one covering Jutland and Fuen, and the other covering Sealand. The island of Bornholm has its own coordinate system called System 45.

• Add User Defined: To define a new coordinate system, go to the Localization under the EQUIP tab. You will find the Edit Projection List button under the SYSTEM tab. Then select the Add User Defined button. Enter a name for your system (e.g. PRVI for Puerto Rico/Virgin Islands), then select a projection (in the example below,

Lambert_Conformal_Conic_2SP) and enter the appropriate parameters. Note that all latitude and longitude values are in decimal degrees and False Northing and False Easting are always presented in meters. All entries involving degree must be in decimal degrees based on a 360 circle.

😂 New Syste	em	📄 🔽 🗙				
System:	PRVI					
Projection:	Lambert_Conformal_Conic_1SP					
Datum:						
Load F	File	User Defined				
Scale Factor:	1	False Northing:				
C. Meridian:	-66.43333333	0 m				
Lat. of Origin	: 17.833333333	3 False Easting:				
		152400.304 m				



User Defined: You may select a predefined Ellipsoid or set your own parameters by typing in a new ellipsoid name and entering values for a and 1/f. The values for dX, dY, dZ, rot X, rot Y, rot Z and scale are "to WGS84". SurvCE will support up to 10 decimal places when saving the projection scale factor.

💝 Define Coordinate System 🛛 🔽						×
Nam	e:		Zone	52		_
Ellips	soid:		Clark	e 1	.866	•
a:	6378206.4		I	m	Scale (ppm):	
1/f:	294.978698	1999			0	
dX:	0	m	rot >	(:	0	"
dY:	0	m	rot Y	:	0	"
dZ:	0	m	rot Z	:	0	"
GSF File is relative to WGS84						

If the values you have are "from WGS84", simply reverse the sign of each value (positive becomes negative and vice versa). You will need to save the system to a file. You may save the system to a ".sys" file or a ".csl" file. Sys files contain only one system definition. Csl files contain multiple system definitions. Both files are ASCII text files using OpenGIS WKT (Well Known Text) format.

😂 Coordinate Projection 🛛 🖪 🔽 🗙
Type: SYS Files Drive: C) Drive
Backap
DOT Codes
geolos geolos MewerJob1.sys mNewJob.sys
NewJob2.sys
Name:



Load File: To load a user-defined coordinate system from a file, Click under the Edit Projection List button under the SYSTEM tab in Localization. Select Add User Defined and then Load File. Change the File Type at the top to ".sys" or ".csl" depending on the type of file you are loading. A ".sys" file will be associated with each job. You can load the projection last used on a survey job by loading its ".sys" file. Select your file and hit OK. If you have selected a ".csl" file, you will be asked to choose from a list of system definitions found in the file. For the ".csl" type, you may verify that the details of your system have been loaded correctly by clicking the edit option.

TS Tab

The TS tab is where you specify the total station scale and adjustment options.

😂 Localizatior	n	2	📕 😂 TS Ground	d To Grid	Image: Second
System TS	GPS P	oints By Helmert	Method:	Average Points	• <u>5</u> /n
			N: 5000.00	00 E: 5000.0000	Z: 10.000
Curvature	e & Refraction		Grid Factor:	1.00014167457	L
Sea Leve	Correction		Height Facto	or: 0.999999521582	2
🔽 Use Grou	nd to Grid: 1.0	0000000000 🔝	Combined F	actor: 1.000141196086	5
Automati	c scale to grid				

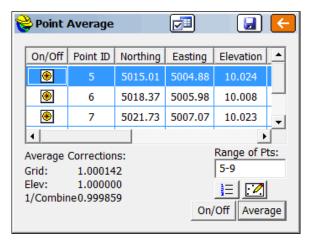
- **Curvature and Refraction**: This option applies only to total station configurations and will be unavailable when your instrument is configured to any GPS option. This factor causes an adjustment in distance measurement. Effects are negligible except over long distances. It is recommended that this toggle be enabled, except in those cases where the instrument factors in curvature and refraction.
- Sea Level Correction: If the sea level correction toggle is enabled (Use Ground to Grid is clicked off), the horizontal distance at the source point's elevation is reduced to the sea level chord using the mean height of the vector. Typically, this value is negligible unless measuring very long distances.
- Use Ground to Grid (Scale Factor): If clicked on (as above), then you can automatically calculate the Ground to Grid factor. For most applications, the Ground to Grid Scale Factor for total station work should be set to 1.0. This uses the actual measurements from the total station for all distances. However to convert total station ground measurements to match GPS measurements, the ground to grid scale factor can be computed (or hand-entered) by

clicking the "Calculate" icon . This leads to the dialog at right (above). A local coordinate and average height can be entered or recalled from the list of points or from the map screen. This will compute the grid factor (from the projection) as well as the elevation factor to produce the combined grid/elevation factor that reduces ground distances to grid. Therefore, for total stations, the scale factor acts as a multiplier. All distance measurements taken by a total station will be multiplied by the scale factor. Because there are two potential



uses of the scale factor (to adjust GPS measurements and to adjust total station measurements), two distinct scale factors are stored and recalled for any job, one for total stations located on the TS tab and one for GPS located on the GPS tab.

• Average Icon: The summation or "averaging" icon at the top of the dialog can be used to get an average height and coordinate position from a range of points when average points as a method is selected. Here is an example where 5 points were used to create an "average" combined factor. This feature recognizes the different elevation impacts of metric versus English units. Be sure that the selected points have correct, non-zero elevations, or scroll right to the V On column and turn Vertical off for purposes of averaging.



• **Calculate**: With Calculate turned on within the "TS Ground to Grid" dialog (at right), the Grid Factor is automatically multiplied by the Sea Level Factor to produce the Combined Factor. With Calculate turned off, you must directly type in the desired Ground to Grid Factor.

Note: The grid projection selected will even impact adjustment of of total station traverses and sideshots. Although the grid projection (e.g. KY North, NAD 83) is typically only associated with GPS, the projection selected will impact adjustment of raw traverses. In the command File, Raw Data, when Process No Adjust or any adjustment routine is selected (e.g. Compass Rule), the option to "Reduce to Grid Coordinates" can be selected. This will compute the combined scale factor at each endpoint of a traverse or sideshot, and then take the average combined scale factor and apply it to the measurement. Similarly, curvature and refraction can be applied as well. In this way, traverses from one known grid coordinate to another will achieve more accurate closures. It is not uncommon for traverses of considerable length and change in elevation to improve in closure from, for example, 1:10,000 to 1:100,000 with the application of both options. So, the use of projections applies not only to GPS but to total station raw data processing.



😂 Process Ra	w File			×			
Total Station	Proj.	Redundancies	Other				
Reduce to Grid Coordinates Scale: 1.00000000							
▼ A	pply Curve	ature Refraction					
Starting Point: 1 Ending Point: 31							

GPS Tab

The GPS tab is where you define the Localization methods, geoid file, and GPS scale factor.

Secolization		误 Localiza	tion			🗾 🗹 🗙
System TS GPS Points	By Helmert	System	TS	GPS	Points	By Helmert
Base Translation by Rover Read Localization Method Multi Point Method: Plane Similar One Point Azimuth: State Plane G Geoid File: ContinentalUS_NGS20 Geoid Interpolation Method: Quad Vuse Grid to Ground: 1.000000	ity ity ity ity ity ity ity ity ity ity ity	Localizati Multi Poi One Poir Geoid Fil Geoid Inte	ion Metho int Methoo nt Azimuti le: Cont	d Plane d: Plane h: State tinentalU	ver Readii e Similarit e Plane Gr S_NGS20 : Quadr	y v id v 12B.grd

Figure 1: 1-Point or No Localization File (Left), Multi-Point Localization File (Right)

• **Multi-Point Method (Transformation Types)**: The transformation can be by plane similarity, rigid body, or seven-parameter Helmert methods. Plane Similarity and Rigid Body both use a best-fit least-squares transformation. The difference is that the rigid body method does a transformation with a translation and rotation, without scale. The plane similarity does a rotation, translation and scale. These two methods only apply when two or more points are held horizontally in the points tab. The Helmert method requires the user to enter the seven parameters on the BY HELMERT tab.



💝 Localiz	zation				X		
System	TS	GPS	Points	By Helmer	t		
dx: 🚺		m ro	ot X: 0				
dY: 0		m ro	ot Y: 0		•		
dZ: 0		m ro	ot Z: 0	'	•		
Scale (p	pm):	0					
Calc	Calculate from Points						
Οι	itput to T	ext File					

- **One Point Azimuth (North Type)**: This option applies to the rotation when using one-point localization. For this alignment method, the grid coordinate is translated to the local coordinate. Then the rotation can use either grid north or geodetic north.
- Use Grid to Ground (Scale Factor for GPS): The Read GPS and Calculation options do not appear for multi-point localizations. In that case, the scale factor is fixed by the localization itself. When only 1 point is used for localization (for a translation), or no points are used in the localization file (position is derived from the reference station GPS), then you have the option to set a grid to ground scale factor. Icons allow you to "Read from GPS"

L to auto-calculate the Grid to Ground factor or more formally calculate the Grid to

Ground factor using the Calculate Icon . For most applications, the Grid to Ground factor (scale factor) should be set to 1.0 to work on the grid coordinate system using GPS. The combined scale factor represents the "combined" grid/elevation factor that reduces ground distances to grid. Therefore, for GPS, the scale factor would be the reciprocal of the standard combined scale factor, taking you from grid to ground. The example below presents the options that appear when **Calculate** is selected. A coordinate is used to obtain the grid factor, and an average elevation is used to obtain the sea level factor. The combined factor is then computed. Since this combined factor is "ground to grid", the reciprocal is taken to obtain the "grid to ground" scale factor. Since the scaling must be based on a "scale point", it is necessary to enter the scale point in the lower portion of the dialog shown below. The scale point can be entered, you can take a GPS reading, or it can be set to the single point in the Localization file.



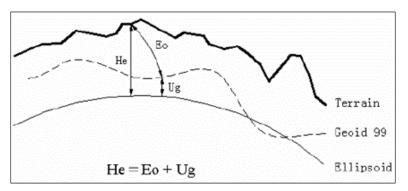
À GPS Grid To G	round Scale 🛛 📖 🔽 📘	🗙 😂 Point	Average	1			←
Method: Avera	ge Points 💌 🏹	On/Of	Point ID	Northing	Easting	Elevation	De
N: 5023.4074	E: 5007.6186 Z: 10.012		7	5021.73	5007.07	10.023	
Grid Factor :	1.000141653077		8	5023.41	5007.62	10.010	
Height Factor :	1.000004742561	•	9	5025.09	5008.17	10.003	•
1/Combined;	0.999853625119	Average	Correction	ns:		Range of P	_
-Scale Point Point Id: set by Average P	N: 5023.407 E: 5007.619 oints Set New Scale Point	Grid: Elev: 1/Comb	1.00014 1.00000 ine0.99985	00	On,	7,8,9	age

Within the Calculate option, using the method Read GPS obtains the coordinates to be used for scaling and for the scale point. Alternately, you can enter the coordinates, pick them from a list, or select from the map. In GPS, the Scale Factor (1/Combined) is applied to the distance between the coordinate and a base point. The coordinate is then set by starting from the base point and moving in the direction to the coordinate for the adjusted distance.

You can click the "Summation" icon Ima at the top of the dialog and obtain the combined factor from an averaged selection of points. The combined factor, always "Ground to Grid", will then be inversed and displayed as 1/Combined to represent "Grid to Ground". In the form of 1/Combined, it acts as a multiplier to scale all GPS measurements from the Scale Point.

• Geoid Separation File: This option will incorporate the geoid undulation in determining the orthometric elevation of the measurement. The definition of the geoid model as currently adopted by the National Geodetic Survey is the equipotential surface of the Earth's gravity field which best fits, in a least squares sense, global mean sea level. Orthometric elevation measurements are used in survey calculations. In order to convert ellipsoid heights (He) as measured by GPS into orthometric elevations (Eo), you must provide for a correction between the GPS-measured ellipsoid (reference ellipsoid) and a constant level gravitational surface, the geoid. This correction is the geoid undulation (Ug). SurvCE has preinstalled the US and Canadian geoids. Use XPort or SurvCOM to download the Geoid Separation File. This option only has significant impact with one-point or no-point (reference station-based) alignments. The zip file containing the Geoid Files (GSF, Geoid99 or EGM) is found on the SurvCE installation CD, and a portion of any such file can be specified (by size and center point) for downloading to the data collector using Carlson X-Port or Carlson SurvCom. SurvCE allows binary *.grd geoids and standard *.gsf geoids. Geoid files will be backed up in the backup folder. If geoid files are lost, they will be automatically restored from backup.





• **Geoid Interpolation Method**: Three methods are provided: Quadratic, Bilinear and Bi Cubic Spline. The default setting is Quadratic.

How to Use Geoid Files with Carlson SurvCE

The US and Canadian Geoid Files are part of the Carlson SurvCE 6.0 Insall.

- 1. Download and/or install either Carlson X-Port or SurvCOM to the desktop computer.
- 2. Download and/or install "CarlsonGeoidGrids.exe" to a location on your desktop computer (Typically installed to the "...\Program Files\Carlson X-Port\" directory).
- 3. If you have Microsoft ActiveSync already installed on your computer, make sure that it is not currently occupying the COM port. *To do this:*

Launch ActiveSync and select **Connection Settings** from the **File** menu. Remove the check box that refers to the port you intend to use with Carlson X-Port (Typically COM1).

Select **OK** to exit **Connection Settings** and close ActiveSync.

- 4. Connect your handheld device to your desktop computer using a serial cable.
- 5. Run Carlson SurvCE on the handheld device and select **Data Transfer** from the FILE tab.
- 6. From within the **Data Transfer** dialog, select the **Carlson Civil/Carlson Survey Transfer** option.
- 7. Leave the data collector waiting for communications as shown by the resulting **File Transfer** dialog.
- 8. Launch either Carlson X-Port or SurvCOM from your desktop computer. If you are using Carlson X-Port, select **Carlson SurvCE** from the **Tools** menu to launch SurvCOM.
- 9. From within SurvCOM, and while connected to the handheld computer via a serial cable, you should be able to see the contents of the handheld device on the right and the contents of the desktop computer on the left simultaneously. If you do not see the handheld device on the right, you are not connected.
- 10. Select the Geoid icon located at the bottom of the SurvCOM dialog.
- 11. From within the Set **Geoid Area** dialog, verify the path to the geoid files is set to the installed location of these files as defined in step 2 of this document (Typically "...Program Files\Carlson X-Port\").
- 12. Select the desired geoid model to extract an area from.
- 13. Key in the approximate latitude and longitude of the center of the area.



- 14. Define the grid size for the area you want the model to cover (Supported sizes are 50-250 miles, 80-400 kilometers and 1-5 degrees, however, keep the size 100 miles or smaller for better performance).
- 15. Name the geoid model with any name that you want (e.g. "geoid"). You may want to name this file with a logical name for the location of the area for future reference (e.g. "geoid-LA").
- 16. Select the **OK** button to automatically transfer the file to the "...\Survstar\" directory of the handheld device. A copy of the file will also be created on your desktop computer in the currently selected folder.
- 17. On the handheld device, go to the FILE tab and select Job Settings, then choose the GPS tab.
- 18. Select the **Geoid Separation File** button and choose the geoid file you created and transferred with SurvCOM.
- 19. You have now completed the definition and selection of the geoid file. Select **OK** to exit the **Job Settings** dialog.

Points Tab

This tab is where the user adds pairs of positions to create a localization.

😂 Locali	zation			🥖 🛛		\checkmark	X
System	TS	GPS	Po	ints	By I	Helmer	rt
Pt ID	Northing	Easting		Eleva	tion	H Res	Γ
1 5	5000.0000	5000.00	00	10.00	00	0.000	C
•							
Scale:1	.000000			C 2	ot <u>R</u> o	tate On	ly
Avg HRe	es:0.0000 A	vg VRes	:0.00	000			
Add	De	lete	E	dit		On/Off	
Load	l Vi	ew	Мо	nitor		Save	
							_

- View: The local coordinates are shown in the POINTS tab by default. Pressing View will switch the view to show the geodetic, Lat/Lon coordinates.
- Scale: The Scale Factor, shown in the Localization dialog when two or more localization points are used, is a multiplier and represents "grid to ground". When configured to GPS in release 1.50.004 or higher of SurvCE, any GPS localization scale factor is displayed within the UNITS tab of Job Settings in inverse form to represent "ground to grid".
- Add: Enter the alignment or localization points by coordinate values or by entering a point number. If you choose the point number method, you can enter a point number or select them from the point list. If you choose the From List method, you can access points in the Control File, if a Control File is active (See Job Settings, Options). You can average as many readings as you like when you add points and view the range and residuals. It is recommended that you use the point number option and carefully hand-enter your local grid system coordinates first, using either List Points, option Add, or Keyboard Input. Entry of coordinates "on-the-fly", in the field,



provides opportunity for error. Once you click OK in the coordinate dialog, you will have three options for establishing the GPS position for the named local point.

😂 Local Point	🔽 🔽	😂 GPS Coordinates	X
Please enter local coordinate a point ID from the current or			
Point From File:	<u>]</u> =	Read GPS	
Local Northing:	ft	C Enter Latitude/Longitud	le
Local Easting:	ft	O Erom Raw File	
Local Elevation:	ft		

Add Method 1 - Read GPS: This allows you to collect measurements from the GPS receiver and average as many readings as you choose. Once the readings are complete, the software will present a dialog that displays the range and residuals of average readings.

Add Method 2--Enter Local Latitude/Longitude: This allows you to hand-enter known geodetic coordinates for the local position. The elevation should be the ellipsoid elevation in the current job units if a geoid model is not applied. If a geoid model is applied, then the elevation should be the orthometric elevation in the current job units. This method allows manual entry of a localization file without occupying points in the field. Note that you do not enter the decimal point for decimal seconds.

📚 Enter Lat	/Lon	🔽 🔽
Use dd.mms	ssss format.	
Latitude:	N 0°00'00"	
North	O <u>S</u> outh	
Longitude:	W 0°00'00"	
West	C East	
Elevation:		ft



If you use manual entry of a localization data set, it is important that you either utilize an existing base GPS receiver with the fixed antenna location that was used to survey the original geodetic positions, or that you set up your base on a known GPS position measured previously using that localization data set. Good survey practice would include checking into known positions to verify the quality of your hand-entered GPS localization and verifying low residuals in the Localization screen. With all data pairs used for both horizontal and vertical control (none turned off), the resolutions for this data set will appear.

Add Method 3 - Point from Raw File: This allows you to use a point from the raw data file that has been previously collected via GPS. This is just like Read from GPS except you are recalling a point previously measured and stored in the raw file. For this to work, you must have the base antenna in the same position as when the original raw file was collected, or you need to set your base antenna over a known coordinate from the original survey and enter those original coordinates and the new base antenna height within the command Configure Base.

- **Delete**: Allows you to delete the selected item from the list. Note that it is not necessary to delete a localization point if you simply want to avoid using it. You can disable both the horizontal and vertical component of the point but keep it available for use later.
- Edit: Allows you to edit the selected item in the list. It will display the northing, easting and elevation of the localization point, which can be changed.
- **On/Off**: Allows you to remove the horizontal or vertical components of your localization points. This is a frequently used feature that enables the use of one point for vertical control only (turn off its horizontal component) and other points for horizontal control (turn off their vertical, if appropriate). Points with no known elevation (0 for example), would obviously be used only for horizontal control, as shown in this example.

裬 Localiza	tion				 ✓ ×
System	TS	GPS	Points	By H	elmert
Easting	Elevatio	on H R	es V Res	B H On	V On
000.0000	10.0000	0.00	0 0.000	Y	Y
•					F
Scale:1.00	0000			2pt <u>R</u> ota	te Only
Avg HRes:	0.0000 A	vg VRe	s:0.0000		
Add	De	ete	Edit	0	n/Off
Load	Vi	ew	Monitor	·	Save



Note that in this example, it takes three horizontal control points, active "H On = Y" to get horizontal resultal results, and four vertical control points, active "V On = Y" to get vertical residual results. You can employ trial and error to remove different points from consideration both vertically and horizontally and watch the residuals of the remaining control points improve or degrade. In this way, if you have four or more total control points, you can determine the best combination to use as horizontal and vertical control.

- Load: This allows you to load any localization file for modifying or for the purpose of associating it to the current job. Note that the **OK** button must be used if the intention is to associate the loaded file to the current job.
- **Monitor**: Goes to the standard Monitor screen. This is particularly useful to verify the quality of your satellite coverage and your fixed or float status. You always want the best possible fixed status when conducting a rover-based localization.
- Save: Allows you to save the control points in a file.
- 2 pt Rotate Only: Allows you to use the second point in the localization file for direction but not for scaling. In this case, any scale factor set on the UNITS tab in Job Settings would be active.
- OK: Pressing OK will temporarily recall the current Localization as you work. If you change the Localization file, Save, then Cancel, the original Localization file will still be active. Pressing OK is what makes it active, and current. In this case, you would need to Load the new Localization file and press OK to make it active. You can choose to Add localization points midway on a job, and not actually use them by pressing Save, then Cancel. Then when the job is complete, you can recall the Localization file with all the old and added localization points, go to Process Raw File, and re-calculate all surveying points according to the new Localization.

Discussion of Localization Techniques

If you do a base localization by entering Latitude and Longitude or known coordinates on the designated coordinate system, then you do not need to add localization points. A base localization would put you on grid north and grid scale and would work for any new job where you are not trying to match existing coordinates. However, any time you are working on a project that has existing coordinates, you will most likely need to do a Localization. Even if that existing job is supposedly on state plane, UTM or another known coordinate system, the project coordinates often fail to match grid scale and grid north exactly, requiring localization. When localizing, it is advisable to use at least three points for horizontal control and four points for vertical control, in order to get a measure of residuals (or accuracy). The program will "best fit" a plane through all activated (H=On and/or V=On) control points. The residuals are how much each activated point is off of the plane surface. Because multiple elevation points may create a slightly tilted plane, some surveyors will verify that the vertical control has low residuals and is accurate using multiple vertical control points, then turn off all but one (V=Off) and use only the nearest vertical (elevation) as they progress through the job.



Note: The Scale Factor chosen in UNITS under Job Settings will cause all GPS measurements to be adjusted by the scale factor. For GPS, scale factors can only be entered for one-point localizations (base or rover). For multi-point rover localizations, the scale factor is computed by the localization and fixed. It appears graved out under UNITS in Job Settings. When a scale factor is used for one-point localizations, scaling occurs along the vector outward from the single localization point in the direction of the measured point. For GPS, the scale factor acts as a divisor. A scale factor of 0.9 will calculate the measured point 1/0.9 units further away from the single localization point. Therefore, it is recommended that you keep the scale factor set to 1.0. When configured to total station, the scale factor is sometimes used to go "ground to grid". When configured to GPS, the scale factor in is sometimes used to go "grid to ground", to better match total station scaling. The scale factor is defined as "ground to grid". To go "ground to grid" from high elevations, for example, it would be less than 1. It would multiply total station measurements and reduce them to grid. It would divide GPS measurements and expand them to ground. If your goal is to work on the specified state plane, UTM or other grid coordinate system, and you are planning to use a one-point localization, then the scale factor should be set to 1, unless you are trying to match "ground" coordinates, where the coordinates are "true north" but not "true scale". In all other cases, matching ground coordinates with GPS is best accomplished with a multi-point rover-based localization. The resulting "effective" scale factor multiplier will appear in the localization screen, such as the 0.999779 value shown in the last figure.

After a change in a localization file, any points measured in the field by GPS will be converted from Lat/Long to local coordinates by using the new localization file. For this reason, it is a good idea to re-convert older GPS measurements to the same, compatible coordinate system by going to **Process Raw Data**, option **Process GPS**, within the COGO tab.

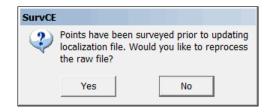
Geoid Files

The Geoid file is loaded onto SurvCE using Carlson X-Port. You first select the area of interest, then X-Port "carves out" the geoid for that area and downloads it to SurvCE. You set the Geoid file in the EQUIP tab in the main menu and then tap **Localization**. In the Localization routine, tap the **GPS** tab and then tap the **Geoid File** button. The Geoid should be used principally with one-point localizations. Starting with a known position for the base (or using a one-point rover localization and approximate base position), the program will add or deduct the geoidal separation from the computed Z value on all measurements and will match more closely to geoid-based surface elevations. The Geoid can also be used with multiple-point rover localizations, since the added accuracy provided by the geoidal calculation can reduce vertical residuals. This is true, however, only if the points being matched had Z values that, themselves, considered the geoid. Since you will get a best-fit plane that minimizes vertical residuals with or without use of the geoid, it is often not used with rover-based localizations.



Changing or Updating the Localization File

There are two ways to change a localization file. One method is to edit an existing file by deleting elements, and the second is to add additional localization points. In either case, whenever a change in the ".dat" localization file is detected, you are prompted whether you would like to reprocess any previously stored GPS points found in the raw file. The dialog below appears.



If you answer Yes, you will be directed to the Process GPS command found within COGO, Process Raw File.

Recalculating Stored GPS Points

There is no requirement to survey all localization points first, unless you are doing stakeout. For simple topo or data gathering, you can set up your base, survey in one or two localization points with the rover, then gather data in **Store Points** as needed. As you move cross country and encounter another known, or unexpected, control point, you can localize on it and add it to the list. The next step would be to verify residuals, and if the results are good, you can reprocess the raw file and keep your entire survey fully updated. If the residuals are disappointing, you can choose not to include the new point in the localization file. Either remove it or turn its H and V components off. You can also choose **Process Raw File** to recalculate all GPS measurements at any time.

Including the Base Position in the Localization File

To use the base in the localization, you should configure the base with the **Use Local Coordinates** option under **From Known Position**. Here, you configure the base by entering the local point (5000,5000,100, etc.) and start a new localization file (or use an existing one if it applies). Then, at your rover, you can add more points to the localization as necessary.

Localization and the Raw File

If the scale for GPS is determined from the localization, a "GPS Scale" record of 1.0 and a "Localization Scale" equal to the calculated scale appearing in the Localization screen will be written to the RW5 file.



Using the Localization File to Improve Base Localizations through Logging Static Data The Localization File (.dat) typically applies to rover-based localizations. But if you did a **Read GPS** on your base antenna position and then took GPS shots with no rover localization and logged static data on the base in the meantime, it is possible to submit that logged information to the OPUS program and obtain an accurate base position. At this point, it is still possible to recalculate all the field shots taken earlier from the less accurate base. To do so, follow the procedure outlined below.

- 1. Store the Base Point (Reference Tab in the Monitor screen).
- 2. Add a point to the now-empty Localization File. For the local point, enter the grid system coordinate computed by OPUS or another program. For the geodetic Lat/Lon point, review the raw file and select the point you stored for the base.
- 3. Reprocess the raw file through the localization. All CRD points should then be relative to the new calculated (e.g. OPUS-generated) coordinate.



5.13 Monitor / SkyPlot



The Monitor/Skyplot command allows you to review local position and quality of data.

• Quality: Under the QUALITY tab you monitor the status and number of satellites. You can also review the horizontal and vertical RMS values, as well as HDOP, VDOP, PDOP, TDOP and GDOP values. Some instruments refer to RMS values as CEP and SEP. For the CSI DGPS and the Sokkia Axis 3 receivers using OmniStar, the BER value will be shown in order to give indication of the strength of corrections received. When set to CSI DGPS, the age of corrections is also displayed. If connected to a network, the Base Selection will be shown. The number of satellites (SATS) is shown.

Monita	or/Skyplot	t			←
Quality	Position	SATView	v SATIr	nfo	Ref
Status:	FIXED		tellites: cal Elev:	14 120.	.1451
Local No	orthing: 5	5023.4074		02	/08/17
Local Ea	sting: 5	5007.6186		11:4	9:12.0
HDOP:	2.90	VDOP:	3.80		
TDOP:	2.00	PDOP:	3.20		
GDOP:	3.77				
HRMS:	0.036				
VRMS:	0.038				

The Status is shown as either:

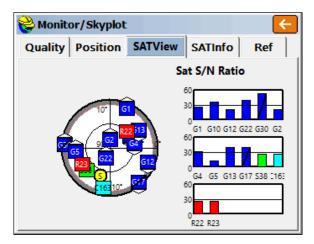
AUTONOMOUS: No radio communication between base and rover. DGPS: Corrections from differential sources such as WAAS or SBAS. FLOAT: Communication has been established, but ambiguities have not been resolved. FIXED: Position has been resolved.



• **Position**: Under the POSITION tab you see the current position given in latitude, longitude, ellipsoid elevation, geoid separation, and orthometric elevation. You will also see the local grid coordinates here.

裬 Monite	or/Skyplot			←
Quality	Position	SATView	SATInfo	Ref
Geoid Sl Geoid: Localiza Local No Local Ea Local Ele	le: Elevation: hift: tion: Newer: orthing: isting:	W 83°45 397.293 -109.140 C:\Car Job1 Base 5309.02 5100.64 120.150	06 IUS_NGS20 9 Shift: None 87 18 1	12B.grd

• SATView: Under the SATView tab, the spatial orientation of the satellite constellation is shown. You can also see if the satellite is rising or falling in the sky, by the associated arrow. Click on any satellite number to see individual satellite details, including the precise signal/noise ratio. You can also toggle satellites on and off if supported by the GPS. If a satellite is turned off, it displays with a line through it within the Signal/Noise Ratio graphs.





• **SATInfo**: This tab shows information on Satellites.

PRN is the satellite reference numbers. * indicates satellite in use for position calculation. **AZI**: is the satellite azimuth.

ELV: is the satellite elevation above the horizon, including rising (>) and falling (<) direction. The "*" designation indicates that the satellite is used in the calculation of position.

🖲 Moni	tor/S <mark>ky</mark> plo	←	
Quality	Position	SATView	SATInfo Ref
PRN	AZI	ELV	S/N L1:L2 🔼
G10*	119	29 >	44:31
G12*	149	29 >	45:31
G14*	179	29 >	46:31 🔤
G16*	209	29 >	47:31
G18*	239	29 >	48:31
G20*	269	29 >	49:31
R33*	0	44 >	40:31 🔍
R35*	44	44 >	41:31
R37*	89	44 >	42:31
R39*	134	44 >	43:31 🞽



• **Ref**: The REF tab to the right of SAT Info appears with most GPS configurations (not with GPS Simulation). The REF tab will show the base station information stored to the reference file, which is created during base configuration. The Magellan/Ashtech GPS, for example, will show the distance from rover to base. The base coordinates can also be stored by pressing the Store button.

You simply enter a point number and description, and the precise base coordinates are stored in north, east and elevation, according to the localization file settings. Then the base coordinate point can be used for total station work as a setup or backsight. If a base position of 0,0,0 is detected, representing in invalid base setup, the Store button will be grayed out. If the driver does not specify the type (ARP/APC) of the reference elevation when provided by the rover, SurvCE will make the assumption that if the correction type is RTCMv3, the elevation is ARP.

误 Monito	or/Skyplot	:		←				
Quality	Position	SATView	SATInfo	Ref				
Reference Station Coordinates								
Latitude: N 42°21'41.71900'' Longitude: W 71°09'53.46860'' Store								
	Ellipsoid Hgt: 0.0000 Antenna							
Antenna Type: 5.250 ASH110454 (69.4mm) Distance to Ref: 4670.6856								
Northing: 2956910.0449 Easting: 746745.6856								
				000				
Elevation	n: 21.3668	s /	Ant Hgt: 2	.000				

With Leica GPS, it also shows the status of the radio signal in the middle two lines. If the radio signal is interrupted, a "No Radio" message will appear. The Utilities button associated with the Leica GPS configuration takes you straight to the radio settings, including cell modem configuration.



5.14 Mission Planning



SurvCE includes Mission Planning. This option is found by clicking on the helmet within the Monitor/Skyplot screen, as seen in the figure below.

Note: Mission Planning is also available in Equip – GPS Utilities – Mission Planning as well.

Mission Planning can help select the best times for field surveying to ensure accurate real-time kinematic (RTK) data gathering using GNSS equipment. By predicting when satellites are most available, Mission Planning reduces wait time, time to fix and the likelihood of inaccurate field measurement due to poor satellite geometry. Lack of satellites is a consideration in all GNSS surveying, including static. Mission Planning can be used to select times of maximum satellite availability to conduct field work.



Almanac

The almanac file contains the information of future satellite orbit positions. Select either to download the almanac file from the receiver itself or answer 'No' to the dialog to load the almanac from a previously stored '.alm' file.

In the example below, an almanac was acquired using a Trimble planning file 'current.alm'

😂 Load Almanac	📄 🚺 💌
	1
Download from Internet	
Load Preexisting	

Once the preferred almanac file is loaded, the user will be presented with the Mission Planning screen. Options, or tabs, available to the user are Settings, Obstructions, Availability, and Skyplot. Each option will be further described below.

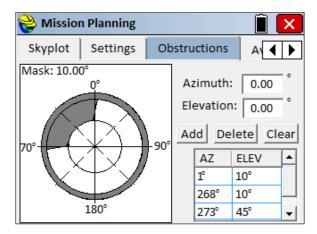


Settings Tab

😂 Mission Pla	anning			Ì X
Availability	Skyplot	Set	tings	
Lat: N 38°38'	52"	Lon:	W83°45'4	4"
Elev Mask: 1	HAE: 12	21.095	m	
Start Date:		3/09/2017 🔹		
Start Time:		11:00 Local 🔹		
Time Span:		4h 💌		
Time Granularity:		10m		-
GPS	GLO		BDS	GAL

In the Settings tab, the user can select the latitude and longitude of the specified location of interest (default position is the current user's position solution). The Elevation Mask, HAE, Start Date, Start Time, Time Span, Time Granularity, and satellite constellations can all be specified by the user.

• Obstructions Tab

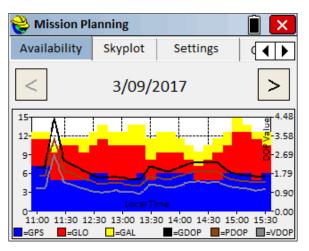


Future satellite availability will depend on how open the sky view for signal reception will be. Obstructions play a large part in satellite signal reception and is included in the Mission Planning software package. If you have a high building or a ridge blocking satellite signal reception to your Northwest, this obstruction can be entered here.

Obstructions can be entered manually or by clicking in the window on the left. In our example, there is a building blocking satellite signal reception, roughly in most of Quadrant 4, from an Azimuth of ~270 degrees to ~0 degrees at an elevation of ~45 degrees, enter in those values to update the Obstructions screen on the left.



• Availability Tab



In the "Availability" tab, the vertical scale at left shows the number of satellites. The vertical scale at right shows the "Dilution of Precision" values which are graphed by 3 distinct lines for GDOP, PDOP and VDOP. The PDOP line, which is brown, is typically given the highest priority and should be less than 4 for better results. A tolerance can be set for the PDOP value reported with any measurement, and a warning would be issued prior to storing any reading above the set PDOP tolerance. This is done in the command Equip Menu, Tolerances.

For RTK surveying, where accurate readings are measured real-time in the field, it is best to have at least 5 GPS satellites available, supplemented by satellites on other constellations. If conducting a GPS-Only survey (such as under SAASM conditions), a minimum of 5 GPS satellites are required in order to fix.

Tap the right arrow key to move to the next day to review the next 24 hours of satellite availability. Use the Settings tab to specify your expected Latitude and Longitude position and to modify the duration of the view, from 24 hours to other selections like 12 hours or 6 hours. The default "granularity" of the chart in the figure above is 1/24 of the duration. So, if a 12-hour duration is used, default granularity for the bar chart is every 30 minutes. However, granularity can be revised for more narrow or wider bar chart presentation. A 10-minute granularity would lead to very narrow columns in the bar chart if covering a 24-hour period as shown above.



Skyplot Tab

😂 Mission Planning						<
Availability	Skyplot	Settings		Obstr	ud 🖣 🛛	
Sats: 13 N			11:00, 3/09/2017 38°39'01" N 83°45'40" W HAE: 121.095m (Local Time)			> N
		•E	TYPE	E PRN	AZ	
🔪 🗶 🌂	-@\$//		GAL	26	289°	П
			GPS	17	338°	П
s °			GLO	75	280°	
=GPS =GL0 =GAL			GAL	1	280°	Г
=GPS =GLO	PGAL		•			۲

In the Skyplot tab, the user will be able to see the various satellites in view for a given time. The Time Granularity stipulated in the Settings tab allows the user to click through the Mission Planning specified time span. In the example above, the user can click right to view the satellite view in 30 minute intervals. Colors indicate both the satellite constellation (GPS = Blue, GLONASS = Red, BeiDou = Cyan, Galileo = Yellow) and tracking status. Satellites below the selected 'masking' elevation will appear lighter. The table below shows satellite status.

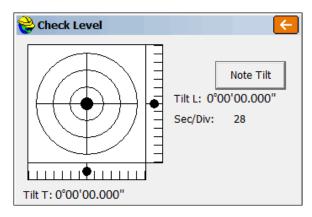
Satellite Constellation	Tracking	Not Tracking
GPS	Blue	Light Blue
GLONASS	Red	Light Red -or- Pink
BeiDou	Cyan	Light Gray
Galileo	Yellow	Light Yellow



5.15 Check Level



This feature is only available on Total Station instruments that provide information from electronic compensators. It allows the user to Check the level of the instrument from within the software.



Tilt T: Shows the compensator value.

Tilt L: Shows the compensator value.

Note Tilt: Records values to .RW5 File



5.16 Tolerances



This command allows you to set operating tolerances for the collection of points. A tolerance band will show to the user when in Live Survey Screens (Store Points / Stake Points) when the user is currently out of preferred tolerances.

] JOB:20180306_UPDATE	×	🔍 🛐 ЈОВ:20180306_UPDATE 🛛 📔 🗙
1	Fixed(Sim) ▮+16/19 30 ft	S	Fixed(Sim) I+I 16/19 30 ft S
	Not Within Tolerances - Red Band Showing	Ā	Within Tolerances - Red Band Not
	Λ	0	
	£	C	
	N:26215.6002 E:13641.4722 Z:750.0050 HRMS:0.115 VRMS:0.225 PDOP:2.37 GDOP:3.10		N:26216.5287 E:13641.5004 Z:750.0111 HRMS:0.012 VRMS:0.024 PDOP:2.37 GDOP:3.10

Total Station Tolerances:

Tolerances			X
H. Obs:	0°00'30"	•	
V. Obs:	0°00'30"	0	
EDM Tol:	5	mm	
Stakeout Tol:	0.328	ft	
Proximity Radius:	1.640	ft	

- **H. Obs**: This specifies the horizontal observation tolerance as an angle field. A tolerance of zero is not allowed.
- V. Obs: This specifies the vertical observation tolerance as an angle field. A tolerance of zero is not allowed.
- Edm tol (mm): EDM fixed tolerance in millimeters specifies the EDM error that is independent of the length of the line measured.
- Stakeout Tol: This specifies the maximum difference between the target location and actual staked point. When the staked point is beyond the tolerance, SurvCE displays a warning dialog. The Stakeout Tolerance is systematically applied to all stakeout commands. The program will respond with a warning screen such as "Stakeout is beyond the Tolerance Setting. Do you wish to continue storing?" The angle and distance tolerances are applied to multiple distance measurements (when Configure Reading specifies multiple Num Dist



Readings) and when multiple angle measurements are taken in Set Collection or processed in Process Raw File.

• **Proximity Radius:** This option refers to the change from navigation mode to stakeout mode (when the target becomes a large bullseye).

GPS Tolerances:

Tolerances		X
HRMS Tolerance:	0.098	ft
VRMS Tolerance:	0.197	ft
PDOP Tolerance:	3.500	
Stakeout Tolerance:	0.328	ft
Proximity Radius:	1.640	ft

- **CEP/H.OBS Tol:** A measurement of accuracy defined by the radius of the circle containing 50 percent of the individual measurements being made, or the radius of the circle within which there is a 50 percent probability of being located.
- **SEP/V.OBS Tol**: A measurement of accuracy defined by a sphere within which there is a 50 percent probability of locating a point or being located. SEP is the three-dimensional analogue of CEP.
- EDM Tol: EDM fixed tolerance in millimeters specifies the EDM error that is independent of the length of the line measured.
- **Stakeout Tol**: This specifies the maximum difference between the target location and actual staked point. When the staked point is beyond the tolerance, SurvCE displays a warning dialog.
- **Proximity Radius:** This option refers to the change from navigation mode to stakeout mode (when the target becomes a large bullseye).

Note: CEP tolerance and SEP tolerance are only used by Trimble. All others refer to it as H.OBS and V.OBS Tolerance.

Note: Even if you are fixed, if you attempt to store points and your GPS tolerance values are exceeded, you will obtain a warning screen.



5.17 Peripherals



A Peripheral is a device that must be used in tandem with a GPS receiver or a total station. Peripherals can all be configured from the Peripherals menu under the EQUIP tab. Lasers, Light Bars, and Depth Sounders are all supported as peripherals. If a peripheral is not currently in use, it is strongly recommended that you deactivate it for efficiency. Lasers such as the Leica Disto can be used for horizontal offsets and can be set to supplement the rod height for data collection "at the pole" using robotic total stations or GPS for marine or ATV surveys.

Lasers

Currently supported lasers are Laser Atlanta, Leica Disto, Laser Impulse IP200, Laser Impulse CR400, and Sokkia Contour. If you have a different laser, contact Carlson Software to discuss adding support for it. With GPS enabled, a laser can be used to provide an offset from a GPS reading. For more information, see the GPS Offset section of the manual. With a robotic total station enabled, a laser can be used to automatically measure the rod height of each total station reading.

📚 Peripherals 🛛 🔽 🗙	😂 Configur	re	🔽 🔀
Laser Depth Sounder Light Bar	Type:	Cable	•
Active	Type.	Cubie	
Type: Atlanta 💽 Comm Setup	-		
Auto GPS Update Auto Laser Read			
Alignment: 0°00'00" Align Laser			
Num. Rdgs. To Avg.: 1	Port:	COM 1	▼ Defaults
Laser Height: 0.000 ft 🗌 Ignore Vertical	Baud:	9600 💌	Parity: None 💌
Target Height: 0.000 ft	Data Bits:	8 💌	Stop Bits: 1

To activate a laser for use with GPS, follow these steps:

- 1. Plug in your laser to any of your device's COM ports; make sure that it is adequately charged and turn it on.
- 2. Enter the **Peripherals** menu, and select the LASER tab, as shown above.
- 3. Check Active
- 4. Select the type of laser you are using.
- 5. Enter the height of your laser from the ground. This value will be added to the vertical offset returned by your laser. For accuracy, this value should be specified with respect to the same ground elevation that your GPS rod height was specified.
- 6. Directions for aligning your laser will be given in a different section. For now, leave the laser alignment value set to 0.
- 7. If you want GPS to be automatically updated between each laser read, enable Auto GPS Update. If you want the Read Laser button to automatically trigger the laser, enable Auto Laser Read.

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- 8. Set appropriate COM port settings, by clicking on **Comm Setup**. To load the default settings for the laser you specified, select the **Default** button. However, you will still need to set your COM port number manually.
- 9. Click **OK** to save settings or **Cancel** to revert back to your old settings.

Activating a laser for use with a robotic total station follows a similar procedure. Attach the laser to the prism, pointing towards the ground. Every total station read will automatically trigger the laser, and the read value will be used as the rod height.

Using the Laser

1. Once the laser has been properly set up, enter the GPS Offset method and press Read Laser.

SurvCE	
	Reading From Laser (please trigger laser)
	Cancel

- 2. A progress window should pop up, indicating that Carlson SurvCE is ready to read from the laser. Aim the laser and fire at a target point. Keep firing until your laser returns a valid reading, and the progress window disappears.
- 3. To test whether your shot was successful, verify that the values on your screen correspond to the values on your laser's internal display. Note that not all lasers return azimuth and vertical offset data, in which case this information will have to be entered manually.



Laser Alignment

This option is only relevant to lasers with internal compasses. The purpose of this option is to allow you to compensate for any discrepancy between the laser's internal compass and the North determined by GPS. The alignment factor will be automatically added to all azimuth values returned by the laser. The alignment factor can either be entered manually or calculated using the laser and GPS. To calculate this factor using the laser, follow these steps:

- 1. If you don't already have two known points in your vicinity, use GPS to store two points within 50 feet of each other.
- 2. From the LASER tab of the Peripherals window, select Align Laser.

Laser Depth Sounder Light Bar Image: Active Image: Comm Setup Type: Atlanta Comm Setup Image: Active GPS Update Auto Laser Read Alignment: 0°00'00" Align Laser Auto Laser Read Num. Rdgs. To Avg.: 1 Laser Height: 0.000 ft Target Height: 0.000 ft	💝 Peripherals 🛛 🔽 🗙	😂 Laser Alignment	🔽 🔽
	Laser Depth Sounder Light Bar Image: Active Type: Atlanta Comm Setup Image: Auto GPS Update Auto Laser Read Alignment: 0°00'00" Align Laser Num. Rdgs. To Avg.: 1 Laser Height: 0.000 ft	Occupied Point:	Read Laser

- 3. Choose an Occupied Point from your point list and prepare to fire your laser from that point.
- 4. Choose a Target Point from your point list and prepare to fire your laser at that point.
- 5. Click **Read Laser**, and when the "Reading Laser" progress bar appears, fire your laser at the target point from your occupied point. An azimuth reading will appear in the Laser Reading box, and two values will be calculated. The Reference Angle is the azimuth of the vector from the occupied point to the target point. The Alignment Factor is the difference between the azimuth read by the laser and the Reference Angle.
- 6. Press **OK**, and the Alignment Factor that was calculated will appear in the Laser Alignment box.
- 7. Click **OK** again to save the new alignment settings.



Laser-Specific Configurations

If you're having trouble establishing communication with the laser, you may need to change certain settings on your laser's instrument panel. Here are laser-specific setup instructions for some of the lasers supported by SurvCE.

- Laser Atlanta: Make sure your Laser Atlanta baud-rate and message formats agree with those you specified in SurvCE. Also, make sure the laser format is set to Laser Atlanta Original (LA1KA). Consult your Laser Atlanta manual for instructions on how to do this.
- Laser Impulse: Make sure your Laser Impulse baud-rate and message formats agree with those you specified in SurvCE. Supported formats are IP200, and CR400. Consult your Laser Impulse manual for instructions on how to do this.
- Leica Disto: Make sure your Leica Disto's baud-rate agrees with those you specified in SurvCE. Consult your Laser Impulse manual for instructions.
- Sokkia Contour: Make sure your Sokkia Contour's baud-rate agrees with those specified in SurvCE. Consult your Sokkia Contour manual for instructions.
- **MDL LaserAce**: Using SurvCE 1.50.008 (or higher), you can use the LaserAce, but should configure your peripherals screen to Impulse (CR400). Using the MDL selection will invert the inclination. Use 9600 baud rate. Use a Topcon/Sokkia data cable (not a Nikon cable!). The laser must be configured to the same units as the job since SurvCE does not convert the measurement.



Depth Sounders

Currently supported depth sounders are:

- Fuji PL
- Generic NMEA
- Horizon
- Hydrotrac
- Innerspace
- Navman
- Odom Digitrace
- SLD 100
- SonarMite
- SonarMite DFX

If you have a different depth sounder, contact Carlson Software to discuss adding support for it. You can use a depth sounder with GPS to map an underwater surface. When the depth sounder is enabled, SurvCE will alternate between reading from GPS and reading from the depth sounder. *Note: If you aren't using a depth sounder, you must be sure this feature has been deactivated, or you may experience slow GPS readings.*

When active, incoming Depth readings are viewable in Monitor/Skyplot. Elevation values in the Store Point screen are automatically depth adjusted. Depth sounder records can be reprocessed in the RAW Data. Dual frequency depth sounders now allow storing dual points in Auto by Interval when 'Both' Frequencies option is selected.

💝 Peripherals	🔽 🔽	😂 Conf	igure	🔁 🔽 🔀
Laser Depth Se	ounder Light Bar	Type:	Cable	•
Cunit Mode	Model: Horizon			
Centimeters	C Decimeters C Feet			
High	C Low C Both	Port:	COM 1	✓ Defaults
	nen "Z:" is available	Baud:	4800	▼ Parity: Even ▼
Use Water Elev	ration 0.000 ft Comm Setup	Data B		▼ Stop Bits: 1 ▼

To activate the Depth Sounder, follow these steps:

- 1. Plug in your Depth Sounder to any of your device's unused COM ports and turn it on.
- 2. Enter the **Peripherals** menu, and select the DEPTH SOUNDER tab, as shown above.
- 3. Check Active
- 4. Select the Type of Depth Sounder you are using.
- 5. If the Unit Mode radios are not grayed, you will have to set the units to correspond to those output by the depth sounder.
- 6. Specify the Port the Depth Sounder is plugged in to.

Light Bars

Currently supported light bars are Mikrofyn and Apache. Light bars can be used with either GPS or total stations to provide prominently displayed direction arrows, when staking out a



polyline/centerline, or in the Elevation Difference routine, when trying to cut or fill toward a target elevation.

😝 Perip	herals	🗾 🗹 🔀
Laser	Depth Sounder	ight Bar
V /	Active	
	Light Bar Model:	Mikrofyn
	Grading Tolerance	: 1
	COM Port:	COM2 -

To activate the light bar, follow these steps:

- 1. Plug in the light bar to any of your device's unused COM ports and turn it on.
- 2. Enter the Peripherals menu, and select the Light Bar tab, as shown above.
- 3. Check Active
- 4. Select the Type of light bar you are using.
- 5. Set the **Grading Tolerance** to the maximum permissible deviation from the target path or elevation.
- 6. Specify the Port the Light Bar is plugged in to.

Output

Total stations will output supported NMEA messages. These messages can be logged to a file or to a selected DC port.

🖲 Peri	ipherals		🔽 🗙	🖲 Configure NMEA O	utput 🔽 🔀
Laser	Depth Sounder	Light Bar	Output	✓Log to file	No File Selected!
Configure NMEA Output		✓Log to DC port	Comm Setup		
				NMEA S	entences



5.18 GPS Utilities



Every GPS manufacturer and model has a different set of GPS Utilities. The primary purpose of the Receiver Utilities is reset and/or troubleshoot the GPS receiver.

😝 GPS Utilities		😂 GPS Utilities	
Reset Receiver	Reset RTK Engine	Hard Reset	Reset RTK Engine
Hard Reset	Send Command	Reset Factory Defaults	Send Command
Power On Receiver	Set Satellite Status	Power Off Receiver	Set Satellite Status

GPS Utilities Parameter	Description	
	The Bluetooth settings in SurvPC's Bluetooth Manager (discussed in Comm	
Bluetooth	Setup) do not actually change anything in the receiver itsef. In order to make	
Settings	changes to the receiver's internal Bluetooth settings, it is necessary to go into	
	Receiver Utilities and click on Bluetooth Settings.	
Check RTK	This tells the user current RTK Status	
Configure RTK Device	This allows the user to configure RTK Parameters	
Disable Wifi Hotspot	This allows the user to disable the Wifi Hotspot	
Eject File Card	This allows the receiver to unmount the SD card from the housing (allowing for removal)	
Enable Remote		
Control		
Enable Wifi	This allows the user to enable the Wifi Hotspot	
Hotspot	This allows the user to enable the Wifi Hotspot	
GSM Modem	This will reset the GSM Modem, helpful with a weak signal	
Reset		
Hard Reset	This will initiate a Hard Reset command to the receiver	
Known Point	This allows the user to initialize the receiver's position, helpful in PPP	
initialization	configurations	

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Network	This allows the user to connect to the APN, allowing for RTK correction	
Connect	streaming	
Network	This allows the user to disconnect from the APN, allowing for the network to	
Disconnect	disengage data streaming	
OmniSTAR		
Status	This allows the user to see status of the tracked OmniSTAR signal	
Power On / Off	This allows the user to power on / power off the receiver	
Receiver	This allows the user to power on / power on the receiver	
QuickStart	This allows the user to utilize the receiver's quickstart capabilities	
Reset Factory	This allows the user to react the receiver's configuration to factory defaults	
Defaults	This allows the user to reset the receiver's configuration to factory defaults	
Reset Receiver	This allows the user to reset the receiver, usually does not erase flash memory	
Reset Receiver	(check with your specific receiver manufacturer for full details)	
Reset RTK	This allows the user to reset the RTK Engine, helpful if a dominant satellite	
Engine	signal becomes occluded	
Sandmanitian	This allows the user, in a PPP configuration, to set the position prior to the	
Seed position	convergence period.	
Send	This allows the year to cond a common dimentivity to the receiver	
Command	This allows the user to send a command directly to the receiver	
Sensor	Allows for receivers with IMU capabilities to be calibrated	
Calibration	Allows for receivers with five capabilities to be calibrated	
Set Radio	This allows the user to configure the radio parameters for correction streams	
Parameters	This allows the user to configure the facto parameters for correction streams	
Set Satellite	This allows the user to specify satellite constellations and particular satellite	
Status	signal reception	
StarFire Status	This allows the user to see status of the tracked StarFire signal	
Theft	This usually will setup a PIN (check with your manufacturer for further	
Protection	details)	
Update Clock	This allows the user to set the clock from GPS signals	
from GPS		
Upload	This allows the user to upload firmware to the receiver	
Firmware		



Sensor Calibration – One Point Test

SurvCE offers a 'One Point Test' utility in GPS Utilities to help users to get more accustomed to the IMU capabilities of their receiver.

lone Point Test	🔽 💟	🖲 One Point Test	🔽 🚺
FIXED Sensors: Noise	Incline: 0°36'03.75" Tilt Dir.: 235°40'08.31"	FIXED Sensors: Noise	Incline: 0°37'30.00" Tilt Dir.: 234°47'09.90"
Wait for a fixed position, level the receiver, and press start to store a level position.		Check-point deviations: SDist Error: 0.003ft Elv. Error: 0.034ft Level Test Point: N: 1779504.0355ft E: 418252.0305ft Elv: 445.089ft	
Rod Hgt.: 2.000 ft	Start	Rod Hgt.: 2.000 ft	Re-measure

To use the feature, make sure your Rover has a FIXED solution shown in the upper left, then level the receiver and press the Start button to take a level reading. Then hold the tip of the pole in a fixed location, and practice tilting the top of the pole. The software will apply corrections based on the tilt, and the screen will display the error between the fixed location and the calculated location. Errors will be grayed out when the position is not FIXED or too much noise is preset or if measured tilt is >30 degrees. Every receiver is different, and calibration is tied to location and temperature. Using the One Point Test can help field crews understand the limitations of their receiver. Very bad results in this screen could indicate that the receiver needs to be re-calibrated.

GPS Utility for GPS Simulation

If running GPS simulation, the starting point can be reset using the special GPS utility. Enter the new Lat/Lon for the position.

😝 GPS Simulation Utilities 🛛 🗸 🗸					
Use dd.mmssss format.					
	<u>North</u>	O South			
Starting Latitude: N	38°38'51.72	844988"			
	● <u>W</u> est	C East			
Starting Longitude: W	83°45'44.07	7914"			
Starting Ellipsiod Height	: 397.283				
Always use this position					



6 Survey

This chapter provides information on using the commands from the Survey menu.

😂 JOB:NEWERJOB1		1	😂 JOB:NEWERJOB1		i 🗄	0
<u>F</u> ile <u>E</u> quip	Survey COGO	<u>R</u> oad	<u>F</u> ile <u>E</u> quip	<u>S</u> urv	/ey	d
1 Store Points	6 Auto by Inte	erval 🕞	1 Store Points	2	<u>6</u> Grid/Face	=
2 Stake Points	a Log Raw GP	s 🍃	2 Stake Points	¤	7 Resection	9 ?
3 Stake Line/Arc	C 8 Leveling	2	<u>3</u> Stake Line/Arc	IC	8 Set Collection	L
4 Stake Offset	6		<u>4</u> Stake Offset	6	<u>9</u> Leveling	3
5 Elev Difference			<u>5</u> Elev Difference		0 Remote Elevation	⊿



6.1 Orientation (Instrument Setup)



The instrument setup dialog is displayed upon entering every active survey routine, unless "Prompt for Total Station Setup" is clicked off within **Configuration**. You also go directly to the Orientation screen whenever you click the tripod icon in all survey and stakeout routines. So, if "Prompt for Total Station Setup" is clicked off, but your occupied point has changed, then within the survey routine, tap the tripod icon (lower right) to update the occupied point and other setup information. The "From Job" button will recall the occupied point, instrument height, backsight point and orientation from a previous job, which is useful when creating a new job while already set up in the field.

裬 Store Points	🗾 🔽 🔀
Single Setup Re	mote Benchmark
Occupy Point:	3036
Instr. Height:	4.58 ft
Backsight Point:	1311 📃 📝 🍙
Backsight N Azi:	270°08'26"
Backsight HT:	6.5617 ft
Use Backsight Confirm NEZ	HT for Foresights From Job Backsight

When simply confirming the backsight information, if the OK button (green checkmark) is active, you can simply press Enter or click OK to move on to the active survey screen. If the OK button is grayed out, that means the program has detected a new occupied point (or the first one of the survey). Then you must click the Backsight screen and take an angle and/or distance measurement to the backsight.

When configured to robotic total stations, the **Tripod** icon takes you first to the robotics control screen for quick adjustments, and then back to more foresights. From there, you can tab to the backsight screen to access all of the backsight functions, then easily return when you are finished to the Foresight Screen.

If the user enters a rod height or instrument height in this screen, and then presses cancel, SurvCE will prompt the user to save the entered heights.



• Occupy Point: You can manually enter the occupied point ID (occupied/setup point) or click the List icon and select the point from a list of points. You can also choose the point by clicking the Map icon and selecting the point from the map itself by tapping a specific point. Finally, a third icon offers the ability to occupy a station and offset on a known horizontal alignment, without knowing a point number.

误 Point Projection	🗾 🗾 🔽
Pt ID: Sta: 0+62.520 Off: L -32.226	dot <u>∑ ≡</u>
El: 10.000	
Centerline	C:\Caron Projects\Data\
DEMO	Select CL Reload CL
	CL: DEMO Beg: 0+00.000 End: 3+08.327

In the Station/Offset method, you must load a horizontal alignment (centerline) file and then specify a station and offset. If you click the "store to disk" icon, it will store the station and offset and after clicking OK in this dialog, you will be prompted for a description, and the next available point will automatically be assigned. If you enter a station and offset that is equivalent to a known point, that point will populate in the Pt ID field. And if you enter a point in the Pt ID field, it will confirm to you the station and offset. In road work, this option can be used simply for confirmation of the correct station and offset for any entered point.

- Instr. Height: This is the height of the instrument from the center of measurement (typically middle of the lens) to the tack in the hub, or ground elevation over which the instrument is set. Units for the instrument height will be set according to the options in Job Settings. The units for the job are displayed (ft, ift or m). If you brought a feet and inches tape to the field, and you are set in decimal feet units, you can enter the instrument height as 63" (in which case 5.25 will be computed) or as 5.6.3.8 (5 feet 6 and 3/8", in which case 5.5313 will be computed).
- **Backsight Point**: Here you enter your backsight point ID, or pick it from a list or from the map itself, using the icons to the right. You can also click the station and offset icon, as with the occupied point. A backsight point ID is required, even if you choose to enter an azimuth or bearing only.



- **Backsight Bearing or Azimuth**: This displays the bearing or azimuth between the two entered points, when both points have coordinates. If **Angle Type**, in **Job Settings**, is set to **bearing**, then a backsight bearing will appear. If set to **azimuth**, then the backsight azimuth is shown. (Azimuth should always be used with a 400 circle/gons configuration). When both point IDs have coordinates, the backsight is fixed and predetermined and therefore the bearing/azimuth field is disabled since it cannot be altered. However, if the backsight point has no coordinates, then you must enter a backsight bearing or azimuth, which will be used to calculate the null or zero coordinate point ID.
- **Backsight Height**: This is the height in feet or meters (depending on your configuration) of the target, from ground elevation to the center of the lens for example. Even if working in English units, you can enter a 2-meter target height using 2m. This converts to 6.5617 feet automatically after you press Enter.

Note: The backsight target height will default to the previous backsight target height on future setups. The foresight target height is kept distinct and will default to previous foresight target heights, but will not automatically match the backsight target height. If you prefer to survey by setting the prism pole to a fixed height for both backsights and foresights, be aware that you will have to put in 2 initial target heights: one for the first backsight in the backsight screen and one for the first foresight in the foresight screen, in order to get both "remembered" values established.

- Use Backsight HT for Foresights: This option will link the backsight height and the foresight height to accommodate the use of a single prism for both the backsight and foresight readings, rather than a fixed tripod at the backsight and pole for the foresight.
- **Confirm NEZ**: This option will display the full coordinates and description of both the setup and backsight points. By default, the Setup coordinates will be displayed. You can tab to the backsight coordinates. Press Enter or tap OK to exit this dialog.
- From Job: This will recall an occupied point, instrument height, backsight point and backsight orientation from another job. You should use this option when you are already set up, have previously taken a backsight and other measurements and wish to start a new job with the same backsight orientation and information. This is known as the "Restore Occupation" feature. Select your "source" raw file containing the last backsight used. The occupied point and backsight point will be added to the current job file automatically.
- Backsight: Continues to the Take Backsight screen.
- **OK** or pressing **Enter**: Continues straight to the **Foresight** screen. If **OK** is not highlighted and not ghosted, pressing **OK** will still go to the Foresight screen, even if Enter does not.
- Settings Icon. At the top of the screen, the "Settings" icon to the left of the green check will bring up the Configuration Options, and is the same as selecting Equipment, Configure.



6.2 Orientation (Backsight)



The backsight dialog has **Setup** and **Results** tabs showing the results of a measurement to the backsight.

裬 Store Points			<u><</u>	8	Backsight	:		/ 🧲	×
Single Setup	Remote Ben	chmark							
					Set to Zero	<u> </u>	°00'00"		
Occupy Point:	3036) <u>=</u> 🗹 厄			Setup R	esults			
Instr. Height:	4.58	ft			OC Point:	1	BS Point:	2	
Backsight Point:	1311]= 🗹 🍋			BS AZI:	45°00'00"	BS Bearing:		E
Backsight N Azi:	270°08'20	5"	1	1	Inst Hgt:	0.000ft	BS Hgt:	0.000ft	
Backsight HT:	6.5617	ft							
Use Backsig	ht HT for Fo				Set Angl	e Chec	k Angle	Check	
Confirm NEZ	From J	lob Backs	sight			Set Angl	e and Read		

• Set Angle Option List: There are three options for setting the reference angle in backsight. They are found in the options list at the upper left of the Backsight screen:

Set to Zero: This is the most commonly used option. A message is sent to the instrument to set it to zero, then the backsight is taken at a zero reference angle. Angles are then typically turned to the right from zero.

Set to BS (Backsight) Azimuth: In this scenario, the backsight direction in the gun is set to the azimuth of the backsight. For example, if the backsight azimuth is 180 degrees, then an angle to the right of 10 degrees would read 190 degrees from the instrument. This is useful in underground mine surveying because it ensures that the readings displayed by the total station always refer to true azimuth. Some surveyors are "azimuth" surveyors and others prefer "set zero".

Set To: Allows the user to set the value.

Use Current (Do Not Set Angle): Uses whatever direction reading is already in the instrument.

- Set Angle and Read: This button will set the horizontal angle and read the distance to the backsight. The program defaults to the Set Angle and Read option (the large, lower button), on the assumption that in most cases, you will be taking a distance measurement to the backsight.
- Set Angle: This button will only set the horizontal angle. If you are just backsighting an object or plumb bob without a measurement, choose Set Angle. You can tap Set Angle on the screen or, using the keyboard, enter ALT-S.

Note: On most buttons, the underlined letter in the name is the hotkey which, in combination with the ALT key, will access the function of the button. On this menu, for instance, ALT-A would go to **Check Angle**.



- Check: This enables the surveyor to determine whether the instrument has drifted off the point. Based on what is presented here, the surveyor may decide to reset the BS angle, or to actually re-level and re-shoot the BS point. More commonly, you would do a Check Backsight after taking a large set of foresights. You may want to be sure that you haven't bumped the instrument or experienced settlement in the tripod legs.
- Check Angle: This button will simply read the angle currently in the instrument and compare it to the reference angle. Choose Check Angle to re-sight on the backsight and obtain an angular error report (no distance comparisons are made).
- **Turn to BS**: With robotic total stations, you have the option to automatically turn to the backsight. This button will turn the instrument to the previously set backsight angle so that a **Check Angle** or **Set Angle** can be performed. Once you press **OK** to go back to the foresight screen, the instrument will automatically prompt if you want to return to the previous foresight position.

Whether in a conventional or Manual Total Station configuration, pressing **Set Angle and Read** or pressing **Enter** will cause a backsight to be taken. In Manual Total Station configuration, a dialog will appear for you to manually input the angle and distance measurements.

Pressing Enter or OK completes the backsight setup and leads to the foresight screen, where shots are taken, readings are presented, and points are plotted graphically.

Types of Total Station Backsights - Handling Missing Information

The SurvCE backsight procedure will allow last minute entry of the backsight coordinate values if none are found or will calculate the backsight coordinates using the azimuth and distance of the measurement. If both the Station and Backsight have coordinates (non-zero northings, eastings and elevations), the backsight azimuth is computed, and the coordinate values are not altered.

Known Station and Backsight Azimuth to Backsight Point of Unknown Coordinates

In the case that the coordinates of the station are known and you shoot a backsight point of unknown coordinates, a backsight point will be calculated. Note that when a zero-coordinate backsight point is encountered, the program will prompt the user to "Enter Coordinates or Use Azimuth". This prompt appears only when the **Use Azimuth** option has been selected. If you choose only to **Set Angle**, the backsight point will not be calculated, but is still a viable entry in the raw file. Some raw file processing programs make use of this backsight point with zero coordinates as a backsight azimuth reference. It is recommended that you use distinct new point IDs for all foresight points. Don't re-use a backsight point ID that served as a "dummy" point to initiate the "set zero" backsight, unless you plan to re-use it for the same backsight again.



6.3 Orientation (Remote Benchmark)



This is a command for total station applications only, in which the elevation of one or more remote, but known, points are used to compute the elevation of the occupied Station. The **Remote BM** tab is the 2nd to the right in the Backsight screen. The main screen is shown below.

误 Store Point	s	🗾 🔽 🗙
Single Setup	Remote Benc	chmark
		1
Occupy Point	: 1	Read
Instr. Height:	0.0000ft	Results
Oc. Pt. Elev:	10.00000ft	Store
BM Point:	6	
Target Hgt:	4.7	ft
BM Elev:	10.008	ft Confirm NEZ

• **Read**: You have the option to transfer the elevation from a single benchmark by taking a reading on it, any number of times, in any face. You may also use multiple benchmark points, any number of times, in any face. If you turn on Direct and Reverse for Resection in Configuration, Sets tab, robotic instruments will perform a D&R automatically for remote elevation readings as well.

Re	sults			\checkmark	•
Ave	rage Sta	tion Elevation:	14.	7078	
On	BMark	BM Elevation	Calc dZ	Meas dZ	Stn E
Y	6	10.0078	0.0078	-4.7000	14.70
•					

- **Results**: The readings taken on the benchmark are reported in the Results dialog. All of the readings taken will determine an average instrument point elevation.
- **Store**: Click Store to update the instrument point elevation. A store point record will be recorded to the raw data file.



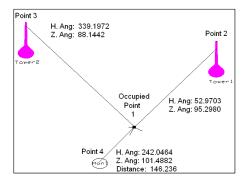
6.4 Orientation (Advanced Occupation)



The Advanced Occupation command allows for multiple points to be used to orient the backsight, conducting a least squares analysis on all measurements taken. It is sometimes referred to as the "Multiple Backsight" command. The Advanced Occupation command will also locate the occupied point if sufficient measurements are taken, allowing for the storing or overwriting of the occupied point coordinates. The appearance of this option in the backsight screen is itself dependent on turning on the "Show Advanced Backsight" option within Configuration. This leads to a third "tab" option within the Store Points, Stake Points and other commands involving backsights, called "Occupation", short for "Advanced Occupation".

💝 Configure 🔽 🔀	😂 Store Points 🛛 🔽 🔀
General View Sets	Single Setup Remote Benchmark Occupation
Use Ctrl Pts for Map Selection Use Unique IDs for Linework Show Continuous Total Station Angles Show Advanced Backsight No. of Readings to Avg - TS: 1 GPS: 1 Enter/Store Icon - TS: Read & Store	Occupy Point: 1 i= i

Although standard backsight procedure may be to take one or more readings to a single backsight, the Advanced Occupation command allows multiple readings to be taken for the backsight, to points identified in advance, leading to a 'best fit' backsight orientation computed by least squares methods. Consider the graphic below, showing a proposed occupied point (tripod) and three known point IDs as originally surveyed and precisely located based on a due North backsight.





Although it is sufficient to backsight to point 4, from known occupied point 1, taking additional measurements to point 2 and point 3 can lead to an "averaged" backsight and best fit orientation. Furthermore, if point 1 is not known, the position can be determined by the least squares calculations within Advanced Occupation, similar to a resection. Even if point 1 is known, if the calculated position is saved and not overwritten, then a redundant position for point 1 can be stored to the raw file, leading to more precise calculation of point 1 by Network Least Squares methods using office software, such as Carlson SurvNet.

In the above example, points 2 and points 3 can be considered to be towers and sighted for angle only measurements, while the measurement to point 4 would include both angle and distance. Furthermore, the data for these points will be recalled from a control file, so that they can be re-used on multiple jobs. And in this example, the angles will be recorded in gons/grads, or the "400 circle", with distances in metric. In the new file (Ville2.crd), a control file which we will call RadioTower.crd is referenced within Job Settings, Options tab. Note that is it not necessary to extract the backsight points from a control file. However, in developed areas with known control points, it is a useful technique to store control points to a distinct file so they can be easily recalled in all new jobs. The elevations on the radio tower points represent only the vertical positions originally measured and can be ignored when used in Advanced Occupation (or in Resection). The radio tower points will be used only for their north and east coordinates.

💝 Pts:	3 <= 4) 🥩	—	裬 Job Se	ttings				×
Point ID	Northing	Easting	Elevation	Descrip 🔺	New Job	System	Format	Options	Stake	1
2	2734379.45	808827.41	251.083	Radio1		-	1			
3	2734374.23 2734071.32	808350.89 808526.18	291.067 224.493	Radio2 MON1	🗹 Use	Control Fil	е			
	2/3/07/152	0002010		-	Store Store Use Reca	e Stamp Ea e GPS Acco e GPS Vec Code Tabl all Job Roa	ach Point uracy in Ra tors in Rav e for Desci d Files	v File when	ŀ	d
•					1.4 Auto	Lond Mon			•	_
Edit	Add	F	ind	Delete						

The Advanced Occupation command can even be run from a file containing no coordinates, assuming backsight points can be referenced from a control file. Begin by selecting the command Store Points in the Surv Menu, establish point 1 as the occupied point, 2 as the backsight and enter the correct target heights (0 for the radiotower point 2). Then click to "Occupation". The first screen appears below:



😂 Store Points	🗾 🔽 🔀
Single Setup Remote BM	Occupation
	Desc: OccPt
	Use Known Elev None
Use Backsight HT for For	esights
Configure	Observations

If the occupied point is not known, as in this case, then N, E, Z values appear as None. If the point is known, then the N, E, Z values appear with their coordinates, and you must decide whether to "Use Known E/N" and "Use Known Elev" before proceeding. The next step is to click the Observations button. Note that if a previous list of targets was created, you will be prompted to re-use the target list. In any case, you proceed to the following screen(s):

😪 Add Target 🛛 🔽 🗙	😂 Add Target 🛛 🔽
Pt. No: Target Height: Use Known E/N N: None E: None HA V ZE V SD	Pt. No: 2 i= i> i= Target Height: I ft Desc: Radio1 i= ✓ Use Known E/N ✓ Use Known Elev X: 251.08300ft E: 808827.41130ft ✓ HA ✓ ZE SD
On/Off No Horizontal Angle Zenith Angle	On/Off No Horizontal Angle Zenith Angle
New Reading New Reading	1 New Reading New Reading
	4 >

Entering point 2 as a target leads to presentation of the coordinates for 2. Since this is an "angleonly" measurement, turn off the slope distance "SD" option and turn off the "Use Known Elev" option. The "Zenith Angle" option is also irrelevant but can be left on or off. The goal of Observations is to load in advance all targets that will be used for the multiple backsight measurement. So if in this case, our goal is to backsight control points 2, 3 and 4, we would select those point IDs. Note that if the current job contains no points 2, 3 and 4, then you can simply enter them as targets, and the program will automatically find them in the control file where they don't exist in the current job. However, if the current job contains points 2, 3 and 4, you would need to use the "From List" icon to the immediate right of the Target prompt and then select the "Control" file option at the top of the List Points dialog as shown below. This ensures the selection of point 2 from the control file.



💝 Pts:	3 < = 4 🔿 J	ob 🔍 Contr	ol 🤯 🛛	7 🗲
Point ID	Northing	Easting	Elevation	Descrip_
2	2734379.45	808827.41	251.083	Radio1
3	2734374.23	808350.89	291.067	Radio2
4	2734071.32	808526.18	224.493	MON1
•	1			• •
Edit	Add	F	ind	Delete

The process of loading, in advance, all targets to be used is then repeated for points 3 and 4. Additional points are added by tapping the "Add" button shown below:

Ċ	At: 1					F	X
1	On/Off	Target	HA	H Res(s)	Norm	ZE	VF
		2	0/(0)	TT Ke3(3)	Norm	0/(0)	VI
			-7(-7			-7(-7	
	•						►
[s Measure.	-		
l	Add	Edit	Up	Down	Solve	Measu	ire

In this example, we would add points 3 and 4. Note that for point 4, a target height of 2 meters will be used, and the slope distance reading and elevation of point 4 will also be used in the calculation.



💝 Add Target 🛛 🔽 🗙	💝 Add Target 🛛 🔽
Pt. No: 3 i= i i= i=	Pt. No: 4 j= ∑ [] Target Height: 0 ft Desc: MON1 [] ✓ Use Known E/N ✓ Use Known Elev Z: 224.49300ft E: 808526.17750ft ✓ HA ♥ ZE ♥ SD
On/Off No Horizontal Angle Zenith Angle	On/Off No Horizontal Angle Zenith Angle
1 New Reading New Reading	1 New Reading New Reading
4	4

When distance measurements are involved, the prism offset can be entered distinctly for each measurement.

Set	D/R	Target Type	Prism Offset	No
(Value	New Value	Prism	0.00mm	1
				_

When the entire list of targets has been entered, you then select the target to measure first (e.g. point ID 2) and then tap "Measure".

	ZE V 0/(0) 0/(0) 0/(0)	F
	D/(0) D/(0)	
(0/(0)	
	0/(0)	
		l
re.	_	1
	Measure	1
	re.	1 1

You will be prompted to the turn to the target in direct face and take the reading. Assuming you set zero on the instrument to the backsight to point 2, the following measurements may be entered:



📚 Manual Read 🛛 🔽 🔀	Complete
> Angle Right: 0°00'00"	Measurement complete. Do you want to complete a set to the rest of your points?
> Zenith Angle: 95°29'30"	
Measurement to Point 2	Yes No

After the first measurement is taken, you are asked if you wish to complete the set to the rest of the points. Click Yes. Then you can take readings to the remaining points, as shown below:

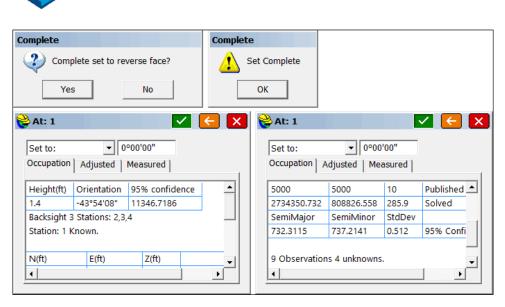
😂 Manual Read 🛛 🗹 🔀	😂 Manual Read 🛛 🔽 🗙
> Angle Right: 286°22'30"	> Angle Right: 189°07'57"
> Zenith Angle: 88°13'54"	> Zenith Angle: 101°48'49"
	Slope Distance: 146.235

Figure 2: Measurement to Pt 3 (Left) and Pt 4 (Right)

When all direct measurements are taken, you will be asked to continue the measurements in reverse face. If you do not wish to do both direct and reverse, you answer N and then continue. The program will announce, "Set Complete". You will return to the list of targets and can then click the green check mark to continue:

00	At: 1			7		(X	
	On/Off	Target	HA	H Res(s)	Norm	ZE	VF	
	ę	2	1/(1)			1/(1)		
	Ŗ	3	1/(1)			1/(1)		
	Ŗ	4	1/(1)			1/(1)		
	•						►	
Add Edit Up Down Solve Measure								

Here, you will either be led to the results screen showing the successful calculation, or it will report, "Unable to retrieve solution results". In the case above, the computed results are shown below:



Note that an added feature of the Advanced Occupation routine is the calculation of the occupied point coordinates. In this example, the original point coordinates for point 1 are: N 2734186.7757, E 808615.8663, Z 228.511. The degrees of freedom is the difference between the number of observations and the number of unknowns. The degrees of freedom increase if more redundant measurements are taken, such as reverse readings or multiple distance readings, and 20+ degrees of freedom would indicate strong statistical confidence. When the OK (green check) button is clicked, you have the option to save the occupied point, in which case you can overwrite the current occupied point, save to a new point ID, or save to the raw file only. Then you continue into the Store Points command or other commands and can take new measurements.

If you have taken both direct and reverse readings, the report includes data on the collimation of the instrument, provided that the collimation option is turned on within the settings option within Advanced Occupation. The Settings option includes the following settings:

8	At: 1					(X	8	Settings			Image:
	On/Off P D	Target 2 3 4	HA 0/(0) 0/(0) 0/(0)	H Res(s)	Norm	ZE 0/(0) 0/(0) 0/(0)	VF		Solution Instrumental Errors: Collimation Zero Index Physical Constant: Refraction Coefficie			r /BR-BR /BD-BR
	 ↓ ↓	Target o	or Press	s Measure. Down	Solve	Measu	▶ Jre		Measurement Accuracy Horizontal Circl Vertical Circle: Distance:	r	1 1 1	s s mm

• **Instrumental Errors: Collimation**: Leads to a report on the collimation of the total station instrument provided that both direct and reverse measurements are taken to the same foresights.



- Instrumental Errors: Zero Index: This, when enabled, will allow the Zero Index errors computed and displayed in the Solution report.
- **Physical Constant: Refraction Coefficient**: This option should be selected only if the instrument itself does not automatically apply refraction correction in the reported readings.
- Sets Order: The two choices are to take ALL backsight direct readings first followed by all backsight reverse readings (BD-BD/BR-BR) or to be prompted for the reverse reading following each backsight direct measurement (BD-BR/BD-BR).
- Measurement Accuracy: Horizontal Circle: Estimation of accuracy is used in least squares calculation.
- Measurement Accuracy: Vertical Circle: Estimation of accuracy is used in least squares calculation.
- Measurement Accuracy: Distance: Estimation of accuracy is used in least squares calculation.

Prism Offsets can be changed for each total station measurement taken that includes a distance reading. In the above screens, the instrument was set to "Manual Total Station". When set to an actual field instrument, the Target dropdown appears.

😂 Add Target		😂 Add Target	🔽 🔽
Pt. No: 4 i= i i= i i= i i= i <t< td=""><th></th><td>Use Known E/N N: 2734071.32350f Z: 2 E: 808526.17750ft</td><td>Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: 224.49300ft desc: MON1 Desc: Leica 360 Desc: MON1 Desc: Leica 360 Desc: MON1 Desc:</td></t<>		Use Known E/N N: 2734071.32350f Z: 2 E: 808526.17750ft	Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: MON1 Desc: 224.49300ft desc: MON1 Desc: Leica 360 Desc: MON1 Desc: Leica 360 Desc: MON1 Desc:
Horizontal Angle Zenith Angle Slo	pe Dist.	On/Off No Horizontal Ang	le Leica 360 🔺
New Reading New Reading Ne	w Readi	1 New Readi	Leica Mini 360 Leica 0mm Leica Circle
•	•	•	Leica Mini ReflTape v

A reflectorless reading, above left, contrasts with a Leica 360 prism reading, above right. If measuring angle-only readings to objects such as radio towers and church steeples, you can stay in prism mode but just click off the SD (slope distance) component. Click Target Settings and you can set the prism offset from a list of options. Target types are shown in the dropdown.



Add Targe	t		X
Pt. No: 4 Target Height ✓ Use Know N: 2734071.3 E: 808526.17 ✓ HA ✓ ZE	/n E/N ✓ Us 32350f Z: 224 7750ft	MON1 se Known Elev 4.49300ft	
On/Off No	Horizontal Angle	Leica 360	^
1	New Reading	Leica Mini 360 Leica 0mm	
•		Leica Circle Leica Mini ReflTape	~

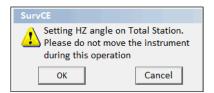
After cylcing through all targets and being prompted for reverse readings (optional), you are returned to the target list. If you highlight a target and click Measure again, you are in effect launching another set of readings.

After completing a set, if you click Measure for measurements, you can accumulate multiple readings which can vary from target to target, depending on whether you choose to skip certain target readings, do direct only, etc. Each direct and reverse measurement counts as a reading. You can turn all readings to a target on or off and by clicking Edit, you can turn any individual reading to a target on or off, as shown below:

误 Edit Targel	t	🔣 🔽 🚺
Pt. No: 2 Target Height	: 0 ft Desc:	
Use Know		Known Elev
N: 2734379.4 E: 808827.41		08300ft
🗌 на 🗌 се	SD SD	
On/Off No	Horizontal Angle	Zenith Angle 🔺
2		
•		v

When the process is complete and you exit Advanced Occupation, the program adjusts the backsight orientation with the following prompt, after which it announces "Operation Complete. Angle Set."





For any reading, within the Edit option, you can delete aspects of the reading. If you want to delete the entire entry in the list of targets (for example, you want to delete target 4 from the list), then select 4 and click Edit, which brings you to the screen in the lower left, then click the eraser icon at the top of the screen and click on "All" (lower right).

📚 Edit Target 🚺 🗹 🗙	💝 Delete 🔽 🔀
Pt. No: 4 i= i	Target ID: 4 Target Desc: MON1 Target Height: Oft C Last Measurement Only C Last Set Only C Sets Only
On/Off No Horizontal Angle Zenith Angle	Sets and the Target
New Reading New Reading	 All Sets Only C Sets and the Targets

For robotic total stations, the instrument will turn automatically to the direct and reverse positions for the selected targets, provided that within Configure, Sets tab, the "Auto Turn/Auto Read" and "Robotic Set" options are selected as shown below:

裬 Configure			🔽 🗙
General View	Sets		
 Reverse Face - Auto Turn ✓ Auto Read ✓ Calculate Recipr 	5	у	•
Set Collection Rou	tine Optior	าร	
Review Readin			
Set Order: Robotic	Set	▼ No. of Set	ts: 1



6.5 Orientation (Robotics)



The term "Robotics" applies to Geodimeter, Trimble 5600, Leica, Sokkia and Topcon robotic instruments. The Robotics tab has some variations per equipment type.

Store Point	s		X
Single Setup	Remote B	BM Robotics	
Search	Standby	Settings GPS Searc	h
< P-Search	P-Search >	Turn to Ang Check BS	5
Use Arro	ow Keys to	o Turn Instrument	

Arrow Keys for Joystick

ALT-J will take you directly to the robotics dialog from elsewhere in the program. The arrow-key motion is sometimes referred to as the Joystick Speed.

Leica: Tapping once in the direction you want (e.g. up) causes the instrument to move slowly, two taps medium, and 3 taps fast speed. Tapping the other direction (e.g. down) stops the movement.

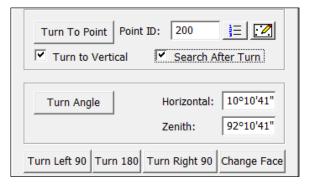
Geodimeter/Trimble: Press the arrow key once. After a small delay, the instrument will move an incremental amount. Do not rush too many presses as they all will be completed.

Topcon: Holding down the arrow keys on the keypad of the CE data collector allows you to move the base instrument up and down, left and right. When you release the key, the motion stops.

- Search: This button will initiate a search to look for the prism or reflector. For Leica, Search initiates an ATR search. Pressing the Search or Quick-Lock buttons will lock the instrument to the prism and put the instrument back into tracking mode.
- **PowerSearch**: For Leica, the **PowerSearch** option will conduct a fast search, typically less than 10 seconds. **PowerSearch** will find the prism regardless of the original direction the instrument is pointing.
- QuickLock: Topcon has an additional search option called Quick-Lock which appears when configured for Topcon 800/8000 Remote using RC2. A Quick-Lock search will find the prism in less than 15 seconds.



- **Standby**: This button takes the instrument out of tracking mode. This is useful, for example, in allowing the user to set the prism pole down to drive a stake.
- **Turn to Angle**: This button opens an additional dialog that prompts you for the angle to turn (which can be entered, picked from the Map, or point-based). See the figure below. You can turn to a known point number or to an entered horizontal and zenith angle using **Turn Angle**. When enabled, the **Search After Turn** option, searches and locks on a prism after turning the angle (potentially changing slightly the computed angle). Change Face reverses the face. The lower three buttons (**Turn Left 90, Turn 180** and **Turn Right 90**) are common angle turns and minimize user entry when needed.



- Settings: This button leads to a series of settings screens that allow you to dial in the speed of motion, range of motion, and other factors governing arrow-key driven movement and automatic searching.
- Check BS (Backsight): This button will engage the instrument to automatically check the backsight and lead the user to the Backsight screen with Setup and Results tabs. The Setup tab reflects the setup used and the Results tab reflect the most recent backsight check.

Setup Results								
	Angle:	Dist:	Elv(Z)(m):					
Calculated	Calculated: 338°23'36" 7.796 10.000							
Measured	: 338°23'37"	7.796	10.000					
Delta:	0 00'09"	0.000	0.000					

6.6 Store Points (TS)



This command is designed for total stations and manual entry. It is the principal data collection routine with total stations. **Store Points** interacts with numerous settings, including the feature



codes that will draw line work. All settings in **Configure Reading** will impact **Store Points**, including the Number of Distance Readings, Average Direct & Reverse, Hgt/Desc Prompt on Save, Angle Only in Reverse Face and Function of Enter Key. See File, Feature Code List, for discussion of drawing linework, symbols, Line Details and Point Details (option to re-measure existing points).

Foresights

The **Foresight** screen is entered automatically after exiting the **Backsight** screen. In the backsight screen, if the green checkmark ("OK") is active, you can go directly to the Foresight screen by pressing Enter or clicking the icon itself. And if you turn off "Prompt for Total Station Setup" within **Configure**, you go directly to the foresight screen if there is already a valid backsight. There are two major types of Foresight Screens: (1) Standard Total Station, (2) Robotic Total Station. See the Store Points (GPS) section of this manual for more information on GPS. Only total station setups will be discussed here.

Store Points	🔁 🖂 🔁		Backsigh	t 💽	🔁 🗹	← ×
Single Setup	Remote BM Robotics		Use Current	t 💽 04	°00'00"	Turn to BS
Occupy Point:	1 📔 🔀 🖾		Setup	Res	ults	
Instr. Height:	0 m		OC Point:	1	BS Point:	2
Backsight Point:			BS AZI:	78°51'13"	BS Bearing	N78°51'13"E
Backsight N Azi:	0°00'00"	-	Inst Hgt:	0.000m	BS Hgt(RL)	0.000m
Backsight HT:	0 m (Reflectorless)					
Use Backsight	HT for Foresights		Set Ang	le Chec	k <u>A</u> ngle	Check
Confirm NEZ	From Job <u>B</u> acksight			Set Angl	e and <u>R</u> ead	



Restore Occupation (from Previous Job)

The backsight can also be used from a previous job, simply click on 'From Job' to set the backsight. A Restore Occupation screen will be presented to the user to ensure the correct job is selected.

📚 Store Points 🛛 🗾 🔽 🗙	😂 Restore Occupation 🛛 🗸
Store Points Single Setup Remote Benchmark Occupy Point: Instr. Height: Backsight Point: Backsight N Azi: Backsight N Azi: Backsight HT: S ft	Restore Occupation Please ensure that the instrument position, circle orientation, and instrument height have not changed since the previous setup. Source: C:\Carlson Projects\Data\Sarah1.rw5 Destination: C:\Carlson Projects\Data\Sarah2.rw5 Change Source Source Orientation No setmation found in source file.
Use Backsight HT for Foresights Confirm NEZ From Job Backsight	

Standard Total Station Foresight Screen

Store Points (standard sideshots and traverses) can be run in either full graphics mode or full text mode. The Text screen is accessed by tapping the helmet in the upper left and selecting Text. To go back to graphics, click the helmet and select Graph. Graphic backgrounds can include linework that you create yourself using commands such as PL and 2DP and O2 (offset) in the Map view. Graphics can also include drawings that you import from DXF using the command IDXF ("in" DXF) found in the Map view of SurvCE. When you exit SurvCE, this linework can be configured to "save on exit" and stay associated with your point file. Note that linework drawn by feature codes or IDXF is on layers which can be "frozen" (hidden) or "thawed" (shown) by the Layer command under **View** in the **Map** screen.

裬 STORE PTS 👘		■ ✓ ‡	X	😂 STORE PTS	🗎 🔁 🔀
Pt: 11 AR:135°11'23" ZA:89°23'51" SD:50.2110	OP Pt: 1 HI: 1.4000 BS Azi: N:4954.84 E:4977.95 Z:7.2280			Pt: 11 Image: Second sec	- B 8/6
Desc:			Ø	● BLD ■First	- <u>*</u> 🎜
CONFIGURE	TRAVERSE	READ		I I MON1 I I I OccPt	<u>_</u> _
BS/SET	OFFSET	STORE		Point	 ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓



Enter saves the measurement immediately. If you do a Read, you can review the data within the Text view. If you re-enter the rod height, it re-calculates the Z elevation of the measured point. As you enter the description, a pulldown appears of your Feature Code List or previously entered descriptions. As each letter is entered, such as "e" for edge of pavement, every description beginning with "e" or "E" appears, enabling quick selections. Some users prefer the text screen to take readings because of the larger buttons and text size. The program remains in the Text mode until Graphic mode is chosen again. Graphics mode is selected either by tapping the Helmet and selecting "Graph" or by clicking the graphic icon (1+EP) at the top of the Text screen. Graphic mode is default.

😂 STORE PTS 📋 🔁 🗙	😂 STORE PTS	
Ph. 1102		Ī
Pt: 1193		.
> Category: ALL		
		P
* BLD		A
	Pt: 11 Desc: EP ▲ 4.7	<u> </u>
	Pt: 11 Desc: EP 23/14.7 AR:135°11'23" ZA:89°23'51" SD:50.2110	N

Unless the rod **hgt/description** prompt is enabled, the **Store Points** screen is designed to "quickstore" points, where the user is expected to enter, ahead of time, the correct description and rod heights in the edit boxes shown at the bottom of the dialog.

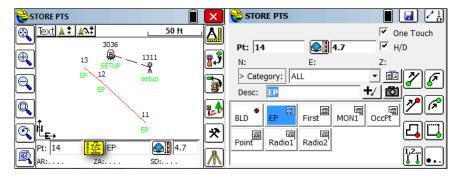
Note: SurvCE is designed to produce a 1 keystroke point store, by pressing Enter. If you experience more prompts storing a point, it is because you have certain settings active that cause additional prompts. These settings include 2 options within Configure (Prompt for Height and Description, Prompt for Point Notes), Store FCL Only within Feature Codes, Special Codes, Settings (will prompt if description does not match a feature code), the use of GIS attributes as set in Feature Codes, or the use of "Read or Store" rather than "Read and Store" within Configure. "Read or Store" will turn the first Enter into Read (to review the shot) and the second Enter into Store. Set to "Read and Store" with no Prompt for Height/Description, points are typically stored as fast as you press Enter.



• One-Button Measurement with Field Code: To reduce keystrokes to a logical minimum, there is a way to store points and select distinct descriptions with a single tap of the screen. This is the 1-button feature that can be found within Configuration, View Tab, when selected from the Store Points, Stake Points or other active survey screens. (It is not found in View when selecting Equip-Configuration). To use this feature, select "One Touch (Topo)" as shown below, but also, within the General tab of Configure, turn on both of the following options: "Use Groups of Codes/Desc" and "Show Codes/Desc as Buttons".

😂 Configure 🔽 🔀	😂 Configure "Navigate To" Info 🛛 🔽 🗙
General View Sets	General View Sets
Show Slope Info in STK Points Visual Alert in STK for GPS not Fixed Use Groups of Codes/Desc Show Codes/Desc as Buttons No. of Readings to Avg - TS: 1 GPS: 1 Enter/Store Icon - TS: Read & Store	Method: Coding Style In-Out & Left-Right to Ref One Touch (Top. Ref. Object: None Instrument One Touch (Top.) Move Relative To: One Touch (Top.)

Then when taking a measurement, a screen of icons appears for each description code in the Feature Code List, and by clicking on the icon, you can both take the measurement and select the description, limiting the number of taps to one. With Height/Description Prompt turned off, taps can be limited to the single selection of the desired feature code icon. Only if you need to end line or start or curve would a second tap be necessary. Start by selecting the description list using the "List with Lightning Bolt" icon highlighted below. Then select the desired code, or enter a new code creating a new icon for future use. One tap takes the measurement and applies the correct code. If there are more than 8 codes, a scroll bar will appear to access all of the codes. Clicking the graphic icon in the upper right (1+EP) returns to the normal graphic screen used to take measurements.





- Sokkia-Style: The SDR33 and earlier SDR data collectors have a convenient concept for "Store Last, Read Next". In this method, you get your descriptions set up and take a shot. The reading is displayed at the bottom line of the screen. You examine it, satisfy yourself it is correct, move to the next point, and take another shot. This was done on the SDR collectors with the Read key, but with SurvCE, can be accomplished with Enter.
- Normal Foresight Style: The most typical method is the "Read and Store" procedure as set in Configure. This takes a one keystroke measurement. But you must remember to enter the height and description ahead of time, before pressing Enter. If you want an "after-shot" chance to change the height and description, turn on "Prompt for Height/Description Prompt" within Configure. The Enter key can also be used for Read First, Store Later. This is the "Read or Store" version. Your first Enter is a read, only (like pressing R or entering ALT-R). Your second Enter is a store, which can be followed by the Hgt/Desc Prompt on save. This is the most cautious designation of the use of the Enter key for taking shots. Note below that after the read, the point is displayed with a question mark, and the raw data is displayed. It is saved only when Enter is pressed again (or S is pressed, or even Alt S-all of which store a previous Read). In the final Store Point dialog (with Rod Hgt/Desc prompt turned on), you will find the Point Description field. Along with the designated Feature Code list, all descriptions entered for the current job will accumulate in the available Point Description List, allowing the user to select the text graphically, arrow key to the desired text, or highlight and select the correct text after entering the first character in the edit box. An entry of "P" goes right to all text starting with the letter "P". Then you can select the one you want. The Enter key will continue on at this point.

Rod Height Icon

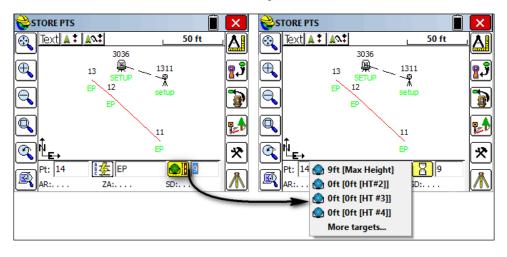
In both graphics shown above (normal graphic screen and "One-Touch" screen), a "prism" icon

appears with special functions. First, the icon displays the type of prism used. In this case, a "classic circular glass prism" is selected. Each prism has its own distinct icon. Secondly, this icon, if tapped, allows a single 1-shot measurement at a distinct rod height and will return to the current rod height after the single shot. When tapped, the following screen appears:

😂 More targets	🗾 🗲
	Height Value 1 Shot
Last Used:	9 ft 🧕
Pick Target from the List	1 Shot
HT #1	9 ft 🞯
HT #2	0 ft 🧕



If the pole was raised to 8.1 feet for a single measurement, you would enter 8.1 in the "Last Used" line and then click the 1-shot icon to the right. Then after the measurement is made, you would return to 6.5617 (2 meters), the "Last Used" rod height. If you have distinct positions on the prism pole that you may wish to recall, you can click the "Settings" icon at the top of the screen and enter them. For example, if the Maximum rod height was 9 feet, you can enter that height and even describe the target position as "Max Hgt". Then you can switch to this height for a series of shots by selecting it using the prism icon, or you can select it once using the 1-Shot icon and return to the "Last Used" height. Within Settings, there is even an option to "Use Hotlist to Pick Targets", so when you click the prism icon, you actually see the Hotlist of heights and can select them quickly using the icon as shown below. This Hotlist offers quicker access to multiple, frequently used rod heights. Turn off "Use Hotlist to Pick Targets" to restore the screen option shown above, which has the convenient "1 Shot" option.





Height/Description Prompt

When this option is turned on within **Configure** (**EQUIP** menu), you obtain the full list of Feature Codes plus any descriptions you have entered that are not included in the Feature Code list. Shown below is a reflectorless shot (rod height=0) with Height/Description Prompt on.

😂 STOP	RE PTS	📄 🔁 💌
Pt: 3	4	
)	
> Cate	gory: ALL	• E
Desc:	EP	_ @ % &
• 1	See Field Notes	<u> </u>
10	Light Pole	
z Î^ 100	Centerline Concrete Pavt.	
z Ĩ^ 101	Edge of Concrete Surface	
zÎ 102	Concrete Curb Flowline	 ↓ ↓

Symbols are shown as circles, and polyline features as lines. Polylines that are 3D include the "Z". As a short-cut to entering the special codes to start and stop lines, you can use the icons that appear at right. Of the 8 icons shown, going left to right starting at the top, they represent start polyline, start curve, end polyline, end curve, close polyline, close rectangle, designate specific "unfinished" active line, and "more options", leading to icons for Offset Horizontal and Offset Vertical.

Robotic Features

The status of the robot is displayed in the upper left-center, next to TEXT and above the Map. Status modes include:

- **Tracking**: Locked onto the prism and following it (shows the "man with pole" icon). If not tracking, there is a line through the icon.
- Locked: Shows the "Lock" symbol, meaning the instrument is following the prism. You can be locked and following the prism but not tracking (taking distance measurements, showing position of prism on the screen).
- Standby: Stopped in the last position it was in and ready to resume Tracking.
- Searching: Looking for the prism (shows an hourglass).
- No Data: Brief mode between losing the prism and beginning an automatic search.

The **search/standby** and **lock** icons let you initiate a Search after a lost lock condition, or go to Standby if currently locked (to drive a hub and stop the gun from moving), or go back to Lock, from Standby (after driving the hub). In the graphic shown above, you are in Prism Mode (as opposed to reflectorless, which would show a line through the prism). You are locked and "tracking" real-time, meaning distance measurements are being taken.

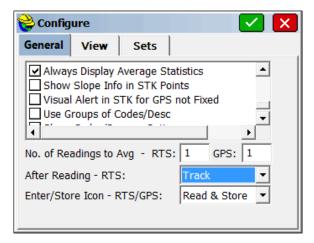


Continuous Reflectorless Measurement for TS

For instruments that support it, it is now possible to press the tracking icon in reflectorless mode to begin continuous reflectorless measurement.

The tracking icon, takes the EDM signal on and off. With the signal on, more power is used, but you gain a lot by seeing continuous, real-time distance readings and by seeing your position on the screen, in the form of a triangle. Shots are nearly instantaneous, but respond to the "fast-tracking" mode of the EDM (typically 10mm). If taken out of EDM Tracking, you lose your real-time movement on the screen, but measurements will respond to the accuracy of your Equipment Settings, which may call for standard or fine mode.

When a measurement is made and the instrument is locked on the target, tracking can occur (distance measurements), which then shows the target moving on the screen as a triangle. This uses battery, so "After Reading - RTS" is a setting, which you can choose Standby, Lock, Track, or Previous State, found within C for Configuration (when using robotic total station drivers).



Leica robotic total station users in particular, when doing topography or as-built surveys, prefer to set "After Reading – RTS: Track", in order to save battery between measurements. Instead, they simply keep the instrument set "After Reading – RTS: Lock" or following the prism, but not tracking (taking distances).

Note: The response to losing lock when taking foresights with robotic total stations is for the instrument to stop where it is. If you have enabled Search when Lost Lock in instrument settings, the instrument will start searching immediately on loss of lock. Alternately, when running remotely, you can use the joystick-arrow controls to move the instrument towards you and obtain lock again.



6.7 Store Points (TS Offsets)



Making offset points using a total station requires tapping the O/Offset button (or entering ALT-O) within the Store Points Foresight Screen. If you are set to the graphical icons in **Configure**,

you would select the "offset to tree" icon. This works from both the Graphic and Text screens when foresighting. There is no distinct total station "Offset" command—it is an offshoot (literally) of standard Store Points.

The Offset command includes the Read option to take a fresh measurement, to which the offset options then apply. Most users select O for Offset to do both the new measurement and the offset entries. However, you also have the option to apply the offset entries to the last measurement taken in Store Points. For this second alternate approach, you use the normal Store Points command to do R for Read or S for Store (or Enter to take the measurement) and then use the O for Offset command to use the last measurement (as displayed), and apply the offset options and click Store. In this second approach, if you chose R for Read and took a reading, and then selected O for Offset, you can then offset that reading with the option to store or not store the initial Read measurement. If you enter the Offset command after storing a point in Store Points, the last measurement will be used (and used for the Distance in the Distance/Angle, 2-reading option), and a new point ID will be stored. Within Offset, whenever you do a fresh, new Read, you will substitute the new reading for the one previously stored in memory. If you have no previous measurement, a new Read is required within O for Offset. So in summary, you can offset something you've already measured, or you can take a fresh measurement (typical method), using O for Offset.

The total station Offset command must be selected each time it is used.



• **Distance/Angle** (sometimes referred to as "Shoot a Big Tree"): The Distance/Angle method requires two measurements. The first measurement is the distance, followed by the prompt to read the angle. Note that the dialog, shown in the next figure, prompts you to Read Distance first.

💝 Offset				<u>)</u> 📀	
Dist/Ang	Point	2 Point	Ang Rd	gs Setti	ings
Record Vertical		ngle from		st Readin Igle Read	
Pt: 1193	B Desc	:	ÊΞ	нт: 4.7	0
			Prism	at angle	rdg.
R	ead Distan	ce Read	d Angle	Store	•

In the case of shooting a large tree, where the goal is to shoot the center of the tree, you would take a shot to the middle-side of the tree, equivalent to the distance to the center of the tree. Then you would take a second shot, as prompted, to the middle of the tree, for horizontal angle only. Note that for the elevation of the shot, you can use the distance measurement or the angle measurement (second reading), and apply the vertical offset, if any, accordingly. After both measurements are taken, the results are displayed. You are then returned to the dialog to take your next offset.

• **Point (Plus/Minus)**: The Point Offset takes a shot and deducts or adds a distance relative to the line-of-sight in all three directions (L/R, In/Out, Vertically Up/Down) using the dialog shown in the next figure.

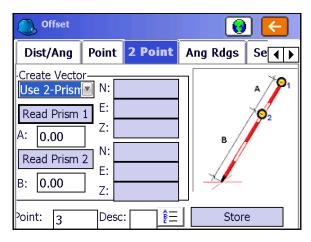
😂 Offset				0	\leftarrow
Dist/Ang	Point 2 Po	oint Ang	Rdgs	Settin	gs
Relative	Point Facing Ins	strument			
◯ <u>I</u> n	Out	Value:			
C Left	Right	Value:	1.500		
 <u>U</u>p 	O <u>D</u> own	Value:	3.100		
Pt: 1193	Desc: Wa	ll 👔	≡ нт:	4.70	
	AR: 359°59'49"				
	ZE: 91°49'55" SD: 7.684	Rea	d	Store	



• Before the shot, tap **Read**. After the shot, when the raw data is displayed in the lower left, tap **Store**. You will remain in the command until you tap **Close**.

Repeat Shots Using Offsets

When taking multiple measurements in traffic or other conditions where you must move away quickly, one technique is to use the Offset button in Store Points, and then the Point method. You do a Read and enter 0 for all offsets, then Store. Then change the description and tap Store again (no additional Read is necessary), and a second point with a different description (or rod height or offset) is stored. Some office software programs require distinct readings on the same point to process multiple descriptions, in which case the use of Offsets to store multiple readings with one field measurement is recommended.



• **2-Point Offset:** This creates a 2-point 3D "vector", where the offset direction, distance, and vertical offset are computed from the delta N, delta E and Delta Z of the two points that are measured or entered. If **Read Inst** is enabled, then the two points are measured in the field. If, instead, you wish to obtain the offset vector from two points, then disable **Read Inst** and enter the two point numbers. The offset entered will extend the vector from point "P2" in the direction of "P1" to "P2". The vector offset will also impact the elevation that is calculated. This might be used to calculate a point at the top of a cliff, for example, where you stand above the cliff top, pick up two points on the slope to the cliff edge, and estimate the distance to the cliff face from the second point. The offset by two points routine will write an SS record in the RW5 file (raw file), which enables re-processing.



💝 Offset			💽 🧲
Dist/Ang Point	2 Point	Ang Rdgs	Settings
Point: 1193 Hgt: 0.00 Desc: Wall		Read	Store

• Angle Readings: This allows for angle-only measurements to be stored in the RW5 file.

😂 Offset	t			0) 🧲
Dist/Ang	g Poin	t 2 Poin	t Ang R	dgs Sett	ings
				-1	
		Laser Settir	gs		
				-1	
		Robotics			
		1			
	✓ кеаа	target heig	nt from la	iser	

• Settings: The Settings tab appears with robotic total stations running remotely (from the prism) and permits reading the target height from a laser and accesses the entire range of laser devices found in the **Peripherals** menu option under **Equip**.

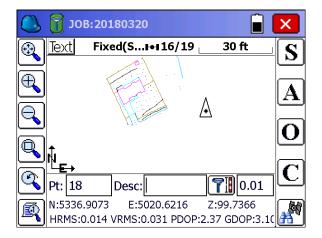


6.8 Store Points (GPS)

Te

Store Points is the principal data collection routine for GPS equipment. Store Points interacts with numerous settings, including the feature codes, and will draw line work. The Store Points screen in GPS shows the cursor moving on the screen in real-time. Measurements can be taken anytime by pressing **Enter**, . The screen will pan automatically, so you are always in view as you move. Points will plot on the screen as shots are taken. See File, Feature Code List, for discussion of drawing linework, symbols, Line Details and Point Details (option to re-measure existing points).

In GPS mode, **Enter** has only one function: Read & Store. The after-shot antenna height and description prompt can be enabled in **Configure** (C or ALT-C from the Store Pints screen.). If you don't have the height and description prompt turned on, then each shot is a single press of **Enter**, and you must enter antenna height, description, or point ID changes prior to pressing **Enter** and taking the shot.



For GPS, coordinates, status (Fixed, Float, Autonomous) and HRMS and VRMS accuracy estimates are displayed at all times. The icons at the left are for zooming and panning. From top to bottom, they are: zoom extents, zoom in, zoom out, zoom window, zoom previous and point display control.



If you prefer to work in a pure text screen, without graphics, you can tap the helmet icon and select Text (or Text if that option has been selected in Job Settings). The following dialog will appear.

STORE PTS	X	📚 STORE PTS 📋 🛃 🗙
		NO DEPTH
	r,	Pt: 1193 6.543 SATS:14 N:418412.4253 HRMS:0.048
	P	E:1779748.7296 VRMS:0.070 Z:499.8940 PDOP:3.200
	P	Desc:
	*	
Pt: 1193	٨	MON/SKY CONFIG OFFSET STORE

Another feature of Text mode is that when you enter a description, the program uses the full screen to display available descriptions and automatically scrolls to the descriptions that begin with the letters or numbers that have been entered. In the example below, the entry of "e" scrolls to the descriptions beginning with e (EBOX).



The Text screen uses a large character size for easy viewing, and limits options to Monitor/Skyplot, Configuration, Offset, and Store. You can return to the graph view by tapping the GRAPH button. You can also temporarily view your points on the screen by tapping Map, then tap Back to return to the text-based data collection screen. Note that the program will remember which screen you were in last (Graph or Text) and return to that mode of data collection automatically.



Snaps are available for the user by clicking on the top banner of the screen.

	JOB:2	20180320	🔒 🔀
(Text F	Info	Ĩ [#] ─S
M		🛃 _END	
۳		🗡 _MID	
\bigcirc		🖌 _NEA	
<u> </u>		∑ _INT	
Q	+	O _CEN	
Ľ	N LE→	<u>-?</u> _FRH	
0	Pt: 18	📥 _PER	0.01
	N:5336.90	Undo Last Vertex	7440
R		15 VRMS:0.024 PDOP:2.37	- ST

In addition to pressing **Enter**, Points can be Stored by selecting this icon (ALT-S). If a point is stored using a point ID that has already been used, the user will be presented the Point Protect screen.

Oint Protect	×			
Point ID 2 already used!	1			
Use New Point ID	3			
Overwrite	Point ID:			
Average with Prior Measurements				
Store Raw Data Only				

The Point Protect screen allows the user to select a new point ID or overwrite the currently saved point information for the selected point ID. The Average with Prior Measurements is selected, the software will check the distance between the new coordinates and the existing coordinates. If this distance is greater than 10cm, the user will be prompted to confirm to continue with the average. The prompt is meant to avoid averaging to the wrong point.



With GPS, since shots tend to cluster around the true point location, it may be preferred to **Average** 10 or more GPS readings when taking measurements. You will be prompted for how many readings to take (up to 999).

Average GPS			🛛 🔽 🔀		
Number of Epoc	hs		10		
OTime in minutes			30.000		
✓ Ignore invalid re	adings				
🗹 Always Display A	verage Sta	tistics			
Beep on rejected	Beep on rejected rdgs Log Avg. Observations				
Repeat every	0	mins. for	0 hrs.		
SATS:16/17 Status:FIXED					
HRMS:0.014 VRMS:0.029					
Configure	Tolerances		Monitor/Skyplot		

Taking 100 readings is also a way to gauge how fast your GPS equipment takes measurements. If 100 readings are taken in 20 seconds, you are reading at 5 per second, or 5 hertz (hz). After the readings are taken, a display appears showing the range and standard deviation of the readings. If IMU is enabled and calibrated, the average position will adjust for the tilt of the pole and average calculated ground coordinates.

SurvCE will include a line in the RW5 file to report the min, max, and average latency when using the average routine.

Average GPS	💝 Avera	ge Resu	lts		\checkmark	
Taking Reading #5 of 10		eadings:	10/10	_		_
5 Valid readings recorded.	Fixed:		10/10			
SD.North: 0.0298		Average	e	StdDev		
SD.Fast: 0.0308	North:	420447.	144ft	0.0329ft		
SD.Elev: 0.0004	East:	178041	1.385ft	0.0302ft		
	Elev:	499.870	ft	0.0008ft		
SATS:14 STATUS:No Depth						
HRMS:0.044 VRMS:0.112		Min		Max		
Stop Averaging and Store Cancel Averaging	North:	420447.	094ft	420447.180ft	1	





This icon leads to **Offset** reading screens with options for keyed-in offsets as well as offsets taken by laser devices. These devices can measure distance only or distance and azimuth (ALT-O). See <u>Store Points (GPS Offsets)</u> for more details.

ờ Distar	ice/Angle	2		💽 💽
Laser	Offset	Results	Me	thod
	zimuth:		ft	AZ Reference
Vertical	Offset:		ft	
	Read GPS			Store
	03.1304 E			87 Z: 499.872 No Depth

*****C Configure

This icon will take you to the **Configure** dialog, also found on the EQUIP tab. From this dialog, you can set the number of readings to average, specify to only store fixed readings, and turn on or off the Hgt/Desc prompt on Save (ALT-C).

💝 Configure 🛛 🔽 🔀	📚 Configure "Navigate To" Info 🛛 🔽 🗙
General View	General View
Store Fixed Only (GPS) Prompt for Total Station Setup Prompt for Height & Description Prompt for Point Notes No. of Readings to Avg - TS: 1 GPS: 1 Enter/Store Icon - TS: Read & Store Enter/Store Icon - RTS/GPS: Read & Store	Method: Coding Style Direction L/R & Distance Classic



Monitor/SkyPlot

This icon will take you to the Monitor/SkyPlot screen for GPS status, coordinates and Lat/Long display (ALT-D).

😂 Monita	or/Skyplot	t			
Quality	Position	SATView	SATI	nfo	Ref
Status:	FIXED		tellites: al Elev:	14 49	9.9004
Local No	orthing: 4	18377.142	7	(2/09/17
Local Ea	sting: 1	779737.23	84	11	:28:31.1
HDOP:	2.90	VDOP:	3.80		
TDOP:	2.00	PDOP:	3.20		
GDOP:	3.77				
HRMS:	0.036				
VRMS:	0.098				

Height/Description Prompt and Camera Feature

Within Configure, you can turn on the Height/Description Prompt which provides an extra screen after the point measurement to verify all data such as antenna height and description, with the full list of selected feature codes available to choose from, as well as icons for special codes such as Start Curve, End Curve, Close, etc. If the data collector has a camera feature, the camera option is also specifically available in the Height/Description Prompt screen. So, to utilize the camera option, there are two prerequisites: (1) The data collector itself must have a built-in camera feature accessible by SurvCE, and (2) Prompt for Height & Description must be turned on.

裬 Config	ure				$\overline{}$	X
General	View]				
Promp	ot for Heig ot for Poin	al Station 3 ght & Desc nt Notes cate of Bac	ription	⁻ Last R	▲ ea(↓	
No. of Rea	adings to	Avg - TS	: 1	GPS:	1	
Enter/Sto	re Icon - 1	TS:	Read	& Stor	e ▼	
Enter/Sto	re Icon - I	RTS/GPS:	Read	& Stor	e ▼	

The Prompt for Height & Description is described in the section on Equip, Configuration. The use of the camera feature within Store Points (GPS) is described below. Photographs in SurvCE can be associated, as GIS data, with the measured point and description. Within Store Point, in the



Height/Description Prompt screen below, a camera icon appears next to the Description edit box, if properly configured.

😂 Store Point	X X
Pt ID: 1194 76.543 Repeat Store Avg Same Pt ID N:418572.0372 HRMS:0.047 E:1779800.7131 VRMS:0.097 Z:499.8934 PDOP:3.200 > Category: ALL Desc: Desc: Contemportant Contemportant Contemporta	? ?
* BLD	
	1,2 J

To add photographs to a point (e.g. point 1194) or line, click the camera button.

Photograph Gallery

In SurvCE multiple photographs can be associated with a point or line. In the Photograph Gallery a photograph can be captured or selected.

Take a Picture

To take a picture click the Capture button to launch the camera program. This will use the camera on the data collector.

Select a Picture

Browse existing photographs by clicking on the Select button. These photographs will be copied to the job Photograph folder and linked to the point.



Capture Leads to Camera Program in Windows

To display your camera options and features pick the menu button. The camera options shown are for the Nautiz X7 data collector. These will vary by make and model of data collector. To take a picture press the **return** button on the data collector.

To close and save the photograph click OK on the screen or press OK on the data collector. In the case of the Nautiz X7, do not use the Camera button. This will open a Camera program not linked to SurvCE.



6.9 Store Points (GPS Offsets)



The GPS Offset command allows you to calculate and store points by specifying an offset from a GPS position. Offsets can either be entered manually or read automatically from a laser. There are three GPS offset methods: Distance/Angle, Intersection, and Two Point. The current method can be set from the Method tab.

😂 Distar	nce/Angl	e		🛛 💽
Laser	Offset	Results	Method	
Intersect				
		2 Poir	t	

Distance/Angle Offset

In the Distance/Angle method, offsets can be specified manually by choosing the OFFSET tab, or with a laser, by choosing the LASER tab.

• **Manual Offset**: Under the OFFSET tab, offsets are specified by entering azimuth, vertical, and horizontal distance offset values as show below. The azimuth can either be specified with respect to north, or with respect to a specified point. Current GPS coordinates are shown at the bottom and can be updated via the **Read GPS** button. When all necessary data has been entered, you'll be able to store by tapping **Store**, or preview the point you're storing by selecting **Map**, or **Results**.

😂 Distar	nce/Angle	9			-
Laser	Offset	Results	Me	thod	
Horz Of Offset A Vertical	zimuth:		ft ft	AZ Reference North Pt	
1	Read GPS			Store	
N: 4185 HRMS:		E: 17798 VRMS: 0		47 Z: 499.911 FIXED	



Laser Offset: For more accurate offsets, lasers can be used for either the distance (with direction and vertical offset entered by the user) or for both distance and direction (where the laser gun includes compass directions). The Leica Disto, for example, provides distance only. The Laser Atlanta provides both distance and direction. Laser measurements are popular on construction sites and mine sites where it is dangerous to stand beneath highwalls and unstable rock conditions. Readings are taken from a safe location to the rock or dirt face. They are also useful for utility pole surveying and other forms of "windshield" surveys. The laser devices are often mounted on the pole beneath the GPS antenna. Special poles are available that offset around the lasers, allowing them to mount vertically, in-line with the center of the pole. If the antenna height is 2.5 meters, and the laser is mounted 0.7 meters below the antenna and 1.8 meters above the ground, you would enter 1.8 as the laser height. Laser types and laser height are set by clicking Settings in the LASER tab within Offset. This takes you to the same screen as can be found from the main menu on the EQUIP tab, under Peripherals. Under the LASER tab, offsets are read automatically from the laser attached to the serial port. Upon triggering the laser, you will see the reading displayed in terms of five parameters: Horizontal Offset, Vertical Offset, Slope Offset, Azimuth, and Zenith Angle, as shown below. The azimuth can either be specified with respect to north, or with respect to a specified point. Current GPS coordinates are shown at the bottom, and can be updated with the Read GPS button, or you can choose to have the GPS position read automatically before each point store by choosing Settings and enabling Auto GPS Update. When all necessary data has been entered, you'll be able to store by clicking Store, or preview the point you're storing by clicking Map or Results. Before you can begin using the Laser offset feature, you must configure the laser, either by clicking Settings, or by selecting Peripherals from SurvCE's main menu. Under the peripherals menu, you will have to activate your laser, select your laser type, and choose a COM port. It is also recommended that you deactivate all other peripherals except GPS while using the laser. For more details on laser setup, see the <u>Peripherals section</u> of this manual. Once you have activated a laser, you may click Read Laser to begin collecting data from the laser. In order to expedite the data collection process, the methodology for reading an offset from the laser has been optimized so that you do not need to touch your data collector between shots. This option can be enabled by selecting Multiread Laser. If you are a first-time user, it is recommended that you disable this option. If Multiread Laser is disabled, pressing Read Laser will pop up a dialog asking you to trigger the laser, as shown below. From here, you can either cancel, or fire the laser to record the shot. If Multiread Laser is enabled, when you press Read Laser, a dialog will appear asking you to trigger the laser, as shown below. Each time you trigger the laser, a new shot will be collected, and if there was a previous shot, it will be automatically stored. Between shots, the laser reading and the offset-adjusted position to be stored are displayed. If Auto GPS Update is enabled during peripheral setup, a new GPS position will be read for each shot. If a bad reading is taken, you can prevent it from being stored by pressing Reject Last Shot. When finished, click Exit Shot Sequence.



误 Distan	ice/Angle	2		1 💽 🕻	
Laser	Offset	Results	Method		
Horz O Vertica Azimut Distano Zenith	l Offset h: :e:		AZ Refere	ad Laser	
Get Po	oint Rea	d Laser	Read GPS	Store	
N: 4185 HRMS:		E: 17798(VRMS: 0	02.355 Z: 4 .070 FIXE	499.911 ED(Sim)	

• **Results**: Before storing, you can preview the data by selecting the RESULTS tab. If valid data has been entered in the LASER or OFFSET tab, the result will appear as shown below. In this window, you can also change the GPS antenna height, or specify a vertical difference for your target point. You can also specify the point ID and description for the point that will be stored.



Offset by Intersection

Use Offset by Intersection to calculate a point based on two GPS positions and two distance offsets. The distance values can either be manually entered or input with a laser. To use a laser, you must first activate it by selecting Settings. For more information on laser setup, see the Peripherals section of this manual.

😂 Distai	nce/Angk	2		🛛 💽 🧲	💝 Inters	section	1		💽 💽
Laser	Offset	Results	Method		Offset	Resu	ts Meth	od	
		Distance// Interse 2 Poin	ect		Read Read Read	Point 1 Dist 1 Point 2 Dist 2 tings	N: 41860 E: 17798 Z: 499.9 Dist 1: N: E: Z: Dist 2:	810.5626	HRMS: 0.046 VRMS: 0.091 FIXED(Sim) ft HRMS: VRMS: ft

- Offset: Under the OFFSET tab, press **Read Point 1** to read the first point from GPS. Now enter the distance of the point to be stored, or press **Read Dist 1** to read this distance from a laser. Repeat this process for the second point. Switch to the RESULTS tab to see your solution. If your distances and GPS can't be triangulated, you may have to return to this tab to adjust the values.
- **Results**: After you have two GPS positions and two distances that form a valid triangle, click on the RESULTS tab to view the resulting point. If valid data has been entered in the OFFSET tab, the result will appear as shown below. In this window, you can adjust the GPS antenna height, or specify a vertical difference for your target point. You can also specify the point ID and description for the point that will be stored. The intersection method generates two solutions, so you will have to select which one you want by clicking the appropriate radio button.



Offset by Two Point

Use Offset by Two Point to calculate a point based on two GPS positions and a distance from the second point. If **Straight** is selected (lower right dropdown), the distance offset from the second point is along the 3-D vector created by the two GPS points. If **Left** or **Right** is selected, the offset is perpendicular to the 2-D vector created by the two GPS points, and the second point's elevation is used as the elevation of the resulting point. The distance offset can either be manually entered or input with a laser. To use a laser, you must first activate it by selecting **Settings**. For more information on laser setup, see the <u>Peripherals</u> section of this manual.

裬 2 Poin	t		💽 💽
Offset	Results	Method	
HT: 6.	543 ft Z:	418602.2795 1779810.5626 499.905	HRMS: 0.046 5 VRMS: 0.091 FIXED(Sim) HRMS:
	Point 2 N: 543 ft Z:		VRMS:
	Offse	t: 🚺 f	t Straight 💌
Set	tings	Read Dist	Store

- Offset: Under the Offset tab, press Read Point 1 to read the first point from GPS. Repeat this process for the second point. The GPS antenna height used for each GPS read can be adjusted individually by editing the HT fields. Now enter the offset of the point you would like to store, or press Read Dist to read it from a laser. Finally, specify the direction of your offset, and switch to the RESULTS tab to see your solution.
- **Results**: After you have two GPS positions and an offset, click on the RESULTS tab to view the resulting point. If valid data has been entered in the OFFSET tab, the result will appear as shown below. In this window, you can specify a vertical difference for your target point. You can also specify the point ID and description for the point that will be stored.



6.10 Stake Points



This command allows you to stakeout a selected point by guiding you to the point with a series of commands and directions. The point can be a Point ID or the endpoint, mid-point, intersect or other "snapped" point on a map (using the Map icon). Various options can be set in EQUIP, Configure, View Point to adjust how the directions are provided to best suit your needs. The Tools icon or C to Configure also will access the View Point settings. You should also review the Job Settings under FILE before staking. The dialogs are varied slightly with respect to total station or GPS equipment. Both types are documented here, illustrating the differences between the dialogs.

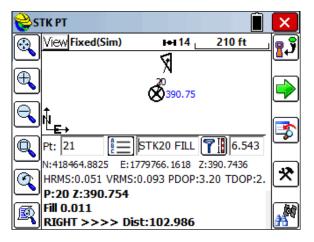
😝 Stake Points		
Point ID: 68		Point by Direction Obstructed Point
Source: Current	Job	Azimuth:
Add To List	Pick From List	Classer
Northing:	9954.8820	Slope;
Easting:	20098.6350	> H. Distance:
Elevation:	101.0810	
Description:	CP/CHIS X	

Note: While in graphics mode stakeout, if you press the down - arrow key, you can increase the plan view size and eliminate some of the text information. Pressing the up-arrow key again reveals the cut and fill.

After selecting OK, the main stakeout window appears in MAP view. In manual total station mode, the angle to turn to and the distance to the stake point will be displayed at the bottom of the screen.



Shown below are the graphic icons, set under EQUIP, Configure, using GPS Simulator.



A read function is required to update the directional display information. You should see your points in the map with an icon showing your target location (the circle with the X inside).

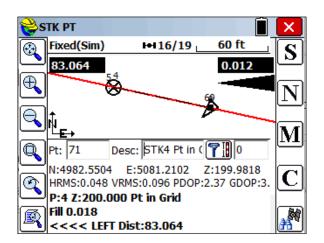
Measurements are taken typically by pressing **Enter**. **Enter** also transitions automatically from the Stake Points entry screen to the Stk Pt measurement screens above. Point Stakeout can be conducted without touching the screen, using the Enter key and entering point IDs using the keyboard. Both screens are explained below, starting with the graphic Stk Pt screen.

• Store points – Obstructed Point

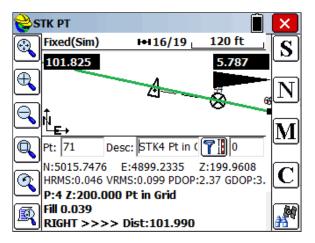
Stake Point using the Obstructed Point method allows the user to stake to a point that is in some manner not possible to survey; such as a car over a manhole. The method proceeds with the user storing a point away from the obstructed point to establish a line. Once this line is established, the user can stake a point anywhere on that line and the software will output the distance to the obstructed point. The process is as follows:

- Select Obstructed Point from the Stake Points menu.
- Select the obstructed point from the point list.
- Store a point to establish an orientation line between that point and the obstructed point.





• Navigate to that line (which will turn green once within the stakeout tolerances) and store the point.

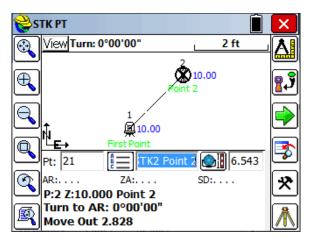


• The Obstructed Point Alignment screen will show the user the distance along that line the obstructed point can be found.



😂 Obstructed Point Alignment 🛛 🔽							
Northing Easting	Elevation						
Staked: 7592.780 8651.703	199.970						
Design: 7593.212 8651.964	199.976						
RIGHT >>>> Move: Dist:0.505 ft Fill 0.006 VOff 1: Elev: VOff 2: Elev:	5						
HRMS:0.050 VRMS:0.093 F	PDOP:2.371						
Store Point ID: 11							
Point Description: 2 Thing Dist: 0.5	05 FILL 0.0 👔 📃						

• Total Station or Robotic Total Station running Direct: After reading and taking the shot, the display will be updated with a distance and direction to the stakeout point. Buttons on the right from top to bottom are Read, Store, Next, Menu, Configure and Setup. Enter is treated as R for Read. Pressing S (or "Store to Collector" icon, 2nd from top right) will go to the Stakeout Report screen and allow you to write to the "cutsheet" file the cuts and fills and optionally to store the measurement as a new point ID.



• GPS or Robotic Total Station with Tracking On: Your current position is read immediately (no Read button needed). R takes a fresh reading. If you press R for Read or S for Store, you will go to the Stakeout Report Screen. Enter is treated as R for Read and takes a fresh reading, then proceeds to the Stakeout Report screen. If you are outside of accuracy tolerance, you will be warned and asked if you wish to proceed. In the Stakeout Report screen, you can save your cut and fill data to a cutsheet file and optionally store a new point ID based on the fresh measurement taken. If you click off tracking, then the angle



to turn for staking is displayed, same as with regular total stations running direct. With robotic total stations, if you are locked on and tracking, you will see instantaneous instructions on directions to move to the point, meaning that you do not neeed to take a reading to locate the point. Just move to the point based on the instructions. If the screen is not updating, it is recommended to turn off lock and then re-acquire lock by tapping the lock icon twice, verifying that tracking also is on. Then the instructions to move will stream in real-time.

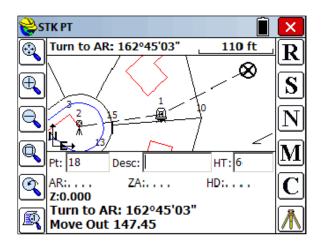
- Robotic and Motorized Total Stations, "Turn to Point": In Total Station, Search Tab (Equip menu, or accessible through the tripod icon or C for Configure), you can turn on "Turn to Horizontal" in Stakeout. If this is turned on, the instrument will turn to the target point automatically. If "Turn to Vertical" is also on, and the correct target height is entered, the instrument will turn to both the horizontal and vertical position of the target. Do not use "Turn to Vertical" if the elevation of the target point is 0 or not accurate.
- Point ID: This is the point which you are staking. You can enter it in here and hit the Enter key to view the elevation, northing and easting before selecting OK. If you want to stake out a range of points, you can enter in the points in the following format: 3-10,2,15-20. This would stake out the points from 3-10 sequentially, then point 2, then 15 through 20 sequentially. N for Next would move to the next point in the list. If you are using a control file in total station mode, and you enter a point number which also is present in the current job file, it will choose the control file point if Control File Has Priority is enabled in the stakeout section of Job Settings. If you enter a point number that is not in the control file, but is in the current job's coordinate file, then that point will be used. You can also select the points to stakeout from a list by selecting the **List** icon. If you select the List option, you can select the points for stakeout from the active job file or the control file. To do this, you must toggle between the files using the **Job** and **Control** toggles at the top of the dialog. You can select a range of points by selecting the first point to stake then pressing the shift key and selecting the last point to stake. All points between the two selected points will be staked in sequential order. You can also add to the selection of points to be staked by pressing and holding the CTRL button and individually selecting the points to be staked. The final way to select an individual point to be staked is by selecting the Map icon and tapping on the point to be staked. Using the Map icon, you can also select points to stake from linework on the screen, using the endpoint, intersect and other "snaps".
- Add to List, Pick from List: When you select, or enter multiple points, they appear in the Point ID dialog window. You can then pick Add to List and create a list of these points in the order they were selected. When you Add to List, the Point ID dialog is cleared, and you can select more points, place them in the dialog and click Add to List again. Then you can stake any of them using Pick from List, where the points appear as shown below:



8	🔍 Job 🤇	🔍 Control 🗾		/ 🧲
Point ID	Northing	Easting	Elevation	Descr 🔺
⊕ 2	5002.00	5002.00	10.000	Point 2
⊕ 3	420028.71	1780275.10	397.297	
() 9	3325.65	50222590.00	838.995	EP
- 10	3355.28	5038.43	838.995	EP
- 11	3404.53	5037.02	838.989	EP
- 1 2	3410.85	5089.35	838.995	EP OH
- 13	3388.95	5130.42	838.995	EP
- 14	3339.64	5139.79	838.986	EP OH
- 15	3370.03	5108.37	839.002	EP PC
- 16	3377.57	5085.95	838.995	EP
9 17	356.85	5070.77	838.988	EP PT 🖵
Ĩ		1		• //

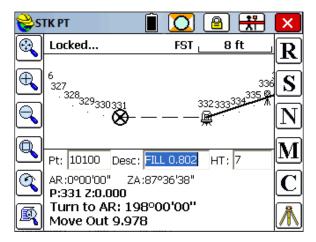
- Source: When you press Enter after selecting the point (or points), the program will display the source of the points, either as Current Job or Control File. The display of the source is important for verification. You may discover, for example, that someone has turned on Control File Points have Priority in the stakeout settings, and this is a way to catch the mistake.
- Northing, Easting, Elevation: You must have a northing, easting and elevation entered for the point you are staking out. If you type in the point number of an existing point and hit OK, these values will appear automatically. The description of existing points is displayed at the bottom of the dialog.
- **Point by Direction**: In addition to staking a point ID or entered coordinate, you can stake a point defined by a direction and distance, and even slope, from the entered point coordinate. This allows you to stake points without calculating point numbers or point IDs for the target point. Simply enter the bearing/azimuth, horizontal distance and also slope, if applicable. If the distance entry is not known but must be computed, the calculator is accessible from the distance dialog box by hitting the ? button. Shown below is a stakeout of a point calculated at NE45 degrees, 100 feet, from point 10.





N for Next (Increment Up or Down)

On some projects, you may find that it is more convenient to stakeout points in descending order.



This can be accomplished by going to File, Job Settings, Stake tab, and switching to increment in descending order. If Increment ID Down is set, then N for Next would go to point ID 330, then to 329, etc.



😂 Job Settings	🔽 🔽						
New Job System Form	at Options Stake						
✓ Limited to Instrument Precision: 0.000 ✓ Store Data to Note File Merge Ctrl File Pts for Control Pts Have Print ✓ Use Automatic Desc Stake Offset Desc	e Stk Increment Pt ID:						
Auto Descriptions Cutsheets							

View Pt

Depending on your settings in the **View Pt** tab of **Configure** (in the **EQUIP** tab), the direction to stake will either be Right/Left Distance, Azimuth and Distance, or North/South East/West Distances. The cut or fill is the elevation difference between the point read and the point being staked. Normally, you take a shot simply by pressing **Enter**. After a total station shot is taken, you will see your "In-Out" distance to the target point. For total station stakeout, the direction of the reference is shown by a little arrow in the lower right of the screen.

💝 Config	jure Stake	eout Info	🔽 🔽			
General	View	Sets				
Method: In-Out &	Left-Right	to Ref 💌	Collapsed Report: Measurements			
Ref. Object: Measurements Instrument Navigate Data None						
Move Rel Ref. Obj		•				
🗌 Use (CL for Ref.	Object (wl	hen applicable) Proximity STK(Pts)			



Stakeout Report Dialog

Selecting S to Store will display the Stakeout Report. You can turn off the Store Point option, and just reference the Stakeout Report screen for information. If the tolerance distance is exceeded for staking out, you will be notified and asked if you want to continue storing. (Stakeout Tolerances are set under Tolerances in the EQUIP menu).

😂 Stakeout Report		X
Northing Staked: 418323.141 Design: 3355.278 RIGHT >>> Move: pict:1823551.0	Easting 1779719.796 5038.431)28 ft Fill 448.24	Elevation 390.749 838.995
VOff 1: Elev:	120 IL FIII 440.24	0
VOff 2: Elev:		0.0.000
	IS:0.029 PD int ID: 21	OP:3.200
Point Description:	TK10 EP FILL 448	.249 <u></u> €⊟

The coordinates for the Stake Point and the Target Point are displayed. The delta North, East and the elevation difference (Cut/Fill) are also displayed. The vertical offset input boxes allow for elevation calculations based on the input vertical offset values. The vertical offsets can be entered in inches in English units in two forms (10" using the inch designator, or 0.10.3.8 for 0 feet 10 and 3/8ths inches). The second form requires 3 decimals to be used.

If **Store Carlson Cutsheet Data** in Note File has been enabled, the vertical offset(s) specified will be recorded in the .not file for the job. If under **Set Cutsheet Format** in the Stakeout section of Job Settings, a Set Pt Cutsheet Format has been established with a named file for storage, then cut and fill data will be saved to a cutsheet ASCII file. If using GPS, the HRMS, VRMS, and PDOP values are also displayed. Fields for Point number and point description input are also displayed. If, for example, you choose not to store a staked point, but only report the design point, design elevation, surveyed elevation and the cut and fill, you could produce a simple cutsheet report as shown below. One vertical offset per shot was recorded (-10"). The cutsheet can be reviewed from within the active stakeout screen using Alt V. You can also click on the helmet and go to View Data to see the cutsheet report, while actively staking out, and you will be returned to the stakeout screen. Cutsheet data is always stored to the raw file, so if you forgot to store the cutsheet information, you could create a new point cutsheet file and select "Cutsheets from Raw File".

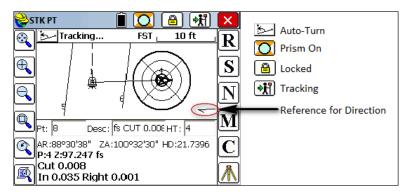


😤 Edit CutSheet File SubdivPt.txt 🥢							
DesignPt	DesignEL	StakeEL	Cut				
2	843.31	846.39	3.08				
2 -0.83	842.48	846.39	3.91				
13	842.47	846.39	3.92				
13 -0.83	841.64	846.39	4.75				
15	842.43	846.39	3.96				
15 -0.83	841.60	846.39	4.79				
Insert Up Down Special Delete							

Pressing **OK** (which optionally will Store Point if enabled) will return to the Stakeout Points dialog to select the next point for staking. If the Use Control File option is set under the Job Settings, you have the option of staking control file points. If you enter in a point number to store that is the same as a point number in the control file, the point in the control file will remain unchanged. It will only modify the point in the current coordinate file. If the point being stored is the same as one in the current job file, the **Point Protect** dialog box appears stating that the point you chose is already used. The next available point number is listed with the option to overwrite the current point or use the new number.

Review of Stake Points Graphic Screen (Robotic Total Stations)

The Stake Points screens below illustrates many options available to the user when using a robotic total station.



• Auto Turn: This option only appears if you are configured for a robotic total station with Turn to Horizontal set on in Search. Search can be accessed using the Tripod Icon (lower right) and selecting the Robotic tab, leading to Search or by clicking Total Station within Configuration and selecting the Search tab. Even C for Configure gives access to Search. Clicking Auto-Turn will turn the instrument to sight on the target point. If Turn to Vertical is also on, the instrument will sight the vertical position correctly, based on the target height.



Do not use Turn to Vertical if the elevation of the target point is inaccurate or zero. Note that with Turn to Horizontal on, the instrument will do the turn automatically in stakeout. You only need to click Auto Turn if you want to force a new turn to the target if the instrument has been moved off the target.

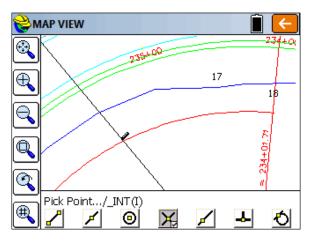
- **Prism vs Reflectorless**: For total stations with reflectorless capability, a prism icon is displayed at the top of the screen which allows the user to toggle between prism and reflectorless mode.
- Locked vs Search: For robotic total stations, the lock and search (binoculars) icon is used to display the status of the instrument. When the lock is shown, the instrument is locked onto the target. If you press the lock icon, it will switch to Search mode. For Tracking to occur (distance measurements leading to known target position shown by triangle), the instrument must be locked. If the binoculars are shown, the instrument is in Search mode, and pressing the Search icon (binoculars) will start the search process, with the window of the search determined in Settings. When the prism is found after a search, it returns to lock mode.
- **Tracking**: Tracking is available with robotic total stations, and indicates that distance measurements are being taken to the target. Tracking on leads to known position of the target, which then appears as a triangle. Tracking will use more battery life on the instrument. If turned off, the tracking off icon appears as a rodman with a line through it. With tracking off but lock on, the direction of the instrument typically appears as a line or beam radiating from the instrument position. In all stakeout routines, with tracking on and active, instantaneous, real-time instructions to move to the point are provided.
- **Reference Line for Direction**: The Left and Right instructions for direction to move are provided in reference to either a point or the instrument as set in View Point. This reference direction is shown in the lower right of the screen.

Staking by Graphic "Pick Point" Selection

One of the interesting features of SurvCE point stakeout is the ability to stake to points on line elements without the creation of point numbers. You can just stake to the graphics using the

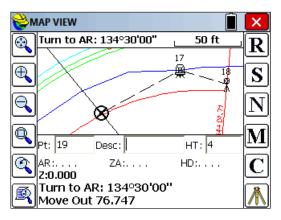
"from Map" selection icon: In this way, any drawing is a fertile field of available stakeout points, and complicated intersections involving spiral curves and other elements can be staked simply by using commands like Offset followed by snapping to intersections. Consider the example below:





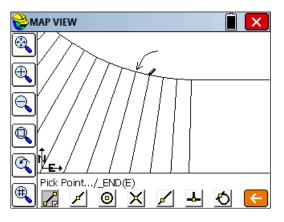
The road section from 234+00 to 236+00 is in a spiral curve and the goal is to intersect the rightof-way of the road, which is at a 50' offset from the centerline, with an original property line running NW to SE. Rather than use complicated coordinate geometry, the Map screen can be used to select Draw, Offset and create a 50' offset line of the road, shown above. Then within Stake Points, where point 17 is the occupied point and 18 is the backsight point, the point to stake can be selected using the Map icon, and then the intersect snap (highlighted in gray above) can be used to find the intersect of the spiral curve to the property line. Note that the snap to the right of the intersect is the "nearest" snap--it picks up any point you pick on the linework, not necessarily at an endpoint or intersect point. Upon clicking the orange return arrow at the top right, the target point is computed. No target Point ID is created or is necessary. You can simply "stake to the

drawing".



Using the graphic screen selection of points, you also have the ability to see the last point picked. So, if you are selecting a series of tightly-spaced "endpoints" of lines, using the endpoint snap, you can see your last point, and pick the next one, by reference.





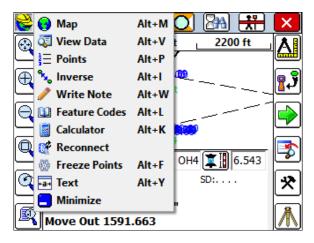
The last point selected is shown by a pencil, so if you are staking endpoints right-to-left, you select the next point shown illustrated here by an arrow. The previous "snap" used, such as "endpoint snap" highlighted above, is the default, allowing you to pick the next point immediately. If you don't pick a new point but instead click on the orange arrow, the program will default to the highlighted point (indicated by the pencil), and you will be re-staking the last point selected. So this option allows you to re-stake the last point and also reference the last point when staking another.

Note: The graphics screen will show text such as stationing (e.g. 235+00) or lot numbers if the text is first converted to polylines before being imported as a DXF or DWG file. Carlson Survey, for example, has a command called "Text to Polylines" that can be used to convert standard text into polylines for presentation within SurvCE and other programs.



Using the Helmet Options

While in Stakeout, and without leaving the command, the Helmet can be used to access various reports and even conduct basic editing. When the Helmet (in the upper left) is clicked, the dropdown menu of "quick access" options appears:

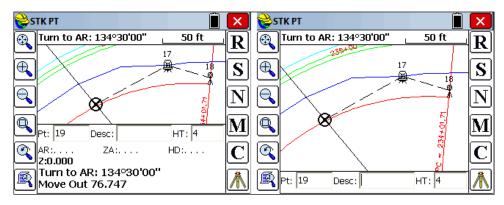


Some of the more useful commands to access, at any time, are Inverse (obtain 2D and 3D distance between points), View Data (review the cut and fill "cutsheets" and review and edit the raw file), Points (review the coordinates in the job file, delete and edit as desired) and Freeze Points (to freeze the point numbers and reduce clutter on the screen). The Calculator can be accessed to compute angles between points (triangle solution, pick 3 points), to compute math expressions and to convert between Lat/Long and grid coordinates, among other things. The "Reconnect" option is a quick way to reestablish the Bluetooth connection to the instrument.

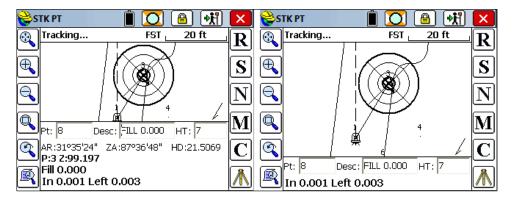


Graphics Screen Expansion: Normal (None), Navigate Data, Measurements

One of the special options available in Stakeout is the ability to maximize the graphics screen using the down - arrow to enlarge the graphics (reduce the lines of text instructions) and the up - arrow to return to normal graphics. Since the text instructions for stakeout are minimized in expanded graphic mode, you can control what content is provided in the one-line instruction by the setting in Viewpoint (Viewpoint tab within C for Configure, see discussion above). When the "Maximized Map" is set to None, then for total stations in direct mode, the instructions are the angle right to turn (top of screen) and the one-line display shows only the new point number and target/rod height. The screen at right is referred to as the "Maximized Map".

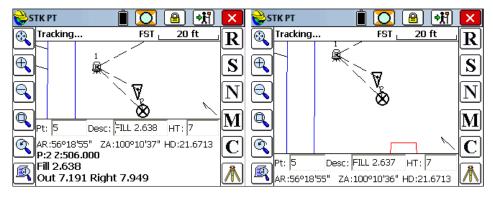


For robotic total stations in tracking mode and for GPS, the "None" setting in ViewPt, Maximized Map shows only the target and the lower line at right. In this case, the "**Navigate Data**" setting is beneficial. This adds an extra instruction line. Shown below is Stakeout with Navigate Data set for Maximized Map within ViewPt, running a robotic total station in tracking mode.





There is a third mode for the Maximized Map which is called "Measurements". With this mode set, and running a robotic total station, the larger map appears as shown below, with the current measurement data presented on a second line.



The expansion of the graphic screen in stakeout can be accomplished two ways: (1) press the down - arrow to expand, up - arrow to return to normal (at left) and (2) place your finger or stylus in the first line, near the "Desc" and pull - down and repeat the process and pull up the screen. (For restoring the full screen, the up - arrow is the easiest method).

Stakeout Points using the Text Screen Mode

Some surveyors prefer a text screen for stakeout with no graphics and large, bold text characters. Using the Helmet, as described above, you can select "View" or enter Alt Y and go to Text mode for stakeout. The program then goes to a different display mode with larger text for improved readability, as shown here:

💝 Configure Stakeout Info	🔽 🔀 🔮	STK PT	📃 📋 🚺	🖸 🔒 👫 🛃 🔼
General View Sets		STRUMENT		STAKE PNT: 12
Method: Collapsed Re	port:	Æ		Pt: 6
In-Out & Left-Right to Ref 💽 None	-		\mathbb{S}	Desc: Fill 2.372
Ref. Object:		((())	3 81	READ STORE NEXT
Instrument Move Relative To:		Π	7777	TURN/MOVE TO STK -
Rod		\sim		TURN(AR):131°46'55"
		~		MOVE OUT:1591.663
✓ Use CL for Ref. Object (when applicable)		10 ft		
Proximity ST	K(Pts)	BS/SET	CONFIG	Connection Lost
		AR:57°15'55	i" ZA:97°55	'29" HD:26.0415 🔹 💽
				30 Z:503.6277
	1	AR:57º15'55	" ZA:97°55	29" HD:26.0415



The instructions given are controlled by the settings in Configure, View Pt tab. In this case, the instructions are In-Out, Left-Right facing the instrument from the perspective of the rod or prism. This would be a typical configuration for running as a one-man crew working from the rod and facing a robotic total station. In the "bullseye" diagram, the target point is the center of the bullseye, the instrument is shown relative to the target point (which is at the top of the circle if due North) and the backsight is shown as a square target relative to the instrument. Your position is shown as a triangle, with tracking on (or with GPS). As you look at the instrument, you need to go Left to the center of the setting at the bottom of the screen, and your instructions can be set dynamically, within the stakeout screen, without needing to return to Configuration, by using the pulldown options in the middle right of the screen (current setting is In-Out, Left-Right). Your goal in Text mode is to get to the middle of the circle.

Another feature of Text mode is that when you enter a description, the program uses the full screen to display available descriptions and automatically scrolls to the descriptions that begin with the letters or numbers that have been entered. In the example below, the entry of "e" scrolls to the descriptions beginning with e (EBOX).

😂 STK PT	😂 STК РТ 📋 🏹 🗙
Wiew Turm: 262*24*51" 110 ft ▲	INSTRUMENT STAKE PNT: 398
	Pt: 1042
€	Desc: Ave
	READ STORE NEXT
	IN: 69.861 ft
	RIGHT: 47.923 ft 110 ft FILL: 6.015 ft
AR: 3°00'00" ZA: 90°00'00" SD: 50.0000ft P:398 Z:117.891 Ave	110 ft FILL: 6.015 ft BS/SET CONFIG
Turn to AR: 262°24'51" Move Out 0.001	AR: 3°00'00" ZA: 90°00'00" SD: 50.0000ft
😂 Stakeout Report 🛛 🔽 🗙	😂 Description: 🔽 🗙
	> Category: ALL
Northing Easting Elevation	
Staked: 800128.312 2686515.748 0.054 Design: 800046.392 268537.345 6.069	
5	DECK DECK DEFAULT
Move: In 69.86 ft Right 47.923 ft Fill 6.015 ft	
VOff 1: Elev:	а [™] опсн опсн // 6
VOff 2: Elev:	
ZA:90°00'00" AR:3°00'00" SD:50.0000	
Store Point Point ID: 1042	I ¹ DR DR I ¹ DRV DRV
Point Description: STK398 Ave CUT 1.398	EBOX ELEC BOX ▼

Click the one you want and then press Enter on the keyboard to return to Stakeout.

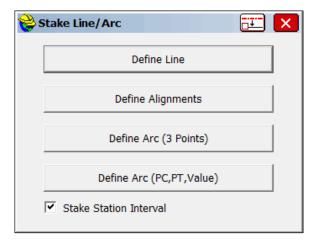


6.11 Stake Line / Arc



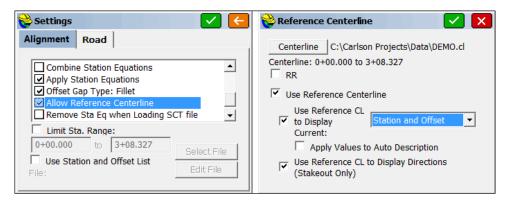
This command opens a secondary dialog where you can choose between Define Line (single line, no curves), Define Alignments, Define Arc (3 points), and Define Arc (PC, PT, Value). If within the Configure option, "Prompt for Total Station Setup" is clicked on for total station work, the Stake Line/Arc command will go first to the backsight screen. When taking the backsight, note that with Leica "ATR", or Sokkia "Search on Read" or Topcon "Auto Aim" clicked on, you can be sighting your backsight slightly off the prism, and the instrument will read and lock to the crosshairs. This can save time on dialing in precisely to the center of the crosshairs, both for backsights and for foresights. This can accelerate the work especially when doing repeated stakeout measurements.

Stake Station Interval: The Stake Station Interval option, when clicked on, leads to a dialog that includes the station and offset to stake and the interval to increment. It allows the staking of particular locations on an alignment. When Stake Station Interval is clicked off, the program reports the station and offset of measured points and for your current position (GPS and robotic total stations), and does not prompt for a target station, offset and interval.





Reference Centerline: The middle icon on the top line leads to global settings that allow a master centerline (horizontal alignment) to be designated for reference, while you stake out a separate alignment for L and R instructions. For example, if you are staking a curb or right-of-way, you could designate the main road centerline as the "master centerline" and the curb or right-of-way alignment as the target alignment for stakeout. If you "Use Reference CL for Station and Offset", then you obtain reports of the station and offset of your position relative to the master (reference) centerline. Other options include reference CL to Display Directions", then your instructions to move in the field lead you to the target alignment but reference the master centerline. In the screen below, you select the name of the master centerline. You can also designate whether curves are based on "railroad" definition or standard road definition. Note that even the appearance of this option is controlled by Job Settings, Stake Tab, Alignment Settings, option "Allow Reference Centerline".



Define Line

This command allows you to stakeout to a line between two points by guiding you to the point with a series of commands and directions. It is also specifically the option to use for staking a "Point-On-Line" such as when marking a property line. A Reference Alignment can also be used (see discussion of Reference Alignment within the Define Alignments option below).

This option is for setting out points along a line including the cut or fill, or for staking out points relative to the line. One application, for example, would be staking a pipe between two known points (inlet and outlet), where offset stakes can be set with cut/fill noted. Station Store might even be used to calculate, in advance, the inlet and outlet points based on a known station, offset and elevation. For all staking, there are configuration settings that govern the type of instructions you receive in stakeout. You should review the settings in the **Stake** tab under **Job Settings**, as well as the **Configure** option within **Equip** before staking. The dialogs are varied slightly with respect to total station or GPS equipment. Both types are documented here, illustrating the differences between the dialogs.

Stakeout by Define Line also has a **Point On Line** tab that enables, in total station mode, staking of the intersect with the specified line on the current line-of-sight. This is often used to set stakes or flagging along a property line by sighting gaps in tree lines. The surveyor finds a gap in the



line, takes a reading to the prism and is advised how far to Move In or Move Out to stake the line at the current line-of-sight. The Point on Line tab also includes the standard perpendicular method, where any measurement is used to compute the direction and distance to move to go to the point on the line perpendicular to the measured point. For GPS configurations, Point On Line offers only the Perpendicular method.

误 Define Line		
First Point ID: (from Current Second Point	Job	
North Azimut	270°00'00"	Use Points
Slope:	-0.00%	
- Method	2 Point	C Azimuth
Start Sta:	0+00.000	
End:	502175+52.982	Confirm NEZ

The Define Line dialog gives you the following options:

- **First Point ID**: This is the starting point of the line. You can enter the point here by point ID. The first button brings up the list points dialog where you can select the starting point of the line from a list. The button directly to the right allows you to choose your point from the map instead. If you pick a point from the map in a crowded area of points, you will be directed to the list points dialog to select the desired point among those near to your chosen position.
- Second Point ID: Pressing Enter from the first point moves the curser to the second point. This is the ending point on the line that is only available for entry if Method is set as two Point for defining the line. The procedure for selecting this point is the same as for the first point.
- Azimuth: This option will be available for input only if Method is set to Azimuth. If Method is set to Two Point, then the Azimuth is inactive, but still displays the azimuth or bearing between the two points of the line. The Azimuth method will prompt for bearing if Angle Type is set to bearing in the Format section of Job Settings.
- Slope (%): Just like the Azimuth, this option will be available for input only if Method is set to Azimuth. If Method is set to Two Point, then the slope is inactive, but still displays the slope between the two points of the line.
- **Method**: This options lets you choose how to define your line. The available options are by two points, or one point and an azimuth and slope.
- **Start Station**: This option defaults to 0 within Stakeout Line, but can be changed to any starting station.
- **Confirm NEZ**: Selecting this button brings up the Confirm NEZ dialog box. This screen displays each point as a tab at the top of the screen. Listed is the point number, Northing,



Easting, Elevation and Description of the point(s) selected for the line. After you confirm the points, selecting the back arrow will take you back to the line definition screen. Pressing Enter after Confirm NEZ automatically continues to the next screen.

If "Stake Station Interval" is off in the opening dialog to Stake Line/Arc, then you would go directly to the measurement screen as shown below. If using GPS or robotic total stations, your current station and offset is shown immediately, real-time.

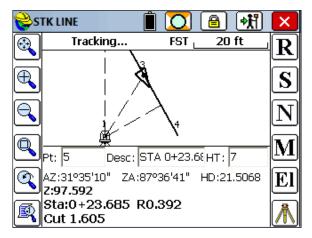


Figure 3: Stake Station Interval Off

For standard total stations, a measurement must be taken (Enter key or R for Read) to see the Station, Offset and Cut or Fill. With total stations, dashed lines are drawn from the instrument to the backsight, to the current point being measured, and perpendicular to the defined line. In the graphic above which applies to robotic total stations, the icons on the top line indicate battery status (full), prisms are being used, the instrument is locked on the target prism, and tracking readings are occurring so that the position of the prism can be computed (the triangle). If you choose "Stake Station Interval" (set in opening screen) when using Stake Line, then you will be prompted for the station to stake, as shown below:



😂 Stake Line		🗾 🔽 🔀
Station/Offset	Point On Li	ine
Start Sta: 0+0	0.000 End Sta	502175+52.982
Station:	0+25.000	🔶 🄶 듣
Interval:	25	
🔿 Left 🆲 R	ight	Off. Inc: 0
Offset 💌	0	
Elevation:	838.995	🗌 Override Design
Segment (H): Cutsheet: Non		(V): Grade

Figure 4: Stake Station Interval On

Clicking OK (green checkmark) proceeds to the stakeout screen. The settings button on the top of the screen, left of the green checkmark, will let you stakeout the precise end of the alignment (in addition to even stations), extend the alignment and do many other special features such as load a list of targeted stations and offsets to stakeout along the alignment. In the graphic stakeout screen, you will be advised to move to the target point based on the Viewpoint settings under Equipment, Configure, Viewpoint tab. It is recommended to click on "Use CL for Reference Object (when applicable)" when the horizontal alignment is clearly visible or known in the field. Otherwise, you could use the instrument as reference for total station work, moving in or left and right as you face the instrument. Here, the reference is the alignment itself, and you are advised to move In towards the alignment and Forward along the alignment.

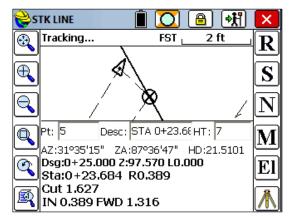


Figure 5: Stake Station Interval On

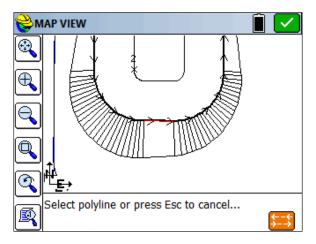


Define Alignments (Horizontal)

Stakeout Centerline only requires a horizontal alignment, but you have the option to specify a vertical alignment which will lead to cut and fill results as well. Additionally, you can specify a reference alignment. This feature allows you to stake the offset off of one alignment (e.g. curb) and report the station of a reference alignment (e.g. centerline).

😂 Define Ali	gnments		🛛 🔽		
Horizontal	Vertical				
1 Centerlin	ie File				
2 Select Po	olyline	4 Preview	5 Edit		
3 Define Point List		6 Save As			
Centerline: C:\Carlson Projects\Data\DEMO.cl Start Station: 0+00.000 ft Ending Station: 3+08.327ft Cutsheet: None					

- Centerline File: Select a centerline file defined in the Roads Menu or uploaded and converted to ".cl" format.
- Select Polyline: Select a polyline on the screen to define the alignment.





Reverse Alignment Direction: After selection of a polyline, you can use the "Reverse" icon to reverse the direction of the alignment, ensuring that it increments the stationing in the desired direction. This feature is found throughout the software where horizontal alignments are selected from the screen. In the case of File-based or Point-based alignments, the direction is defined by the file or point order itself. This option is available within Stake Offset, Point Projection, Station Store, Store Sections, Stake Slope and Stake Road.

- **Define Point List**: Enter a sequence of points to define the alignment.
- **Preview**: Displays the alignment graphically, highlighted as a bold line.
- Edit: Use this to edit the selected alignment.
- Save As: If an alignment was defined by points or a polyline, you can optionally save it as a centerline file.
- Start Station: Enter the starting station unless it was pre-determined by a centerline file.
- End Station: This shows the ending station of the selected alignment.

Defining Alignment (Vertical)

This is optional in this command. If your goal is to ignore elevations and you are auto-recalling roading files, the Vertical Alignment will be used and cut/fill will appear unless you turn off Apply Vertical Alignment.

误 Define Al	ignments		🔽 🔽		
Horizontal	Vertical				
1 Profile F	ile				
2 Select Pe	olyline	5 Preview	6 Edit		
3 Define Point List		7 Save As			
Profile: C:\Carlson Projects\Data\DEMO.pro Start Station: 0+00.000 ft					
	on: 3+08.00 /ertical Alignr				

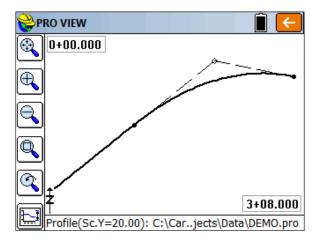
- **Profile File**: Select a profile file defined in the Roads Menu or uploaded and converted to ".pro" format.
- Select Polyline: Select a 3D polyline on the screen to define the profile.
- **Define Point List**: Enter a sequence of points that have elevations to define the profile.
- **Preview**: Displays the profile graphically.
- Edit: Use this to quickly edit the selected profile.
- Save As: If the profile was defined by points or a polyline, you can optionally save it as a profile file.
- Start Station: Enter the starting station unless it was pre-determined by a profile file.
- End Station: This shows the ending station of the selected alignment.



• Apply Vertical Alignment: Toggles on/off the vertical alignment for 2D or 3D staking.

Note: For file names to be recalled, Recall Job Road Files needs to be enabled within Job Settings, Options.

Shown below is an example of what will you see when you tap **Preview** in either tab. Notice that the centerline is shown, along with any existing point numbers in the vicinity.



With Stake Station Interval On, the alignment selection screen continues into the Station/Offset screen where you select your station and offset to stake out. Using Define Alignments, the Point on Line option becomes Point on CL in the screen that follows. With both horizontal and vertical alignments defined, the final stakeout screen (e.g. station 375) includes cut and fill values. Shown below is an example in GPS mode. The centerline was picked from the screen (Select Polyline) and the vertical alignment was selected from a file.

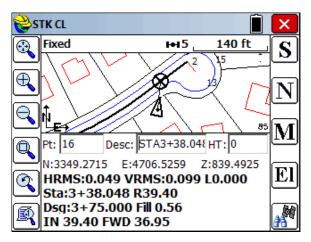


Figure 6: Stake Station Interval On

Reference Centerline Example



If a Master Centerline or "Reference Alignment" is used and Stake Station Interval is Off, and "Use Reference Centerline to Display Station and Offset" is on, you will obtain the cut/fill from the target alignment but the Station and Offset, noted with the "*" symbol, from the Reference Centerline:

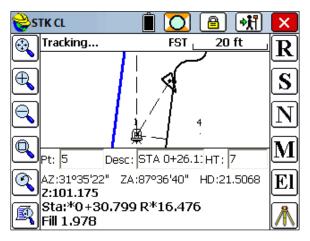


Figure 7: Stake Station Interval Off

However, with Stake Station Interval On, and in addition, "Use Reference CL to Display Directions" on, the same position shown above is displayed with both current position and instructions to move provided in relation to the Reference Alignment.

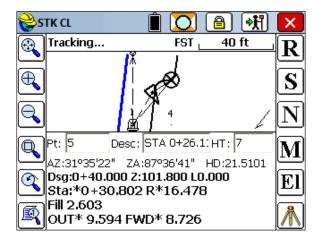


Figure 8: Stake Station Interval On

The example above illustrates a common use of the Reference Centerline. The bold (blue with color screens) reference centerline may be easier to follow than a curving target alignment such as a curb line. Therefore, the forward and in-out instructions referencing the master centerline may



be more useful in moving quickly to the target point. Any display with an "*" designation is in regard to the Reference Centerline. The reason for the difference in fill is that with Stake Station Interval On, the target elevation (101.80) is computed at the target station to stake, whereas with Stake Station Interval Off, the target elevation is computed at the current offset on the target centerline (station 0+26.1, which is the default station in the description field). The Reference Centerline station is 0+30.8).



Define Arc (3 Points)

This routine requires three points to define a unique arc, which is then used for stakeout by station and offset. The first point becomes the beginning of the arc. The prompting is shown below.

裬 Define Arc (3 Points)	🔽 🔽
	🗆 RR
First Point: 2	
Second Point: 4)= Z
Third Point: 5	
Start Sta: 0+00.000	End:

The points can be entered in, chosen from the list points button, or selected from the map. After selecting the three points, choose OK (green checkmark) to go to the Stakeout Arc dialog. The special stations are limited to PC (start) and PT (end). After choosing a station and offset to stake and selecting OK, the main stakeout window appears in map view. In total station mode, an angle to turn to and a distance to go will be displayed at the bottom of the screen. Taking a reading to the current target position will update the display with a new out/in distance and a right/left distance depending upon your job settings. You should see your points and centerline or curve in the map with an icon of the point you need to stakeout to (the circle with the X inside). When using GPS, after selecting **OK** to the Stakeout Arc dialog, you will be placed in the Map screen at your current position with directional instructions to the target point continually updating. You can click "RR" to stake out a 3-point arc by railroad definition. Cuts and fills are computed from the elevations of the points which determine the 3D profile of the arc, and the profile will trend to zero if any of the points have zero elevation. If points are picked using the "snaps", such as when picking the end of a line, a new point ID will be assigned to the picked point. If this point ID has zero elevation, the profile will trend to zero and will impact cut/fill reports. Points can be assigned elevations using Edit Points. The Reference Centerline and Stake Station Interval options as discussed above apply also to all methods of Define Arc. The Point on Arc option only appears if Stake Station Interval is On, since this option appear in the interval dialog.

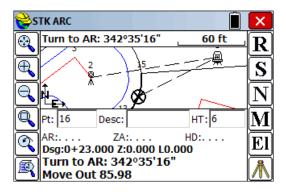


Define Arc (PC, PT Value)

This option for defining the arc requires four input parameters: The Start point, End Point, Curve Direction, and any of the following: Radius Point, Radius Length, Arc Length, Delta Angle or Degree of Curvature. The starting station defaults to 0 but can also be changed. See the figure below.

裬 Define Arc	(PC,PT,Value)		🖌 🗙
Direction Cu	ve Left 🖲 Cur	ve Right	
Start Point:	15	1=	
Radius Point	•		
	2]= 🖸	
End Point:	13		
Start Sta:	0+00.000	End: 102+5	2.256

When selecting the PC point, option Radius Point and PT point, enter the point ID, choose the point from the list points screen button, or pick the point from the Map button. When you pick using the Map button, you can pick the point numbers or use one of the "snaps" at the bottom of the screen, like "endpoint snap" and pick a line element. In this case, a new point ID will be assigned to the picked point. After selecting **OK** you will be directed to the Stakeout Arc dialog. After selecting **OK** to the **Stakeout Arc** dialog, the main stakeout window appears in map view. Here we are staking station 75 at 0 offset. In total station mode, an angle to turn to and a distance to go will be displayed at the bottom of the screen. Taking a reading to the current target position will update the display with a new out/in distance and a right/left distance depending upon your reference settings in **Configure Reading**. You should see your points and arc in the map with an icon of the point you need to stakeout to (the circle with the X inside). When using GPS, after selecting **OK** to the **Stakeout Arc** dialog, you will be placed in the **Map** screen at your current position with continuously updating instructions to the stakeout point.





Stake Line/Arc (Station/Offset)

When Stake Station Interval is clicked on, then selecting OK on the Define Line, Define Alignments or Define Arc dialogs presents the Stake Line dialog for defining the stake location parameters (e.g. station, offset, interval and even elevation).

😂 Stake Arc			
Station/Offset	Point On A	rc	
Start Sta: 0+00	.000 End Sta:	48+35.727	
Station:)+00.000	اھ ک	Ξ
Interval:	25		
🔿 Left 🖲 Rig	ght	Off. Inc:	0
Offset 💌 🕻)		
Elevation: 1	LO	Override	e Design
Segment (H): C Cutsheet: None		(V): Grad	e

- Station: This is where you enter the station to stakeout.
- **Station** +: You can advance to the next station as defined by the alignment points or station interval using the right green arrow icon.
- Station -: You can go back to the previous station as defined by the alignment points or station interval using the left green arrow icon.
- **Station List**: Select a specific station using the station list icon.
- Interval: This is where you choose the distance by which to increment the stations.
- **Calculate Interval**: This is used to divide the entire line into equal parts, which results in a calculated, non-rounded, incremental station.
- Offset/Skew List: This is where you enter in the offset distance from the line. Select one of the left/right radio buttons to determine the offset side. This list also provides additional methods of offsetting, such as Skewed Offsets, Bisectors, Intersections and PI or Radius Points. A Skew Forward angle is measured forward from the perpendicular, and a Skew Back angle is measured back from the perpendicular. So looking forward down a tangent centerline, a pipe with a Skew of 70 degrees (in DD.MMSS) from the forward tangent would be a Forward Skew Angle of 20 degrees, as measured forward from the perpendicular (normal) offset.
- Elevation: This is the design elevation. If the defined geometry is 2D, then this option will be active.
- **Override Design**: This allows the user to override the design elevation of 3D geometry.
- **Off. Inc**: This is for entering an optional incremental offset along the line. This is a rarely used feature that would trend the offsets away or in to the centerline.
- Segment: This defines the current segment of the alignment based on the entered station.

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- **Cutsheet**: This shows the currently selected Alignment Cutsheet file.
- Settings: This icon takes you to the Job Settings that apply to alignment staking. See Job Settings (Stake) for more details. Note that this is where you instruct the software to include and stop at critical alignment locations.

Stake Line/Arc (Point On Line)

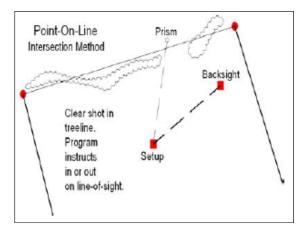
The Point On Line option appears when Define Line or Define Alignments is selected with Stake Station Interval clicked on. The options appear in the Stake Line (Interval) dialog. It offers a Perpendicular to Line method for total stations and GPS. This method projects any shot onto the alignment perpendicular or radial in curves and prompts for the distance and direction to move to the alignment intersect point. However, only if you select Define Line as the method to define the alignment and you are set to total stations, is there a "Find Intersect to Line" option, which enables "line-of-sight" staking of lines. This is often used by surveyors who are setting line in tree lines, moving to gaps in the trees for readings, then moving in-out along the line-of-sight and driving stakes when perfectly on line. It is useful for any line or boundary staking, such as property lines, rights-of-way and construction lines. For GPS, only the Perpendicular method is available.

Total Stations: The **Offset to Line** option is grayed out when the **Find Intersect to Line** method is selected and available only when the Perpendicular option is chosen.

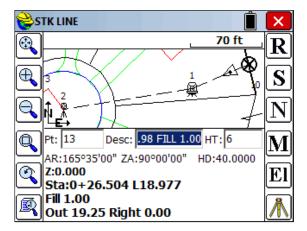
📚 Stake Line				\checkmark	×
Station/Offset	Point On Li	ne			
Find Ir	ntersect to Lin	e			
C Find P	erpendicular	to Lin	e		
Offset to L	ine:	0			



Total Stations, Define Line, Point On Line, Intersect to Line: The Intersect Method is used to set line by moving in or out at the current line of sight. A major application is setting line where the line is largely blocked by trees or obstructions, and you must set the line in gaps where you do have a line of sight.

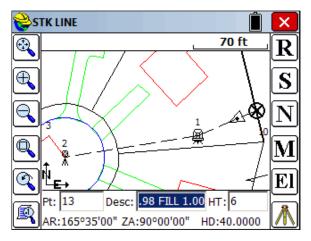


In the Intersect mode, the first screen always displays the target point on the line (or the extension of the line), perpendicular to the setup or station point. When the first reading is taken, the program will display the In-Out distance to the line along the line-of-sight. Regardless of the Reference Centerline settings, the instructions will be In-Out to the target line. However, if Reference Centerline is active, the station and offset to the reference centerline will be shown, with an "*" prefix.

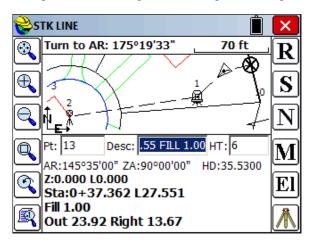




When staking a line defined by points with zero elevation, the cut or fill values will be displayed but should be ignored. Notice that the screen expands to show more graphics by pressing the down - arrow key.

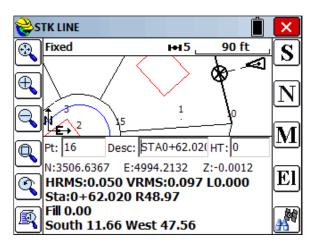


Total Stations/GPS, Perpendicular to Line: When configured for the Perpendicular to Line method, the program will show the direction and distance to move to find the nearest point on the line to the measured point. The instruction received (In/Out versus North/South or Azimuth/Distance) will depend on the setting within Configure Reading.



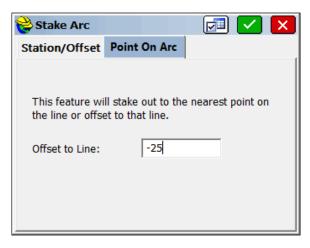
The "Turn to AR" advice at the top of the screen refers to the angle to turn to intersect the defined line at 90 degrees from the instrument location. For GPS, the Point-On-Line screen instructions are similar.





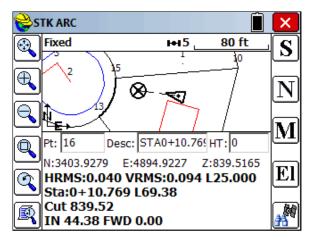
Stake Line/Arc (Point on Arc)

Both the Stake Arc (3 Points) and the Stake Arc (PC, PT, Value) routines have a Point On Arc option similar to the Point On Line option. This appears if Stake Station Interval is clicked on in the opening screen of staking options. In the dialog below, we have chosen to calculate a left 25 offset from the arc. Any measured point will then be translated radially onto the arc that is 25 units left of the specified arc.





When a measurement or GPS reading is taken, the target point will be radial to the curve, at 25 units offset from the curve, as shown below.



The above example might be useful for setting stakes at a 25' building setback from the right-ofway line. For GPS, information is provided "real-time". As you move, you see the instructions to contact the nearest point on the arc (or offset to the arc). For total stations, you are first instructed to measure to the nearest point on the arc (or arc offset) from the instrument setup. Then after you take any shot, the instruction refers to that measurement.

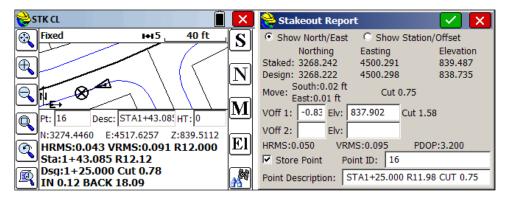
Note: The Turn to AR advice refers to the angle to turn to contact the centerline at 90 degrees (right angles) to the instrument setup.

After selecting **OK**, the main stakeout window appears in map view. In total station mode, it will be waiting for a shot or reading. You should see your points in the map with an icon showing the location of your target (the circle with the X inside).

Note: If the points defining the line are at zero elevation, the program will still report a cut and fill -- in this case a cut from the GPS elevation of 839.52 all the way to zero. If the points defining the line are at a known elevation, the elevation will be interpolated to determine the design and target elevation of the point to stake and will be applied to a zero offset or non-zero offset stakeout position.



All Stake Line/Arc Options: Store a reading and the coordinates for the Stake Point and the Target Point are displayed. Store by pressing Enter or S to Store. The delta North, East and the elevation difference (Cut/Fill) are also displayed. The Vert Offset 1 and Vert Offset 2 allow for elevation calculations based on the input vertical offset values. In English units, a vertical offset of -10" can be entered for example in that form, and the program will auto-calculate -0.833 as the offset. If Vertical Offsets are detected, and a point is stored, you are prompted for additional descriptions for the vertical offsets. If "Alignment Cutsheet" storage is on (as set in Job Settings, Stake tab), an additional cutsheet "row" will be created for each vertical offset. Shown below is a stakeout of station 125, Right 12, and the resulting Report screen.



Note that you have the option to store a point in stakeout. If the point being stored is the same as one in the current job file, the **Point Protect** dialog box appears stating that the point you chose has already been used. The next available point number is listed with the option to overwrite the current point or use the new number. If you "Show Station/Offset", you will see the Station and Offset of the design (1+25.000 R12.000) and staked point (1+25.000 R11.979), for example.

Cut and fill data, including vertical offsets, will be stored in the Alignment Cutsheet File if named and turned on within **Job Settings**, **Stake tab**, **Cutsheets**. Finally, the data is always stored to the raw (.rw5) file as cut/fill (cutsheet) information. If you forgot to create a cutsheet file, you can make a new one, and when formatting the cutsheet, select "Cutsheets from Raw" as one of the options. You can review the cutsheet using the Helmet, View Data option. You can also review the cutsheet with the shortcut, Alt V, from the active stakeout screen. Both will return you directly to stakeout. If using GPS, the HRMS, VRMS, and PDOP values are also displayed, as are Fields for Point ID and point description input. After the point has been stored, you are taken back to the Station/Offset dialog to select the next point for staking.

When you return to the Stakeout Line screen after storing a point, there is a tab option for **Next Alignment** that allows you to define a new alignment, without exiting the command.



6.12 Stake Offset



This command will stake out up to two user-defined horizontal offsets to a centerline at any station, as well as an unlimited number of offsets per station, if you are using a predefined Cutsheet Station and Offset List (loaded using the Settings button). It will also stake out the centerline itself. Station intervals can be entered, and the program will auto-detect, at the user's option, special stations such as the TS, SC, PC, PT, CS, ST and vertical curve points (including high and low points). Because individual stations and offsets can be entered, and also because pre-made station and offset lists can be recalled in the field, Offset Stakeout can be applied to virtually any offset point along a centerline.

Prerequisites and Procedures

Stake Offset requires both a horizontal and vertical alignment. If total stations are involved, **Stake Offset** passes through the normal backsight confirmation screens that Store Points and other forms of Stakeout require.

The Offset Stakeout command is a three-screen routine. The first screen identifies and loads in the alignment files. The second screen identifies the offset points to stake (slopes and distances) and the intervals or lists of stations/offsets to stake. The final screen goes to the standard graphics, shows the target points, and guides you to the destination, with N for Next continuing onto the next station in the interval or list.

Identifying the Alignments

The first screen has tabs for selecting both the horizontal and vertical alignments. See <u>Stake</u> <u>Line/Arc</u> for more detail.

😂 Stake Offset	🗾 🔽 🗾	📚 Stake Offset	🗾 🗾 🔽
Horizontal Vertical		Horizontal Vertical	
1 Centerline File		1 Profile File	
2 Select Polyline	4 Preview 5 Edit	2 Select Polyline	5 Preview 6 Edit
3 Define Point List	6 Save As	3 Define Point List	7 Save As
Centerline: C:\Carlson P Start Station: 0+00.00 Ending Station: 3+08.327 Cutsheet: None	00 ft	Profile: C:\Carlson Start Station: 0+00.00 Ending Station: 3+08.000	



🗾 Settings

Use this button in the upper part of the screen to select predefined station lists and critical stopping points along the alignments.

😂 Job S	ettings				X
Stake	Alignment	Road			
□ Increment from Starting Station □ Extend Alignments ☑ Stake Start and End Stations □ Stake CL Alignment Points □ Stake Profile Points					
Limit Sta. Range:					
0+00 I Use File:	e Station and C	3+08 Offset List		Select Fil Edit File	

Within this option, you can click the **Stake** tab and edit your default Stake Offset Descriptions shown below. See <u>Job Settings (Stake</u>) for more details.

😂 Job Settings 🛛 🔽 🗙	😂 Default Descriptions	🔽 🔽
Stake Alignment Road	Description Alias	
Limited to Instrument Precision Precision:	LCurb LCurb	
0.000 -	LEOP LEOP	
Store Data to Note File	CL CL	
Merge Ctrl File Pts for Stk Increment Pt ID:	REOP REOP RDitch RDitch	
Control Pts Have Priority • Up • Down	RCurb RCurb	
✓ Use <u>A</u> utomatic Desc Stake Offset Desc	Rearb Rearb	
Auto Descriptions Cutsheets	Alias: LCurb	Update Item



Entering the Offset Points as Slopes and Distances

The Offset Stakeout screen allows you to enter one or two offsets from the centerline. The first offset requires a percentage slope and a distance. The second offset is for a curb or ditch and is prompted in the form of "distance over" and "elevation change up or down".

Stake (Offset	📰 🗾 🔽 🧲
Station: Interval:	3+75.000	
Offset:	12 12	Set Stakeout Target >
X-Slope:		REOP
Height: Offset:	0.5	
	r	

- Settings: The Settings button returns to the Settings dialog, allowing you to load another cutsheet list or specify more or less special stations. Note that in Settings, if you called for a Station and Offset List, then most of the options in the Offset Stakeout dialog are fixed, and your only choice is to stake the particular offsets named in the list. Also, note that Offset Stakeout, when not using a List, allows for the staking of three points on the Left or Right Side: Center, Curb (or Ditch) and EOP. On the left, it becomes LEOP, LCurb or LDitch. On the right, it becomes REOP, RCurb or RDitch. You must enter data for the right as well as the left if you are staking both sides of a road. So, there are five points total that can be staked when you use the dialog entry, since the centerline is covered in both the Left and Right scenarios.
- Back: The Back button returns to the first screen.
- Station: This is where you enter the station you wish to stakeout.
- **Station** +: You can advance to the next station as defined by the alignment points or station interval using the right green arrow icons.
- **Station** -: You can go back to the previous station as defined by the alignment points or station interval using the left green arrow icon.



Station List: Select a specific station using the station list icon.

Station	List			÷
Station	Description	 		
	Description			
1+50.000				
1+75.000				
2+00.000				
2+25.000				
2+50.000				
2+75.000				
3+00.000				
3+08.000	PRO End			
3+08.327	Road End			_
				•
		[Select	
			001000	_

- Interval: This is where you enter the distance by which the stations should be incremented.
- **Calculate Interval**: This is used to divide the entire line into equal parts, which results in a calculated, non-rounded, incremental station.
- Next Offset: The green arrow found to the right of the offset entry box will switch from RCurb to REOP to CL and back, and the large solid circle will move and highlight the correct location. These abbreviations are defined in the Settings dialog or the Stakeout tab of Job Settings.
- Left/Right: You can specify whether to stake the left or right side of the road. The offsets are applied symmetrically. If you have a special case on a specific side of the road, do the right and left separately, with separate slope and distance entries.
- **Offset**: This is the first offset from centerline. Units are as configured in **Job Settings** (feet or meters).
- X-Slope: This is the first offset slope. Negative represents downhill.
- Stake Curb/Ditch: This will allow the user to input and activate a second offset defined by offset distance and height from the first offset.
- Stake Curb/Ditch (Height): This is the vertical difference from the first offset to the second offset. A positive entry is interpreted as a curb and a negative (downhill) entry is interpreted as a ditch.
- Stake Curb/Ditch (Offset): This is the distance from the first offset to the second (outer) offset.

When using a Cutsheet Station and Offset list, you must select the **List** button, highlight the offset you wish to use and press **Select**. The routine will stay on this offset as it progresses through the stations until the user selects List again and specifies a new offset.



The Stake Offset command will store to the Alignment Stakes cutsheet file format if the file is named and made active for storing. The data can include station and offsets as formatted.

😤 Edit CutSheet File SubdivPt.txt 🥂 🧲				
DesignPt	DesignEL	StakeEL	Cut	
2	843.31	846.39	3.08	
2 -0.83	842.48	846.39	3.91	
13	842.47	846.39	3.92	
13 -0.83	841.64	846.39	4.75	
15	842.43	846.39	3.96	
15 -0.83	841.60	846.39	4.79	
Insert	Up Down	Special	▶ Delete	



6.13 Elevation Difference



This routine will report a cut/fill in comparison to a design surface at any location within a project. The **Elevation Difference** command will save cutsheet data if cutsheet files are named and made active within **Job Settings**, **Stake** tab. For any surface where a centerline is defined (Road Design and Section, or Grid/Triangulation/Elevation with centerline defined), the routine will not only report, but optionally store cuts, fills and centerline position data into an alignment-style cutsheet file. With no centerline defined, the Road, Grid and Elevation methods will store cut and fill data into a point-style cutsheet file. Elevation Difference can also be used with a light bar.

Prerequisites and Procedures

There are five types of data that can be used to define the design surface.

- Grid File: You may use a .GRD file that has been created using software packages including Carlson Civil or Carlson Survey. You must transfer this file to the collector via the File Transfer routine prior to running this command.
- Triangulation File: You may use a .TIN file created within SurvCE using the Triangulate & Contour command found in the Map screen under Tools, Surface. You can also use a .TIN or .FLT file that has been created in Carlson Civil or Carlson Survey office products, in which case you must transfer this file to the collector via the File Transfer routine prior to running this command. Note that triangulation files can be imported from LandXML or DXF format using the command File, DTM Import, found in the Map screen.
- Elevation: You may use known elevation that you specify in the Set Elevation field.
- **Road Design**: This method requires a Template, Centerline and Profile file at a minimum, and can utilize superelevation and template transition files.
- Section: This method requires a Cross-section file and a Centerline file.
- Select Type of Surface Model: Specify the type of surface to be used. With the exception of the Elevation method, the 4 other methods allow the option to specify a vertical offset (such as to subgrade) and lead to a follow-up file selection dialog.
- Set Elevation: This option is available when the Elevation method is used for defining the surface model. Enter the desired elevation of your surface in this field.



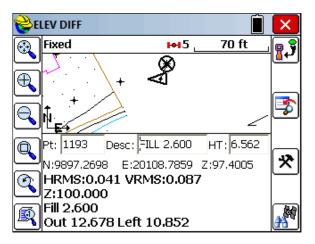
😽 Elev Difference 🛛 🗸 🗸	×
Select Type of Surface Model Grid Road Design Triangulation Section Elevation From Alignments Set Elevation: \$\phi00.000\$ ft	
VOff: 0.000 ft Use Horizontal Alignment for Sta-Off report Stakeout Pattern	
Light Bar Settings	

- Vertical Offset: This is used in conjunction with grid, triangulation, roading and section files. It allows the user to vertically offset the surface (as defined in the file) by the amount specified in the box.
- Use Horizontal Alignment for Station-Offset: This allows the user to specify a horizontal alignment file (.cl file) for reporting station and offset of your current location to the reference alignment. With total stations this is reported whenever a shot is taken. Using GPS or robotic total stations, with tracking on, your current position is updated in real time as the rover or prism is moved. This option is available with Grid, Triangulation and Elevation types of surface models. (A centerline is required for Road Design and Section-type surfaces).
- Stakeout Grid Pattern (GPS Only): The first prompt asks if you want to use the last stakeout pattern. To make a new pattern, you specify, in effect, the lower left corner ("left side" option) or the lower right corner ("right side" option) of a rectangle, and specify the starting point, direction point. Shown in the figure below is a 10x10 layout at 50' interval (10 rows and columns are added to the starting point, producing 11x11 grid points). The number of cells in the grid ranges from 1x1 to 20x20 and are laid out in a grid beginning at the starting point going towards the direction point.

😝 Pattern Set	tings		X
Starting Pt ID:	9	Ξ.	
Northing:	3325.6498	Easting:	50222590.0
Direction Pt ID:	16	Ξ 🗹	
Northing:	3377.5716	Easting:	5085.9521
Grid Interval: 50.000	Number of C 10 x 10		Alignment: Left Side Right side



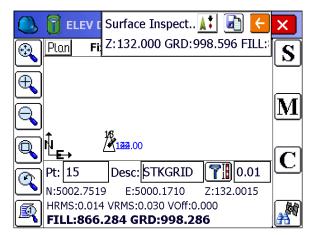
The program will then show the grid point nearest to your GPS position.



Surface Inspector

This allows the user to inspect a file loaded by clicking on a point on the screen or using snaps. When an object is selected, the Surface Inspector appears in the upper portion of the screen. The Surface Inspector will show for the specified point, the elevation of the file, point elevation and cut or fill values. The software has an option "Recall Job DTM Files" and allows the users to select the last TIN and/or Alignment (if checked), speeding up the process.

Stakeout and Store routines can be initiated from the Surface Inspector Screen.



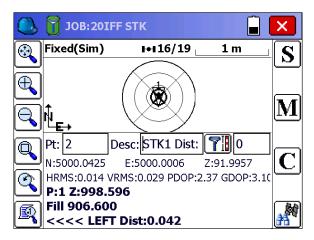
- The data at the top refers to the selected point information.
- The data on the bottom continues to represent the live updating current instrument position.



Stake using the Surface Inspector

To initiate the Stake Command using the Surface Inspector, click on the Stake Icon **I**. This will present the user with the Elev Diff STK screen.

The bullseye will appear when the position becomes closer to the preferred stake out point.



The Stakeout Report will be presented to the user after the point is stored.

Stakeout Report			
Northing Easting Staked: 4999.861 5000.001 Design: 5000.000 5000.000	Elevation 91.997 998.596		
RIGHT >>>> Move: Dist:0.139 m Fill 906.599			
VOff 1: Elev: VOff 2: Elev:			
HRMS:0.011VRMS:0.028PI✓Store PointPoint ID:2	DOP:2.371		
Point Description: STK1 Dist: 0.139	FILL 906 ÊΞ		

Repeat the process for another point to stake if preferred.



Store Points using the Surface Inspector

To initiate the Store Command using the Surface Inspector, click on the Store Icon . This will present the user with the Store Inspected Point screen.

Store	ted Point 🗹 🗙
Point ID:	2
	STKFILL FILL 90
Description.	

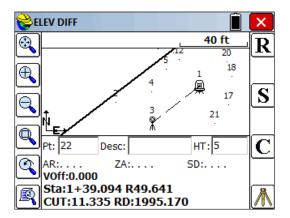
To stop, press the M or modify Icon. Press the orange arrow to exit.

• Light Bar Settings: This button allows you to specify parameters for enabling the light bar, setting the grading tolerance, and specifying the COM port. The two light bars currently supported are Mikrofyn and Apache. SurvCE can actually drive the grading process, as shown below, where an Apache light bar is used on a motor grader. In effect, this offers extremely low cost "grade indicate" machine control.





Pressing **OK** from the main **Elevation Difference** dialog will first prompt the user to load the surface files involved (unless elevation method was selected). Then, when **OK** is pressed again, the ELEV DIFF screen in the following figure will appear. This screen provides the user with a plan view of the project. When a shot is taken, cut or fill from the current vertical location to the design surface is reported in the lower left portion of the screen. The computed design surface elevation for your current location is also reported.



When Road Design Files are selected, there is an extra Settings option at the top of the screen that is used for setting the location of the Profile position on the template.

😂 Design Files 🛛 📰 🗾 🔽 🗙	误 Settings	🔍 Or 🔍 of 🔽 🔀
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327 Profile C:\Carlson Projects\Data\DEMO.pro Profile: 0+00.000 to 3+08.000 Template C:\Carlson Projects\Data\DEMO.tpl Optional Files Superelevation Superelevation None Tpl Grade Table None Load Roading Files Save Roading Files	Apply Profile at Fix Offset Template ID Reference Alignme Vert Off of Profile:	C Left Right

In road design, the position of the profile is sometimes placed on an inside edge-of-pavement or at some other offset from centerline, as defined by a fixed offset, a template ID or even a completely distinct reference horizontal alignment. Even when specified, the application of the special profile can be turned off and on. Note that the "Off" status is equivalent to the default condition of profile grade at Template ID "Center". If the Profile positioning is set to "On" in Settings, you will always be prompted with the Settings dialog after loading the Roading files, so that you are reminded of any unusual, active profile offset before continuing by pressing Enter (OK) or changing a setting.

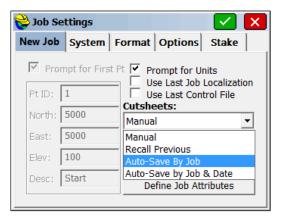
If you click the helmet icon in the upper left of the screen and select **View Data** from the Help options, or enter Alt V, you can select **Cutsheets** and the **Edit File** option to review the stored cut



and fill data at any time, assuming a "cutsheet" file has been named and set active. The data might appear as follows:

误 Edit CutShe				
Staked Sta	Staked Off	Stake Elev	Cut	
1+39.09	Right 49.64	2006.51	11.34	
1+43.25	Left 23.06	2005.87	10.45	
1+29.37	Right 11.39	2007.84	13.26	
1+29.73	Right 1.06	2006.55	11.83	
Insert Up Down Delete Special				

The order of the columns in the cutsheet is set by the user when the cutsheet file is named. In this case, the "Use Centerline for Station-Offset" was clicked on, and the shots were stored to the "alignment-based" cutsheet because a centerline was active. All shots were cut, so if you scrolled right to the fill column, it would be blank. Columns can be extended and compressed by moving the vertical bar between columns. In addition, cut and fill data is also stored to the Raw File associated with the job name. Then when a new cutsheet file is named, you can choose, "Cutsheets from Raw File". For those users who always want a cutsheet file to be made in commands such as Elevation Difference, you can auto-create a new cutsheet with the job name as the prefix, whenever you start a new job, by the following selection within **Job Settings**, **New Job** tab:



6.14 Grid / Face





This command enables points on both vertical and non-vertical planes to be coordinated by angleonly observations. This feature is most often used to pick up details of a building where the prism cannot be placed. You first establish the plane, then take angle-only observations for features such as windows.

The building face is defined by observing three accessible points on the building or by entering their known coordinates. After angle-only observations are made, SurvCE then calculates and stores coordinates of the angle intersection observation with the plane. You can use SurvCE to survey the vertical face of buildings or other vertical planes.

Vertical Plane Survey

The Define Plane dialog can be accessed by selecting the Grid/Face option from the SURVEY tab of the main menu.

😂 Define Plane	
Define Plane:No Solution!Point 1: $\frac{1}{2}$ $\boxed{2}$ Point 2: $\frac{1}{2}$ $\boxed{2}$	Read Read
Point 3: Sideshots: Only Angles and Store B Angles+Distances and store C	Read A C

- **Point 1, Point 2, Point 3**: These fields indicate the points that define the building face plane. Both Point 1 and Point 2 must have horizontal coordinates to properly define the building face. For a vertical plane survey, point 3 is not required and can be left blank.
- **Read** :: These three functions allow for three methods to define the coordinates of a point. The coordinates of the points can be manually entered into the Northing, Easting and Elevation fields. Manually entered coordinates will not be stored in the coordinate file.

Existing point IDs can be entered into the Point ID field. These points must be defined by coordinate data. As soon as you enter the point ID, press **enter** and the coordinates will appear in the Northing, Easting, and Elevation fields. Existing points can be selected from a points list by selecting the **Point List** icon. Highlight the desired point and press enter or tap **OK**.



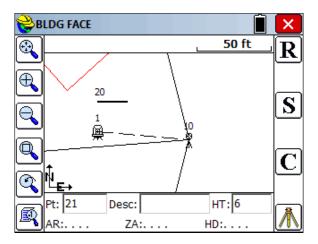
Existing points can be selected from the map screen by selecting the **map** icon. To select a point, tap it on the screen. If two or more points are close together on the screen, you will be asked to select the intended point from the point list.

Lastly, the points can be taken with the total station by pressing Read.

After you have specified the two defining points for the building face plane, SurvCE will determine the available solution. One of the following messages will be displayed in the dialog box.

- **Vertical** SurvCE has enough data to fix a vertical plane (the vertical example is shown in this above figure).
- **3D** SurvCE has enough information to fix an arbitrary plane.

Press **OK**, and the following dialog will appear. The building face or vertical plane is drawn as a solid line, and any measurement taken by angle only reading (e.g. angle right of 270, zenith angle of 83 degrees), will plot as a point with calculated x,y,z position, such as point 20.



Non-Vertical Plane Survey

Surveying a non-vertical plane is similar to surveying a vertical plane. Once the plane has been defined, picking up detailed observations follows the same general process detailed above. All three points must be defined for a non-vertical plane survey. When defining a non-vertical plane, the three points cannot be in a line.

6.15 Resection



This command allows you to calculate coordinates of an unknown instrument setup point given the angles and distances from up to 20 distinct reference points. The reference points are recalled from your working job file. If a control file is active in **Job Settings**, and the entered point ID is

Page | 343



not found in the current working coordinate file, then the point will be recalled from the control file automatically. You can also access points from the control file by using the **from list** icon.

Direct and Reverse measurements can be activated within the **Configure** screen in Resection. The options within Configure expand (e.g. for "Auto Turn" capability) if you are using motorized or robotic total stations versus conventional total stations. If you choose **Direct & Reverse**, then the reverse measurements count as part of the 20 allowable measurements, so the maximum number of reference points becomes 10. As long as you have at least 2 distinct points, you can shoot the same point twice or more with a direct or D&R measurement.

裬 Config	ure				Х
General	View	Sets	Settings	Search	
Trave Resect Topog Stake Set Coll	ew Readin	D&R) I D&R) ad D&R) D&R) tine Optior Igs I I	IS Review Sets cate Points Vo. of Si		
	, .			,	

Elevations can be ignored on any measurement. Angle Only Readings can be mixed in as well. This is useful when sighting radio towers and church steeples with known coordinates. In fact, all of your resection points can be measured by angle only, in which case 3 or more points are necessary for an accurate calculation. Sometimes if the 3 angle-only points are in the same quadrant of view, a solution won't be found, requiring additional points. When elevations are used, measurements will contribute to the calculation of the setup point elevation.



After entering the routine, the first screen appears as follows:

Resection [0]	×
Press Enter or Read to take R	eading #1
Point ID: 2	Read
Desc:	Calculate
N: 13804797.8389	Ignore Elev
E: 1064291.8664 Z: 328.0837	Angle Only
Status: Standby Horizontal: 0°00'00" Zenith: 90°00'00"	Settings Configure
Inst Hgt: 5.3 ft	Configure

The points can also be selected from the point list or directly from the map screen by pressing either the list or map icons. You will also be prompted for the Instrument Height and a Target Height. On reading #1, you will be asked if you want to Set Zero on the first resection point (optional). The user will be shown the status of "Setting to Zero" if selected. If you don't Set Zero, the current azimuth of the instrument will be used. If you click on "Set Azi" then you will not be prompted to Set Zero and when the resection is complete, the known resection points will be used to set the correct azimuth in the instrument. The Robotics and "Status: Locked" displays only appear with motorized and robotic total stations. Reflectorless measurements can be taken in Resection by clicking Prism ICON, which switches back and forth from prism to reflectorless. The software supports continuous reflectorless measurements for all capable total stations.





If you press **Configure**, you can set standard errors for the measurements, as shown below. These settings allow you to take advantage of network least squares and weighting in the calculation performed by SurvCE. The default values are shown. You can also enable **Direct & Reverse** measurements here, in addition to using **EQUIP**, **Configure**.

Configure	Resectio	on				
Distance Stan Constant: PPM:	dard Error 0.005 5	s	m	Angle Standar Pointing: Reading:	d Errors 5	s
Setup Standar Resect Pt ID: Foresight Pt	rd Errors	0.005 0.005	m	Set to Zero Set to BS Azir Set to: Use Current Set to Zero		-
			Defa	ults		

Press **Read** when you are ready to take a measurement. The angle right, zenith angle, and slope distance are recorded.

Repeat this process for all measurements of the resection. After the second measurement, there is enough information to conduct the resection calculation, so the **Calculate** button at the top of the dialog becomes active and can be selected. If you select Calculate, you can review the data, then return to taking more shots by hitting back arrow rather than OK, which would prompt to store the point. After selecting Calculate, if you intend to measure to additional resection points, you have the option with robotic and motorized total stations to automatically turn to those points, as shown below:

😂 Resection	🔘 🔀
Press Enter or R	ead to take
Point ID: 9	Calculate
Desc: EP	Configure
N: 3325.6498	Ignore Elev
E: 50222590.0000 Z: 838.9950	Angle Only
	Set Azi
Status: Locked	Robotics (Alt+J)
	Read
Inst Hgt: 5.3 ft	T ft



If you select Turn To Point, you go to the standard Turn to Point dialog that is used in Stakeout, and you can Search after the Turn and Turn to Vertical (recommended) to be directly on the desired target point. Be sure to set the correct target height for the additional resection points.

Using the Robotics option, you can go to Settings and change the prism constant for distinct measurements. With non-robotic total stations, the Robotics button changes directly to a Settings button, allowing changes as shown below. The prism constant in the FS setting is what is used for all Resection measurements.

裬 Instrument Setup	🌆 💽 🛃
Current Comms Sett	ings Search
EDM Mode	Standard 💌
FS Target	Leica 360 🛛 🛨 🛠
BS Target	Leica 360 🔹 🛠
Guidelights	Off 🔹
Guidelights Intensity	Medium 🔻
Laser Pointer	Off 🔹
Compensator	Enable 💌

Any time Calculate is selected, the Review Resection screen appears. The input data is displayed in a list structure, and you have the ability to turn certain measurements on/off and recalculate the solution, without the necessity of re-measurement. You can also edit point numbers, instrument and rod heights, and more here. When satisfied with your edits and the solution, you can store the results of the resection.

Since there is redundant data, the final calculated coordinate differs slightly from the individual measurements. The command reports the calculated coordinate's northing, easting, and elevation, and the difference between the calculated coordinate and the individual solutions as residuals, which indicate the quality of the data. High residuals suggest a problem with the input data. If you select the red X in the Review Resection Screen, you are returned to the Read screen in case you want to collect more shots. Here in the Read screen you can truly Cancel if that is your intention. Shown here is a resection to 2 points using D&R (direct and reverse), with angle only in the reverse face. Note that even in a 2-point resection, a closure calculation is presented. During a 2-point resection, the user has the option to hold the first located point and the azimuth between the two located points by checking the 'Rotate-Only' checkbox. If the 'Rotate-Only' checkbox is unchecked, both located points will be held (normal resection).



Review Resection	 		
Pt ID XY On Z On H Ang A	Ang Residual 🔺		
106 ON ON 0°00'11"			
105 ON ON 313°02'01" 0°00'	'08'' •		
Inst. Hgt: 5.3	Edit ON/OFF		
Results:	Rotate Only		
N:1266417.0007 StDev N:0.00	012		
E: 2065201.9556 StDev E: 0.0005			
Z: 5505.05 Z RMS: 0.000	D		
Closure: 33208			
Dist RMS: 0.001 Ang RMS:(s):	:8"		

In the "Store this Point?" dialog box shown below, you are prompted for the point number and description of the calculated point (the occupied station/setup point). With three or more resection points, residuals are presented showing the accuracy of the calculation. When you press **OK** from the "Store this Point?" dialog, you will be setup on the calculated point backsighting the first point measured in the resection.

Store this Point?	🔽 🔽
North: 1266417.007 East: 2065201.9556 Elev: 5505.05	Ang RMS(s): 8" Dist RMS: 0.0013 Elev RMS: 0.000 StdDev N: 0.0012 StdDev E: 0.0005 Closure: 33208
Point ID: 5	
Description: se	tupÊΞ



A minimum of 3 angle-only measurements can also lead to an accurate calculation of the resection point, as shown below:

6	🗟 Review Resection 🛛 🗸 🧹							
	Pt ID	XY On	Z On	H Ang	S Dist	Dist		
	7	ON	ON	0 00'02"	0.0000	0.00		
	6	ON	ON	185°38'20"	0.0000	0.00		
	5	ON	ON	160°18'43"	0.0000	0.00		
	•					•		
h	nst. Hg	gt: 5.3			Edit O	N/OFF		
	-Resul	ts						
	N: 499	9.9943		StDev	N: 0.000			
	E: 500	0.0025		StDev	/ E: 0.000			
	Z: 99.9	9993		ZRMS	5: 0.0024			
	Dist RI	MS: 0.0	00	Ang F	RMS (sec):	0		

Select the Angle Only toggle before taking an angle only measurement with no distance. If the angle only measurements are accurate in the zenith angle to a specific location, an accurate elevation can also be calculated from as few as 3 angle-only measurements with no distances. Within Angle Only mode, you do not need to change to reflectorless mode, since by definition no distance will be measured. You can stay in prism mode. If measurements are taken to steeples and radio towers and only x,y position is known or the precise elevation point to sight is not known, then only the x,y position of the occupied point will be determined accurately, and high Z RMS values will result.

During a Two-Point resection, the user will have the option to hold the first located point and the azimuth between the two located points by checking the 'Angle Only' checkbox – If the 'Angle Only' checkbox is unchecked, both located points will be held (normal resection).



6.16 Set Collection



The Set Collection routine allows you to collect and average sets of angles to multiple foresights.

Setup

The opening dialog is the standard setup dialog shown below that allows the user to specify the instrument and backsight information.

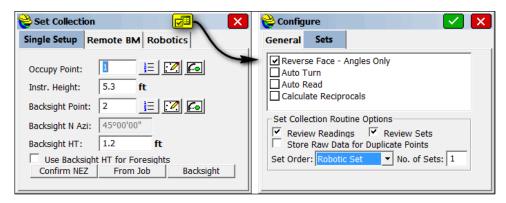
😂 Set Collection	ı		×
Single Setup R	emote Be	enchmark	
Occupy Point:	1 5.3	<u>}</u> ≡	
Instr. Height: Backsight Point:	2		
Backsight N Azi:	45°00'00		
Backsight HT: Use Backsig Confirm NEZ			ıt

• **Configure**: This button displays the dialog shown below and allows you to specify options available for the way the angle sets are to be collected.

😂 Configure 🔽 🔀	💝 Configure 🔽 🔀
General Sets	General Sets
Store Fixed Only (GPS) Prompt for Total Station Setup Prompt for Height & Description Prompt for Point Notes	Calculate Reciprocals
No. of Readings to Avg - TS: 1 GPS: 1 Enter/Store Icon - TS: Read & Store -	Set Collection Routine Options Review Readings Review Sets Store Raw Data for Duplicate Points Set Order: BD-FD/FR-BR No. of Sets: 1



For robotic total stations, the **Robotic Set** option is available.



Number of Sets: This input box allows you to define the number of angle sets that are to be collected to each point. An angle set is defined as a direct and reverse reading to the backsight and the foresight (i.e. BD-FD/FR-BR). If multiple foresights are defined, only a single backsight-direct and backsight-reverse set of readings will be collected for all foresight points.

Num of Readings to Avg (TS and GPS): This input box allows you to specify the number of distance measurements that are to be taken during each sighting.

Set Order: This drop list allows you to specify the order the angles are to be completed. The definition for the abbreviations are:

- Backsight Direct (BD)
- Backsight Reverse (BR)
- Foresight Direct (FD)
- Foresight Reverse (FR)
- Since the backsight dialog is the first reading in all cases, only the following options are available:
- **Robotic Set**: Only available for motorized, auto targeting instruments. This option will turn all reverse sightings without any assistance from the user. The order will be the same as BD-FD/FR-BR.
 - BD-FD/FR-BR
 - BD-BR/FD-FR
 - BD-FD/BR-FR
 - BD-BR/FR-FD

Reverse Face – Angles Only: This toggle is intended for use with non-coaxial instruments. Only direct face readings will be measured, and all reverse face readings will be for angles only. **Auto-Turn**: This toggle will allow the motorized instrument to automatically advance to the next position if it was previously measured. The software will pause at the next location and wait for the user to initiate the reading.

Review Readings: This toggle will pause the software after every reading and display the measured data.

Review Sets: This toggle will pause the software after the completed set for review.

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- **Confirm NEZ**: This button allows you to quickly verify the instrument and backsight coordinate values.
- **Backsight**: This button is required to initiate the first reading and backsight orientation for the set collection process. The following dialog will be displayed. The user must measure either an angle only or an angle and distance to the backsight in order to proceed with the OK button. The Set Angle selection will prompt a warning "For use with a backsight prism use Set Angle and Read". It is recommended that the Set Angle or Set Angle and Read buttons be used to record the initial backsight reading.

Backsigh	t			∕ ←	Þ
Set to Zero)	▼ 0°00'0	0"	Turn to E	s
Setup	Results				
OC Point: BS AZI: Inst Hgt:	1 45°00 5.3001	'00" BS E	-	2 N45°00'00 1.200ft)"E
Set Ang	le	Check Ang	gle	Check	
	Se	t Angle and	Read		



Define Foresight Points

After the Backsight dialog is accepted, the next step in the process is to enter in the point IDs for all of the foresight points that you intend to sight. The dialog shown below is intended to receive predefined point IDs. To enter points, begin in the top left input box and work your way down to the bottom of the left column, then start at the top of the right column and work down to the end.

😂 Foresight Point(s)			\sim	X
Enter new point ID's or so list:	elect point	s from ma	ap or	
1196	Ξ	. 🖊		
Pt ID Job Used				
Add Pts Delete				

Take Readings

Once the foresight points have been specified, the next dialog will be determined by the set order. If the next reading was to be FD, since the BD was already recorded, then the dialog will prompt as shown below. Pay attention to the prompts in these dialogs as they inform you as to which point and which face is expected based on your configured set order. Press the Enter button or select the OK button to record the reading.

😂 Set Collec	tion		X			
Station: 1	Backsight	t: 2				
Turn to Foresight, Direct Set #1						
Press En	ter to Read P	oint 13				
Target Ht:	2	ft				

Reading Review

Unless robotic sets are involved, after each measurement an optional Reading Review dialog appears where the measurement can be accepted or rejected. This option is set in Configure.

裬 Reading Review	
Point: 13	H.Obs: 320°07'21"
TargetHgt: 7.000 S.Dist: 55.000	V.Obs: 75°13'00"
Ac	cept Data?
Yes	No



The sequence of shots continues.





Completed Set

At the end of the set collection process the Set Report dialog will be presented. If you had specified 2 points (or more) in the initial "Set Collection Point Order" screen, you would obtain a tabbed dialog of all the points to review.

Set Re	-	12				
OP: 1 BS: 2 FS: 13						
		H.Ang.	V.Ang.	S.Dist.		
F1 FS		320°07'21"	75°13'00"	55.0000		
BS		0°00'00"	90°00'00"	120.000		
F2 FS		327°15'55"	268°01'00"	55.0000		
BS		339°50'12"	270°01'40"	60.0000		
4				i Fi		

After all of the **Reciprocal Calculation** and **Store Point** dialogs have been accepted, the dialog below will be presented.

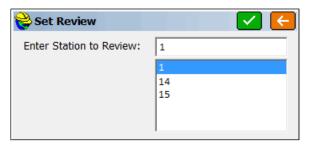
💝 Set Col	lection	
STN: 1		
Number o	of Sets: 1	
	Change Station	
	Collect More Sets	
	Review Direct-Reverse Report	

Change Station: This button will take you to the Instrument Setup dialog and advance the point numbers so that the original occupied point is the backsight and the last foresight point is now the occupied point.

Collect More Sets: This button will take you to the Backsight dialog and maintain all of the previous setup information.

Review Direct-Reverse Report: This button will allow you to select the occupied point ID from a list of points that were used with set collection. The software will then generate a report of all of the sets measured from the specified occupation point.





In the figure above, select a point number and tap OK to view the report. The report is shown below.

Mea	ins				
Hora	zAngle	SD	Distance	SD	Vertical 9
239	°25'43"	85°39	'11" 27.500	0 27.50	00 86°48'
Ohe	ervation				
ODS	creation	15			
		-	HorzAngle	Distance	e Vertical
		-	HorzAngle 0°00'00"	Distance 120.000	e Vertical 90°00'00
Тур	e Setup	FSight			
Typ BD	e Setup 1	FSight 2	0°00'00"	120.000	90°00'00



6.17 Leveling



This routine allows you to run trigonometric level loops using a total station or digital level loops using a digital level. There are also manual entry modes available for both types of level loops. The raw data collected for a total station is slope distance, zenith angle and prism height. For digital levels, the vertical difference and if available, the horizontal distance is stored in the raw data file.

The calculation routines assume there is only one loop per level file. A benchmark is required at the beginning of the loop (BM+) and a benchmark is required at the end of the loop (BM-). After the BM+, measurements back to a known elevation (TP-) and measurements forward to establish an elevation (TP+) are alternated. Any number of side shots to points (SS-) or stations (STA-) is allowed while traversing. Spurs (series of TP+ and TP- measurements off the main loop) are allowed and will be adjusted correctly. A spur after the BM- is allowed.

The opening dialog is where you set up the level loop. If road files are used, an additional tab in the leveling measurement screen will be made available for entering station and offset data. To use a digital level instead of the current total station, click the Select button to the right of the Instrument and choose from the available options, which include Manual 3-Wire, Manual 1-Wire, Manual Digital Level and Sokkia SDL. Manual Total Station entry can also be done by choosing **Manual Total Station** on the **EQUIP** tab.

😂 Leveling		X
Instrument: Level File: C: Project: Operator: Loop:	Current Total Station \CarData\Level File Dem	Select o.tlv Select
Date:	Temp:	
Time:	Press:	
🔽 Use Road	Files	Select Road
	C:\Carlson Projects\Data\I C:\Carlson Projects\Data\I	

Use the **Select Road** button to choose the horizontal and vertical alignments you wish to associate. Click the **Use Road Files** toggle to enable the use of the selected files. If Use Road Files is turned off, the STA+ tab will not be shown.

After the loop has been opened or created, select the Green Check button (OK) to advance to the measuring screens. The first reading of the loop must be a benchmark (plus) reading to establish



the instrument height. Enter the point ID or known benchmark elevation, the prism height (trig levels), and a description. Then press the **Read** icon or **Enter** to measure. Once the reading has been taken, select the **Store** icon to keep it. You can take as many readings on a single point in any face that you like. You can also review the readings and disable any prior to storing.

📚 Leveling 🛛 🔂 💽	😂 Leveling 🛛 📴 🌗 🧲
BM +	BM +
Pt ID: 2	Pt ID: 2
HT: 5 BM Elev: 100	HT: 5 BM Elev: 101.97
Desc: Bench	Desc: CP/CHIS X
VDiff: 5.00 HD: 200.000	SD: 7.685 ZA:269°09'31" VDiff: -0.113
Elev: 105.00 Reading Count: 1	Avg Elev: 107.139 Elev Spread: 0.112
Reading Count: 1	Reading Count: 2
Review Readings Robotics	Review Readings

Figure 9: Trig Leveling (Left) / Conventional Leveling (Right)

Some of the fields below only apply to one of the Leveling types. See screen shots above to see which apply.

- Pt ID: Use this field to retrieve the elevation from an existing point in the coordinate file.
- **HT**: Use this to enter the prism height. If using a digital level, this field will be gray, and will be populated with the rod reading from the level.
- **BM Elev**: Enter a known elevation for the benchmark. This field will auto-populate if a point ID is selected.
- **Desc**: Enter the point description.
- Review Readings: This allows you to enable or disable specific readings prior to storing.
- **Robotics**: Use this to control the robot.
- Read: Use this icon to take a reading.
- **Store**: Use this icon to store the reading.



Configure: Use this icon to setup direct and reverse settings and review options.

😂 Configure	Leveling	🔽 🔀				
_	Avg Direct & Reverse: 🗹 BM & TF 🗌 SS 🔲 STA- 🗹 Review before storing					
		Store then Read				
Function of B	Enter Key:	Read then Store				
		Read or Store				
Station Inter	val:	50				
Centerline:	C:\Carlson	Projects\Data\DEMO.cl				
Profile:	C:\Carlson	n Projects\Data\DEMO.pro				
Select Road 📃 Use road files						

- Avg Direct & Reverse: This option will allow you to determine which readings take direct and reverse pairs. (only applies to Trig Leveling)
- **Review before storing**: This toggle forces the **Review Readings** dialog prior to storing. This is the same dialog that comes up when the **Review Reading** button is pressed except the Review Reading dialog has a Store Point button that stores the shown measurements

💝 Store	Level Data		🔽 🗲	Store	Level Data		🔽 🛃	
							1	1
Status	Z Ang	S Dist	Elev	Status	VDIST	HDIST	Elev	
ON	91°50'29"	7.685	107.217	ON	91°50'29"	7.685	107.217	
Results Avg Ele Vert Sp	eading	Min	HT: 5 F Error: Elev: 107.27 c Elev: 107.27		/: 105.000 read: 0.000	Min	F Error: Elev: 105.000 K Elev: 105.000	

Figure 10: Trig Leveling (Left) / Conventional Leveling (Right)

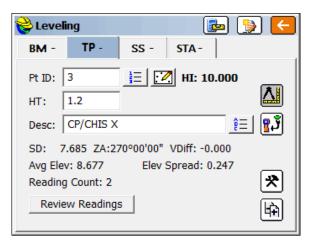


The **Status** field shows if the measurement is turned on or off. Measurements that are off will not be used in any calculations. Elev shows the calculated elevation which will be the elevation at the total station or level on a plus shot (BM+ or TP+) or the elevation at the rod on a minus shot (BM-, TP-, SS- or STA-).

Any measurement can be highlighted by clicking on the measurement. A measurement must be selected before using **Edit Reading** or the **ON/OFF** button.

All the values in the Results section are about the elevation calculations. The **Sel Error** field shows how different the calculated elevation of the currently selected measurement is from the mean of all the measurements that are on.

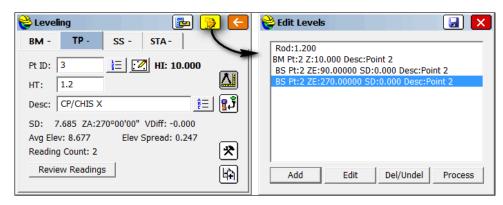
Once a benchmark (plus) reading has been taken and stored, the **Minus Reading** dialog will be shown. This dialog allows you to read the minus reading to a turning point (TP), benchmark (BM), sideshot (SS), or a sideshot on an alignment (STA). Turning points advance the setup while sideshots do not. A reading to the benchmark in the minus screen will end the loop.



Level Reading Mode: This icon switches the interface between taking plus or minus readings.



At any time during the loop, you can edit a reading using the **Edit Levels** icon to the left of the red X (Cancel) button.



Once the minus reading on a benchmark has been recorded, you can then process the loop using the Process icon which is to the left of the Edit Levels icon. Once you've processed the loop, a Review File dialog will be displayed. At this point you can choose to save the report or proceed to the Processing Options screen.

📚 Leveling 🛛 📴 🚯 🧲	≷ Review File 🔽 🛃 🧲
BM - TP - SS - STA-	Processed 02/10/2017 14:28:50
Pt ID: 3 j≡ ☑ HI: 10.000 HT: 1.2 ▲ Desc: CP/CHIS X j≡ j≡ SD: 7.685 ZA:270°00'00" VDiff: -0.000	Length(-): 0.000 Length(+): 0.000 Loop Length: 0.000 Closure: No Ending Benchmark Error:No Ending Benchmark
Avg Elev: 8.677 Elev Spread: 0.247 Reading Count: 2	Units: US Ft BM+ HT:1.200 Z:10.000

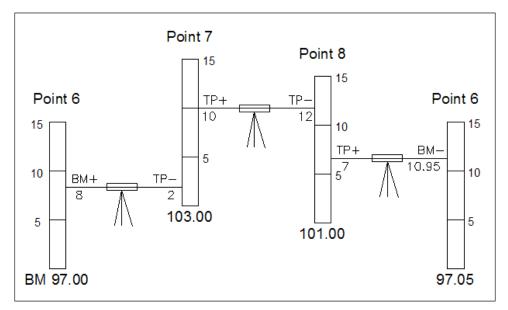
The Processing Options screen allows you to update all existing points in the coordinate file with the leveled elevations. It also allows you to overwrite the point descriptions using what was entered during the level loop and will compute coordinates for any points that were defined by station and offset.



<mark>è</mark> Upda	Update Points in Job					
Pt ID	Orig El	New El	El Diff	Desc		
2	10.000	10.000	0.000	Point 2		
Use	Use Adjusted Elevations					
Sto	☐ Store STA- as Points Skip Existing ▼			-		
Save Report			Update Job			

Manual 1-Wire Example

If you select the 1-Wire method of Leveling, the graphic below may be helpful in selecting the options to conduct a simple level loop:



You "+" to your "backsight" and you "-" up to your foresight, and you name the points as you go. You start by referencing a benchmark, and you close the loop by referencing the starting point or a second benchmark.

After entering the example, pressing the Edit Levels icon shows all the measurements made. All the horizontal distances (HD) are shown as 100 because 1-wire leveling does not provide a



horizontal distance. Giving all the segments the same distance causes the level adjustment to give all the segments the same weight.

误 Edit Level	5		🛛 🛃 🔀		
	2007 Time:	11:11:18 Pre	ss: Temp:		
Rod:0.000					
BM Pt:6 Z:97	'.000 Desc:	BM			
BS Pt:6 VD:	8.000 HD:1	00.000 Desc:	BM		
FS Pt:7 VD:	2.000 HD:1	00.000 Desc:			
BS Pt:7 VD:	10.000 HD:	100.000 Desc	::		
FS Pt:8 VD:	FS Pt:8 VD:12.000 HD:100.000 Desc:				
BS Pt:8 VD:	7.000 HD:1	00.000 Desc:			
FS Pt:6 VD:	10.950 HD:	100.000 Desi	::BM		
Add	Edit	Del/Undel	Process		

Pressing the Process icon shows the results.

Review File		←
Processed: 01/05/2017 11:17:14		
Length(-): 300.000		
Length(+): 300.000		
Loop Length: 600.000		
Closure: 0.050		
Error: 1:12000		
Loop: Short 1-wire		
Operator:Ken		
Project: Example		Ψ



Scrolling to the end shows the adjustments that will be applied to the last two measurements.

À Review File	🔽 🔽 🧲
[
TP+	_
Pt:8 Desc:	
VD: 7.000 HD: 100.000	
dZ: -7.000 HI: 108.000	
Adj: -0.042 AdjHI: 107.958	8
BM-	
Pt:6 Desc:BM	
VD: 10.950 HD: 100.000	
dZ: -10.950 Meas: 97.05	0
Adj: -0.050 BM: 97.000	
]	

Pressing the green check icon brings up the Update Points in Job dialog.

6	👌 Update Points in Job 🛛 🗙					
1	Pt ID	Oria El	New El	El Diff	Desc	
		Orig El				
	6 7	97.000	97.000 102.983	0.000	BM	
	8		100.987			
	Use Adjusted Elevation: Use Level Descriptions Store STA- as Points Skip Existing					
	Save Report				Update Job	

Save Report will put the information shown in the Update Points in Job dialog into a text file for your records.

Update Job saves the new elevations to the points in the job. **Skip Existing** will not replace a point's elevation if it already exists but **Replace Existing** will.



6.18 Auto by Interval



Auto by Interval allows you to acquire and store data at a set interval value of either distance or time. This function is available with all GPS or certain robotic total stations only.

Robotic Total Stations: When the routine is selected using a robotic total station with Prompt for Setup within Configure on, you will be directed to a **Confirm Orientation** dialog, in which you will be asked to confirm your orientation. The opening or main dialog appears as shown below.

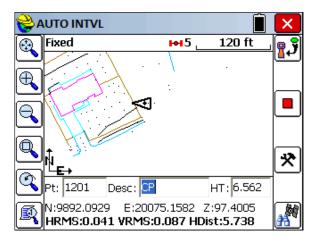
😂 Auto by Int	erval 🔀 🔽			
Single Setup	Remote BM Robotics			
Occupy Point:	1197 📄 🗹 м			
Instr. Height:	5 ft			
Backsight Point	: 1195 🚊 📝 🍙			
Backsight N Azi	: 270°00'00"			
Backsight HT:	5 ft			
Use Backsight HT for Foresights				
Confirm NEZ	From Job Backsight			

After the backsight is confirmed or measured, the **Auto Store by Interval** dialog will appear as shown in the figure below. In GPS mode, you will see the Auto Store by Interval dialog immediately. In the Auto Store by Interval dialog box, you set the type of interval (distance or time) and the value of the interval. You also set the starting point number for the data set. You can assign a point description for all points acquired with this command. During actual data collection, you can change the description.

8	🍦 Auto	Store by Interva	l I	\checkmark	X
	-Interva	al Type			
	Oist	ance		🔿 Time	
	X/Y:	10	ft	10	
	Z:	10	ft		
	Starti	ng Point ID:	119	9	
	Descr	iption:	СР		



Data is acquired in the standard collection **MAP** view screen. The point ID, description, and rod height fields can all be changed while the command is active. For example, to change your point description from td (top of ditch) to gr (ground shot), simply type "gr" over the "td" in the Desc field without interrupting your collection.



- Store: Pressing the Store icon immediately stores the point at your current location, overriding the interval.
- **GPS Start and Stop**: This button alternates between stop (square, red) and play (arrow, green) icons. While the GPS is running or the robotic total station is tracking, the stop icon allows you to stop the surveying equipment from taking readings. When the button is pressed, the GPS or robotic total station stops, and the button switches to the play icon, which can be pressed to resume the readings.
- Monitor/Skyplot: This button can be found on the bottom right of the MAP screen for GPS. This "binocular" icon opens the Monitor/Skyplot dialog.

Note: In GPS mode, if you run Auto Points at Interval and points do not store, check that your RMS tolerances for storing are not set too low. Points will be stored only when your RMS values are less than those specified in tolerances under the EQUIP tab. Also, note that you may find that the points store at a distance apart exceeding that specified by your interval due to latency and your speed of movement.

Note: Auto by Interval will display a red status bar whenever an error / blunder is detected.



GPS Receivers:

For GPS Receivers, this routine allows you to store a point automatically as soon as the receiver is level. To use this feature, select Equip – GPS Rover. In the Receiver tab, enable the Use IMU option. Select the green check to continue. Please note the 5Hz minimum position rate with this feature: If less than 5Hz is selected afterwards, the IMU feature will be disabled.

😂 GPS Rover	📃 💽 🔽		
Current Comms Rec	eiver RTK		
Antenna Type: [HEMS3	21 ▼ TE Vert C Slant		
Antenna Height: 0	ft Abs. 131.9mm		
Elevation Mask:	10 °		
Position Rate:	5 Hz 💌		
Use IMU			
Audio Mode:	Silent 🔹		
Advanced			

To view the electronic bubble on the screen, please go to Equip – Configure and select the IMU tab. In the IMU tab, the option to 'View GNSS Level' is available to enable / disable.

裬 Config	ure			<u> </u>
General	View	IMU		
View	GNSS Lev	el		
Corre	ect Tilted P	ole		



Auto Store when Level Routine: to begin, the user needs to set the acceptable level tolerances. This is configured at Equip – Tolerances, as shown below.

😝 Tolerances		
HRMS Tolerance:	0.098	ft
VRMS Tolerance:	0.197	ft
PDOP Tolerance:	3.500	
Stakeout Tolerance:	0.328	ft
"Navigate To" Tolerance:	16.404	ft
Level Tolerance:	0.049	ft

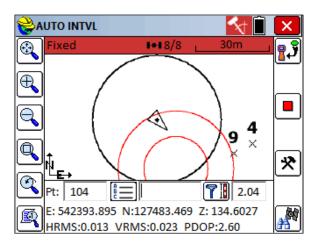
The Auto Store when level Routine is located at Survey – Auto by Interval. The option for 'Level' will be shown in the first screen of the routine.

🔁 Auto Store by Interval 🛛 📝 🗙			
◯ <u>D</u> istance X/Y:	10.0000	ft	
Z;	10.0000	ft	
○ <u>T</u> ime	1	s	
Level Time Tol:	5	s	
Dist Tol:	0.5000	ft	
Starting Pt ID:	104		
Description:	ÊΞ		
Record Max Num	ber of Points	: 100	

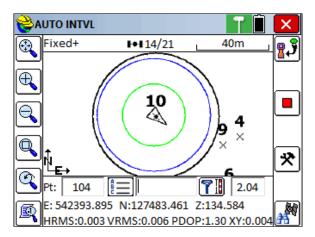
The 'Time Tol' setting controls the time the receiver needs to be level before a point is stored automatically. The 'Dist Tol' settings controls the minimum distance between two automatically store points, preventing multiple point storage over the same point. Define the preferred starting point ID and description and whether to enable a Maximum number of points. Once all the configuration is complete, click on the green check to continue.

Points will now be stored automatically whenever the receiver determines it is within acceptable level tolerances set previously. The red bar shown in the figure below indicates the receiver is not within level tolerances.





As soon as the receiver is level for the specified length of time, a point will be stored. If you selected the Audio option in Equip – GPS Rover, an audible alert will sound.





6.19 Remote Elevation



This command allows you to observe a point that cannot be reached vertically, such as a power line, building top, etc. The routine uses two observations - one for the base point and one for the vertical angle to the target object. The routine then calculates the target point's elevation.

By placing the prism below or above the desired point, Carlson SurvCE stores information about the base point. Then you can take a second reading, observing only the zenith/vertical angle to the true target point. Using these two observations, SurvCE calculates the intersection of the extended zenith/vertical angle with a vertical line from the base point to determine the elevation. Reporting includes the elevation of the target object as well as the elevation difference between the prism and the target object.

Steps to take a remote elevation reading are as follows:

- 1. Select **Remote Elevation** from the **SURVEY** tab of the main menu.
- 2. Confirm your orientation and re-shoot the backsight as necessary.
- 3. Press Enter to observe base point (see the figure below). Point the instrument toward the target and press Enter.

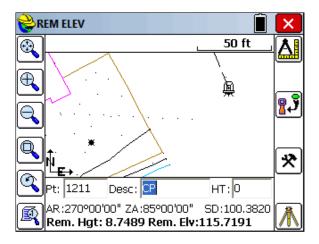
癸 Remote E	levation		🗹 🗙
Press En	ter to Rea	d Base Po	oint.
Target Ht:	Z	ft	

Press Enter to shoot target elevation (see the figure below). Sight instrument on the desired point (such as a wire or top of pole or point on a building) and press Enter.

Remote Elevation				
Press Enter to Read	d Targ	et Elev	ation.	
ОК		C	ancel	



Back in the REM ELEV screen, your angle, zenith, and distance are shown, along with the remote height and remote elevation.



- **Read Icon**: This allows the user to take additional shots above or below the previously defined base point. Pressing the Enter key will also repeat this command.
- Store Icon: This button stores the current target offset point to the job file
- Configure Icon: This takes you to the Configure settings also found on the EQUIP tab.
- Instrument Icon: This takes you to the standard Instrument Setup dialog.



6.20 Log Raw GPS



This command allows you to log static data to the receiver or a data card (depending on instrument type) for use with post processing software. If a raw data log file has been started through SurvCE, points stored by Average or Single Store methods (not Auto by Interval) will be tagged in the raw data log file automatically given the receiver supports this feature.

Post Processing (Logging Static Data) for NovAtel/Sokkia

Go to the SURVEY tab and select the **Log Raw GPS** button. You will see a screen with options (see the figure below), or an error message stating that the data collector could not connect to the receiver. If you receive an error message, check connections and the data card.

😂 Log GNSS		<
File: Nor	e	
	Start/Resume File	
	Tag Point	
	Close File	
	File Manager	
Static		

Tap on the **Start/Resume File** button to start logging raw data. From this point, you can choose the **File Manager** button to see what files are on the receiver's card. You can delete files here if memory is low. More information on the **File Manager** dialog will be covered later.



The **Start New File** dialog contains place to enter a new File Name, Antenna Height, Antenna Type, and [Logging] Interval as shown in the figure below.

😂 Log GNSS		Cel 😂 Start Ne	ew File	
File: Nor	ne Start/Resume File	File Name	1	lewJob
	Tag Point	-		
	Close File	Antenna H	leight: 0	Change Antenna
	File Manager	Antenna T		NONE
Static		Interval:	1.00 seconds	

Next is the **Tagging Site dialog**. To start tagging a site, enter the information requested including site name, site code, and antenna height (changing is optional--see Changing the Antenna). You will also decide here whether you want the site to stop automatically after a duration of your choice, or when **End Site** is selected. Tap **Start Site**, and all the information entered will be grayed out until the site is ended. Stop the site at any time by clicking **End Site**. Before ending the site, you will have the option to change the antenna information (in case you made a mistake). View the satellite status at any time using the **View Status** button. This will not affect the tagging of the site.

Logging to file 'file	e0001'		Exit	
Start Site	End Site	View	Status	
Site Name: site	Site Du	ration: 00:	00:01	
Site Code: 1				
Antenna Height: 0.0000 ft. File: file0001				
Change Antenna Ht. File Duration: 00:00:58.0				
Stop Logging:				
Manually After 10 minutes GDOP: 3.5 PDOP: 3.8 HDOP: 1.7 TDOP: 1.8 SATS: 5				

You can tag as many sites as you wish. When you are done, click the **Exit** button. SurvCE will ask you if you want to continue logging the file. If you do, click Yes, and the next time you select **Log Raw Data**, you will go directly to the dialog box shown above. The file name will appear in the main post process screen if it is being logged. If you wish to leave the receiver logging, you can exit the setup, and the next time you come back to post processing, the software will know you are still logging a file.



File Manager

Under the SURVEY tab of the main menu, select the Log Static Data button. You will either see a screen with three buttons, or an error message stating that the data collector could not connect to the receiver. If you receive an error message, check connections and the data card. Click on the File Manager button to see what files are on the receiver's card. In this dialog, you see a list of files, along with their respective sizes.

ť	😂 Files on Receiver:	÷
	Name	
	SOK1.PDC 9932 bytes	
	11281614.PDC 33484 bytes	
	00463320.PDC 5624 bytes	
	11281709.PDC 32532 bytes	
	00463330.PDC 479100 bytes	
	00460250.PDC 56208 bytes	
	Storage Location: 27 files	
	Free Memory: Free memory: 476160 bytes	
	Format	

Post Processing (Logging Static Data) for Topcon

Go to the Survey Menu and select the Log Static Data button. You will see a screen with four buttons.

😂 Log GNS	SS	(
File: N	lone	
	Start/Resume File	
	Tag Point	
	Close File	
	File Manager	
Static		



If you want to manage the files (to see how much memory they are using and to delete files) on the receiver, click the File Manager button. If a file is open, you can now tag sites. Otherwise, open a file by clicking the Start File button.

The file name can be chosen from a list of existing file names using the suggested file name, or a file name of your choice. The antenna height and antenna type can be changed using the **Change Antenna** button (see Changing the Antenna). The interval can be selected from the list, or you can enter your own, in seconds.

📚 Start New File		X
File Name:	Ne	dotw
Antenna Height: Antenna Type: Interval: 1.00 se	0 TPSHIPER_V econds	Change Antenna NONE

After starting a file, you will be returned to the main screen. From here you can leave the file recording, manage files, exit, or start tagging sites. To tag a site, click the **Tag Site** button.

😂 Tag New Site	🔽 🔽
Free Mem on Receiver: File: 8N40318B Site Name: Site Ant. Height: 6.5430 ft	54102792 bytes Change Antenna
Interval (in Seconds): Close Site Tag: O Manually O Af	15 ter 1 minutes



The **Tag New Site** dialog shows the available space on the receiver and gives you the ability to enter a site name, change the interval, and change the antenna. You can choose to have SurvCE stop logging the site automatically after a specified time period or stop it manually. Even if you choose to stop logging automatically, you will still have the option to stop it manually using the **Stop Point Logging** button.

癸 Recording site 'Site'
Site Duration: 00:00:06
Time Remaining: 00:00:54
Antenna Height: 6.543 (Vertical)
Antenna Type: 'Unknown'
Monitor/Skyplot
Stop Point Logging

After you exit this screen (automatically or manually), you will be returned to the main post processing screen. From here, you may tag more sites, close the file, or manage your files.

When you are ready to close the file, hit the Close File button.



7 Cogo

This chapter provides information on using the commands from the COGO menu.

😂 JOB:NEWJOB		1	0
<u>F</u> ile <u>E</u> quip	<u>S</u> urv	vey <u>C</u> OGO <u>R</u> oa	d
1 Keyboard Input	E	6 Station Store	~
<u>2</u> Inverse	**	7 Transformation	N
<u>3</u> Areas	?	8 Calculator	
<u>4</u> Intersections	1	<u>9</u> Manual Traverse	å.
5 Point Projection	<u>م</u>	0 Point Average	۲



7.1 Keyboard Input



This feature allows you to manually enter or edit coordinates in the current job file or the current control file. The option to edit points in the control file only appears if **Use Control File** is enabled in **Job Settings**. There are fields for Point ID, Northing, Easting, Elevation and Description. If adding a point to an existing job, SurvCE displays a point ID one greater than the highest in the file. If starting with a new job, the point ID will default to 1.

📚 Enter and Edit Coordinates 🥂 🧲				
Type CRD: Alphan	umeric			
Source:	🖲 Job 🛛 🔾 Co	ontrol		
Point ID:	1			
Northing:	3466848.2391	ft		
Easting:	4899345.1831	ft		
Elevation:	935.1935	ft		
Description:	PK Nail	ÊΞ		
Prev	Next Store	Utilities		

- **Previous and Next**: These buttons move back and forth through the coordinate file, skipping points with zero coordinates. The **Next** button will not store the current data to the file.
- Store: This writes the entered data to the file and advances the display to the next point. If you are editing an existing point, when you press **Store**, SurvCE will warn you that the point number has already been used. You then have a choice to overwrite this point number or use a new number.

If you want to create a duplicate point, simply change the point number and press Enter or Store to save it. If you a duplicate point with a different elevation, change the point ID and elevation and press Enter or Store to save it.



• Utilities: The Utilities button allows the user to modify or delete a point or range of points. The Utilities screen appears below:

😂 Point Utilities	×
Range of Pts: 3-5	
DESC: IP (Found)	Ê
Modify	Delete

There are two uses of the command: to Delete a point or range of points, and to Modify the descriptions of a point or range of points. For example, if you wished to assign the description "IP (Found)" to points 3 through 5, you can enter the point range and description as above, and then tap "Modify". You will have a confirming screen as shown below:

SurvCE						
Are you sure you want to change the descriptions for the range of points: 3-5 to IP (Found)?					D IP	
	Yes			No		



7.2 Inverse



This command reports the bearing and horizontal distance between any two user-specified points that are contained within the current job. If under **Units** in **Job Settings**, Angle is set to Azimuth, then inverse will display azimuths instead of bearings. You can override the display settings in the **Point Inverse** screen by choosing between Bearing (Brg N,E or Brg E,N), North Azimuth (NAz N,E, NAz E,N) and South Azimuth (SAz N,E or SAz E,N) at the bottom right of the Inverse screen.

Inverse can be run in either 2D or 3D mode as selected at the top of the screen. In 2D mode, the program displays only the bearing and distance between the two points. As many as four inverses can be viewed at once, as shown below.

😂 Point Inverse 💿 🧕 🤉 🖸 🛃 🛃	(
Pt5: N5015.0068ft E5004.8826ft Z10.0239ft	\sim
Bearing: N18º02'24"E HDist: 3.534ft	
Pt6: N5018.3670ft E5005.9770ft Z10.0078ft	
Bearing: N18°02'24"E HDist: 3.534ft	
Pt7: N5021.7273ft E5007.0714ft Z10.0232ft	
Bearing: N18°02'24"E HDist: 1.767ft	
Pt8: N5023.4074ft E5007.6186ft Z10.0104ft	
Bearing: N18º02'24"E HDist: 1.767ft	
Pt9: N5025.0875ft E5008.1658ft Z10.0032ft	•
NAZ N,E Brg E,N	<u>^</u>
< Brg N,E	
Next Pt: 9 3 Ξ . Next Pt: 9	-
inextru is Show. big N,E	



In 3D mode, the report also displays the slope distance, elevation difference, slope in percent, and slope as a ratio, between each point. The Northing, Easting, Elevation and description of the specified points are also shown.

Ś	😂 Point Inverse 👘 💿 20 💿 30 🛃 💽 🧲	
	Pt4: N2734071.3235ft E808526.1775ft Z224.4930ft M	
	Bearing: S16°24'22"W HDist: 2844889.251ft	
	SDist: 2844889.259ft EDiff: -214.469ft	
	Slope: -0.01% -13264.80:1	
	Pt5: N5015.0068ft E5004.8826ft Z10.0239ft	
	Bearing: N18º02'24"E HDist: 3.534ft	
	SDist: 3.534ft EDiff: -0.016ft	
	Slope: -0.45% -219.83:1	
	Pt6: N5018.3670ft E5005.9770ft Z10.0078ft	
	· · · · · · · · · · · · · · · · · · ·	
	< >	
	Next Pt: 5 Show: Brg N,E 🗸	

To run the inverse routine, enter the first point number at the bottom (you may also select from a point list or select from the map screen). Press **Enter**, and then input another point and press **Enter** again.

If a control file is specified in **Job Settings**, then when you run inverse, you can choose the List icon at the bottom center of the screen and then select points from the control file. In this way, you can inverse between points in your current file and your control file as needed.

If under **Units** in **Job Settings**, Angle Unit is set to Grads/Gons, then the Inverse command will default to the 400 circle and will display North azimuths.

- **Clear Command**: Use this icon to clear the results window.
- **Save Command**: Saves any inverse to a TXT file, and will auto-append data if the same TXT file is used.

问 Inverse.txt - Notepad	-		×
File Edit Format View Help			
Pt4: N2734071.3235ft E808526.1775ft Z224.4	1930ft	MON1	^
Bearing: S16°24'22"W HDist: 2844889.251	lft		
SDist: 2844889.259ft EDiff: -214.469ft			
Slope: -0.01% -13264.80:1			
Pt5: N5015.0068ft E5004.8826ft Z10.0239ft			
Bearing: N18°02'24"E HDist: 3.534ft			
SDist: 3.534ft EDiff: -0.016ft			
Slope: -0.45% -219.83:1			
Pt6: N5018.3670ft E5005.9770ft Z10.0078ft			~



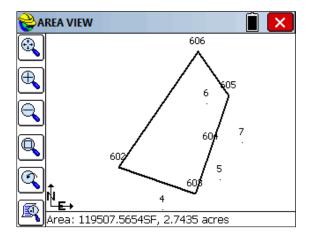
7.3 Areas



This command calculates the area of a closed figure that is defined internally by user-entered point numbers contained within the current job, or by a polyline picked from the screen. The polyline method allows selection of figures with arcs.

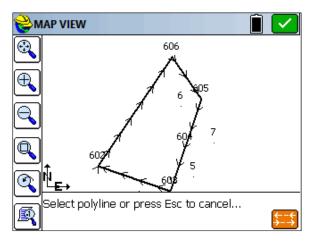
6	Area	a Calculation				X
	Detine	Area by Point ID	s, or by	Selec	ting a Polylir	ne:
			1		2 52	
	Pt ID	Job Used				
	602	Current				
	606	Current				
	605	Current				
	603	Current				
	602	Current				-
	Add	Pts Delete				

You may specify individual point numbers or type in a range of point numbers to define the area. Individual point numbers can be entered as 602,606,605,603,602 or each number followed by Enter. After clicking OK (green checkmark), the area is reported at the bottom of the map screen. A temporary polyline is also drawn between the points. Results are reported in square feet and acres when units are set to feet, and square meters when units are set to metric.





If the polyline method is used to solve the area, the program will bring up the MAP screen where you pick a polyline. Since the area can be written to a raw file (see below), you can use the direction icon in the lower right of the screen to confirm or change the direction that the polyline is drawn.



When you are certain that you have selected the desired polyline, press **OK**, and the graphic screen presents the area. Since the point-defined area is a straight point inverse, the advantage of the pick polyline approach is that the polyline may contain arcs.

raw file?
No

At the end of each area calculation, you are asked if you would like to "Write result to raw file?" This will write a line in the raw file as "Calculate area of polyline 602,606,605,603,602: Area = 119507.5654SF, 2.7435 acres." For point-defined figures in metric, the raw file record presents square meters.



7.4 Intersections



This command allows for the calculation and storing of points based upon standard surveying practices of Bearing-Bearing, Bearing-Distance, or Distance-Distance Intersection calculations. Data can be entered manually or defined by selecting points from a point list or map. The kind of intersection calculation to be performed determines the number of possible solutions. With a Bearing-Bearing calculation, there will be only one possible solution. Bearing-Distance, and Distance-Distance calculations will have two possible solutions prompting the user to pick the desired solution. Note that in intersection calculations of Bearing-Distance and Distance-Distance there may be no solution for the input data. In these cases, Carlson SurvCE will display the message, "No Valid Solution."

Intersections	💽 🔽 🚺
- First Point	
Point ID:	
Azimuth:	Use Points
Distance:	ft off:
Second Point	
Point ID:	
Azimuth:	Use Points
Distance:	ft Off:

From the **COGO** Menu, select **Intersections**. Fill out the appropriate data fields to perform the desired calculation. The **Enter** key moves forward through the edit boxes. The current Angle setting in **Job Settings**, **Units**, dictates whether angles are prompted as azimuth or bearings.

• Off: Use these edit controls to create intersections that are defined by parallel offsets to the defined or computed direction.

All Intersect routines create SP records in the raw file, storing the calculated coordinates for each new point. This SP record is identical to records created by keyboard input.



Bearing-Bearing

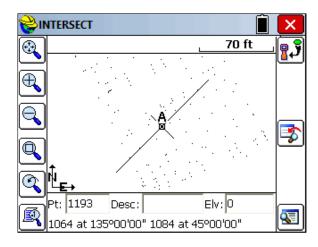
This method locates a point at the intersection of two lines. Select Point 1 by entering the desired point number or pressing the **Point List** icon and selecting the desired point. Pressing the **Map** icon will allow for selection of the desired point directly from the screen.

Note: when selecting a point from the screen, if the desired point cannot be determined from the picked point on the screen, a listing of the nearest points to the desired location will appear allowing for verification of the targeted point. If the list appears, select the desired point from the list by clicking on it.

Define the bearing from the first point by typing in the bearing or by specifying two point IDs. Repeat the procedures for defining the bearing from the second point.

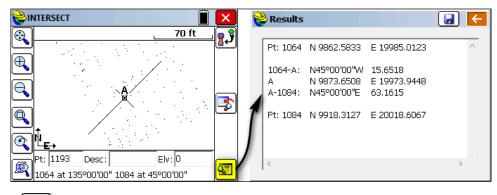
Bearings can be entered in three forms:

- SE40.5945 becomes S40d59'45"E
- S40.5945E becomes S40d59'45"E
- 240.5945 becomes S40d59'45"E





Once data entry is complete, press the **OK** button. The calculated point will appear on the screen with the input data detailed at the bottom of the screen. Store, Modify (review and revise) and Results options are located on the right side of the **Map** screen.



• **Save**: Use this icon to save a report of the inverse.

The results screen will display the coordinates of the base points, the inverse bearing, the distance from the base points to the calculated INT1 point (and INT2 for distance intersections), and the coordinate data for the calculated points. Note that calculated points are labeled as Int1 and Int2 until the points are stored. These Option Buttons are present on all **Map** screens displayed while in the Intersections routine. Once **Store** is selected or the **Enter** key pressed, the stored point will inherit the specified point number, description, and the elevation displayed at the bottom of the screen (optional). There can be only one solution for a bearing-bearing intersection.

All Intersect routines handle the 400 circle, if configured to grads/gons within **Job Settings**, **Units**.



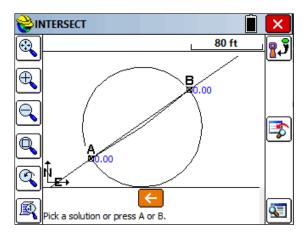
Bearing-Distance

Define the Bearing from the first point, then define the known horizontal distance from the second point.

ons	🔜 🗹 🚺
6	
235°00'00"	Use Points
	ft Off:
it	
1040	
	Use Points
40.000	ft Off:
	235°00'00" 235°10'00" it 1040

Select **OK** and the map screen will appear showing a circle radiating from the distance base point and a line from the bearing base point, defined by the entered bearing. The line is extended to intersect the circle at the two possible solutions.

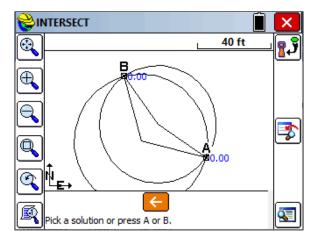
Pressing **Enter** or **Store** will display the prompt "Pick a Solution". To select the point, simply pick it from the screen. Picking near the desired solution is sufficient. The program will select the nearest solution position. Pressing **Enter** again will accept the second possible solution for the intersection.





Distance-Distance

Enter the known horizontal distances from both points.



Select **OK**, and the map screen will display showing circles radiating from the first and second selected base points. Lines leading from both base points to the two possible intersections of the circles are also shown.

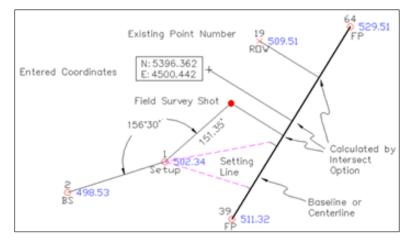
Pressing **Enter** or **Store** will display the prompt "Pick a Solution". Select the desired calculated solution. To select the point, simply pick it from the screen. Picking near the desired solution is sufficient. The program will select the nearest solution position. Pressing **Enter** again will accept the second possible solution for the intersection. If there was no solution for the input data, SurvCE will display "No Valid Solution".



7.5 Point Projection



This command allows you to calculate the station and offset of any entered or surveyed point relative to a known centerline or baseline. Note that the Station Store command will calculate a point at a given station and offset. Point Projection does just the reverse — it calculates a station and offset for any given point. It also will calculate the "Intersect", or the projection of that offset point on the baseline. This baseline "intersect", or perpendicular projection point, can be staked out and stored. The application of the routine is shown below.



The coordinates from which to project can be entered in three ways:

- By point number
- By entering the coordinate values
- By taking a GPS or total station reading

The station, offset, and vertical difference of the point is then calculated, and the **Intersect** button (see the above figure) will calculate the projected perpendicular intersect point on the baseline. This Intersect can also be staked out using the Stake button.

You must first define the baseline. You can define the baseline by one of the following methods:

- Define Line: Select two points to define the line.
- Define Alignment: Select a predefined centerline file (.cl file), graphically pick a polyline or enter a sequence of points.
- Define Arc (3 Points): Select three points on the arc.
- Define Arc (PC, PT, Value): Select the start and end points of the arc and enter the radius length.



6 🔗 🛛	Point Projection	Х
	Define Line	
	Define Alignment	
	Define Arc (3 Points)	
	Define Arc (PC,PT,Value)	

If you choose **Define Line**, you must then define the line in the dialog box as shown below.

裬 Define Line		
First Point ID: (from Current		
Second Point	ID: 1040	
North Azimut	225°00'00"	Use Points
Slope:	-21.21%	
Method	2 Point	C <u>A</u> zimuth
Start Sta:	0+00.000	
End:	0+14.142	Confirm NEZ

Method(s)

- With the **2-point** method, you simply enter two point numbers, or choose them from the point list or MAP. The azimuth and slope between the two points is calculated, along with the ending station, based on the entered start station.
- With the **Azimuth** method, you define the line by entering a first point and then entering an azimuth and slope. You can confirm the coordinate values of the points by choosing **Confirm NEZ**. When the line is defined, choose **Continue**. You must now define, or designate, the point that is offset from the line in the **Point Projection** dialog.

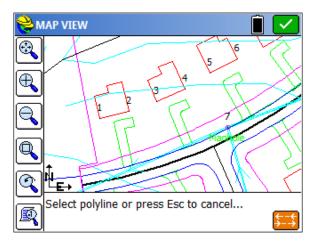


Point Pr	ojection		b	🗾 🧲	-
Point ID:	1001				
Northing:	9908.6459			Read	
Easting:	20026.3177			Intersect	
Elevation:	91.4084	HT: 6.543	ft	Stake	
Desc:	CP/NAIL		ĝΞ	Store	
Centerline: By Points(6,1040) Station: -140+82.006 Offset: Left 7154.274 Elev at PRO: 3088.2445 (extrapolated) Vert Diff: F2996.8361					

You can enter a point ID, select one from the list, or select one from the map. You can also enter coordinates to define a new point or read values from the instrument. As soon as enough information is entered, the station, offset and vertical difference is displayed or the message "OFF CENTERLINE" is displayed. This message lets you know that a station/offset cannot be computed for the coordinates entered.

- Read: This command reads the instrument to gather coordinates for point projection.
- **Intersect**: This command will project the coordinates entered perpendicular, back to the centerline and enter these new coordinates into the Point Projection dialog. From there you can store or stakeout the intersect points.
- **Stake**: This command will allow you to stakeout the displayed coordinates (typically used to stakeout the intersect points).
- Store: Pressing Store after Read stores the offset coordinate. Store after Intersect is selected stores the coordinates for the intersect point on the centerline (perpendicular from the offset point). Store after entering coordinates or a point number for the offset point, without selecting Intersect, will simply store the offset point coordinates again as a new point number. Store is most often used to save the calculated intersect points to the coordinate file. Pressing Store will save an SP (store point) record in the raw file, and a note record will indicate that the point was calculated within Point Projection.
- Computing Ranges of Point Offsets with Special Report: A range of points can be entered leading to reporting of all stations and offsets to a selected horizontal alignment (centerline). In the example below, a centerline has 7 points shown at offset.





If point 1 is entered, you get the normal station and offset report. And if point 1 has an elevation, and "Use Vertical Alignment" is clicked on when selecting the alignments, you will get a cut and fill as shown:

😂 Point Pr	ojection	🔁 🛃		
Point ID:	1]= 2		
Northing:	3337.2459		Read	
Easting:	4398.4759		Intersect	
Elevation:	841.839	HT: 6.610 m	Stake	
Desc:		ÊΞ	Store	
Centerline: 2D Polyline Station: 0+41.304 Elev at PRO: 840.1080 Vert Diff: C1.731		Offset: L82.275		

When entering a range of points, use normal range conventions (e.g. 1-6, or 1-7,10,14-16). You can present the range appearance by clicking the Settings icon at the top of the screen, just left of the back arrow. You can compare Survey to Design where if the field point is 841 and the profile vertical alignment is 840, it would be a Cut 1, or you can compare Design to Survey in which case that would be a Fill 1. Comparing Survey to Design is normal operation.



<mark>è</mark> Settings	🗹 🗙
🗌 Include Header	
Include Station, Offset, Elev	
Include Coly III	Survey->Design
<u>R</u> ound Station to the Network	earest 5
Offset Prefix: Left: L	Right: R

Then click the report button to see the results for points 1 to 7, as output to a TXT file and viewed in Notepad.

Projection4.txt -	Notepad				- • •
File Edit Format	View I	Help			
0+41.304 ,L 0+86.930 ,L 1+31.460 ,L 1+77.185 ,L 2+22.791 ,L 2+68.853 ,L	fset 82.27 82.20 83.16 84.28 88.96 87.43 14.36	,Elevation ,841.839 ,841.839 ,840.449 ,840.449 ,840.598 ,840.598 ,840.598	,Cut ,1.731 ,2.400 ,1.437 ,1.644 ,1.766 ,1.501	,Fill , , , ,0.630	,Point ID A , , , , , , , , , , , , , , , , , , ,

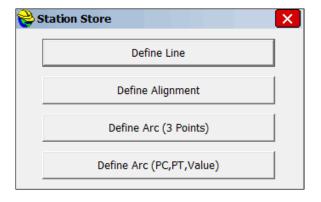


7.6 Station Store



Station Store is a pure calculation routine that will create points based on a station and offset from an alignment. The alignment may be defined as a centerline, a 3-point arc, an arc defined by a PC, Radius and PT, a selected polyline, or a sequence of points. The user may also assign an elevation to the calculated point. Station Store is useful for calculating right-of-way locations, which are typically defined as station and offset. Station Store might also be used to enter elevations of pipe culverts, for example, where inlets and outlets are located at distinct stations, offsets, and elevations. Then the two calculated points at the inlet and outlet can be used within Stakeout Line to stake any point along the culvert, with the cut/fill calculated. Although the command Stake Centerline, found within Stakeout Line/Arc, will directly stakeout a particular station and offset to a centerline, some users prefer to pre-calculate the station and offset and assign a point ID, then stake by point ID. Station Store permits this pre-calculation of points at any station and offset.

The very first screen within Station Store offers several methods of defining an alignment, similar to Stake Line/Arc.

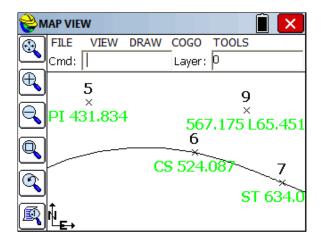




The following screen is where you enter the station, offset, and elevation to compute and store a point location.

😂 Station Store	🔁 🗲			
Station:	000 End Sta: 0+14.142 Interval: ↓ ↓ ↓ ↓ 50			
Segment (H): OFF CL (V): Extrapolated Desc: 5+67.175 L65.451				
5+67.175 L65.451 ÊΞ				
Store Multiple _{Pt} ID:	9 Store			

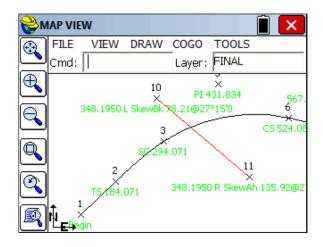
In this example, a right-of-way point on a metric-based horizontal alignment is calculated at 0+567.175, offset left 65.451 meters, and assigned point ID 9. Note that the program detects that point 9 is within a spiral curve segment of the defined alignment.





The description is fixed as the station and offset but can be edited using the command Keyboard Input or File, Points. The "Interval" option is not typically applied, unless Store Multiple is selected, in which case points will be stored sequentially at the entered offset from the starting station to the ending station as entered. In addition to calculating a station and offset perpendicular left and right, skewed pipes can be calculated by selecting the "skew back" or "skew ahead" options in the pulldown list where "offset" is the default. A zero skew pipe is perpendicular to the horizontal alignment. So, a "skew ahead" of 20 degrees would be 20 degrees "ahead" of the 90 degree offset, or 70 degrees to the right of the forward tangent. Here is an example where both ends of a pipe are calculated, with the resulting graphic shown below. Decimal places on the stationing are set under File, Job Settings, Format Tab, Station Display.

😂 Station Store 🛛 🗔 🧲	📚 Station Store 🛛 🗔 🧲
Start Sta: 0+00.000 End Sta: 0+14.142 Station: Interval: 3+48.195	Start Sta: 0+00.000 End Sta: 0+14.142 Station: Interval: 3+48.195 Image: Start S
Segment (H): OFF CL (V): Extrapolated Desc: 3+48.195 L SkewBk 78.21@27°15'00" []] 3+48.195 L SkewBk 78.21@27°15'00" []] Store Multiple []] 10 Store	Segment (H): OFF CL (V): Extrapolated Desc: 3+48.195 L SkewAh 78.21@27°15'00" 3+48.195 L SkewAh 78.21@27°15'00" ፪Ξ Store Multiple Pt ID: 11





7.7 Transformation



This command allows you to translate, rotate, and/or scale points in the current job. Any point drawn on the map screen will be updated automatically in addition to updating the coordinates.

All three transformations can be performed individually or all at once if desired. You first fill out the options in one or more of the tabs (Translate, Rotate and Scale), and then you press Enter and obtain a second screen where you fill out the range of points to transform.

😂 Linear Transformation 🛛 🔽 🗙
Translate Rotate Scale Align
Delta: 0.0000 E: 0.0000 Elv: 0.0000 Original Pt ID: Image: Sector
N: Elv: Elv: Elv: Elv:
N: Elv:



Translate

On the translate dialog, enter in the Delta North, Delta East, and the Delta Elevation. These values represent the change in the original coordinate values and the desired coordinate values. When complete, select the OK button on the dialog, or navigate to the ROTATE or SCALE Tabs for further data input.

📚 Linear Transformation 🛛 🔽 🗙	😂 Linear Transformation 🛛 🗮 🔽 🗙
Translate Rotate Scale Align Delta: N: -10.0000 Elv: -3.0000 Original Pt ID: 6 = • • • N: 5010.0000 Elv: 101.0000 Elv: 101.0000 Destination Pt ID: 1040 = • • • N: 5000.0000 Elv: 98.0000 • •	 Points: Highest Point ID: 1040 Range of Points: 1-1040 Add to Point IDs: Qverwite Existing Point IDs Qverwite Existing Point IDs Store in New CRD File Linework: 0 Automatic - All Layers Process Frozen Layers Manual - Select

The lower portion of the screen shows an alternate method of defining a translation by comparing an original point to a destination point. Data entered here, as point ID or directly entered northing, easting and elevation, will lead to computation and display of the delta N, delta E and delta Z in the upper portion of the screen.

- **Range of Points**: Enter the range of points to translate. Ranges can be entered in the following format: 1-20,32,40-45, etc.
- Add to Point Numbers: Enter a number to add to existing point numbers when creating new point numbers. This option is not available when overwriting your existing point numbers. See example below under Use New Point Numbers.
- **Overwrite Existing Point Numbers**: Overwrites the existing point coordinate data with the new coordinate data.
- Use New Point Numbers: Uses new point numbers for the new coordinate positions while keeping the existing point numbers and coordinate data. Each time a point is to be overwritten, you will be prompted whether to overwrite or use a new point number. This method is only recommended when you are transforming very few points and wish to give each a specific point number assignment.
- Store in New CRD File: This option writes the transformed points to a new CRD file while keeping the existing point numbers and coordinate data. You may also choose to input a number for Add to Point Numbers, but this is not required.
- Linework: This option allows for linework transformation. When this option is selected, options below become accessible.
- Automatic All Layers: This allows for the user to select all linework as part of the linear transformation.
- **Process Frozen Layers:** This option allows the user to select Frozen Layers to either be included or excluded from the linear transformation.
- **Manual Select:** This option allows for the user to manually select linework to be included in the linear transformation routine.



When **OK** is pressed, a second screen appears which controls the range of points to be translated.

Assuming you have 55 points in your file, you could "preserve" these 55 points by adding 100 to the point numbers and saving the transformed points as 101 through 155. If you choose **Overwrite Existing Point IDs**, the Add to Point Numbers option is not available. If you choose **Use New Point Numbers**, then you will be prompted to enter a new point number for each existing point to be overwritten (recommended only when you are overwriting a few points). You can even store the transformed points in a completely new CRD file by selecting **Store in New CRD File**.

Raising and Lowering Elevations: Users often ask, "How do I raise or lower elevations on a range of points?" The answer is the **Translate** option in the **Transformation** routine. To adjust elevation only, enter only the delta elevation (leave Northing and Easting at 0 translation).

Rotate

The ROTATE tab is used to rotate points in a coordinate file. Enter the desired degree of rotation into the degree of rotation data field. Specify the rotation base point. This can be accomplished by either entering the point number of the desired point manually, or by selecting the point using the **List** or **Map** icon. You may also enter in coordinates for the rotation point if the point is not present in the coordinate file. Lastly, you can define the rotation by referencing two points (such as "From 1, To 2"), then specifying the desired new bearing for these points. Even the new bearing itself can be computed from two points used as a reference.

The second screen appears, which allows you to set the range of points to transform and choose how to store the newly calculated points. For all rotations, the rotation value is written into the RW5 file as dd.mmss (the current angle format).

Scale

The scale tab is used to scale the points in a coordinate file. The northing, easting, and optionally, the elevation, are multiplied by the specified scale factor. Enter the desired scale factor in the scale factor field. Select the base point by entering the point number of the desired point manually, or by selecting the point using the **List** or **Map** icon. You may also enter coordinates for the scale base point if the base point for scaling is not present in the coordinate file. The coordinate of the base point will remain unchanged. All other points will scale. If the **Ignore Elevations** toggle is enabled, then only the northing and easting values are scaled. Note that you can scale your points from base coordinate 0,0,0 by entering a scale factor and answering Yes to the warning screen.



Raw Data Records

The transformation raw data records are expressed as one string per command with the values separated by spaces. These records will be recorded to the raw data file for processing purposes so that all Carlson processors will recognize the records and perform the transformation during reprocessing.

- **TRANSLATE**: Range Dx Dy Dz Process_Zero_Z
- **ROTATE**: Range Angle Base_Y Base_X
- SCALE: Range Scale Base_Y Base_X Use_Z
- ALIGN: Range From1 To1 From2 To2

Example:

CC, Translate, 8-9 200 50 0 0 CC, Rotate, 7 33.1234 79613.662 15619.725 CC, Scale, 7 1.5 79613.662 15619.725 CC, Align, 8-9 8 6 9 7



7.8 Calculator



This command eliminates the need to carry a separate calculator in the field. The calculator can be used to do scientific computations, standard calculations, conversions, triangle calculations, including angles, and curve calculations.

Standard Calculator

Most basic calculations can be performed using this tab in the calculator. Memory functions are also available.

💝 Calc	ulator					×
Standa	Standard Scientific Conversion Generic					
0	1	2	3	%	sqrt	<
4	5	6	7	1/x	+/-	CE
8	9	+	-	*	1	С
MR	MS	MC	M+			=

Scientific Calculator

Values can be entered on the X register by typing on the keypad. The values can be rolled up and down with the up and down - arrow keys and the Roll and RollD buttons on the screen. The Enter key finishes the entry of a number and pushes the stack. The C on the touch screen clears an entry. Additional functions on the screen can be obtained through touching the scroll [<] and [>] area of the screen.

误 Calcula	tor			×
Standard	Scientific	Conversi	on Gener	ric
SumY SumX				
т				0.0000
Z				0.0000
Y				0.0000
Х				0.0000
Sin	Cos	Tan	d'"	RollD
ASin	ACos	ATan	<>DMS	Roll
<		С		>



Conversion Calculator

Conversion values can be entered for various unit types and scenarios.

• M to Ft: This option provides for conversion between many units. Enter a value in any field and press Enter to find the conversion value.

误 Calculato	or				×
Standard S	Scientific	Conve	rsion	Generio	c
M-Ft Feet 215.35	Deg O		C LL Meters 65.63		Az-Br
> Int'l Feet 215.35043					
S	olve				

• **Degree**: This option allows you to convert to/from Degrees, Decimal Degrees, Gons/Grads, Decimal Degrees, and Mils (6400). Enter a value in any field and press Enter to find the conversion value.

裬 Calculator		×
Standard Scientific	Conversion	Generic
○ M-Ft ● Deg ○ DD.MMSS 33°22'11"	Gons/G	H-Grid C Az-Br Grads(400) 74691358
Decimal Degrees 33.3697222222	Mils(64	100) 395061728
Solve		



• Slope Distance to Horizontal Distance: This option allows you to convert slope distances with zenith angles to horizontal distances and vertical differences, and vice versa. See figure.

裬 Calculator			×
Standard Scientific	Convers	ion	Generic
C M-Ft C Deg Slope Distance	<u>H</u>		tal Distance
Zenith Angle 89°12'58"		ertical 1.3681	Difference
Solve SD/ZA		So	olve HD/VD

LLH - Grid: This option allows you to convert from Latitude/Longitude to grid system coordinates and vice versa. If you are configured for U.S. State Plane Coordinates, the routine conveniently displays your zone, and you can even change zones for quick calculations without altering your GPS zone settings in Job Settings. Otherwise, the calculation is based on your Job Settings GPS Zone. To solve for northing and easting, fill in the latitude and longitude and press Solve N/E. To solve for latitude and longitude, fill in the northing and easting and press Solve Lat/Long. You can set the state plane zone at the bottom of this dialog.

误 Calcula	tor			×
Standard	Scientific	Conversio	on Gene	ric
C M-Ft Lat DMS: N 38°38		<u>S</u> Nor	LLH-Grid thing 5950.3714	
Lon DMS	: • w (1'40"		ting 84816.465	55
Hgt: 2 Solve L		ID: Save	Hgt: 미 의 Sol	2 ve N/E
Apply Apply	y Localizatio	n 🗆	Apply Geo	oid

After completing a conversion, you may enter a point ID and press **Save** to save the coordinates to the current job. You can also change the type of transformation or zone system used. If you don't want NAD 83 (primarily used in the U.S.) you can go to **Job Settings, GPS** and change the Transformation type. For example, you could change the Transformation to UTM or NTF-France. Then, back in Calculator, your coordinate to Lat/Long calculation would be based on the configured transformation. Note that when converting Grid System Coordinates to WGS84 coordinates and going WGS84 to Grid, the geoid separation file (if any) is applied to the calculation.

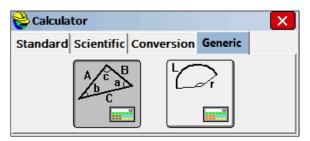
Az-Br: This does a straight, simple calculation converting azimuths to bearings. A prime example, shown below, would be converting an azimuth of 119.2547.



误 Calcula	tor		×
Standard	Scientific	Conversion	Generic
C M-Ft North Azi	muth	Bearin	H-Grid (Az-Br g 34'13"E
S60°34'1	3"E	○ 1 No ● 2 So ○ 3 So	g Code: orth-East outh-East outh-West orth-West
	Solve		

Generic Calculations

There are two types of calculations that can be performed from the Generic tab. Click the large, square icons to go to the Triangle or Curve calculator.





Triangle Calculator

The figure below shows the Triangle calculator. The top of the dialog box indicates the mode of calculation. To change the mode, simply use the pull-down and to select the desired mode.

- Side-Side-Side
- Angle-Side-Angle
- Side-Angle-Angle
- Side-Angle-Side
- Side-Side-Angle

ờ Triangle calculator	←
	Pi 👗 B
Side-Side 💌	P ₃ ^A ^{P₂}
Side(A):	<u>``</u>
21.1200	^ U
Side(B):	
15.8400	Clear
Side(C):	
26.4000	Solve
Select 3 points from:	

After choosing a mode, simply apply the values to the appropriate blank and hit Solve. Points from your current job can be selected to fill out the blanks as well. The points can be selected from the screen or from the point list by picking the appropriate button icon. After the calculations have been performed, you will see the Clear, Results, and View Triangle buttons. Clear will clear the entry fields. Results will show the results dialog again. View Triangle will draw the triangle on the screen connecting the points chosen for the calculation. The triangle calculator, using 3 points, is a convenient way to calculate the interior angle between 3 points. For example, if you were setup on 1, backsighting 10, and turned a 90 degree angle to 21, then the triangle defined by 10 to 1 to 21 would indicate a 90 degree angle at point 1.

😂 Triangle Solution	🛃 🗲
P ₃ C	
Side(A): 21.1200	^
Side(B): 15.8400	
Side(C): 26.4000	
Angle(a): 53°07'48.37"	
Angle(b): 36°52'11.63"	
Angle(c): 90°00'00"	¥



Curve Calculator

The figure below shows the Curve calculator. Simply use the pull-down at the upper left to select the desired method of curve calculation.

- Radius-Delta Angle
- Radius-Chord Length
- Radius-Arc Length
- De.g. of Crv.-Delta Angle
- De.g. of Crv.-Chord Length
- De.g. of Crv.-Arc Length
- Delta Angle-Chord Length
- Delta Angle-Arc Length
- Chord Length-Arc Length

😂 Curve calculator		
Radius-Chord Radius(R): 500.2100	Type Degree of Roadway Railroad	Curve:
Chord Length(C): 924.2500		2
Clear	Solve	
Select 3 points or an ar	: 📃 🗹 🔣	

The type of curve can be toggled between roadway and railroad. Values can be entered into the blanks by keyboard entry, by selecting points from the current job, from a point list, from the screen, or by selecting an arc drawn on the screen. Once the values are entered, the results are displayed on the screen. The results can be viewed by selecting the **Results** button. The curve can be viewed on the screen by selecting the **View Curve** button.

😂 Curve Solution	÷
$ \begin{array}{c} L \\ C \\ $	
Type Degree of Curve: Roadway	~
Radius(R): 500.2100	
Delta Angle(a): 134°59'41.08"	
Arc Length(L): 1178.5462	
Chord Length(C): 924.2500	
Tangent: 1207.4571	~



7.9 Manual Traverse



This command allows for manual entry of angles and distances and calculates sideshots or traverses from a known occupied point. If the direction is defined by a bearing or azimuth, a backsight point is not required. If the direction is defined by angle left or right or a deflection angle left or right, then a backsight point is required.

Manual Traverse is actually a **first** option of three for manual traverse and sideshot entry. A **second** option is to go to the Map screen, and at the command line (Cmd:) enter:

- "I" for Inverse, to inverse to an occupied point, or from backsight point to occupied point, -Then-
- "T" for Traverse or
- "S" for Sideshot, using angle codes 1-NE, 2-SE, 3-SW, 4-NW, 5-AZ, 6-AL, 7-AR following the prompting for angle and distance entry.

This style works strictly off the keyboard and does not require any screen tapping to switch from traverse to sideshot to inverse. The points plot on the screen as you go.

A **third** option for traverse and sideshot entry is to set the equipment type to Manual Total Station and enter the traverse and sideshot data within the Store Points command.

All three of the methods will store data to the raw survey file for re-processing and will allow entry of instrument heights and target heights. In the Map screen, **Traverse Defaults** (TD) will turn instrument and target height prompting on and off. All three methods allow for zenith angle prompting as an option.

The command centers around one main entry screen. You must enter an occupied point for traversing. You must also enter a target point number to calculate.

😂 Manua	al Trave	erse			0	F
Occupy F Backsigh		1	Start			
Target P		6	Desc:		1	Ξ
Bearing		TR Mod	le S45°00)'00"E	SE	•
Slope (%	6)		2.64%		SP	•
Horz Dis	t		4.2824		HD	•
Hdst	Sdst	sNo	hDno			
	Calculat	e		Store		



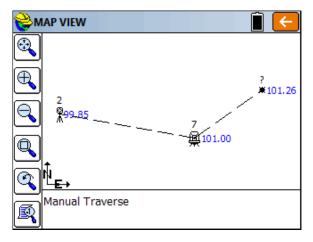
- Horizontal Angle: You must select a horizontal angle method. Options here are AR (angle right), NE, SE, SW, NW, AZ, SAZ (south azimuth), AL (angle left), deflection left, and deflection right. If a bearing or azimuth is selected for traversing, the backsight point number will become inactive. Only an occupied point is required to traverse forward by bearing or azimuth. All other turned-angle methods will require a backsight point number. The stored descriptions for the occupied point and backsight point will display as shown above (TRV MAG and TRV N in this case). Occupied points and backsight points can be selected from the list or the map using the appropriate icons. You can also enter point-defined angles, as in 6,7 for the direction from 6 to 7, or 6,7+90 for 90 degrees to the right of the direction of 6 to 7.
- Elevation/Vertical Angle Method: There are many ways to calculate a vertical differential between the occupied point and target point. The most common method is zenith angle (ZE). Manual Traverse also offers vertical angle, delta Z (elevation difference), slope by percent (SP), slope by ratio (SR), and known elevation (Z). To get the slope from point 6 to point 7, switch to SP mode and enter 6,7 for the slope.
- Distance Method: There are four methods of distance entry: Horizontal Distance (in which case the elevation line is inactive), Slope Distance; Slope Distance, No Elevation; and Horizontal Distance, No Elevation. Both Slope Distance methods will prompt for vertical angle/zenith angle, etc., but Slope Distance, No Elevation will calculate a zero-elevation for the target point number and will reduce the slope distance by the effect of the vertical angle/zenith angle. You can also enter the distance in the form of 6,7 for the distance from 6 to 7, or as 6,7/2 as half the distance from 6 to 7. Note that if you wanted to interpolate a point 12 midway between 6 and 7, you can use all 3 edit boxes to accomplish this. The azimuth or bearing could be entered as 6,7. The slope would be entered as 6,7, and the distance would be entered as 6,7/2. So, if point 6 is elevation 100 and point 7 is elevation 101, point 12 will have elevation 100.5.

₩		N			â 🔀
\bigcirc	FILE .	<u>V</u> IEW	<u>D</u> RAW	<u></u> 0G0	<u>T</u> 00LS
<u> </u>	Cmd:			Layer:	0
₽		:	11		
Q		2 • 9	·0.00 9.85		
Q		10 • 0.0	0		7 · 101.00
<u></u>	•				12 · 100.50
L R	N E→			6	· 100.00
E					10 ft



- Enter Elevation: If Enter Elevation is enabled, a check screen is activated to display the calculated elevation. From here you can override the calculated elevation with a new elevation. This option is useful in combination with Horizontal Distance for calculating points at a known distance and fixed elevation.
- **TR Mode**: Enabling **Traverse Mode** will cause the routine to "traverse up" to the target point number, so that the new occupied point number will automatically change to the last target point number, and the new backsight will change to the last occupied point. You can always manually change the fields for occupied point and backsight point and "force" a traverse, but enabling Traverse Mode will update these fields automatically, so that you immediately "move up", and are awaiting the next angle and distance entries. With TR Mode disabled, **Manual Traverse** defaults to sideshot mode.

When you are entering in the horizontal angle, distance, or elevation/vertical angle information, the program displays the current mode as an extra confirmation at the bottom of the screen. Hitting **Enter** from the last entry line, or tapping **Calculate**, or entering a **C** for calculate, will solve for the coordinates and display them at the bottom of the screen. Hitting **Enter** again, tapping **Store**, or entering **S** will store the points. Before storing, you can also tap the **Map** icon to see the location of the calculated point, in reference to the occupied point and backsight point.



Click **Back** to return. You always have the option to enter new angle and distance information, Calculate, check the Map, then Store, as desired. **Point in Direction** offers the flexibility to check point locations graphically prior to storing.



• **El/Off**: If El/Off is clicked on for Elevation mode, a "check screen" is activated that allows you to see the calculated elevation and potentially override it with a new elevation. This option is useful in combination with **Horizontal Distance** for calculating points at a known distance and fixed elevation. This screen also allows you to offset the point perpendicular to the computed traverse le.g. Enter positive for right and negative for left.

😝 Manual Traverse 🛛 (🌔	😂 Elevation/Offset	X
Occupy Pt ID: 1 Start Image: Constraint of the start Backsight Pt ID: 6 Desc: Image: Constraint of the start Target Pt ID: 6 Desc: Image: Constraint of the start Target Pt ID: 6 Desc: Image: Constraint of the start Target Pt ID: 6 Desc: Image: Constraint of the start F El/Off TR Mode N0°00'00"E NE Bearing NE 7 N0°00'00"E NE Image: Constraint of the start Zenith Angle 90°00'00" ZE Image: Constraint of the start Image: Constraint of the start Horz Dist 0.0000 HD Image: Constraint of the start Image: Constraint of the start N:5000.0000 E:5000.0000 Z:100.0000 Calculate Store Store	Pt ID: 6 Northing: 5000.0000 Easting: 5000.0000 Offset: 0.0000 Elevation: 100.0000 Set El to: 100.0000 Desc:	



7.10 Point Average



Standard Point Average: The standard **Point Average** command works especially well in conjunction with the Auto Store by Interval command found in the Survey menu. If you set the Auto Store by Interval command to storing by Time rather than Distance, you can also set the maximum number of points to store (e.g. 100), and in this way, store a specified number of readings at any desired time interval. Stored points will auto-increment from the entered Starting Pt ID. If the "Record Max Number of Points" is not clicked On, then storing will occur until the user ends the process by clicking the Red Stop icon or the Red X in the subsequent screen. The Auto Store by Interval dialog is shown below:

裬 Auto Store	by Int	erval			×
O <u>D</u> istance	X/Y:	10.0000	ft		
	Z;	10.0000	ft		
Time		5	s		
			_		
Starting Pt ID:		301			
Description:	A۱	/G <u></u> [€			
Record Ma	ax Numl	per of Points	: 10	0	



Point Average is a processing command useful in obtaining both the average value of a set of readings as well as estimates of the variation of the data. If 100 points are measured from 301 to 400, the calculation of the average is shown below:

B	Point /	Average			J 🧲
	On/Off	Point ID	Northing	Easting	Elev 🔺
	•	301	3466847.95	4899345.66	99.
	۲	302	3466847.93	4899345.67	99
	۲	303	3466847.94	4899345.67	99. 🗸
	•				▶
	Average	Coords: f	t StdDev: ft	Range	of Pts:
	N: 34668	47.9378	N: 0.0066	301-4	00
	E: 48993		E: 0.0045]≡[-7
1	Z: 99.00	00	Z: 0.0000		verage

Individual points can be turned on and off for purposes of the calculation. The standard deviation is presented. The range of points is entered using the standard SurvCE convention of dash and comma separators. For example, to average points 401 to 410 as well as 415 and 420 to 425, the entry format would be 401-410,415,420-425. Additional points can be added using the "From List" and "From Map" icons. When new points are added or points are turned on or off, clicking Average initiates a fresh calculation. To store the averaged coordinate values as a point ID, click the "Store to Disk" icon at the top of the screen. Click the back arrow to return to the main COGO menu screen.





GNSS Analysis Point Averaging: If under Job Settings, Options tab, "Apply GNSS Analysis" is turned on, then the Point Average methods and screen dialogs are completely changed within **Point Average**. This analysis approach deals with one Point ID (+ Description as an option) at a time and works if multiple measurements were taken on that Point ID, either as distinct Store Point exercises or as A for Average within Store Points. The method, however, is designed for a field procedure of distinct single point measurements using Store Point, storing the same Point ID (+ Description as an option), typically at intervals over a period of time, capturing different satellite configurations. By using this procedure, greater point positional certainty can be obtained through statistical analysis. The Store Points option of A for average can work similarly if a longer time interval between measurements is used, but the advantage of the individual Store Points approach is that the GNSS rover can be used for other work between returning to the same point to measure it again with the same point ID.

So, if you were mixing topo or data gathering work with key point, boundary point measurement, you could measure the key point, do 30 minutes of topo, measure the key point again, do another 30 minutes of topo, and repeat that procedure, accumulating multiple data on the same point ID for the key point, in preparation for "GNSS Analysis Point Averaging". If all of your work was "key" point measurement, you could simply sequence from one key point to another, returning to the same points over an extended time period. Then the GNSS Analysis method will calculate the measured points to greater certainty (as reported statistically), with blunder detection and blunder removal.

With GNSS Analysis, extensive testing has shown reliability of between 1 and 2 centimeters with multiple readings, but with statistical standard deviations of as little as 3 millimeters. Blunder detection is accomplished using the Chi Square Variance Test. The parameters and error estimates are hard coded in the preliminary release of this feature, based on thousands of point measurements. This trial, fixed parameter feature is provided with the caveat that most testing has been conducted with Topcon and Altus GNSS receivers, and for fixed antenna conditions involving low and secure antenna positions. The parameters for statistical analysis may not apply to your specific condition. These parameters will be converted to user-defined variables with suggested ranges for settings in subsequent releases based on reports from trial usage with a wider range of equipment.

Preconditions to GNSS Analysis: The following preconditions must be set for GNSS Analysis.

- The GNSS Receiver itself must offer the option to store GPS vectors and make this available to Carlson Software.
- File Job Settings Options Tab, apply "GNSSAnalysis" to average identical GPS Pts: IDs or IDS+Descs
- Both the CRD file AND the associated RW5 file of the same name must be on the same data directory: If you just copied a CRD file to a data collector without the associated RW5 file, GNSS Analysis will not work. The companion, same name RW5 file must be present on the same directory. Plus, the data in the RW5 has to contain RMS values, DOP values and vector data, stored based on the following two preconditions.
- File Job Settings Options Tab, enable Store GPS Accuracy in Raw File. This stores the HRMS, VRMS, PDOP and other DOP values necessary for the statistical analysis.
- File Job Settings Options Tab, enable Store GPS Vectors in Raw File When Available. This stores the base to rover vector data necessary for the least squares calculations used.



Job Settings			
w Job System	Format	Options	Stake
Use Control Fil			
Select File C:	\CarProje	ects\Data\Ne	ewJob2.cr
Time Stamp Ea	ach Point		-
Store GPS Acc		w File	1
Store GPS Vec			availabl
Use Code Tabl	e for Desc	riptions	
Recall Job Roa	d Files		
Auto Load Man			

Because it is important to use the same Point ID, and because SurvCE will naturally increment points, it is also useful to turn on "Avg Same Point ID" in the Height/Description prompt screen as shown below:

😂 Store Poin	t	🔽 🔽
N:418323.299 E:1779719.75 Z:390.7410	6.543 ore Avg Same Pt 5 HRMS:1.391 05 VRMS:3.215 PDOP:3.200 ALL	
Desc:	j==	<u> </u>
♥ BLD ■ CP		
≣Start		1,2 ↓↓●••

In this mode, if you measure a point for the second time, with the same ID, the program will assume you wish to overwrite it, will avoid the Point Protect screen and will display the duplicated points in a list as shown below: And on the next measurement, after two appear in the list, the auto-increment is disabled and the program will remain on the same Point ID until you enter a new Point ID to measure. In this dialog, the point you choose to store can be averaged, with any individual point turned on or off in the left column. Click the Store Icon to store the point. Otherwise, the last point measured will be stored. This Point Average screen shown below left appears within the command Store Points itself with the option "Avg Same Point ID" on, as above. The screen shown below right appears if GNSS Analysis is on, Store GPS vectors is on and Store GPS Accuracy in Raw File in on. So, the Store Points screen itself shows, in effect, the same dialogs as appear in Point Average, whenever "Avg Same Pt ID" is on. In that sense, the Point



Average command is a way to recall measurements and do point averaging later, after you take field measurements. Conducting the averaging by standard and advanced "GNSSAnalysis" methods can occur while in Store Points with "Avg Same Pt ID " on or later by going to Point Average. Observations appear as 0 in upper right of dialog, until the minimum of 3 raw measurements for calculation purposes are obtained. Clicking Enter proceeds to the next measurement, equivalent to tapping the Green Check. So, when repeating point IDs and remeasuring points, with Hgt/Description Prompt On, you can take measurements using GNSS Analysis with Enter for the measurement, hit Enter for the Hgt/Description Prompt, and hit Enter for the Analysis review. With Hgt/Description Prompt Off in Configuration, each measurement has a total of hitting Enter twice.

<mark> Point</mark>	: Averag	e		×	💝 н:	3/V:	3	(
On/Off	Point ID	Northing	Easting		Pt ID	N	orthing	Easting	Elevation	Obs (
•	7	418343.5570	1779731.3865		1	418	323.555	1779719.974	397.669	3
•	7	418343.5494	1779731.3967		•					<u> </u>
•	7	418343.5135	1779731.4166		GPS+	GLO	Blunder H	H Chi-sq	H Blunder	✓ ▲
•					6-1)	0.316	357.295	-0.395	; <u>;</u>
	Coords: fi	L StdDev: f1	t L	-	12-	0	0.515	1012.470	0.737	
N: 41834		N: 0.0160	-		•					
E: 17797		E: 0.0113			Pt ID:	1			1	_
Z: 398.0	800	0.0080	On/Off Aver		× Г	An	t. Freehar	d Apriori:1.		Run



Whether working from within Store Points or within the Cogo Menu, Point Average option, with GNSS Analysis on, AND with both vectors on, leads to analysis options as shown below:

1	<mark>)</mark> н: З	3/V	3	7			😂 H: 0∕ V:	0		4	2		U	X
	Pt ID	N	orthing	Easting	Elevation	Obs (Easting		Elevatio	n Obs	St	dDev H	Sto	Dev V
	1	418	3323.555	1779719.974	397.669	3	1779719.7	51	397.399	9 2	(0.022	0	.025
	•					►	•							►
	GPS+0	GLO	Blunder	H Chi-sq	H Blunder	· V 🔺	GPS+GLO	Blu	nder H	Chi-sq	Н	Blunder	٠v	ς 🔺
	6-0	1	0.316	357.295	-0.395	5 :	6-0	0	.156	10.180	☑	0.000)	0.0
	12-0	D	0.515	1012.470	0.737		12 0	-0	.476	0.000		0.685	5	0.0
	•					▶	•							▶
F	Pt ID :	1					Pt ID: 1			1=	2			
>	د ا	An	t. Freehar	nd Apriori:1.	Reset	Run	× 🗆 Ant	t. Fr	eehand ,	Apriori:	1.0	Rese	et	Run

The program defaults to the display above right, by auto-running the blunder removal until H=0 and V=0 in terms of potential blunders. By clicking Reset, the "original" blunder status of all observations can be viewed. This example has only 3 field measurements, and when the 3rd measurement is removed, the remaining two observations pass the statistical analysis parameters. After clicking Reset, you can click Run to allow the program to automatically remove blunders, distinctly in the H and V columns, to obtain the maximum remaining number of measurements that pass the statistical test. With Chi-Square set to approximately 23, the program seeks to get the maximum F test value for the x,y (H) calculation around 10 or less and the maximum Q value for the Z (V) under 1.

If you don't use "Run", you can allow the program to present the highest contributor to errors and then remove these one at a time. In this way, you are rejecting the single observation with the largest contribution to the sum of the squares (standardized residual). Repeat until all observations that qualify for rejection are removed. In the report, the External Reliability is the maximum point deformation, or the maximum effect of a theoretical undetected blunder on the final computed coordinate. The calculations use the covariance information found in the data accuracy estimates of the GNSS receivers. A least squares calculation is used to find the best center point.

Although designed for 5, 10 or more same points readings, here is an example of 3 field measurements and how the blunder detection works when identified and removed manually:



😂н: з	/ V: 3	(2)			<mark> </mark>
Pt ID 1 4 Blund 0.33 0.55	Northing 418323.555 er H Chi-so 16 357.29	5 🔽 -0.39	5 15.008	3	Horizontal Blunders: CHI-Square: 23.0259 Total: 3 2 Degrees of freedom Max at Obs: 3 Max F val: 1012.47 Err. level: 0.001% Nabla: 0.515 Significance: 99.999% Vertical Blunders: Most Significant Steps to eliminate them: 2
Pt ID:	1 Ant. Freehar	j≡	Reset	Run	QN Distrib.:4.4172Total:31 Degree of freedomMax at Obs:3Max Q val:42.031Err. level:0.001%Nabla:0.737Significance:99.999%

Start by entering the Point ID in the lower left of the dialog to study. Press Enter after selecting the point for the data to appear. The "worst" blunder is identified by highlighting to the left of the H or V column. So, in this case, click of the V to the right of the highlight. Prior to doing so, if you click the Report icon (highlighted with red circle), you see the Report at right which shows the high F Value for the horizontal component and also high Q value for the vertical component. The process of removing blunders will reduce these values to acceptable levels (also accomplished automatically by tapping "Run"). So, after removal of the first blunder (V), on the third observation, the next worst blunder appears below, which is the (H) on the same 3rd reading. Note that when one blunder on the same reading is already identified, the next blunder on that reading is identified by reverse coloring (here white, not dark):

😂 н: з/ v: :	2		, (F		<mark>ஜ</mark> Report 🧧 🧲
Pt ID Nor	rthing	Easting		Elevation	Obs 🤅	Horizontal Blunders:
1 4183	23.637	1779719.96	55	397.148	3	Most SignificantSteps to eliminate them: 1
•					▶	CHI-Square: 23.0259 Total: 3 2 Degrees of freedom Max at Obs: 3
PS+GLO Bl	under H	Chi-sq	н	Blunder V		Max F val: 1012.47 Err. level: 0.001%
6-0	0.387	406.657		0.471	13	Nabla: 0.515 Significance: 99.999%
12-0	0.515	1012.470	<u> </u>	0.737	0.	-Vertical Blunders:
•					▶	QN Distrib.: 4.4172 Total: 2
Pt ID: 1			2			1 Degree of freedom Max at Obs: 2 Max Q val: 13.999 Err. level: 0.001%
x 🗌 Ant.	Freehan	d Apriori:1	L.O	Reset	Run	Nabla: 0.471 Significance: 99.999%

Notice how the Q value came down after removing the first vertical reading. Next, remove the "reverse highlighted" (H) reading for the third observation, which in effect eliminates that third reading altogether:



😂 н: ()/V: 2				Report 🧲
Pt ID	Northing	Easting	Elevation	Obs (Horizontal Blunders:
1	418323.328	1779719.735	397.348	2	CHI-Square: 23.0259 Total: 0 2 Degrees of freedom Max at Obs: 2
Chi-sq	H Blunder		Date	Tin 🔺	Max F val: 10.18 Err. level: 0.001% Nabla: 0.156 Significance: 99.999%
LO.180 LO.180	✓ -0.026✓ 0.026		13/27/02 13/27/02	18:52 18:56	Vertical Blunders: Most SignificantSteps to eliminate them: 1
Pt ID:	1	QN Distrib.: 4.4172 Total: 2 1 Degree of freedom Max at Obs: 1			
ктр: х Г	-	Apriori:1.0	Reset	Run	Max Q val: 6.011 Err. level: 0.001% Nabla: -0.026 Significance: 99.999%

With the third observation entirely removed, the horizontal blunders are eliminated (now 0) and max F value is an acceptable 10.18. The vertical Q value is still at 6, and one more blunder has been identified that is "significant" enough that removal is necessary and recommended. This is the vertical reading on the first observation. Remove that to obtain the final result (use of observations 1 and 2 for horizontal, observation 2 only for vertical). Remember, remove to the right of the highlighted item (the H or V):

📚 H: O/V: O 🛛 🔊 📰 🗔 🗙	😂 Report 🗧 🧲						
Pt ID Northing Easting Elevation Obs 5	-Horizontal Blunders:						
1 418323.371 1779719.751 397.399 2	CHI-Square: 23.0259 Total: 0						
	2 Degrees of freedom Max at Obs: 2						
Blunder H Chi-sq H Blunder V Q V [Max F val: 10.18 Err. level: 0.001%						
0.156 10.180 🗹 -0.026 0.000 🔲 13,	Nabla: 0.156 Significance: 99.999%						
0.156 10.180 🗹 0.000 0.000 🗹 13/	Vertical Blunders:						
	QN Distrib.: 4.4172 Total: 0						
Pt ID: 1 I Degree of freedom Max at Obs: 2 Max Q val: 0 Err. level: 0.001%							
x Ant. Freehand Apriori:1.0 Reset Run	Nabla: 0 Significance: 99.999%						

Observation 1 was used for the H only, observation 2 for H and V and observation 3 was not used at all (those observations get a line drawn through as below). This same result is obtained by tapping "Reset". The next "worst" blunder is still highlighted, but there is no reason to continue the process--analysis parameters are satisfied.



📚 H: 0/V: 0 🕼 🕼 🗶	📚 Settings 🛛 🗸					
Pt ID Northing Easting Elevation Obs 5						
1 418323.371 1779719.751 397.399 2						
•	Apriori: 1.000000					
Obs Northing Easting Elevation Stat						
2 418323.407 1779719.758 397.373 FIXE	CHI-Square: 23.025851					
3 410323.665 1779720.125 398.005 FDX	QN Distrib.: 4.417173					
Image: Show Point Code Image: Show Point Code Image: Show Point Code						

The "X" in the lower left of the screen is a somewhat arbitrary designation category. If 3 or more observations are used and pass the analysis, the quality of the observations are ranked 1 through 4 as follows: 1=city center, 2=rural area, 3a=farm land, 3b=forest, 4=unproductive land. The calculation will "qualify" for one of these designations with sufficient observations. Clicking the Settings button shows the hardcoded Apriori, Chi-Square and QN Distribution values. These values were selected based on extensive testing with a variety of commercial GNSS equipment. The "Antenna Freehand" setting will impact the calculations. If the GNSS antenna is on a fixed tripod, that resets parameters for the least squares calculations in terms of expected errors. If "Antenna Freehand" is clicked on, errors from a potentially moving antenna will be higher.



Here is another example, collected in the field using A for Average within Store Points. Note how all 5 observations are used.

铃 н: (0/ V: 0			X	<mark>ಜ</mark> Report	←
Pt ID	Northing	Easting	Elevation	Obs 🤅	Horizontal Blunders:	
101	7718782.174	703258.563	59.822	5	CHI-Square: 23.0259 Total: 0 2 Degrees of freedom Max at Obs: 1	
	under H Chi-si			V 🔺	Max F val: 6.753 Err. level: 0.0019 Nabla: 0.224 Significance: 99.999	-
	0.224 6.753 0.171 3.008			፶ _	Vertical Blunders:	
•					QN Distrib.: 4.4172 Total: 0 1 Degree of freedom Max at Obs: 3	
Pt ID: 3b	101 Ant. Freehand	Apriori:1.0	Reset	Run	Max Q val: 0.558 Err. level: 0.001% Nabla: 0.048 Significance: 99.999	

Shown below is the right-side presentation of the statistically averaged point, including external reliability values and data on the duration of the measurement (delay), which in this case was 13 minutes. Longer delay values are recommended to obtain different satellite constellation configurations.

📚 H: O/V: O 🛛 🕼 💌 🔀								
StdDev	ι H	StdDev V	ExReliab H	ExReliab V	Delay			
0.050	0.050 0.051		0.200	-0.162	00:13:3			
•					►			
Obs		Northing	Easting	Elevation	Stat 🔺			
4	7718782.094		703258.471	l 59.781	FIXE			
5	77	18782.102	703258.501	L 59.758	FIXE			
Pt ID: 101								
3b Ant. Freehand Apriori:1.0 Reset Run								



8 Road

This chapter provides information on using the commands from the Road menu.

😂 JOB:20170213	1
<u> </u>	rvey <u>C</u> OGO <u>R</u> oad
1 Centerline Editor	🛾 🙆 Draw Template 🛛 🥪
2 Draw Centerline	5 <u>7</u> Utilities 🔛
<u>3</u> Profile Editor	👷 🛃 Store Sections 🛛 🛱
4 Draw Profile	👷 🔤 Stake Slope 🛛 🍾
<u>5</u> Template Editor	- O Stake Road



8.1 Centerline Editor



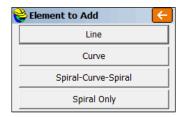
This command allows you to enter new centerlines, as well as recall and edit existing centerline files. Centerline files in SurvCE are ASCII files with a .CL extension. When the routine is selected, a dialog will appear in which you can load existing centerlines or begin entry of new centerline information.

😂 Input-Edit	Centerline		💽 💽						
C:\Carlson Projects\Data\DEMO.cl									
Start Pt ID:		N:	4959.8023						
Start Sta:	0+00.000	E:	4942.2812						
CL Element	Length	End Stat	tion						
∿ ⊾Line	127.6211	1+27.621							
 Curve	92.0000	2+19.621	L						
🔨 Line	88.7062	3+08.327	7						
Load Ad	ld Edit	Delete	EQ Save As						

- **Clear**: This icon, at the top of the screen, clears out all information in the dialog in preparation for entering a new centerline. With no centerline file loaded or saved yet, the file name in the upper left is displayed as "None."
- **Start Pt ID**: If the centerline starts on a point number that exists in your current coordinate (.crd) file, you can enter the point number here, and it will recall and display the starting coordinates. The point can also be selected from the list or map using the appropriate icons.
- Start Station: You must enter the starting station for the centerline. ("Station" is the same as the European term "Chainage.") Many surveyors and engineers prefer not to start centerlines at station 0. If the job backs up or needs to start further back along the centerline, this method will leave you with negative stationing. There are three centerline "forms" as set in **Job Settings, Units**. A starting station of 1500 can be displayed as 1+500 (metric, US-style, showing whole kilometers left of the "+"), as 1500.000 (pure decimal chainage, common to Europe), and as 15+00 (feet, US-style, sometimes also used on metric roads in Canada), often referred to as "station 15 plus 00". In all cases, you would enter it as 1500, but it would display in the correct format after pressing Enter. For example, you would see 1+500.0000 if configured to kilometers. The program will also accept use of the "+" in the entry of the station and will convert to the configured form after you press Enter.



- Northing, Easting: If the northing and easting are not recalled from a starting point number, you will need to enter the northing and easting for the start of the centerline. It is not necessary to enter the northing and easting if you use the Pick PL (pick polyline) option for defining a centerline, since the starting coordinates of the selected polyline are automatically used and would overwrite anything previously entered.
- Load: This command allows you to load an existing centerline for review or edit. SurvCE will check the integrity of the centerline file. This check will happen automatically and the user will have an opportunity to verify the data if errors are detected.
- Edit: Use this button to edit the highlighted element.
- **Delete**: Use this button to remove the highlighted element.
- Add: Returning to the starting dialog, you can add elements to get a centerline started. Typically, you will start with a line or tangent segment, but you can also start on a curve or spiral curve element. When you select Add, you get to choose which element to use. These options include:



• Add (Line): A tangent section of the alignment. This option allows you to enter a point ID or coordinates to define the end of the tangent, or enter the station, or distance and the direction. To force the element to be tangent to the previous element, toggle on the **Tangential to the previous elem** option. This will gray out the direction field and will compute the tangent direction and enter it for you.

癸 Line(Tangent) El	ement 🗹 🗙
Start Pt ID:	Sta: 3+08.327
Nor: 5125.9457	Eas: 5138.9099
End Pt ID:	
End Station:	Northing:
5+08.327	5324.5174
Length:	Easting:
200.0000	5162.7697
North Azimuth:	6°51'05.96652"
Tangential to the	previous elem.



• Add (Curve): A typical circular curve section of the alignment. The first element of the curve defines what the options for the second element can be (See Lists Below). The **RR** toggle allows the user to use Railroad definitions. The **Review** button allows you to verify the Tangent In and Tangent Out bearings or azimuths (depending on Job Settings, Format, Angle Display settings), as well as confirm PC and PT coordinates. For example, this allows you to verify computed Tangent Out bearings against paper plans, before continuing entry of new elements.

😂 Curve Element 🛛 🔽 🗙	Degree of Arc >	Radius >
PC Sta: 3+08.327	Arc Length 💌	Arc Length 💌
Radius >	Delta	Delta
	Arc Length	Arc Length
Arc Length 🔹	Chord	Chord
,,	Tangent	Tangent
R Pt ID:	External	External
Eas:	Mid-Ordinate	Mid-Ordinate
PT Pt ID:	Delta >	Chord >
Tang to Previous Element	Arc Length 🔹	Arc Length 🔹
	Arc Length	Arc Length
	Chord	Tangent
6°51'05.96652" RR Review	Tangent	External
	External	Mid-Ordinate
	Mid-Ordinate	

• Add (Spiral-Curve-Spiral): The Spiral-Curve-Spiral element is really just two implementations of Spiral Only (line-spiral-curve and curve-spiral-line). The advantage of Spiral-Curve-Spiral is that it completes three elements at once and is a fairly common application on high-speed highways. This routine also allows the user to define the spiral-curve-spiral using known points as long as the spiral in and spiral out lengths are entered first.

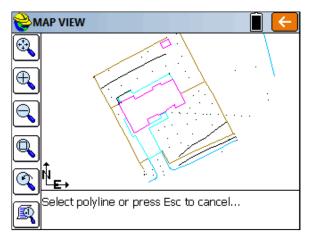
Begin Sta: 3+08.327 S	Spiral In Length: 300.0000
Spiral In Length: Spiral Out Length: 300.0000 300.0000 Data for Simple Curve: Left Right TS: Radius: Arc Len: SC: Tangent Out(North Azi): 90°00'00" PI: End (ST) Sta: Central PI Station: ST Review ST 	None Get Coords None Get Coords None Get Coords



• Add (Spiral Only): The Spiral Only element will handle a spiral between any line and arc segment (e.g. line-spiral-arc or arc-spiral-arc).

f	Spiral-Only Elem	ent				
	Spiral-In Northing: Spiral-In Easting: Spiral-In Station:	5125.94 5138.90 3+08.32	99			
	Spiral Length:		0.	0000		
	Spiral Direction:		•	Left	C Ri	ght
	Element At Spiral Ou	۲	Line	ିର	urve	
	Curve Radius At Spir					

• Pick PL: This option is only visible if you Clear the dialog. With this option, you can pick a centerline from any screen polyline, including polylines with arcs. When you choose Pick PL, you are immediately presented with the graphic screen, where you can pan by dragging your finger across the screen or zoom using the many zoom options. You can choose not to select a polyline (maybe there were none to select!) by pressing OK or Enter. When you select a polyline, it will highlight as a darkened polyline. After selecting a polyline and pressing OK or Enter you will see the polyline elements. Note that if you change the start station to 500, all the stationing for the polyline elements will change accordingly. This is also true regarding the starting northing and easting. If these are changed, all element coordinates will change accordingly, as can be verified using the Edit option.





• EQ: The EQ button allows you to enter station equations.

E	Station	Equations			\checkmark	X
	Original	Station Back	Station Ah	iead		
	3+50.000	3+50.000	1+00.000			
						_
	Sta Back:	0+00.000			Add	
	Sta Ahead:	0+00.000		R	emove	
		1				

• Save As: This saves the file. Enter a name.

Note: You can create new points with Input-Edit Centerline. When you enter and save a centerline, it will prompt "Do you want to save centerline points?" You may answer Yes and save point IDs for the start, end, PI, PC, radius point, PT and any key spiral points found in the file. In the same way, a centerline that you load can be re-saved with new coordinate IDs assigned to all key points, as long as you make some change, like adding a point number to one of the Pt ID fields for a CL Element. If you answer Yes to Save Centerline Points, the dialog box below appears. If you have entered point IDs of your own choosing in the Input-Edit dialogs, use the upper option. The lower option will auto-number from the starting point ID without regard to any numbers you've entered but will respect and not overwrite used points in the file. Points are not stored to the centerline file itself, so after loading a stored centerline, no point IDs will appear.

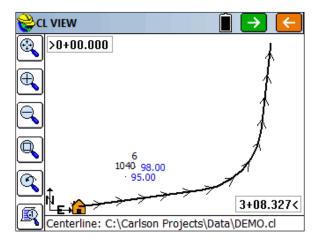
😂 Save CL File 🛛 🖪 🖬 🔽 🔀
Type: CL Files 🔽 Drive: C 🔽 🎓 📂 📰
C:\Carlson Projects\Data\ Backup CSGIS DOTCodes geoids
DEMO.cl
Name:



8.2 Draw Centerline



Draw Centerline will draw the selected centerline on the screen. All the zooming commands [Zoom In, Zoom Out, Zoom Window, Zoom Previous and Pan] are available to you in the **Draw Centerline** command. The program will automatically zoom to the extent of the centerline when drawn. If there are point numbers and polylines on the screen in that area, they will appear as well. This command only temporarily displays the centerline for reference and does not draw it on the screen as part of the .dxf file associated with the job. To actually draw the centerline as a permanent feature (unless erased later), use **Map** (globe icon), **Tools**, **Centerline**, **CL** to **Polyline**.





8.3 Profile Editor



Vertical alignments are typically referred to as profiles. The **Profile Editor** routine allows field entry of vertical alignment files for roads, sewers and other types of alignments. Vertical alignments can also be loaded and edited. In addition, high and low points can be calculated and the elevations of individual stations can be calculated. Vertical alignments, or profiles, are stored as files with a .PRO extension. In Carlson SurvCE, the station ranges of the profile and centerline do not need to match. As long as they have station ranges in common, any profile can be used with any centerline for all advanced Roading commands as well as Survey menu routines such as Offset Stakeout and Elevation Difference by Road Design files.

Profile Entry

Profiles are extremely easy to enter. When the command is selected, if no prior profile has been entered, you will encounter the blank Input-Edit Profile dialog. You can also obtain a blank screen and start a new profile by tapping the Clear icon (eraser) at the top of the screen.

😂 Input-Edit	t Profile		- EA 🛛		😂 Input-Edi	t Profile				F
None PVI Station	PVI El	Slope %	VC Len	-	None PVI Station	PVI El		Slope %	VC Len	
100+78.69	526.49	XXXXXXXX	XXXXXXXX		0+00		0	XXXXXXXXX	XXXXXXXXX	
106+00	529.1	0.5007	600							
114+29.25	520.8075	-1	600	-						_
122+52.25	541.3825	2.5	600							•
Check Sta El: 527.4642 Load Add		Slo	ow Zeroes pe as Ratio cular Curve n-Low Save As		Check Sta El: Load Ad	ld EQ	F		ow Zeroes ope as Ratio cular Curve h-Low Save	As

- **PVI Station**: PVI (Point of Vertical Intersection) is similar to a PI (Point of Intersection) for horizontal alignment. In some locations, the term VPI is used (Vertical Point of Intersection). You can start immediately by typing in the starting station under the PVI column. For our highway example, the starting station is 10078.69.
- **PVI Elevation**: The starting elevation is 526.49. So simply press **Enter** and move from the PVI column to the PVI El column and enter 526.49. Pressing **Enter** again moves onto the next PVI field, where you can enter 10600 for the next station, then 529.10 for the next PVI elevation.



- Slope %: Once a second station and elevation are entered, the program will calculate the percent slope. Alternately, if you enter under the Slope % before entering the PVI elevation, then the program will calculate the PVI elevation. The slope column is a nice check against bad entries in the PVI elevation column. In other words, you often expect even slopes, and you can check the computed slopes against the plans. Slopes can be entered as Slope as Ratio when that option is clicked, and if you click "Show Zeroes", the dialog will show a consistent number of decimals (typically 4) in all columns, causing the data and decimal places to line up vertically.
- VC Lng: Vertical Curve Length: For road jobs, you can enter the vertical curve length in this column. This is the total length of the vertical curve. If the length entered is 600, this means that the vertical alignment transitions through a curve (parabola) beginning 300 units (feet or meters) before the PVI and ending 300 units after the PVI. If a vertical curve is uneven, that is, it transitions from, say, 400 feet before the PVI to 200 feet after the PVI, then the curve must be entered using the form 400-200 (the before and after distances separated by a dash). SurvCE assumes all vertical curves are parabolas (U.S. road industry standard). However, you can tap the **Circular Curve** option when that applies. For sewer and water line alignments, there is typically no vertical curve transition, so this column can be left blank, or 0s can be entered for vertical curve lengths.
- Check Station: When the profile for a highway job has been entered in a dialog, you can also enter a value to Check Stations. This feature is at the bottom of the dialog. This will check the grades at any desired station. When entering stations, you may include the "+" that is often used, as in 12+680.5 (English) and 126+80.5 (metric).
- Load: The Load command presents a list of all previously stored profiles. When one is selected, it displays the profile information in the dialog. To load a stored file, you simply enter the name (for example, "Demo"). No file extension is necessary. Alternatively, you can select a name from the list and accept it by pressing **OK** or **Enter**.



• Add: The Add button will create a new row at the curser position with 0 entries (with the exception of slope, which will compute based on the 0 entries). If, for example, you touch line 2, where we have station 106+00, the Add command will allow you to insert a new row above. This would be necessary if you needed to start the profile at an earlier station. To add to the end of your profile, just click the down - arrow key at the right until a blank line becomes available and make your new entries.

误 Input-Edit	Profile			←	S	Input-Edit	t Profile			÷
None PVI Station	PVI El	Slope %	VC Len			None PVI Station	PVI El	Slope %	VC Len	
100+78.69	526.49	XXXXXXXX	XXXXXXXX			100+78.69	526.49	XXXXXXXX	XXXXXXXX	
106+00	529.1	0.5007	600			0+00	0	-5.2238	0	
114+29.25	520.8075	-1	600	-		106+00	529.1	4.9915	600	-
122+52.25	541.3825	2.5	600	•		114+29.25	520.8075	-1	600	•
Check Sta El: 527.4642 Load	107+25.5	Slo	ow Zeroes pe as Ratio cular Curve n-Low Save	As		Check Sta	107+25.5 d EQ F		ow Zeroes ope as Ratio cular Curve h-Low Save	As

• EQ: This button allows you to select the Centerline. There is also an option to set the Centerline to a Railroad format.

癸 Input-Edit Profile			F	💝 Current Centerline 🛛 🗸 🗙
None PVI Station PVI El 100+78.69 526.49 106+00 529.1 114+29.25 520.8075 122+52.25 541.3825 Check Sta 107+25.5 El: 527.4642 Load Load Add	0.5007 -1 2.5 Slo Cir	VC Len 600 600 600 000 000 000 000 00	As	Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327

• Remove: This button deletes the current line.



• High-Low: This button can be used to calculate high and low points.

😂 Input-Edit Profile			Cel 😂 High-Low points
None PVI Station PVI El 100+78.69 526.49 106+00 529.1 114+29.25 520.8075 122+52.25 541.3825 Check Sta 107+25.5 El: 527.4642 Load Load Add	0.5007 -1 2.5 Sho Slo	VC Len 600 600 000 000 Zeroes pe as Ratio cular Curve Save	PROFILE: High Point STATION 105+00.176 EL:528.0991 Low Point STATION 113+00.679 EL:522.9504

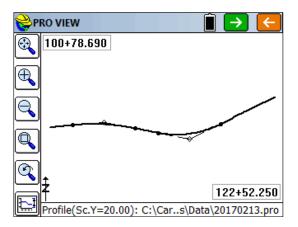
• Save As: This command will save your profile to a specified file name. There is no need to enter a file extension. If you want to save the file as Baker.pro, just enter "Baker". The Save As command will default to the current profile name. If you are entering a new profile, it will default to the current coordinate file name.



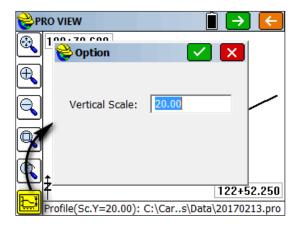
8.4 Draw Profile



The **Draw Profile** command will draw the selected profile on the screen. The profile will be exaggerated (typically 10:1 or 20:1) in order to maximize detail. You can control the vertical exaggeration by selecting the vertical scale icon, located at the lower left of the Draw Profile screen. All the zooming commands [Zoom In, Zoom Out, Zoom Window, Zoom Previous and Pan] are available to you in the Draw Profile command.



If you want to change the display scale, click the icon in the lower left corner. The dialog shown below will appear. Change the scale and tap **OK**.





8.5 Template Editor



Templates for roads, levees, ditches and other earthwork can be created in Carlson Software products such as Carlson Civil or Carlson Roads, or alternately they can be entered in the field using **Input/Edit Template**. These templates can then be used in Carlson SurvCE in the **Stake Slope** command, where the template is one of the design files for slope staking, along with the centerline and the profile. Templates are also used in **Stake Road** (for staking those portions of the road from left shoulder to right shoulder) and for **Elevation Difference** by Road Design Files. Templates can be reviewed graphically using the command **Draw Template**. Templates are not necessary for the command **Stake Offset**, found on the SURVEY tab. In Offset Stakeout, road or other cross slopes from centerline are entered within the command itself.

Currently, SurvCE uses only templates created in Carlson Civil and Carlson Roads or entered directly within SurvCE using the command Template Editor. Every point on a template has an ID such as "EP" and "SH" or "CB1". Templates in SurvCE have only one surface—the surface you are staking. To stake out a subgrade, you could enter the surface grade information, then use a vertical offset in **Stake Road** or enter the subgrade surface directly as a template.

After selecting **Template Editor**, you are presented immediately with the input dialog shown in the figure below. If an existing template is loaded (based on the last template used), you can clear the screen by clicking the clear icon (eraser) in the upper right.

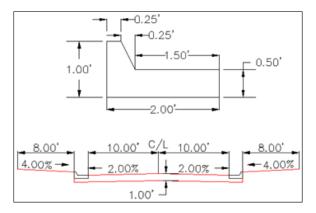
😂 Input-Edit *.tpl Fi	le			🖊 🧲	À Input-E	dit *.tp	l File			I	÷
C:\Carlson Projects\D GRADES: ✓ Left SURFACE Distance Slope 10.000 -2.000% CURB CB	ata\DI Righ	EMO.tpl nt Side Sar Right SURF Distance 10.000 CURB 6.000	ACE	ID	None GRADES: Left SURF/ Distance			ht Side Sa Right SUF Distance	FACE		
Add Edit	Rem	iove 👘 🕔	Jp D	own	Add	Edit	Ren	nove	Up	Dowr	n I
Cut/Fill	Sup	per Lo	bad S	Save	Cut	/Fill	Su	per l	.oad	Save	•

Template grades are entered top to bottom and extend out from the middle position of the template. If you are dealing with a symmetrical template, keep the **Right Side Same as Left** option enabled. This will reduce entries by half. Otherwise, you must select the appropriate side and use **Add** to add entries or **Edit** to revise. One trick, if you have non-symmetrical grades, is to keep Right Side Same as Left on and enter the symmetrical portion (perhaps the pavement lanes and first shoulder lane), then when you get to the outside shoulder or other lane where one side is different than the other, disable **Right Side Same as Left** and complete the non-symmetrical portion of the template. With the **Right Side Same as Left** turned off, you can click the words



Left SURFACE or **Right SURFACE** and the left or right columns become active for editing. Alternatively, you may simply click into the items in the columns and edit or add.

In the curb-and-gutter template shown below, the **Add** option is used to enter the grade breaks from centerline out to the back of shoulder.



Since templates used in Slope Staking help define all grades into the centerline from the slope stake, it makes sense to focus on the subgrades that are built by the dozer, motor grader or trimmer. Thus, despite all the surface grades involved, there are only three distinct grades in this example curb and gutter template between centerline and the pivot point of the cut and fill slopes: 12.00 at -2% (subgrade at back of curb), 0.01 horizontal and 1 vertical, and 8.00 at 4%. For the **Vertical** method, some positive horizontal distances must be entered, such as 0.01 or 0.001. By pressing **Add** in the dialog, we can enter the first two grades.

😂 Grade Dimensions 🛛 🔽 🗙	😂 Grade Dimensions	🔽 🔽
Percent C Ratio C Vertical Slope: -2 Distance: 12 ID: EP	 ○ Percent ○ Ratio Delta Z: 1 Distance: 0.01 ID: TC 	Vertical



Downhill slopes, going out from the middle of the template, are entered as negatives. Note that it is necessary to enter an ID for each break point in the template. This helps identify the description of the grade on the progressive slope stake report (e.g. from the outside going in, 8' at -4% to TC, 0.01' at -1 vertical to EP, 12' at 2% to CL). The shoulder slope going out (8' at 4%) is entered similarly, as above. The Input-Edit Template dialog now appears.

😂 Grade Dimensions 🛛 🔽 🗙	😂 Input-Edit *.tpl File 🛛 💽 🤇
Percent Ratio Vertical Slope: 4 Distance: 8 ID: SH	None GRADES: Image: Constraint of the state of the

You can press **Save** any time to save your work. Here the template has been saved and named "curb." Now it is time to enter the Cut and Fill slopes, which are used in slope staking. If the cut slope is 3:1, but the fill slope is 4:1, you would select Cut/Fill above and enter as shown. Distinct left side and right side cut and fill slopes can be defined. After entry of the cut and fill slopes, press **OK** or **Enter** to return to the main **Template Editor** dialog, and press **Save**. Templates can be drawn using the command **Draw Template**.

😂 Cut/Fill Grades		× 😫	TPL VIEW				
🗹 Right Side Same as Left	t						
○ Percent ● Ratio		€					
CUT - Slope:	3:1		J _	_	•	_	
FILL - Slope:	4:1			•	-		
_Right Side			<u> </u>				
CUT - Slope;	3:1	0					
FILL - Slope;	4:1		∎ ¶				
			Template	(Sc.Y=1.0	00): C:\Carj	ects\Data\	Curb.tpl

For highway projects or subdivision roads with cut slopes down to a ditch line, four template definitions may be necessary for slope staking: (1) Cut Left, Fill Right, (2) Cut Left, Cut Right, (3) Fill Left, Cut Right, (4) Fill Left, Fill Right. The appropriate template can then be used for any condition. Shown below is the Cut Left, Fill Right for a 2-slope (pavement and shoulder) road. The last slope in each column acts as the "pivot point" for the slope stake calculation. The fill slope is set at 4:1 and the cut slope at 3:1.



😂 Input-Edit *.tpl File	🛃 🗲	😪 Cut/Fill Grades 🛛 🔽 🗙
C:\Carlson Projects\Data\C GRADES: Rig Left SURFACE Distance Slope ID 12.000 -2.000% EP 8.000 -4.000% GB 12.000 -3.000:1 BD	Curb.tpl ht Side Same as Left Right SURFACE Distance Slope ID 12.000 -2.000% EP 8.000 -4.000% GB	 ✓ Right Side Same as Left ○ Percent ● Ratio Left Side CUT - Slope: FILL - Slope: 4:1
	nove Up Down per Load Save	CUT - Slope; 3:1 FILL - Slope; 4:1

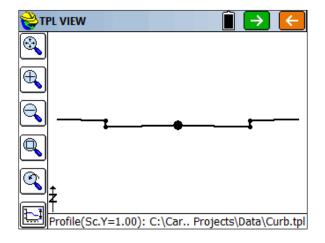
Using this template, cut slopes on the left side of the road will find the pivot at the base of ditch, while fill slopes on the right side of the road will pivot from the edge of shoulder.



8.6 Draw Template



The **Draw Template** command will draw the selected template on the screen. All the zooming commands [Zoom In, Zoom Out, Zoom Window, Zoom Previous and Pan] are available to you in the Draw Template command. Tap the **Menu** button to exit this command. The figure below illustrates this command using the "Highway Road.tpl" template.



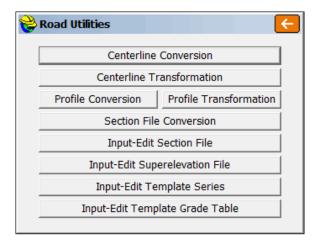


8.7 Utilities



Road Utilities includes necessary routines to convert centerlines, profiles and cross-sections from other formats to the formats used by SurvCE. SurvCE uses ASCII file formats for centerlines (".cl" files), profiles (".pro" files) and cross-sections (".sct" files). These same formats are used by other Carlson products such as Carlson Civil (formerly SurvCADD), Carlson Survey, Takeoff and Construction.

Road Utilities will also scale up or down centerlines and profiles, usually to convert between metric and English units. In addition, Road Utilities includes a command for entering a superelevation file (".sup"). This file can serve as an optional input file and react with templates in commands such as **Stake Road**, **Slope Staking** and **Elevation Difference**. Road Utilities has an option for a Template Series file (".tsf" file). This file will transition from one template to another automatically between designated stations, as long as the templates share identical IDs. The Template Series file can be substituted for a standard template file in **Slope Staking** and **Stake Road**, wherever design files are applied. Finally, a "Template Grade Table" can be entered in Road Utilities, which designates slopes and offsets that apply left and right of centerline for any road segment, between which a proportional grade and lane width transition is calculated. Template Series files and Template Grade Tables are alternate methods of transitioning roads of variable width or slope and should not be used in combination in the same station range.





File Conversion and LandXML: The LandXML file format is becoming an encouraged standard of many departments of transportation (DOTs). This standard is also recommended by Autodesk, Bentley and Carlson. LandXML files have an ".xml" extension and may contain multiple road design files including centerlines, profiles, and cross-sections. The "header" lines within the ".xml" file will indicate what design files are included. In some cases, several files of the same type, such as three or four centerlines or profiles, may appear in the same LandXML file. As more and more software companies offer LandXML file output, this file type may become the preferred form of data exchange. Be aware that each company tends to implement the LandXML format in slightly different ways, much like DXF files for drawing data exchange were sometimes slightly different in format between Autodesk and Microstation, or from release to release. Therefore, if a LandXML file containing centerlines, profiles or cross-section files fails to convert, it is recommended that the file be emailed to Carlson Software so changes can be made in SurvCE to enable conversion. LandXML is an evolving format that is likely to solidify in the near future.

Centerline Conversion

This command converts horizontal alignment files to and from the Carlson centerline format (*.CL). Supported file types include:

- ASCII Inroads (.ASC)
- ASCII LDD (.TXT)
- Caice (.KCP)
- CLIP (.PLA)
- Geopak (.OSD)
- cutsheetc)
- LandXML (.XML)
- Leica (.GSI)
- MOSS (.INP)
- SDMS (.ALI)
- SDR (.SDR)
- SMI Chain (.CH)
- TDS (.RD5)
- Terramodel/Geodimeter (.RLN, .ALN and .ARE formats)



The SurvCE format has a ".CL" extension. These source files can be loaded into SurvCE using **Data Transfer**, located in the File menu options. When performing the conversion, and selecting a particular format, SurvCE automatically looks for the corresponding file extension.

💝 Road Utilities 🧲	😜 Import/Export Centerline 🕼
Centerline Conversion Centerline Transformation Profile Conversion Profile Transformation Section File Conversion Input-Edit Section File	LandXML File (*.xml) C:\CARLSON PROJECTS\DATA\LINN.XML New File CL File (*.cl) C:\CARLSON PROJECTS\DATA\LINN.CL
Input-Edit Superelevation File	New File Existing File
Input-Edit Template Series	Conv. type: LandXML Single
Input-Edit Template Grade Table	Import to CL Export to LandXML

Report Icon for LandXML Files: If you are importing a LandXML file specifically, you can click the Report icon left of the "Return" icon in the upper right of the dialog, and review the source of the data as shown:

😂 Import/Export Center	ine 🔎 🗲
LandXML Info	
1.Version:1.0, Project:20 2.Created using:Carlson S Software 3.Units:Imperial, area:squ linear:USSurveyFoot, volu temperature:fahrenheit, p angular:radians, direction	SurvCE Software, Carlson JareFoot, Ime:cubicFeet, pressure:inHG,
0	к
Import to CL	Export to LandXML



Conversion: Clicking **Existing File** in the upper right (in the Land XML section) will load the file, and clicking **New File** under the CL File section will save the centerline file in the correct format for use in SurvCE. To convert in the opposite direction, select **Existing File** under the CL section to recall a SurvCE centerline file, and then click **New File** in the upper left (under LandXML file) to save it back to a LandXML file, for use in other software.

For file types in which both Import and Export options are available, the conversion procedure forms a "criss-cross": You bring the files into SurvCE by going upper right ("Existing") to lower left ("Select New"). You send the files back to the "non-SurvCE" format by going lower right ("Select Existing") to upper left "New".

When the files have been selected, the appropriate action is highlighted below, "Import to CL" or "Export to <type>". When the process is completed, the program announces "Process Done," and you are free to move on to the next command. Most formats only convert to SurvCE and not back again, and therefore only have "one-way" dialogs. These include ASCII-Inroads, ASCII-LDD, Geopak, Moss, TDS and Terramodel/Geodimeter.

Importing TDS RD5 Files

Importing TDS RD5 Files: If TDS is selected, centerlines can be converted one-way to SurvCE centerlines (centerline files CANNOT be converted back to TDS files). It is important to note that the TDS RD5 file is a dual centerline and profile file. Because the TDS RD5 file does not display the starting station, an extra dialog will appear requesting starting coordinates (which can be recalled from a point) and a starting station.

📚 Enter data	X
Starting Station:	0+00.000
Point From File:	
	1=
Starting Northing:	0.0000
Starting Easting:	0.0000

Verify the Conversion

It is recommended that after converting centerlines, profiles or cross-section files to SurvCE format, you go to the Editor and Draw options for these file types and review the data to verify that the correct file was converted and that the conversion was successful. So, for example, after converting a centerline from Inroads format to SurvCE ".cl" format, go directly to **Centerline Editor** in the Roads menu and verify the data.



Recognizing File Formats

For reference, portions of four of the file types are shown below, as they might display in a Text Editor. The LandXML, SurvCE and SDR examples all reference the file DOT1.CL. These displays may help you recognize these file types in the future. The new LandXML format, endorsed by many Departments of Transportation in the United States, may soon become the standard in the future for internet transfer of roading and other types of design files.

LandXML	<pre><coordgeom> </coordgeom></pre> <a a="" here<=""> <a a="" here<=""> <a a="" here<=""> <a a="" here<="">	0DNMSDR33 V04-04.24 Jul-29-99 14:49 122211 28KIDOT1 1 06NM1.0000000 29NM10078.6900 313.108056 10000.0000 29NM10078.6900 313.108056 10000.0000 30NM10579.9406 9380.4366 32NM11767.2070 7877.9045 30NM11767.2070 7877.9045 30NM12428.9412 6254.1479 32NM1443.1116 -11459.1600 30NM12620.477 5004.1230 30NM1287.5650 -2531.7846
SurvCE	0,10078.69000,L,10000.0000000,10000.0000000 0,10927.33000,L,10579.94056914,9380.43661675 0,935012766,R,2213.9951283,1549.51682467 0,9.35012766,R,2213.9951283,1549.51682467 0,12844.56000,PT,11767.20701020,7877.90450628 0,14792.27000,L,12842.84117284,6254.14793824 0,14792.27000,P,12842.84117284,6254.14793824 0,14792.27000,P,12842.84117284,6254.14793824 0,7125600000,R,3289.62929108,74.23974329 0,16235.38163,PT,13562.04766716,5004.12304528 0,24641.89003,L,17287.56502100,-2531.78459252 0,24641.89003,T,17287.56502100,-2531.78459252	HR++++++++++++++++++++++++++++++++++++

Centerline Transformation

This routine is designed primarily to convert centerline data from Metric to Survey Feet or from Survey Feet to Metric. The image below shows the dialog and scale factor when converting from Metric to Survey Feet.

😂 CL Transformation	←
Current CL File:	
Selec	t File
Scale Factor: 3.28	0833333
Metric to Survey Feet Survey Feet to Metric	Apply scale factor for start station
C Custom Scale Factor	Apply Scale Factor



Apply scale factor for start station: If this option is enabled, then the starting station will be converted using the scale factor. For example, a start station of 1000 would become 3280.833. If disabled, the start station would remain at 1000. If the goal is to change the starting station by a certain amount unrelated to the scale factor, then you must use **Input-Edit Centerline** and enter a new start station in the initial dialog. This will automatically translate all stations in the centerline by the appropriate amount.

When **Apply Scale Factor for start station** is enabled, the centerline is adjusted by the scale factor, after a confirming warning screen.

Profile Conversion

This command converts vertical alignments to and from the Carlson profile format (*.PRO). Supported file types include:

- ASCII-LDD (.TXT)
- Caice (.KCP)
- CLIP (.ALZ)
- ISPOL (.RAS)
- LandXML (.XML)
- Leica (.GSI)
- MOSS (.INP)
- SDMS (.PRO)
- SDR (.SDR)
- SMI (.CH)
- TDS (.RD5)
- Terramodel/Geodimeter (.RLN, .ALN and .ARE)



The SurvCE format has a .PRO extension. These source files can be loaded into SurvCE using the **Data Transfer** feature in the FILE tab. The conversion screen is similar to Centerline Conversion, with the characteristic 'criss-cross' logic for 2-way conversion (LandXML and Leica) and one-way import only conversion for the other options.

😂 Import/Export Profile	🥪 🧲
LandXML File (*.xml) None	
New File	Existing File
PRO File (*.pro)	
None	
New File	Existing File
Conv. type: LandXML	▼ I Single
Import to PRO	Export to LandXML



The SurvCE Profile File Format: It should be noted that of all the SurvCE file types that are ASCII and therefore viewable in standard text editors, the profile (.pro) file has the simplest format. The format is station, elevation, length of vertical curve, and description for road profiles. For example, the Demo.pro file that is typically provided with the software has the following four lines (which can be viewed in Notepad):

0.0000, 997.0000, 0.0000, 200.0000, 1005.0000, 200.0000, (200 foot vertical curve length) 308.0000, 1003.9200, 0.0000, 0.0, 0.0, 0.0 (this is an "end-profile" line)

Profile files can be created from within SurvCE but are simple enough to be hand-entered using a text editor as well. Unequal vertical curve lengths can be entered in the form 150-50, indicating 150 units to the point of vertical intersection and 50 units to the point of vertical tangency. Other ASCII file types, such as centerlines, can be deciphered, but are generally of a more complicated design and are best created using the editors provided within SurvCE.

Profile Transformation

Like Centerline Transformation, this routine is primarily used to scale a profile up or down to go from Survey Feet to Metric or from Metric to Survey Feet.

😝 PRO Transformation	←
Current PRO File: C:\Carlson Projects\Data\201702	13.pro
Select File	
Scale Factor: 3.2808333	33
Apply scale factor for	start station
 Metric to Survey Feet Survey Feet to Metric 	Translate
Custom Scale Factor	Apply Scale Factor

Unlike **Centerline Transformation**, **Profile Transformation** can directly translate the profile up or down. You can also scale the profile stationing and elevations. If you want to apply a translation to selected stations, tap the **Translate** button.



The Translate option leads to its own dialog of entries, which allows you to translate both the stationing and the elevations, as shown below. In this way, you can make the starting station 1000, or raise the entire profile 15 feet or meters.

📚 Translate PRO	🔽 🧲
Range of Stations: 10078.6900-12252.2500 List of Stations:	
10078,6900 10600.0000 11429.2500 12252.2500	Change station: 0.0000 Change elevation: 15
End Station	

By default, the entire range of stations is selected. If you wish to only translate a range, highlight the beginning station, then click **End Station** and highlight the end station. Next, enter the amount to translate in the **Change Station** box. You may also translate the elevation using the **Change Elevation** box. **Tap OK when you are finished.**

Section File Conversion

This command converts section files to and from the Carlson section file format (*.SCT). Supported file types include:

- Caice (.FFF)
- CLIP (.TRV)
- Geopak (.XRS, .XSR, .SOE & .TXT)
- IGRDS (.LIS, .RDS & .TXT)
- Inroads (.TXT)
- ISPOL (.SC1 & .RAS)
- LandXML (.XML)
- Columnar Text (.TXT, CSV & .ASC)
- Terramodel/Geodimeter (.XSC)

The SurvCE format is ".SCT". Section files are used for **Stake Slope**, **Stake Road** and **Elevation Difference**. **Cross-section Survey** also has the ability to output section files. TDS will store cross-sections in an RD5 format that behave as a series of templates, following "rules" for slopes coming from the design profile grade. You can import TDS-style cross-sections using **Input-Edit Template Series** within Road Utilities, and for "Files of Type", select TDS.



误 Import/Export Section	File 🛛 😺 🧲			
LandXML File (*.xml)				
C:\CARLSON PROJECTS\DA	TA\TESTSECTION.XML			
New File	Existing File			
SCT File (*.sct)				
C:\CARLSON PROJECTS\DA	TA\DEMO.SCT			
New File	Existing File			
Conv. type: LandXML	•			

Note that if you select XML Info at the top of the screen, you'll see some of the "header" information associated with the XML file to be exported or imported.

<mark>ề</mark> Import/Export Secti	ion File		i 🔪	←
LandXML Info				
1.Version:1.0, Project:20170213 2.Created using:Carlson SurvCE Software, Carlson Software 3.Units:Imperial, area:squareFoot, linear:USSurveyFoot, volume:cubicFeet, temperature:fahrenheit, pressure:inHG, angular:radians, direction:radians.				
ОК				
Import to SCT		Export	to LandXMI	-



To export to LandXML, you need to load a LandXML file that already contains a centerline covering all or part of the station range in the SCT cross-section file. Otherwise, you will see an error message.



Despite the message, you can add the horizontal alignment portion to the LandXML file after creating the file with sections only. However, if you first create a LandXML file containing one or more alignments, then choose that existing LandXML file to export to, you can select among those centerline alignments when making the cross-section file.

😂 Select LandXML Alignment	×
DEMO	
1	

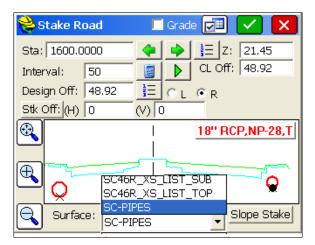
Section files in SurvCE can contain descriptions useful for reference in other routines such as **Stake Road**. If descriptions are found in the source section file, they will be captured by the import process into the ".sct" file for use in SurvCE.



Pipes running longitudinally along horizontal alignments can be imported in the form of crosssections using the Columnar Text form. The example below shows the layout of the pipe format that is recognized by SurvCE.

STA, Offset, FL elev., Link - ID, Link - Library Item, Type 13+00.00, 52.13, 22.32, NP-26, 18" RCP, T 14+00.00, -47.61, 22.08, NP-1, 18" CMP, T 14+00.00, 49.63, 22.02, NP-26, 18" RCP, T 15+00.00, -39.58, 21.78, NP-1, 18" CMP, T 15+00.00, 49.15, 21.73, NP-27, 18" RCP, T 16+00.00, -38.00, 20.22, NP-3, 24" RCP, T 16+00.00, 48.92, 21.45, NP-28, 18" RCP, T

Within Stake Road, Section Method, the pipes can then be loaded as a cross-section file and the pipe inverts can be staked in the same way that road cross-section points can be staked. The pipe format is recognized and the pipes display with their correct diameter shown. Note the ability of the program to display the pipe size, captured as the 5th field in the ASCII file (above):



Input-Edit Section File

This routine is a convenient cross-section editor. It can be used for entering new sets of crosssections or for editing and reviewing an existing set of cross-sections. One nice application is **Slope Staking**. If you know the left and right "pivot points" on stations to be slope staked, you can enter very simple, two-point cross-sections consisting of the left pivot offset and elevation, and the right pivot offset and elevation. Then, without taking a cheat sheet into the field, you can slope stake by cross-section method, and the program will seek these pivot points, and even interpolate the correct pivot points between entered cross-sections.

A better approach would be to include all break points in the sections from pivot left to pivot right, along with descriptions. Then Slope Staking will report the progressive information to grade each point from the catch all the way into centerline. This "section-based slope staking" is a cross



between user-defined (where you need the cheat-sheet!) and design files, where the pivot offsets and elevations are taken from the pivot points in the template as they react with the profile and superelevation files. Sections used in **Stake Road** should be complete cross-section files, with all offsets, to enable precise, interpolated stakeout within the left-to-right range of the sections, on station, or at interpolated stations.

The Input-Edit Section File routine begins by prompting for a cross-section file name. If you wish to start a new cross-section file, just enter a new name.

😂 Section File 🔹 🗈 🔽
Type: SCT Files 💌 Drive: 🕻 💌 彦 📴 🥅
🗁 C:\Carlson Projects\Data\
🛅 Backup
CSGIS
DOTCodes
🚞 geoids
Pictures_RadioTowers
DEMO.sct
Name: DEMO.sct

If you choose to select an existing cross-section file, such as DEMO.sct, after selecting the file, you will see the "Section List" dialog.

Section Lis	st: DEMO		←
Station:			
0+50.000			
1+00.000			
1+50.000			
1+53.272			
2+00.000			
2+50.000			
2+90.588			
3+00.000			
Add	Edit	Remove	Clear
EQ	Load		Save As



From this dialog, you can Add stations, Edit existing stations, Remove stations, Load entire new cross-section files, Save As (to save your changes to the current loaded file or to a new cross-section file), and Clear the list of stations (not recommended unless you want to start from scratch). Select Edit to review a station.

췆 Edit Sta	ation:1+5	3.272	🗾 🔽 🔀
Offset	Elevation	Description	_
-100.000	1004.253	INTERPOLATE	D
-63.461	1003.229		
-54.358	1002.973		
-21.891	1001.976		
-6.779	1001.562		
31.074	1000.546		•
1400.000	000 000	THE PROPERTY AND A	
Edit Station: 1+53.272			
Ado	d l	Edit	Remove
Up		Down	Clear

In this dialog, you can **Add**, **Edit**, **Remove**, **Rearrange**, or **Clear** existing offsets and elevations. Note that cross-section offsets are negative for left of centerline and positive for right of centerline, and can have descriptions such as SH, EOP, CL, Ditch, 21, 22, 23, etc. These descriptions, where they exist, are potentially useful for description-based interpolation between stations, as applied in **Stake Road**. If you want to add an offset at -42.867 called RP, click **Add**. You don't have to highlight the correct offset to add above — the software will sort and place the new entry appropriately.

😂 Edit Section Offset:		
Offset:	-63.461	
Elevation:	1003.229	
Description:		ÊΞ

When you click **OK**, your new entry will be in the list.

The Edit box leads to the same entry dialog as Add. Remove will provide a warning and then delete the highlighted offset and elevation. Up and Down should not be used unless a file conversion led to out-of-order listing of offsets and elevations. When you click OK from the station edit dialog, you can save the revised cross-section file back in the section list dialog.



Input-Edit Superelevation

Roads can contain one or more curves, and each curve can have its own superelevation data. This data includes start station for super transition, station for full super, percent of full super, station for end full super, and station for ending the super transition back to normal crown. In SurvCE, each superelevation data set for each curve would be entered as a "line" of superelevation data in the ".sup" file.

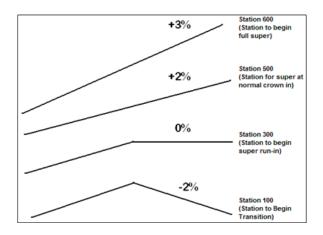
C	Superelevation List: 20170213				+
	Beg Trans	Run-In	Norm Out	Run-Off	End Trans
	•				•
	Add	Ed	lit Re	move	Clear
	EQ		Load	S	ave As

If we had two curves, both with superelevation, then we would do two Adds using this dialog. Let's say, for simplicity, that we have a road with a 2% "normal crown" which has one curve to the left followed by one curve to the right, with the following information:

	Curve 1	Curve 2
Start Super Pivot	Sta: 100	Sta: 2200
Full Super	Sta: 600	Sta: 2500
Full Super %	3% Left	4% Right
End Super	Sta: 1400	Sta: 3500
End Super Pivot	Sta: 1900	Sta: 3800

The first curve to the left goes through three stages as it pivots into full super: (1) the right-side pivots to "flat", (2) the right-side pivots to "reverse crown", where the slope is the same across the template and (3) both the right and left sides pivot from the hinge point (centerline) into full super. All of these key pivot points are entered in the superelevation dialog.





You enter all these key stations (begin, flat outside lane, reverse crown, full super) both going up to full super and transitioning back down to normal crown. Recognizing that the normal crown of -2% transitions from station 100 through a slope of 5%, the transition is 1% per 100 feet, assuming an even rate of transition. Therefore, a "flat" outside slope occurs at station 300, reverse crown at station 500 and full super at station 600, as shown. You will need to compute these stations in advance. These intermediate stations are entered in the superelevation dialog to allow for different rates of transition from normal crown to flat to reverse crown to full super. Normally, the rates of transition are consistent. Note that super left or right is always entered as a positive percent slope — the road centerline curve direction will control the direction of pivot. You are now ready to click Add and enter in Curve 1.

裬 Add Super (Stations):	🔽 🔽
Begin Transition: 1+00.000	Begin Run-In:
Reverse Crown rate in:	5+00.000
Grade Slope(%): 3.000 Curve Type:	Spiral Circular
Max slope of Full Super(%) Begin Full Super:	: 3 End Full Super:
6+00.000 Reverse Crown rate out:	14+00.000 15+00.000
Curve End Run-Off:	End Transition: 19+00.000

When you click **OK**, the first line of the superelevation dialog is filled in. Curve 1 is complete.



Next, we enter Curve 2 as follows, using similar logic.

误 Edit Super (Stations):	🔽 🔽
Begin Transition:	Begin Run-In:
22+00.000	23+00.000
Reverse Crown rate in:	24+00.000
Grade Slope(%): 4.000	Design Speed: 35.00
Curve Type: Max slope of Full Super(%)	Spiral Circular
Begin Full Super:	End Full Super:
25+00.000	35+00.000
Reverse Crown rate out:	36+00.000
Reverse End Run-Off:	End Transition:
Curve 37+00.000	38+00.000

When **OK** is clicked, the two curves are complete and the summary dialog appears. There is one line (or row) for each curve.

Note: If any of the columns are too narrow to display all the text, you can "grip" the vertical line separating columns, much like in programs such as Excel, and make the column wider.

👌 Superele	vation List:	20170213		÷
Beg Trans	Run-In	Norm Out	Run-Off	En
1+00.000	3+00.000	15+00.000	17+00.000	19-
22+00.000	23+00.000	36+00.000	37+00.000	38-
•		1		Þ
Add	Edit	Remove	e Clear	ſ
EQ	Loa	d	Save As	

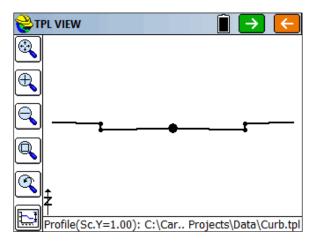
The superelevation file is one of the optional "roading" or "design" files in **Stake Slope**, **Stake Road** and **Elevation Difference**. After a superelevation file has been entered and saved, it will appear as the default superelevation file in all of these commands, unless removed from the design file list by the user.



Input-Edit Template Series

SurvCE allows for two types of transitioning: (1) a single template can transition by being "acted upon" by template transition files (made in Carlson Roads, Topsite, Leica Site Manager or Carlson Civil) and superelevation files, or (2) a template series file can transition between several templates sharing identical IDs but having different slopes and widths between ID points within the templates.

You can load an existing TDS template series file, in the RD5 format, by clicking Load, then clicking the down - arrow for Type of File, and selecting TDS format. TDS templates always have IDs and the same number of template points per cross-section, so once imported, they behave exactly like SurvCE-defined templates. Using the Draw Template option, any particular template in a template series file can be selected and displayed as shown:



The Template Series approach can even be used to transition from normal crown to superelevation, avoiding the need to use superelevation files. The Template Series approach is commonly used to expand the width of a lane to accommodate, for example, a passing lane. Since template IDs must match, if a "special slope" lane "appears" for a certain station range, then the Template Series approach can still be used as long as you add the extra ID point (e.g. EP2) to the normal template, perhaps making that point 0.001 units in dimension initially. In the second, transitional template, the EP2 lane can have the full width of 3.5 meters or 12 feet or whatever applies. If the transition starts at station 500 and ends at station 600, EP2, will be 1.75 meters or 6 feet or exactly half the full dimension at station 550.



Starting with the demo.tpl file, with a 10' lane to ID "EP" followed by a 6' shoulder lane to ID "SH", you can make another template called Road.tpl, with a 12' lane to "EP" and an 8' shoulder to "SH". Note how we have made sure to use the same ID for the road lane ("EP") and the shoulder lane ("SH").

Input-E	dit *.tpl F	ile) 🤇
C:\Carlson Projects\Data\Road.tpl GRADES:							
Left SURF/	ACE		Right	SURF	ACE		
Distance	Slope	ID	Dist	ance	Slop	е	ID
12.000	-2.000%	EP	12.000		-2.00	0%	EP
8.000	-4.000%	SH	8.000		-4.00	0%	SH
Add Edit Remove Up Down							
Cut/Fill		Su	per	Lo	ad	S	ave

If the demo.tpl is used from station 0 to 500, and the Road.tpl is used from 600 to the end of the project at station 1000, then the entry process for a Template Series is as follows:

裬 Input-	Edit TSF File		🛃 💽							
None										
Station	Template									
Add	Edit	Remove	Draw Template							
Load	Save	Save As	EQ							



Click Add and you will obtain the next dialog.

误 Template	e Series		\checkmark	X
Station:	0+00.000			
Template:	None			
C:\Carlson	Projects\Data\	DEMO.tpl		
EQ		Se	lect File	

Choose Select File and pick the first template (demo.tpl). Click OK. Back in the main dialog, click Add again and specify the ending station for demo.tpl as station 500. Then click Add again and specify the first station for Road.tpl as station 600. You do not need to specify an end station, as Road.tpl will be used for the remainder of the project.

误 Input-E	dit TSF File		💽 💽					
None								
Station	Template							
0+00.000	DEMO							
5+00.000	DEMO							
6+00.000	Road							
Add	Edit	Remove	Draw Template					
Load	Save	Save As	EQ					

You then Save the Template Series File. When running **Stake Road**, **Stake Slope** or **Elevation Difference** by **Roading Design Files** and recalling a template file, you have the option to recall a Template Series File and process a set of transitioning templates.

😂 Open TSF File 🔹 🗈 🔽								
Type: TSF File 🔻 Drive: C 💌 🎓 📂 📖								
C:\Carlson Projects\Data\								
🔁 Backup								
Name: Road.tsf								



Input-Edit Template Grade Table

Very complex roads such as exit ramps, with widening and shrinking lane widths and slopes that do not follow a simple superelevation pattern but instead adapt to meet grades of intersecting roads, can be defined using the Template Grade Table feature. Although template series files can be used to model any road, the creation of multiple templates, including all lanes, can be a labor-intensive process compared to entering the precise slope and width for particular template ID points. These slopes and widths are often provided in tabular form in the design documents, so direct entry of the slope/width data, applied to the appropriate template ID or several IDs, is often the most efficient way to handle complex road conditions.

Consider a template that goes from the center of the road to SH and then to SH2. The second segment is always 8 feet dimension at a fixed slope. The first lane, from centerline, is paved and has variable width and slope. The template grade table is applied to the first lane, after which the normal template rules apply. After selecting the command, you name your new (or existing) template grade table, and then the template that it is associated with. This leads to the screen shown below:

e	À Inpu	ıt-Edit	*.tgt Fil	e				(
	C:\Carlson Projects\Data\ramp1.tgt								
	Load TPL C:\Carlson Projects\Data\Road.tpl								
	Left Sl	JRFACE			Right S	URFAC	E		
	ID	Table	Dist	Slo	ID	Table	Dist	Slo	
	SHL	Yes	37.220	-2.0	SHR	Yes	33.500	-2.0	
	SH2L	No	8.000	-4.0	SH2R	No	8.000	-4.(
	•			<u> </u>	_			<u> </u>	
	Rep	ort	Edit		E	Q	Save	e	

The normal slopes of -2% to the edge of pavement (inner edge of shoulder) and -4% to the outer edge of the shoulder would apply if the template behaved normally. But if you click Edit on the right shoulder, for example, you can enter station-based lane widths and slopes as shown below:

Grade		📝 🔽	Grade			📝 🔽	
D: SHR		Side: Right	ID: SHR			Side: Right	
Station S	lope %	Distance	Station	Slope %	Distance		
1085.4500 1.	.610	32.5000	1418.0000	2.000			_
1180.0000 -3	3.900	32.5000	1480.0000	2.000			
1260.0000 -3	3.900	32,5000	1540.0000	4.700			
1361.1100		32.5000	1608.0800	4.700	16.0000		
1378.6100		30.0000	 1754.0000	4.700	16.0000		
1381.2500		28.0000	 1814.0000		16.0000		
1418 0000 2			 1 2066 8600	2 000	16.0000		
Station: 0+00	0.000	Slope:	Station:	+00.000	Slope	:	
)ist:		Show As Ratio	Dist:		🗌 🗆 s	how As Ratio	

In this example, considering first slope, the road begins midway in transition, at slope 1.61% in a curve left, then transitions into a curve right with a slope of -3.9% at station 1180, greater than normal crown, holding this grade through station 1260. Then the road veers again to a curve left of 2% and holds that from station 1418 through 1480, after which it transitions to 4.7% at station 1540, holds that slope through 1754, and transitions back to a uniform cross slope of 2% at station 1814 where it remains through station 2066.86. Note that where no slope entry is entered (e.g. at station 1361.11 through 1381.25), the program transitions proportionally between the last actual entries provided (1260 and 1418).

While the slope is following the instructions of the slope column, the road lane width adheres to the distance column. So, if the right-side shoulder width is 32.5 feet through station 1361.1, you can enter that distance for all stations in that range, or you could simply bracket the distance by entering 32.50 for station 1085.45 and 1361.11 and leave 1180 and 1260 blank for distance. Either way, it will compute correctly. Then for each station where a distinct distance is given in the plans, a new station entry is made, such as at 1378.61 (30') and 1381.25 (28'). If the road transitions from 28' to 16' between stations 1381.25 and 1608.08, then all stations used for slope in that range can be left blank for distance. For station 1608.08, the distance of 16' needs to be entered, to complete the distance transition, and the slope at 1608.08 can be entered (since it is known) or left blank. Either way, it will calculate correctly, since the 4.7% slope is governed by stations 1540 and 1754. Similarly, for the final stations 1754 through 2066.86, the known distance of 16' can be entered or left blank.



At station 1500, the right-side SHR lane is both in slope and in distance transition. The program will calculate this and you can review the slopes by using the Stake Road command, as shown below:

😂 Design Files 🛛 🗾 🔽 🗙	😂 Stake Road 🛛 🔲 Grade 🗾 🖌 🗙
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 1+00.000 to 3+08.327 Profile C:\Carn Projects\Data\20170213.pro Profile: 100+78.690 to 122+52.250 Template C:\Carlson Projects\Data\Road.tpl Optional Files Superelevation C:\Carjects\Data\20170213.sup Tpl Transition None Tpl Grade Table C:\Car Projects\Data\ramp1.tgt Load Roading Files Save Roading Files	Sta: 15+00.000
	Slope Stake

By clicking on the SHR ID point, the program displays the computed offset (21.718) and the computed slope in (2.901%) and slope out (-4%, per the standard template). A similar page of values was entered for the SHL ID point, leading to the uniform superelevated slope left to right. With the **Template Grade Table**, applied to as many template ID points as needed, any complex road can be defined. When running **Stake Road**, **Stake Slope** or **Elevation Difference** by **Roading Design Files** and recalling a template file, you have the option to use a **Template Grade Table** for precise modeling of complex roads.



8.8 Stake Slope



The **Stake Slope** command calculates and stakes out the location of the "catch point" where fill slopes or cut slopes contact the original ground. The command will also set offset stakes to the catch point and will produce a report of the slope stake information. The location of the slope stake is dependent on the position of the "pivot" point where the slope begins and on the slope itself (e.g. 2:1, 3:1, 4:1, etc.). Slope stakes are typically used in highway work to locate the top of slope or top of cut. If design file information is available for the road template and profile, then the slope stake routine will calculate distance and offset information for all "break points" on the template from the slope stake itself back to the centerline. This also applies to slope staking conducted by section files, and descriptions associated with the break points on templates and/or sections are identified by name in the slope stake report.

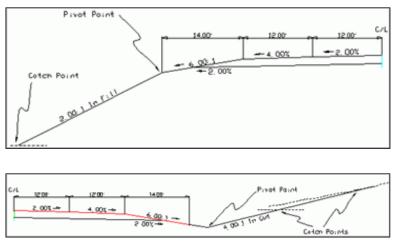
Note: Slope Staking can be conducted within the Stake Slope command from the fixed "pivot point" of the template, the end-points of cross-sections, or the centerline points of a horizontal and vertical alignment (as for a ditch). Slope staking, however, can also be conducted directly within the command Stake Road from any picked pivot point on the template or cross-section. One of the advantages of the Stake Slope command is the ability to obtain catch point information "real-time" using the "non-interval" method of walking parallel to centerline. Stake Slope will also automatically detect the ditch pivot point in cut scenarios using templates defined by Carlson Civil and Carlson Roads. Plus, Stake Slope knows which side of the centerline you are on and slopes stakes automatically to that side. The main advantage of Stake Road is the ability to slope stake from any picked point going either Left or Right as specified, for "staged" or partial roadwork design, or for finding catch points towards the interior of the template (e.g. central median). Stake Road also has a cross-section view option (within the Helmut Help). All slope staking is improved if the instruction to the user is In-Out from centerline and Forward-Back along the axis of the centerline. For this reason, it is best to set the View Point within FILE, Configure to In-Out and Left-Right, but also click on "Use Centerline for Reference Object".

There are "rules" for slope staking. The slope stake is measured from a pivot point, which is userentered, or starts at the centerline itself in "point-defined" alignments or starts at the last template point before the cut or fills when templates are involved or starts at the left and right end-points of sections when using section files. Note that in the command **Stake Road** (which works with both sections and templates), slope staking can be initiated from any desired point. This allows for slope staking of interior, central median catch points and slope staking of any side of an eventual divided highway, being built in stages. Slope staking can be interval based or accomplished based on where you are standing right now, independent of station interval.

Although office plans may predict the position of the catch points, slope staking is necessary to accurately determine the catch points based on actual field conditions. Slope stakes are often set at an offset to the actual catch points, since stakes at the precise top of slope or bottom of fill are likely to be knocked out by earthmoving activity. Furthermore, slope stakes are often marked with information on the slopes and distances in toward centerline or in toward the building pad or other feature. The information on the slope stake, distance and slope from offset stake to slope stake, distance and slope from slope stake to outside shoulder, distance and slope from outside shoulder to edge of pavement, on into centerline. Thus, the slope stake, placed safely beyond the area of construction, tells the story of the cuts and fills in toward centerline or toward the center of the work.



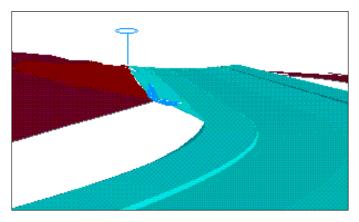
Catch points for both cut and fill are shown in the typical section graphics below. See these two figures.



Note in the "cut" example above (bottom figure) how the catch point may be closer or farther from the pivot point based on the slope of the original ground. With flat ground at virtually the same elevation as the centerline of the road, the catch is found approximately 15 feet from the pivot point in the base of the ditch. But with ground sloping slightly uphill, it takes a full 30 feet or so to find the catch point. The program helps find the catch quickly by modeling the surface of the ground with each shot taken. Thus, by projecting the ground slope outward, the program advises the user how far to go to find the anticipated catch point. Unless the ground slope changes dramatically, the catch point is usually staked within just a few tries.



With GPS, the process is even more automatic, since the ground elevation is being computed continuously as you walk toward the catch point. No "shot" has to be taken until you are positioned right on the catch point itself. This next figure shows a cut condition slope stake in 3D. The "catch" is located at the top of the cut.



Four Methods of Slope Staking

😂 Slope Staking	₽ ∓		×
Definition Method		to CATC	сн

• User-Defined: This is the most commonly used method of slope staking. Here, you simply enter the station, offset and elevation of the pivot point. Do not enter a minus sign for a left offset as in -25, since the program detects whether you are left or right of centerline. The only prerequisite is the selection of a centerline file. Cut and fill slopes are entered in the field.



- **Point-Defined Alignments**: This method is often used for staking the top of cut for a ditch, particularly a V-ditch. You can select the centerline by any of the three classic methods of centerline file, a picked polyline on the screen, or a sequence of points. The vertical alignment can be derived from any picked 3D polyline or from the elevations on the sequence of points, or you can separately enter a profile. This method is useful for slope staking existing flow lines, where you simply take two shots at either end, create an alignment by point number, then set the slope stakes at the user-entered slope ratio.
- **Design Files**: This is the most "formal" way of slope staking, but typically only applies to uniform, simple road, drainage ditch or levee projects where the pivot offset positions do not vary from station to station. While all methods require that a centerline be selected, the design file method additionally requires, at a minimum, a template file and a profile (vertical alignment). For more complex roads, superelevation files and template lane width transition files may also be entered. With the exception of the centerline, profiles and simple templates, the other files are usually created at the office using Carlson Civil, Carlson Roads or TakeOff, and then downloaded onto the field computer.

Note: Whenever the Road Design File option is selected, templates can be selected as a single "TPL" file, or as a series of templates organized as a "TSF" file (Template Series File). The TSF file can be entered within Road Utilities. If the left pavement lane of a road expanded from 10' to 20' for a passing lane, from station 1100 to 1200, you can create two templates, Road1 with the 10' lane and Road2 with the 20' lane. Then if you create the Template Series File shown below, the program will auto-calculate a 15' left pavement width at station 1150. This same feature can be accomplished by using one template and applying a Template Transition File, which instructs on the changing dimensions of portions of a single template. Unlike the Template Series File, the alternate Template Transition File can only be created at the office using Carlson Civil, Carlson Roads or Carlson TakeOff.

0	lnput-Ed	it TSF File		💽 💽	
	C:\Carlson	Proiects\Da	ta\Road.tsf		
	Station	Template			
	0+00.000	Road			
	11+00.000	Road			
	12+00.000	Road			
	20+00.000	Road			
	Add	Edit	Remove	Draw Template	
	Load	Save	Save As	EQ	



One advantage of the design files method is that since each template point has an "ID", the slope stake report will include information to locate all ID'd template points from the slope stake back in to the centerline. In this way, the entire road can be built from the information marked on the slope stake, which is placed outside the construction area at a user-specified (e.g. 5') offset to the actual catch point.

0	11				
		HDIST	BDIST	SLOPE	
	Offset to Catch	5.02	-0.17	CUT 3.4%	29.5:1
	Catch to Pivot	32.20	16.10	FILL 50.0%	2.0:1
	Pivot to Shldr	14.00	33	FILL 16.7%	6.0:1
	Shldr to EOP	12.00	0.48	FILL 4.0%	25:1
	EOP to CL	12.00	0.24	FILL 2.0%	50:1

A report might appear as follows:

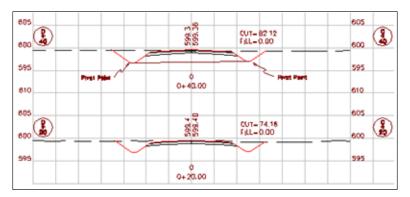
<mark>ಜಿ</mark> Offset Point Report 🛛 🗸 🗸				
Progressiv	O Total			
Offset PT Sta: 0)ffset:	Ele	evation:	
6+49.987 R	126.906	997.219		
	HDIST	VDIST		SLOPE
OFFSET to CATCH	5.02	0.00	CUT	0.0% 9
CATCH to R651_5	87.24	43.62	CUT	50.0%
R651_5 to R651_4	10.66	5.33	CUT	50.0%
R651_4 to R651_3	6.00	2.00	FILL	33.3%
R651_3 to R651_2	4.00	0.17	CUT	4.3%
R651_2 to R651_1		0.17		4.3%
R651_1 to CENTER	R 10.00	0.43	CUT	4.3%
•				Þ

Within the program, the report might appear as shown here:

Progressive or Total: The above report is sometimes referred to as a "progressive" report, since it lists the incremental information from each break point to the next, going in toward the centerline. In some areas, the stake is referred to as a "story stake" or "progressive story stake", because it tells the whole story of the gradework. The program is able to identify the names of the break points (e.g. "SHLDR" and "EOP") because the templates used by the program must have pre-defined IDs for all break points. Specifically, with office-defined templates where cut conditions can have downslopes for ditches followed by upslopes, the program will auto-detect whether to pivot into fill or to create a cut condition, and pivot from the ditch line. You can also click the "Total" option and get offset distances to all break points as totals measured from the offset stake. In either case, the report is issued only if you stake the offset point to the catch.



• Section Files: Section files can be used to identify the pivot points left and right and minimize fieldwork. Consider the sections shown below.



Shown are stations 0+20 and 0+40, with the pivot points for slope staking identified on station 0+40. For the section approach to work, the left-most point in the cross-section must be the left pivot, and similarly, the right-most point in the cross-section must be the right pivot point. The section should only be entered from pivot left to pivot right (the "designed" catch points should be dropped). But since the interior section points have no bearing on the slope staking, they can be omitted, too. So, in the case of station 0+40, a 2-point cross-section could be entered, consisting of pivot left and pivot right. That 2-point section is also shown in the graphic above. It is just as effective for slope staking as a section containing all the break points between pivots. The one exception is if you have entered descriptions for your section points, you can obtain a progressive slope stake report, just as with the templates. Note that if descriptions do not exist, the report leaves them out. Section-based slope staking requires selection of a centerline file and field-entry of the cut and fill slopes.

Section-based slope staking is useful when the pivot points for stakeout vary unpredictably and don't conform to a fixed template. Section-based slope staking has 2 advantages. First, all sections can be entered in the office as 2-point sections (left and right pivot), minimizing field paperwork and reference material. Secondly, odd stations can be staked out (e.g. station 0+27.5), since the pivot points can be straight-line interpolated by the program.

Note: Section files can be used for slope staking within the command Stake Road. In this routine, you can choose sections or templates to stake, and you can pick any point to slope stake from—so any point on the section can become the pivot point. The advantage of slope staking by section file within Stake Road is that you can pick any point (greater flexibility). The advantage of slope staking by section file within the Stake Slope routine is that it automatically uses the left and right end points of the section as pivot points, which means less screen picks are involved (greater speed).

Section files may be entered in Road Utilities, or in an external program such as Carlson Civil, Roads or TakeOff.



Choosing the Slope Staking Method

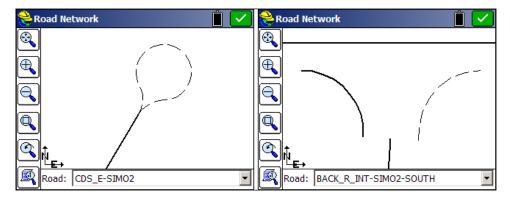
When Slope Staking is selected, you are presented with a Definition Method screen, where you choose among the 4 methods of Slope Staking: User-Defined, Point-Defined Alignments, Design Files or Section Files. The application of these methods is discussed above.

😂 Slope Staking	📰 🔽 🔀			
Definition Method User Entered Defined Alignments Design Files Section File				
Slope Stk Sta Interval Crt Cut/Fill to CATCH				
Load Road Net File	Select Road Net Element			
None				

- Slope Stake Station Interval: When clicked on, your slope stake target is always a fixed point. It is the slope stake at the specified station in the input dialog in all 4 methods. But if clicked off, the slope stake target point moves forward/back station as you move. In User-Defined, the pivot offset and elevation is used regardless of station position. In the other methods, the pivot elevation is recalculated dynamically as you move based on the known information (3D points, profile, sections).
- **Round Station**: This option applies only if you turn off "Stake Station Interval" and move to "fluid" slope staking. If you "round" to an interval, such as 5, then the elevation to stake from is calculated to the rounded station value, as is the up-down station position for the offset. Rounding only applies to the stored report—the target still moves fluidly as you walk forward or back parallel to the alignment.



Load Road Net File/Select Road Element: Carlson Civil 2008 and Carlson Roads 2008 have the option to output an "RNF" file, or "Road Net File", from the RoadNet feature. This file contains every centerline, cul-de-sac and road intersection "curve return" treatment for an entire road network. For example, a complete subdivision road system can be output as a single RNF file, and then SurvCE can stakeout any element of the RoadNet file that is loaded. Since the RNF file contains both templates and final sections, the Load RoadNet File option is accessible when slope staking by Design Files and Section Files. If you select, "Load RoadNet File", it merely loads the files, announces "Process Done" and all road files are placed into a temporary directory. You then need to click "Select RoadNet Element" to choose the element of interest. The three choices are centerlines, cul-de-sacs and the curve returns at intersections. For centerlines, the Center ID of the design template (if that method is used) is applied to the horizontal alignment. Keep in mind that for cul-de-sacs and curvereturns, the position of the horizontal alignment is set in RoadNet within Carlson Civil and Carlson Roads, and typically is set to the edge-of-pavement alignment position. Slope staking will therefore use just the outer part of the template, for example, from EP ID outward, to find that pivot point. If you re-load the same RoadNet File, the program warns you that the prior temporary files will be erased and new ones created. This is done in case you actually modified a profile or other files in the temporary files, in which case you should use SaveAs in the appropriate command to preserve the changes in a new file name. When you Select RoadNet Element after loading an "RNF" file, you can highlight any element to stake, which then appear "dashed" when highlighted:



When you click out of the opening dialog that offers the 4 methods of Slope Staking, you obtain additional input screens.



• User-Entered Dialog: If the User-Entered method is selected, you are first prompted for a centerline, and a dialog appears.

😂 Station for Slope Staking 🛛 🖌 🗙								
Station: 0+00.000 Next Interval: 10								
Pivot Off: 0.000 Pivot Elev: 476.080								
Read Instrument								
Use Point ID:								
Slope:								
CUT: 50.00%								
Display As Ratio FILL: 50.00%								

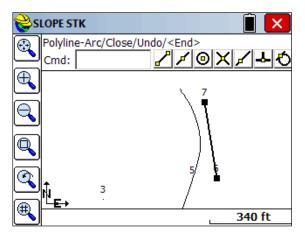
At each station, you can enter a specific pivot offset, pivot elevation and the cut and fill slope ratio that governs. Slope ratios can be entered as percent as well, is "Display As Ratio" is clicked off. Pivot offsets should be entered as positive numbers even left of centerline, since the program will detect which side of centerline you are on from the first total station or GPS reading. The program will take the absolute value of the pivot offset entry, in any case. You can obtain the position to stake from "Read Instrument", which calculates the station, offset and pivot elevation from a measured position. Or you can enter a point number to obtain a station, offset and pivot elevation.



• **Defined Alignment Dialog**: The selection of the Point-Defined method leads to the classic alignment selection screen, familiar to users of Offset Stakeout and Stake Centerline.

😂 Stake Slope			😂 Stake Slo	ре		🔽 🗙
Horizontal Vertical			Horizontal	Vertical		
1 Centerline File			1 Profile F	ile]	
2 Select Polyline	4 Preview	5 Edit	2 Select Po	2 Select Polyline		6 Edit
3 Define Point List	6 Save As		3 Define Point List		7 Save As	
Start Station; 0+00.00	Ending Station: 3+08.327ft				rojects\Data\201 .690 250ft	1 70213.pro ft

Though this is the classic use of the Point-Defined option (using points), slope staking can be conducted from a single centerline and single profile or from a picked 3D polyline. Points can be selected by number or picked directly off the screen.



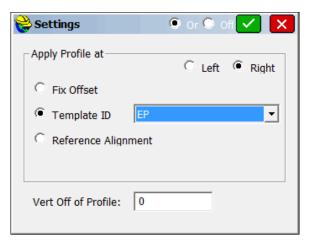
When a new horizontal alignment is selected by 3D polyline or point method, the program will ask if you wish to overwrite any existing vertical alignment selection. The typical answer is yes—you want it for both, and you are ready to stake any station at any interval based on user-entered slopes. Think of points 6 to 7 as the flow line of a ditch with steep side slopes, and the goal is to lay the slopes back at 2:1—a perfect application for Point-Defined Slope Staking.



• Design File Dialog: If you select Design Files, a dialog appears.

😝 Design Files						\checkmark	X	
Centerline	Centerline C:\Carlson Projects\Data\DEMO.cl							
Centerline: 0+00.000 to 3+08.327								
Profile	C:\Car	n Pro	ojects	\Data\2	01	70213	.pro	
Profile: 100+78	Profile: 100+78.690 to 122+52.250							
Template	Template C:\Carlson Projects\Data\Road.tpl							
Optional Files								
Superelevat	ion C:\(Car	.jects	Data\2	017	70213.	sup	
Tpl Transiti	on Non	е						
Tpl Grade Ta	Tpl Grade Table C:\Car Projects\Data\ramp1.tgt							
Load Roading Files Save Roading Files							5	

Centerlines, profiles and templates can be made using SurvCE. In fact, centerlines and profiles can be imported from a variety of file formats using the commands within Road Utilities. Note that templates can be either single template ".tpl" files or multiple templates with transitions in a Template Series ".tsf" file. If the roads have superelevation, the "super" files can be made in Road Utilities. If template transition files are to be used for lane changes, then this file type must be made using external software such as Carlson Civil or Carlson Roads. Note that "sets" of Roading Files can be saved and loaded using the buttons at the bottom of the screen. The Settings icon at the top of the screen, to the left of the checkmark, allows you to place the profile grade at an offset to centerline, such as at the inside edge-of-pavement for divided highways, as shown below:





• Section File Dialog: If Section File is selected, a dialog appears.

癸 Section File				\checkmark	X			
Centerline C:\(Centerline: 0+00.00		Projects\ 08.327	Data\D	EMO.cl				
Profile C:\(Profile C:\Carn Projects\Data\20170213.pro							
Profile: 100+78.690	Profile: 100+78.690 to 122+52.250							
Design Section C:\(Design Section C:\Carlson Projects\Data\DEMO.sct							
Sections: 0+50.000	to 3+0	0.000						
	Continue Last Slope							
Cut: 50.00%	Fill:	50.00%		As				
Load Roading Fi	iles	Save	Roadin	ng Files				

The Section file (which has an "sct" file extension) can be entered in Road Utilities or imported from the LandXML format using Section File Conversion, also in Road Utilities. Note that for all roading design files, there is no requirement that starting and ending stations (chainage) match. All that is necessary is that they have a station range in common (in the above case, 10+00 through 20+00 is common to all files). Roading File sets (as in the above Boneta files) can also be saved to a named set and then re-loaded later for convenience. With cross-sections, the profile is not required, but including the profile will lead to more accurate slope staking between known cross-sections, such as at high and low points in the road.



Setting the Station and Interval for Stakeout

The next screen sets the station to stakeout and the interval and will appear in some form in all cases except section and design files slope staking with interval turned off. In effect, there are 8 ways of going into Slope Staking: 4 methods times 2 interval options (on=fixed station/off=fluid, real-time). You also have 3 more methods if you include the Stake Road routine which offers Slope Staking by Section, Template or Sections Cut from DTM, all fixed station.

癸 Station for Slope St	aking 📃	
Station:	6+00.000	
Next Interval:	5 0	
Read Ins	strument	
Use Point:		· /

The station to stake can also be read from the GPS or total station measurement, allowing you to slope stake "where you are". You can also get the station by entering a point number, in which case it projects the point onto the centerline to determine the station. In the non-interval method, the above screen does not appear. You slope stake wherever you are all the time and are freed of the constraints of staking a specified station.



The User-Defined and Point-Defined Alignment methods have their own pair of "follow-up" screens for the location to stake.

误 Station		$\overline{}$	×						
Station:	0+00.000	Next Interva	al: 20						
Pivot Off:	Pivot Off: 0.000 Pivot Elev:								
Read Instrument									
Us	Use Point ID:								
Slope: —									
		CUT: 2.00	:1						
Display	ay As Ratio	FILL: 2.00	1						
L									

For flow line or V-ditch staking, a 0 pivot offset would be entered from the point-defined alignment. If the ditch were a trapezoidal ditch with a 2 meter bottom width, and the alignment was the centerline, each side of the ditch could be slope staked using a pivot offset of 1 (1/2 of the ditch width from center to pivot point).

Both the Road Design Files and Section Files methods go straight to the navigation (stakeout) screens if no interval is selected (Stake Station Interval turned off). The pivot offset is built into these methods based on the "rules" outlined earlier -- you stake from the pivot to cut or fill in templates, and from the extreme left and right points of cross-sections. With interval turned off, slope staking by "User-Entered" method simply asks for the pivot offset and elevation at the current location, and slope staking by point-defined alignment asks only for pivot offset, obtaining the elevation from the vertical alignment.

Slope staking cannot occur outside the station range of the horizontal alignment. If your horizontal alignment runs from station 0 to 308, you can't stake station -10, either by interval method (naming the station) or by the non-interval, fluid "where-you-are" method.

Warning						
Station out of range!						
ОК						

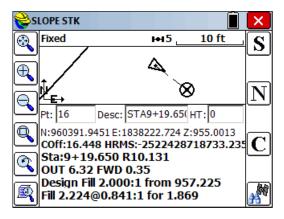


In live stakeout mode, you will get "Off Centerline" when beyond the range of the horizontal alignment.

All paths lead on to the navigation or stakeout (some call it "set out") screen.

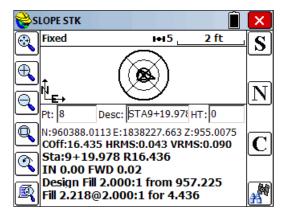
The Navigation (Stakeout) Screen

When configured for GPS, the navigation screen then appears.



Note that because the GPS reads continuously and models the ground surface, the program calculates immediately where the catch point (the circle with the X) is located. You simply walk right to it. If the ground goes uphill or downhill as you approach the point, then the X will move closer or move away, until you are right on it.

As you get closer to the point (within the stake tolerance distance) the program will present a bullseye screen.

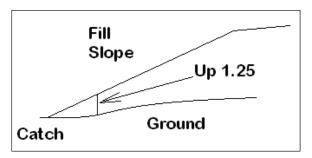




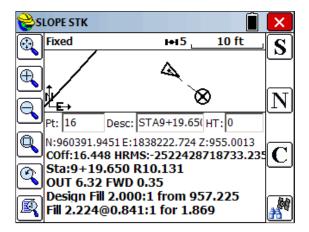
When you are satisfied with the accuracy of the slope stake position, you then touch S for Store (or press Enter to take the shot). In this case, it's time to drive the stake.

Interval and Non-Interval Methods Impact Stakeout Screen

The stakeout screens above are for the interval method. In the non-interval, "fluid" slope staking, where you can drive the stake anywhere, the "Forward-Back" portion of the screen becomes vertical "Current Fill" or "Current Cut". In this fluid stake-out mode, you simply move in or out from the centerline to set the slope stake—there is no correct or incorrect forward or back station. So, the program instead reports the vertical up to the fill slope above you or down to the cut below you.



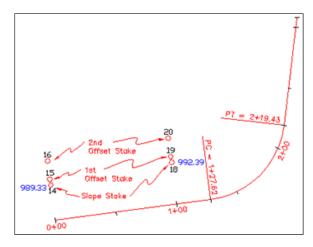
If you are moving out to the catch point along the ground, you would get a report of "CrtF 1.25" or some such number, and the "Current Fill" amount to the ground would decrease as you approach the catch. The actual stakeout screen would appear as shown below. Note that some surveyors will watch the lower line (1.6:1 for 3.65) and just keep moving out until they see 2:1 (or the desired slope) and drive the stake. Others will watch the "CrtF" value decrease to 0 and drive the stake, or watch "OUT" decrease to 0.





Storing the Slope Stake and Offset Stake Points

When S for Store is pressed, you may store the actual slope stake point. You can also store a first offset point (since the slope stake itself can be removed by construction). The slope stake information is typically written on the first offset stake. Then you can also stake a second offset point, to obtain "line" to reset the slope stake if it is knocked out. The first and second offset stakes provide a direction back to the slope stake. When the slope stake is set, the program prompts for setting the first offset stake. Both offset stakes are optional.



The storage of the slope stake points is an option turned on by clicking "Store Point to CRD File". With this clicked off, you can simply slope stake and avoid storing any points. The Description for the point will default to the station and offset. Slope Staking will not respond to settings in Configure Reading for the Height/Description prompt screen. If you are using a named "Slope Stake File" (set in **File, Job Settings, Stake** tab, **Cutsheets** option), you can still control at the point of staking whether you choose to append data to the file by clicking on or off "Store Data to Report File".



😂 Slope Staking Store		📚 Slope	🔽 🔽		
Station C Offset	Elevation	S	Station	 Offset 	C Elevation
Pivot Pt: 6+00.000 R18.000	945.750	Pivot Pt: 6	i+00.000	R18.000	945.750
Catch Pt: 6+00.000 R36.501	955.001	Catch Pt: 6	+00.000	R38.562	956.031
Stake Pt: 5+99.992 R36.478	955.001	Stake Pt: 5	+99.298	R38.562	955.008
Stk-CP: OUT 0.023 FWD 0.	Stk-CP: F1.	.023	FWD 0	.702	
		CP-PP: C10	0.281 @ 2::	1 HD:20.	.562 50%
Stk-PP: C9.251 @ 1.997:1 HD:18.4	478 50.063%	Stk-PP: C9.	.258 @ 2.22	1:1 HD:20	.562 45.025%
Stk-CL: C6.251 @ 5.836:1 HD:36.4	478 17.135%	Stk-CL: C6.	.258 @ 6.1	L62:1 HD:38	.562 16.229%
Store Data to Report File		Store Da	ata to Report	File	
VOff: 0 Elv: 955.001 C(St	k-PP)9.25	VOff:	0 Elv: 9	55.008 C(St	tk-PP)9.26
Point ID: 8 Store Point to	CRD File	Point ID:	8	Store Point to	o CRD File
Desc: STA5+99.992 CATCH R36.	48	Desc:	STA5+99.29	8 CATCH R38	.56

Note that there are two options for the slope stake report: Elevation and Offset. The standard option is the Elevation method. This assumes you were able to survey the actual slope stake point with reasonable accuracy, and it reports the actual stake to pivot point results. If you were staking a 2:1 cut slope, it reports your actual slope (as 1.997:1 in this case), and you can choose to round the result and write "Cut 2:1, 9.25 V, 18.48 H" on the stake. But if at the catch point there are boulders in the way, you can walk out and away from centerline in cut and in toward centerline in fill and drive the stake where you can. In this case, you would choose the Offset method. In the Offset example above, we had to walk past the catch point about 2 units (from 36.50 to 38.56). We drive the stake and note that the catch is at 956.03 rather than 955.01, so we measure up 1.02 on the stake, and draw a horizontal line there as the catch point. An extra line appears in the report that tells us to write "Cut 2:1, 10.28 V, 20.56 H" on the stake. In cases of fill where there are obstructions, walk into centerline so when you drive the stake, you can mark where the fill intersects the stake. Note that this same level of reporting occurs with "non-interval" staking, where you get real-time cut and fill at any point, also allowing you to drive the stake to avoid obstructions.



When Enter or OK is pressed, you are prompted for whether to stake the first offset stake.

<mark> S</mark> lope	🔽 🔽									
9	Station	Offset	Elevation							
Pivot Pt: 0	+00.000	R0.000	997.230							
Catch Pt: 0	+00.000	R126.670	955.007							
Stake Pt: 0	+00.049	R126.726	955.007							
Stk-CP: IN 0.055 BACK 0.049										
Stk-PP: F42.223 @ 3.001:1 HD:126.72633.319%										
Store D	ata to Repo	ort File								
VOff:	0 Elv:	0 Elv: 955.007 F(Stk-PP)42.22								
Point ID:	15	15 Store Point to CRD File								
Desc:	STA0+00.049 CATCH R126.73									

If you are doing "User-Defined" or "Point-Defined Alignment" methods, you are shown the horizontal distance and vertical fill or cut difference to the pivot point, which can be written on the Slope Stake. Additional break-point information appears if you are using the "Design File" or "Section File" method. If you trust that the Slope Stake will not be knocked out, then you are done—no need to set an offset stake.

Pressing OK leads to the prompt to set the first offset stake. If you choose to set the first offset stake, then you can set the offset distance.

<mark>ề</mark> First Off			×	
Station: Offset:	6+50.000 5			
Offset Type	e 💿 <u>D</u> elta Distanc	e from Cat	ch Pt	



Press OK and then you are in a standard stakeout screen. The offset point is a fixed location and the stakeout procedure is similar to point stakeout. This leads to a report of information that can be written on the Slope Stake. Finally, you will be prompted for staking out a second Slope Stake, to establish "line." After the first offset stake is set, and before the prompt for the optional second offset stake, a summary screen will appear. If you have used the Road Design File or Section File methods, you will be presented with every break point into centerline.

<mark>ề</mark> Offset Point	t Report				😂 Offset Point	t Re	port			
Progres	sive	O Tota	I		O Progressive			• Total		
Offset PT Sta: 6+49.994	Offset: R39.976	Elevation: 954.987			Offset PT Sta: 6+49.994	Off: R39	set: 9.976		levation 54.987	:
	HDIST	VDIST	SLOPE	L			HDIST	VDIST		SLOPE
OFFSET to CAT		0.01	FILL 0.3% 34	L	OFFSET to CAT	CH	4.97	0.01		0.3% 34
CATCH to BD BD to EP	17.00 6.00	8.50 3.00	CUT 50.0% 2 FILL 50.0% 2	L	OFFSET to BD OFFSET to EP		21.98 27.98	8.49 5.49		38.6% 19.6%
EP to CENTER	12.00	0.00	FILL 0.0% 99	L	OFFSET to CEN	TER	39.98	5.49	CUT	13.7%
				L						
I			Þ		•					F

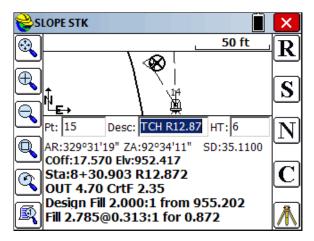
Finally, you will be prompted for staking out a second Slope Stake, a more rarely used option whose purpose is to establish "line" (the direction) from the first offset stake to the slope stake itself. This permits accurate replacement of the slope stake when it is knocked out by construction activity.

Note: When using Road Design or Section Files in Slope Staking, setting the first offset point is the recommended procedure, as it produces the full report, referenced to cross-section and template IDs, for all break points all the way into the centerline point.

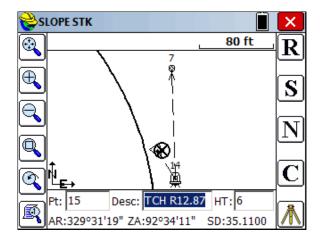


Procedure for Slope Staking with Total Stations

The procedure is nearly identical for Total Stations, except that you must press R for Read (or Enter) to take shots and allow the program to begin calculating the Slope Stake position. Unlike the GPS, SurvCE cannot predict the location of the target slope stake point until at least one measurement is taken.



Note: When using either GPS or total stations for slope staking, you can obtain more graphics and less screen information by pressing the down - arrow key. It literally has the effect of bringing the graphic screen down (see below). Pressing the up-arrow key will pull the screen back up and show the full text. This works in all modes except GPS Simulation, where the up - arrow moves the cursor faster, down-arrow slower.





The Slope Stake Report and Writing on the Slope Stake

Surveyors doing slope staking have the option to write the information on the stake as each is surveyed, or to come back at a later time, refer to the slope stake report, and write on all the stakes after the surveying is complete. The slope stake report file is a comma-separated ".txt" file, configured in **Job Settings, Stake, Cutsheets**, which might appear as follows if formatted in Excel or another spreadsheet form:

#Des Sta	Des Off	Des Elv	Staked Sta	Staked Off	Stake Elv	Desc
1+00.000	L33.849	998.075	0+99.966	L33.453	998.075	Catch Point
1+00.000	L38.849		1+00.019	L38.866	998.15	First Offset Point

Here is another example as viewed in the Edit mode within Job Settings, Stake, Cutsheets, Edit Slope Stake.

😤 Edit CutSheet File slope.txt 🧲					
Design Sta	Pivot Off	Elev: PP/C			
7+00.00	Right 18.0	947.75			
OFFSET to CATCH	H 0.00	V 0.00			
OFFSET to BD	H 14.49	V 7.24			
OFFSET to EP	H 20.49	V 4.24			
OFFSET to CENTER	H 32.49	V 4.24			
7+50.00	Right 18.0 949.50				
OFFSET to CATCH	H 0.00	V 0.00 💌			
Insert Up	Down Sp	ecial Delete			

The columns are configurable with the Slope Stake formatting in Job Settings. Shown above is a "total" report (as opposed to "progressive"). No offset stake was set. The template involved was flat from centerline for 12', then had a 2:1 slope for 6' into a ditch point (ID="BD" for "base of ditch). This cut downslope condition was created within an office-entered template using Carlson Civil or Carlson Roads, and SurvCE automatically detected the cut condition and used the ditch points as pivot points, offset 18 with elevations 945.75 at station 6+00 and 946.50 at station 6+50. Some survey teams use one person to set the slope stakes and another to enter data on the stakes, which is easily done using the stored slope stake report above.

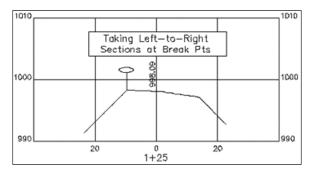


8.9 Store Sections



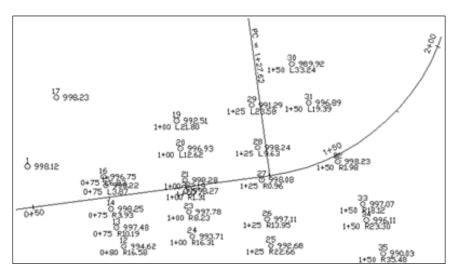
This function collects as-built cross-sections of roads or other alignments and stores them optionally as points, as cross-sections or as an ASCII file, organized by station. The station and offset can be stored into the description field of the points. The station itself can be set to automatically round to the nearest 5, 10 or other station interval (e.g. a shot at 177+98.23 would round to 180+00 if a rounding of 5 or 10 is used). The information can be stored into a ".txt" ASCII file in addition to the points themselves, if "Store Comma Separated File" is turned on, and if point storage is turned on, you can save a ".not" file of the station and offset. You can save the cross-section data to a cross-section file in .SCT or RAW/Geodimeter format. Store Sections can also be used simply to verify your current station and offset as you move along a centerline using GPS or taking total station shots.

This routine is often combined with office software to check as-built road cross-sections against desired grade and to calculate quantities for payment. The field crew begins by taking shots along each desired cross-section, as shown in this figure.

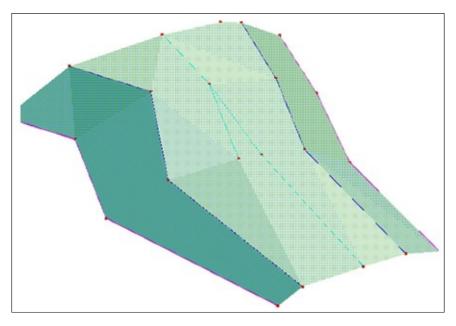


If four sets of cross-sections were taken from station 0+75 to 1+50, the points would appear as shown in the plan view below, and the 3D view shown below that. There is an option to turn off point number storing, in which case the shots can still be stored to a cross-section (.sct) file and report file (.txt).





Here, below, we see the 3D view of this area.





The command begins with a screen where you select the method for defining a centerline.

😂 Store Sections	
Define Line	Define Arc (3 Points)
Define Alignment	Define Arc (PC,PT,Value)
	None

The next screen allows you to choose whether or not to store a file summarizing cross-section data. *This will be the fourth screen in the process of Define Line, Define Alignment, Define Arc (3 Point), Define Arc (PC, PT, Value).*

Because the SCT method requires that you choose an alignment, the option for no alignment ("None") only applies to the Raw/Geodimeter method, in which case a named file is required. Except for this case of option "None", the Section output file is optional because the information will be stored with the points. When you click Select File, you have two file type options when using a horizontal alignment.

😂 File Type	X
• SCT	
C RAV	V/Geodimeter

The Raw file format is a design that is compatible with the old Geodimeter section file format, and includes special prompting for job type. It is discussed in detail below (see the discussion of "None" as centerline option). It leads to a different set of screen options than the SCT format.



Unless you are looking for Geodimeter file format compatibility, you should consider storing a section output file in the ".SCT" format, since it can be converted, using Road Utilities, to LandXML form and then imported to several different roading software packages for plotting and computation of volumes. The ".SCT" section files can also be used directly for volume calculations with Carlson Roads, Leica Site Manager, Topcon Topsite and Carlson Civil. You can also set the rounding—here, a rounding of 10 units (feet or meters) has been selected. The station and offset can also be stored as the point description and as a note file, if the lower options are clicked on.

😝 Store Sections		X
Store Data to Sec	tion File	
Select File Nor	ne	
X-SCT Settings Sta	tion Tolerance:	2.000
Store Comma Se		
Select File C:\	Carlson Projects	Data\CSV.txt
Store <u>P</u> oint in CRI <u>R</u> ound Station to		ta-Off as <u>D</u> esc
Store Station and	Offset in <u>N</u> ote Fi	le

Note that the rounding is fully automatic. If you choose a 5-unit rounding, and are targeting station 0+75, but take a shot at 0+77.93, it will round up to 0+80.

Before collecting the cross-sections, it is important to click X-SCT Settings near the top of the dialog, and set the stations you wish to capture. This way, if the station rounds, per the above screen, to a station that doesn't exist in your list, you are warned before proceeding with storing. This list also includes the left and right "tolerances" for the offsets, which will lead to warnings if you exceed that distance from centerline. If you set a tighter "Station Tolerance" in X-SCT Settings (option Edit) than the "Rounding" Tolerance, you will be warned even though the rounding is correct. In the screen shown below, station 16+70.000 has been added as a special station. Clicking the first line (10+00.000-23+00.000) allows you to set the standard interval, and the additional stations in the list would be for special stations in addition to the standard interval.



Station	Offset Left	Offset F	Right	Interv
10+00.000-23+00.00	0 100.	000	100	0.000
10+00.000	100.	000	100	0.000
10+11.570	100.	000	100	0.000
16+70.000	100.	000	100	0.000
23+00.000	100.	000	100	0.000
•				•

The below, smaller dialog appears when you tap Add Odd Stations, shown in the figure below.

📚 Add odd station 🛛 🔽 🔀				
MIN Sta:10+00.000-23+00.000 MAX Sta: 23+00.000				
Station:	16+70.000			
Left Offset:	100.000			
Right Offset:	100.000			



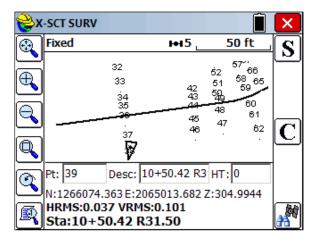
With the first line highlighted, selecting Edit leads to the settings options for the full range of stations.

😂 X-SCT Se	ettings		🛛 🔽 🗙			
MIN Sta: 10+00.000 MAX Sta: 23+00.000						
Range of Stations:						
Beg. Sta:	0+00.000					
End. Sta:	23+00.000	Left Off:	100.000			
Interval:	50.000	Right Off:	100.000			
Offset from alignment to X-Section: 0.000						
Add Start and End Stations Add PI, PC, PT, TS, SC, CS, ST Stations						

With an interval set of 50, and Start/End Stations turned on, the program will only expect you to capture stations at 50 units intervals starting at 10+00 through to 23+00, but also including 10+11.57 and 16+70 in this case. The Offset from alignment to X-Section option lets you, in effect, use an alternate, parallel centerline at a left (negative) or right offset from the main centerline. Unless the Raw/Geodimeter method is used, a station "warning" screen is used if the rounded station is not in the list or pre-selected stations. A capture of station 1075 would round to 1080, but since 1080 is not in "the list", you will be warned before storing. A station of 1667 would round to 1670, which is in the list, leading to no warning screen. Since the rounding was set to 10 in this example, data collected at 45 to 55 would round to 50 (station 1053 would not round up to 1055), and therefore only "even 10" stations will be collected to begin with. So the additional "Station Tolerance", which rounds the collected station data to the listed stations, will not activate.



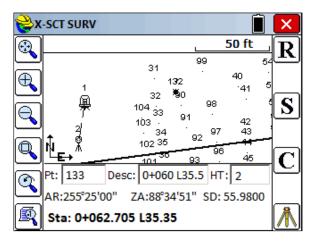
When OK (green check mark) is clicked from the Store Sections dialog, the program immediately proceeds to a point collection mode, with continuous presentation of station and offset (if running GPS or robotic total stations).



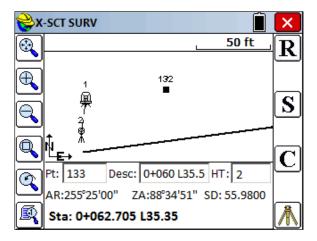
• Storing Points using GPS: There are two methods for storing points in real-time GPS mode: Press the S icon at right (or pick Alt S) or simply press Enter. The "binoculars" icon will bring up the Monitor/Skyplot dialog. You can survey as many cross-sections as desired within the command. Unlike in Slope Staking, Store Sections will respond to the setting for Hgt/Description prompt on save, found in Configure Reading, allowing you to arrow key to desired descriptions or change your rod height after taking the shot. Option C goes to the Configure Reading directly from the data gathering screen. When done, simply select the Menu button, and you are returned to the Road menu. When exiting by pressing Menu, if you have opted to store to an SCT file, you will be prompted to store the cross-section information in SCT form.



• Storing Points using Total Stations: After confirming the occupied station and backsight, as with all total station work, proceed through the same options above until you reach the store point dialog. In the example below, our centerline is metric, starting at station 0+000.



Here, your options are R for Read, followed S for Store, or simply Enter to Read and Store. The backsight icon can be pressed to set a new occupied point or backsight point. Note that we have a very "busy" screen of points. If you just want to see your setup, backsight and last point that was measured, press Alt F. This produces the screen below. You will stay in this mode until you press Alt F again and toggle back to the presentation of all points.





If a shot is taken that doesn't round to a station in the list of "approved" cross-section stations (X-SCT Settings), then a warning screen appears. In the warning dialog shown below, the tolerance has been exceeded on two accounts. We round to 0+80, which is not in the list, and our offset is 186.891 left, which exceeds our anticipated maximum offsets of 100 left and right.

<mark>ề</mark> Station/Offset report	×
Station Tolerance is Exceeded! Current Tolerance: 2.000	
Edit Current Station	0+077.913
Round Station to the Nearest 0+080.000	10 🗸
Use Closest Sta: 0+100.00	0 (Intvl.)
Offset is beyond the limits!	
Current Offset: Left 186.891	
Offset Left: 100.000	
Offset Right: 100.000	Continue Storing

Points Store with Station/Offset Descriptions, as shown below:

29	0+125	L23.58
30	0+150	L33.24
31	0+150	L19.39
32	0+150	R1.98
33	0+150	R18.12

The comma-separated file would appear as follows if presented in a tab-delimited form:

#Point ID	Station	Offset	Elevation	Description
29	0+125	Left 23.5759	991.2901	0+125 L23.58
30	0+150	Left 33.2363	989.9193	0+150 L33.24
31	0+150	Left 19.3923	998.8921	0+150 L19.39
32	0+150	Right 1.9816	998.2340	0+150 R1.98
33	0+150	Right 18.1201	997.0731	0+150 R18.12

When you exit the routine by clicking Menu from the data gathering screen, and have Store SCT file turned on, you will be asked if you want to "process" or add the last shots you collected to the named SCT file. You have the choice to "Process" (use the data) or "Discard".

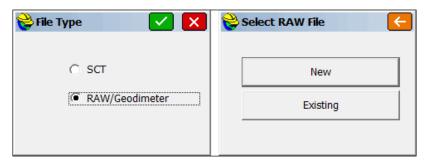


Process SCT File	Cancel
Current SCT Section file: \Disk\Data\test.sct	
Process temporary SCT section file	e
Discard temporary SCT Section fil	e

The program will even keep the section data "on file", so that if you Cancel the above screen, and re-enter Store Sections, you will be prompted again whether to save (process) or discard the cross-section data collected earlier.

Options When Storing in Raw/Geodimeter Format

Different options present themselves when the Raw/Geodimeter Format, or File Type, is chosen.



When Raw/Geodimeter is selected, a distinct set of screens are obtained. This particular format was adapted for highway departments and survey companies that had built cross-sectioning practices around the Geodimeter format. This method requires that you enter the station (chainage) being surveyed, and only uses the centerline position to advise you on your station and offset. A horizontal alignment is not required. The program detects the selection of this format, and before proceeding, opens with a starting screen where job-based information is entered.



😂 Cross Se	ection			
Project	104 North			
Info	As-Builts 24	40-3	300	
Operator	PS			
Instr. No.	17		Date	2-14-2017
Temp.	35		Press.	30.10
Signal Ht.	3.210			
X-Sec X-Sec Job	Туре: 🔎	Or	riginals 〇 Task	Finals
Typicals		•	Cross Sect	tions 🔻
Typicals Roadway Borrow Topsoil Subcut Waste Stockpile		~	Bridge Sur Setout Dev Cross Sect Profile Topograph Fly Levels	ions
Rock Cut		~		

There are pre-set job categories and tasks, which save into defined number categories in the old Geodimeter raw file format. Whereas the SCT method recognizes the station you are on and automatically rounds to it when you are within tolerance, the Raw/Geodimeter method requires that you click the Station button, and set your target station for collection of cross-section data.

X-SC	T SURV				NUD	Station <u>OK</u> <u>C</u> ancel	
٠	Fixed		<mark>н</mark> 5	70 m			
Ð,	t.	54 55 40 .41 53 5 .52 <			S	Station: 0+280.000	
Q	un E+	52 51 43 54	シ_		N	7 Prev Next	
	Pt: 57 N:5000.605;	Desc: 0+140		HT: 2.1		Chainage Direction: Lto R R to L 	
	HRMS:0.0	43 VRMS:0.0	74	51,5025	C	CL Off: 0.000	
<u> (</u>		00.000 R0 42.549 L2			M	Inc. Sta: 20.000	
R	STA	CL/BL	-0.00	СНК			



Then you proceed from the current location to the target station. In fact, although the points that are stored may contain station and offset descriptions, the data stored to the raw file pays no attention to the centerline information. The station and offset on the screen act only as a check on your current location. The direction of taking the sections, (L to R or R to L), is important and is set by specifying "Chainage Direction". Unlike with the SCT format method, pressing Menu to exit does not store the data, but instead the data is automatically stored as you go, as a series of 37 (N), 38 (E) and 39 (Z) record types (Geodimeter format), with header line records, as shown below:

```
50=XSEC1
54=104 North
0=As-Builts 240-300
53=VF
90 = 2
97=0
51=3-28-2004
56=65.0
74 = 30.10
55 = 3
96=2
6 = 2.100
80=280.000
91=1
37=5105.857
38=5069.091
39=991.905
37=5104.091
38=5074.931
39=990.724
```

Starting left to right, the data points begin with a 91=1 record. A right to left section would begin with 91=2. When you "cross 0" or are on the centerline or baseline, you click the CL/BL button which sets a 92=1 record for centerline and 92=2 for baseline, and the next shot is the centerline/baseline shot. If you select the "-0.00" button, this indicates whether the next shot is a tie-in (catch) or extension beyond the tie-in. This sets a 93=1 record for the catch and 93=2 for the extension prior to the subsequent coordinate record. In effect, you tell the program where the centerline or baseline is by shooting that point. Then the station and offsets of the shots for that cross-section are determined relative to that center-of-alignment shot. It does not use a horizontal alignment combined with rounding to determine the station and offset of the shots (like the SCT method does). You tell it the station, the direction of measurement (left to right or vice versa) and you tell it which one the center shot is. This is why the Raw/Geodimeter method is the only method that works with no centerline (the "None" option). For each section, you tell it the station and center shot, and all other measurements are used to determine the left and right offsets relative to the center shot. If the L to R method was used, shots before the center shot are on the left, for example, and their offset is determined by the inversed distance to the center shot. The centerline file or other form of horizontal alignment, if selected, is academic and only used to advise you on



your current station and offset. The CHK button will allow checking into known points to be sure that tight coordinate control is maintained. N moves onto the next station as defined by the interval set using the Sta button.

Note: The. SCT file method is the standard Store Sections method. The RAW/Geodimeter method is a flexible routine designed to adapt to customers who have built their cross-section processing systems around the Geodimeter raw file format.



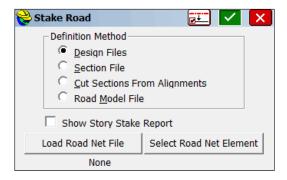
8.10 Stake Road



Stake Road is one of four major commands used in highway work. This command is designed to stakeout specific stations and offsets along a centerline and can be used for slope staking. For example, if your goal is to stakeout the break points like edge-of-pavement and shoulder at station 87+80 on a given road centerline, you would use **Stake Road**. **Stake Road**, therefore, is used primarily to lay out road surfaces for construction. **Stake Road** is typically used to set cut and fill stakes or "blue tops" at specific stations and offsets. The elevation used to determine the cut or fill at each offset is derived from either design files (the template interacting with the profile and centerline) or from cross-sections or from sections that are "cut" from alignments. The "Road Model File" option loads a LandXML file containing alignments for each break in grade, such as edge-of-pavement, shoulder and ditch lines. In each case, at any specific station, you will be guided to the desired offset and will get a cut or fill.

By contrast, if the goal were to simply set random cut and fill stakes along an alignment, at no particular station or offset, then the command **Elevation Difference** would be used. If the goal is to stake out the "catch" in cut and fill, where cut slopes and fill slopes meet existing ground, then **Stake Slope** would be used. However, you can also Slope Stake within **Stake Road**, with the advantage of having the option to see both a section and plan view. **Stake Slope**, by contrast, has one advantage over Stake Road in that it can slope stake at any position, and does not require a station to be specified. The fourth, major highway-oriented feature is Store Sections, which is used to gather "as-built" information on a road. In this command, you take cross-sections of data points along the road, at random or specific stations.

In summary, **Stake Slope** starts the cut and fill work, **Stake Road** directs the precise roadbed work and fine grading, **Elevation Difference** acts as a quick grade check, and **Store Sections** produces the final confirmation of the as-built road for payment and certification. It is highly recommended for all road stakeout that you set on "Use CL for Reference Object" within **Configure**, **View Point** tab.





- Reference Centerline Button: In the opening screen, the button up top, left of the green check (OK), is the "Reference Centerline" button. This button allows a second centerline to be used for instructions on forward and back, Left and Right to stake the point calculated from the primary, first centerline. This is useful when the primary centerline is curving and where a single point may be offset from different positions along the centerline. The second, reference centerline is usually the main road centerline, so that forward-back, left and right instructions are easy to follow. Because this feature is rarely used, its very appearance is configurable. You must turn it on in File, Job Settings, Stake Tab, Alignment Settings, Option "Allow Reference Centerline". If checked, this means a reference centerline will be used for the road options Design Files, Section File and Road Model File. Note that if the refence centerline is on, but carried forward from another job, you might obtain extremely large station and offset data, possibly with negative numbers. The reference centerline station and offset data is always presented with an asterisk (*), so if you see the asterisk followed by clearly erroneous data, look to see if the reference centerline has been left on, pointing to an incorrect centerline, and turn it off.
- Story Stake: The middle zone of the opening screen in Stake Road shows the 4 methods of defining the road, described below. Underneath the method options is the option to turn on "Show Story Stake Report". If this is selected on, then ANY point that is staked out on the road will lead to an entire report on all breaks, starting on the far outside of the section on the side you are on, to the point you staked, then past that point all the way to centerline, as shown below. Note that your current staked position is SHLD1, so since this is on the right side of the road, the first page of the report and the first line of the second page shown cover distances to offsets further to the right, and the lower portion of the second page cover distances from your staked position in to centerline. You can also see the relative cut and fill and distance to the break points on the other side of the road if you click off "Show Report up to CENTER". Then the report would be even longer! Similar to the Slope Stake Report, you can see the progressive horizontal and vertical distances or the total to you current, staked position. Although it is standard to do these reports and mark slope stakes, the Story Stake allows you to mark ANY stake, not just the slope stakes on the outside of the road, but, for example, mark all information on a central depressed median stake, which the contractor can then reference. The Story Stake report applies to all Stake Road methods.



<mark>हे</mark> Offset Point Report 🗸 🗸							💝 Offset Point Report 🛛 🗸					
○ Progressive Total ✓ Show Report Up to CENTER							○ Progressive Total					
Offset PT_Sta: Off	set:	El	evatio	on:			Offset PT_Sta: Offset: Elevation:					
21915.000 R4	5.258	32	2.091				21915.000 R46.258 32.091					
	HDIST	VDIST	SLOPE 🔺				HDIST	VDIST	SLOP	Έ		
OFFSET to DITCH1	113.14	13.70	CUT	12.1%			OFFSET to DITCH	13.67	1.18	CUT	8.6%	:
OFFSET to SHLD6	89.17	1.72	CUT	1.9%	ţ		OFFSET to SHLD1	0.00	0.18	FILL	999.9%	(
OFFSET to SHLD5 83.67 1.27 CUT 1.5% (OFFSET to SHLD	4.00	0.11	FILL	2.8%			
OFFSET to ROAD6	73.67	0.85	CUT	1.1%	{		OFFSET to ROAD2	2 10.00	0.00	CUT	0.0%	(
OFFSET to ROAD4	49.67	0.30	CUT	0.6%	:		OFFSET to ROAD	22.26	0.23	CUT	1.0%	
OFFSET to ROAD3	37.67	0.02	CUT	0.1%	(- 1		OFFSET to CENTE	R 46.26	0.68	CUT	1.5%	Ţ.
							•				►	Ċ

• Road Network (.rnf) Files: The Carlson Civil module of the Carlson office software has a command called Road Networks that will output both design files and cross-section files for street intersections and cul-de-sacs, in addition to main alignment segments of the road. The breakthrough feature allows for staking out of complex intersections, including what are sometimes called the "curve returns" where the edge-of-pavements and other breaklines, in effect, are filleted with inscribed curves. The multiple curves of cul-de-sacs can also be output. It is highly recommended that when Road Network Files are used, you should select the Section File method of stakeout within Stake Road. The outputting of Road Network files is found within Settings in the Road Network command in Carlson Civil, as shown below as "Write SurvCE Stakeout":

Road Network Settings							
Process Options Output Options	Report Options Display Options Transition Defaults						
Triangulate and Contour	Setup						
Merge Road With Existing	Set CivilHydro						
✓ Write SurvCE Stakeout	Set CivilDemo						



Defining the Road

The first dialog that comes up when you select Stake Road is where you define the road by selecting one of the following options.

• **Design Files**: In Carlson SurvCE, design files include templates, centerline, profile and optionally, superelevation and template transition files. If you wish to "clear" a file such as a superelevation file, just click it and choose Cancel. The definitions for each of these files is covered in their own sections of this manual. Design files are recommended for subdivision streets, access roads and simpler highway designs. The Template Grade Table file which can be input and edited under Road Utilities also is used as a "design" file and replaces the need for template transition and superelevation files, covering both options by specifying cross slopes and grade widths across any station range for any template ID.

🔍 Stake Road 🛛 🖌 🔀	🔍 Design Files 🛛 🗾 🔽					
Definition Method Oesign Files	Centerline None					
O Section File	Profile None					
O Road Model File	Template None Optional Files					
Show Story Stake Report	Superelevation None					
Select Utilities From File OFrom MAP	Tpl Transition None					
Load Road Net File Select Road Net Element	Tpl Grade Table None					
0% None	Load Roading Files Save Roading Files					



• Section Files: Sections are made up of simple offsets and elevations that can have optional descriptions such as "EOP", "DL" or "SH" and must be accompanied by a horizontal alignment file (centerline). The vertical alignment or profile is optional but improves accuracy at high and low points. Every cross-section is a "snapshot" of the template at a given station. SurvCE supports using multiple surfaces simultaneously in Stake Road by using multiple section files or by extracting the section for each surface when all surfaces are within a single file (as exported by Carlson Civil). Each surface can exist on its own layer with its own color for easy identification while in the Stake Road dialog. For complex designs, with non-conforming intersections, transition lanes, special ditches, etc., it is recommended to use cross-section data if available. Longitudinal pipes can also be displayed in cross-section and staked out.

🔍 Stake Road		 × 	Stake Road			✓ ×	
Horizontal Vertical 9	Section Other		Horizontal	Vertical	Section	Other	
1 Centerline File	☑ Divided Highway						
2 Select Polyline	4 Preview	5 Edit	Left 1 Centerline		OL	€R	Off:
3 Define Point List	6 Save As			None			0 VOff:
			2 Profile	None			0
Centerline: None			Right		OL	R	Off:
			3 Centerline	None			0
Cutsheet: None			4 Profile	None			VOff: 0



• **Cut Section from Alignments**: Provides the ability to extract cross-sections directly from 3D polylines that exist within SurvCE. The first thing you need to define is the horizontal and vertical alignment files. These form the basis for cutting the sections and determining left and right offsets from the horizontal alignment or centerline. The centerline-defining screen is similar to the screens found in Stakeout Line and other commands.

🔍 Stake Road 🛛 🔽 🔀	Stake Road		🔽 🗙
Definition Method O Design Files	Horizontal Vertical		
O Section File	1 Centerline File		
Cut Sections From Alignments	2 Select Polyline	4 Preview	5 Edit
O Road Model File	3 Define Point List	6 Save As	
Show Story Stake Report	Centerline: None		
0%	Cutsheet: None		

• Road Model File: Loads a LandXML "model" of all alignments associated with the road. Each "break point" on the road such as centerline, edge-of-pavements, shoulders and ditch lines can be considered to have its own horizontal and vertical alignment. By including all of these files in a single LandXML file, and by user selection of the true centerline for stationing purposes, the entire road can be defined in the form of a multi-alignment LandXML file. This method is commonly used in Scandinavia, the UK and by some U.S. Departments of Transportation.

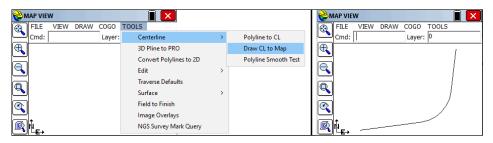
🔍 Stake Road 🛛 🖌 🔀	🔍 Select LandXML File 🔃 🝙 🔽 🗙							
Definition Method O Design Files O Section File O Cut Sections From Alignments	Type: LandXML Drive: C Drive:							
Road <u>M</u> odel File	geoids							
Show Story Stake Report	Pictures_NewJ							
Select Utilities From File From MAP	Pictures_NewJo							
0% None	Name:							

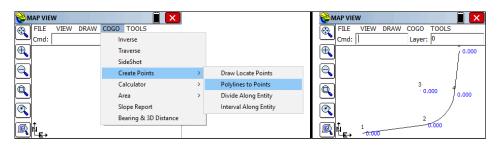


Design File Method

Design File Example Demo: Provided with SurvCE and SurvPC are sets of roading files called Demo.cl (centerline, horizontal alignment), Demo.pro (profile, vertical alignment) and Demo.tpl (template). In SurvCE, these are known as "design files" for road work. In particular, the template is a rule-based design file controlling grade cross slopes, and including definitions for road lanes, curbs and cut and fill slopes. This template approach is best for simple roads such as subdivision and building access roads where rules are strictly followed (except at intersections). For intersections and cul-de-sacs, Road Network Files (.rnf files) from Carlson Civil can be used for stakeout (best done using "Section Files"). Design Files can be acted on by template transition files (which expand and contract road lanes), by superelevation files (which alter cross slopes) and by template grade table files (which both change lane dimensions AND cross slopes). Here is an example of a simple road. You can follow along using the 3 "Demo" files (.cl, .pro and .tpl).

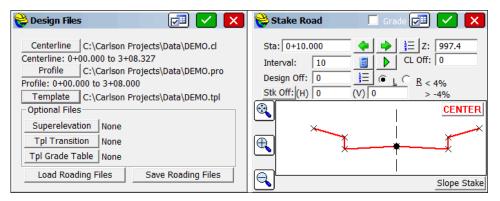
Begin by starting a job named Demo. It does not matter whether you are in metric units or feet. If there are any points in the file, go to Cogo, Keyboard Input, Utilities and delete all points by range (or enter ALL). You can delete any points one-by-one using File, Points, highlight and delete. Now draw the Demo.cl centerline using the command, in the Map screen, under Tools, Centerline, Draw CL to Map. Then use Cogo, Create Points, Polylines to Points to turn the centerline into points at all vertices and radius points. Start numbering at point 1.





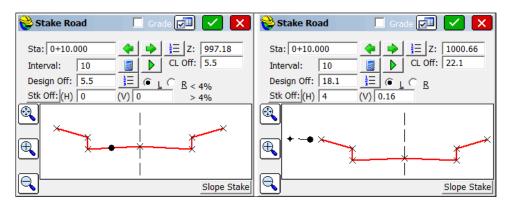


The next step is to go to Road, Stake Roads, be sure no reference centerline is selected (button at top of screen) and select Design Files. To turn off any of the 3 files in the lower, optional section of the dialog (lower left), click those items and remove file using Cancel (red X). Note that the stationing of the centerline and profile do not need to match--they just need to have areas of overlap to work. In this case, the end station nearly matches perfectly (308.327 vs 308). So, you could not stake out station 308.1--there is no extrapolation on the vertical alignment. You will be warned, "No Cross-section..." if you enter 308.1 to stake.



The settings button in the Design Files screen allows application of the profile to any template IDthe default is "Center" or center of road. For divided highways, the profile grade is often the inside edge-of-pavement, rather than the center (which might be a concrete median or central ditch). The settings button in the Stake Road dialog above goes to the standard, 3-tab Road Stake dialog also accessible in Job Settings, Stake option. This controls various things such as vertical exaggeration (here 4x was used) and key station points to increment through (e.g. PC, PT, high points, low points). Select a Design Offset of 0 by entering it or picking the middle of the template (zoom extents to center the template). Set a Stake Offset H=0 and V=0. Note that the slope into the selected point (left of center) is displayed as 2% and the slope right of center is displayed as -2%. Slopes in this display are calculated left to right, not outward from centerline (in which case both slopes would be -2%). Select any point on the template to stake, either graphically by picking or by entering a point. If you pick graphically, you must pick a template "break point", indicated by the X's. All template break points have template IDs like EP for Edgeof-Pavement and SH for Shoulder. If you enter an offset, you can select a point that is not a break point, such as 5.5 Left (shown below):





If you click OK, you begin the stakeout process (requiring Localization if running GPS Simulation). Another option is to stake an offset. Click on the far-left template point (SH) and then enter an offset of 4 units. Then if you want to extend the slope of the last segment, click the "Stk Off" button, choose Extend Current Slope option, and return back to the above right screen. Note the vertical offset is calculated for you (you can always direct enter the vertical offset if you know it). Also, note as you make these various changes to the target point to stake, the Z elevation in the upper right of the screen is re-calculated and the target "CL Offset" distance is displayed, which is now distinct from the Design Offset. When ready, click OK to stake out.

Design File Example with 4% Cross Slope Superelevation using Superelevation File: Let's say the road goes through a superelevation of 4% at the PC at station 127.62 and complete superelevation of 4% at the PT station of 219.62, transitioning from normal crown to full super in 90 feet (e.g. 37.62 start transition, pivot from -2% to 2% on outer lane to "reverse crown" at 97.62 and reach 4% full super at 127.62). In this way, the rate of transition of the outside lane on the curve left is 2% each 30 length of road. Complete the same transition in reverse after the PT, from 219.62 at 4% to 249.62 "reverse crown" (2% slope both lanes) to 309.62 end full super. This can be accomplished by 2 methods: (1) Superelevation Files applied to a single Template or. tpl file or (2) by (Template Series Files--using 3 templates: normal crown, reverse crown and full super). It is very important to first define the template ID point outside of which no superelevation rules are applies. If you have a curb and gutter road, usually the edge-of-pavement (EP in this case) is the outside lane to apply the superelevation--all template points beyond that follow their original definition, including the 4% uphill shoulder slope, even when in superelevation.



😝 Input-Edit *.tpl File	🛃 💽	😂 Super Elevation Settings 🛛 🔽 🗙
Left SURFACE TD Distance Slope TD 10.000 -4.000% EP 0.010 2.000 CB	tt Side Same as Left Right SURFACE Distance Slope ID 10.000 -4.000% EP 0.010 2.000 CB 6.000 4.000:1 SH	Divided Road Transition from Normal to Super(Inside Edge) High Side PP: Low Side PP: High Side PP: EP Low Side PP: EP Max Percent Slope Difference: 7% Low Side Grades to Match Greater SUP Slope: 0

Now to accomplish the above superelevation by use of a superelevation file, enter the following within Road, Utilities, Input-Edit Superelevation Files:

😂 Add Super (Stations):	🔽 🔽	裬 Superele	vation List	: Demo		- (-
0+37.620 0+6 Reverse Crown rate in: 0+6 Grade Slope(%): 2.000 Desi Curve Type: O 9 Max slope of Full Super(%): 1 1	in Run-In: -67.620 -97.620 sign Speed: 35.00 Spiral Circular 4.0000	Beg Trans 0+37.620	Run-In 0+67.620	Norm Out 2+49.620		End T 3+09.6
1+27.620 2+1	I Full Super: -19.620 49.620 End Transition: 3+09.620	Add	Edit	Remo	ve C Save	lear As

Note that 3 transition points are defined: (1) begin transition, (2) run-in and run-out where the pivoting outer lane side has a zero cross slope, (3) reverse crown and full super. So, between these 3 transition points, the rate of transition may vary. In this case the rate is the same, 2% every 30 units of length on the outside lane. This entry creates one line of superelevation, one for each curve involved.



When this is applied, note cross slopes at stations 67.62 (2% and 0%), 97.62 (2%) and at station 127.62 (4%) below:

😂 Design Files 🛛 🗾 🔽 🗙	😂 Stake Road	🗌 Grade 🗾 🗹 🗙
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327 Profile C:\Carlson Projects\Data\Demo.pro Profile: 0+00.000 to 3+08.000 Template C:\Carlson Projects\Data\Demo2.tpl Optional Files Superelevation C:\Carl. Projects\Data\Demo.sup Tpl Transition None Tpl Grade Table None Load Roading Files Save Roading Files	Sta: 0+67.620 Interval: 5 Design Off: 0 Stk Off: (H) 0	
		Slope Stake

Shown below are the reverse crown and full super sections at station 97.62 and 127.62:

😂 Stake Road	📃 Grade 🗾 🔽 🗙	误 Stake Road	📃 Grade 🗾 🗹 🗙
	$ \begin{array}{c c} & & & \\ & & \\ \hline \\ & & \\ \hline \\ \\ \\ & \\ \hline \\ \\ \\ \\$	Sta: 1+27.620 Interval: 10 Design Off: 0 Stk Off: (H) 0	$ \begin{array}{c c} \bullet & \bullet & \vdots \equiv \\ \hline & \bullet & \vdots \equiv \\ \hline & CL \ Off: \ 0 \\ \hline & \vdots \equiv \\ \hline & \bullet & L \\ \hline & \bullet & L \\ \hline & \bullet & E < 4\% \\ \hline \\ \hline & \hline & CENTER \\ \hline & \hline & \hline \\ & \hline & \hline \\ & \hline & \hline \\ & \hline & \hline$
	Slope Stake		Slope Stake



Design File Example with 4% Superelevation Plus Lane Width Changes using Template Series (.tsf) File: Another way to accomplish lane-controlled superelevation is to use distinct templates, linked together as a "Template Series" file. In addition to the standard 10 width road at 2%, add another template for the reverse crown condition and a third template for full super. You need all three, since there is no slope change on the low side until reverse crown at 2% (same slope L and R) is achieved, at which point both sides pivot to full superelevation. We choose to do a second reverse crown template of 8 width to illustrate that you can also change the lane width on any of the additional templates, for a simultaneous reduction or expansion in lane width through superelevation. Here are 2 of the additional templates for this example:

💝 Input-Edit *.tpl File 🛛 💽	🛛 计 Input-Edit *.tpl File 🛛 💽 🧲
C:\Carlson Projects\Data\DemoSuper.tpl GRADES: ✓ Right Side Same as Left Left SURFACE Right SURFACE Distance Slope ID Distance Slope II 10.000 -4.000% CP 1.500 0.000% CP 0.100 0.500 TC 0.500 0.000% CP 0.100 0.500 TC 0.000% CP 0.100 0.500 TC 0.000% CP 0.000% CP	C:\Carlson Projects\Data\DemoReverseCrown.tpl GRADES:

Note here that we have added an additional aspect of lane reduction to 8 units for the DemoReverseCrown.tpl template on the left side. Here we are designing a normal transition up to full super, and then exiting full super at 10-unit width for the EP, transitioning to reverse crown at only 8-unit lane width. So that transition would occur from the PT station 219.62 to reverse crown to at 249.62. To stay and finish at 8-unit lane width for the EP left, we need 1 more final Demo8. TPL, defined as having a 8 unit EP width, left side. This Template Series file is then created in Road, Utilities, option Input-Edit Template Series. Clear anything that is there (erase icon) and then enter as shown:

💝 Template Series 🛛 🔽 🗙	😂 Input-Edit TSF File	💽 💽
	C:\Carlson Projects\Data\Dem	o.tsf
	Station Template	
	0+00.000 DEMO	
	0+37.620 DEMO	
	0+97.620 DemoReverseCrow	n
	1+27.620 DemoSuper	
Station: 0+00.000	2+19.620 DemoSuper	
	2+49.620 DemoReverseCrow	'n
Template: None	3+09.620 Demo8	
C:\Carlson Projects\Data\DEMO.tpl	Add Edit Remo	Draw Template
EQ Select File	Load Save Save	As EQ

Now when Stake Road is run, station 219.62 shows full super and the transition to a 8 unit lane width occurs from 219.62 to 249.62, holding 8 width on the EP lane through to the end (station



308). Note below left that when selecting the template, you actually load the demo.tsf template series file which includes reference to ALL of the various templates as defined within Input-Edit TSF File. You do not use any optional files in the lower half of the dialog.

😂 Design Files 🛛 🗾 🔽	😂 Stake Road 🛛 🗌 Grade 🗾 🔽 🚺	<)
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327 Profile C:\Carlson Projects\Data\Demo.pro Profile: 0+00.000 to 3+08.000 Template C:\Carlson Projects\Data\Demo.tsf Optional Files Superelevation None Tpl Transition None Tpl Grade Table None Load Roading Files Save Roading Files	Sta: $2+19.620$ Interval: 10 Design Off: 0 Stk Off: (H) 0 (V) 0 CL Off: 0 E CL Off: 0 CL OF	
	Slope Sta	ke

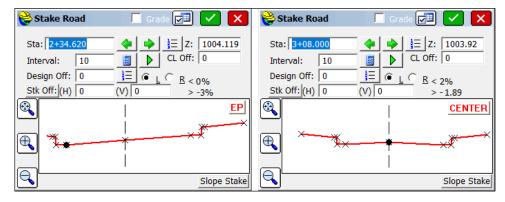
Compare station 219.62 above (end of full superelevation) to station 127.62 (start of full super) further above as defined by superelevation files. They are similar. Also, note station 234.62. It is halfway through the transition from 10 width to 8 width on the left side (EP=9 Design Offset), and also transitioning from full super (4%) to reverse crown (2%). At station 308, the road superelevation has not fully transitioned back to 2% (at station 309.62). Wherever you pick the middle right of the display shows the cross slope left and cross slope right of your picked point. So the cross slope on the right side is -1.89% trending downward to -2%. Also, note the shorter dimension (8 units) of the EP lane left of centerline.



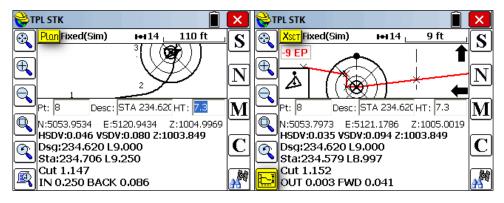
The variations in the road shown below can be seen in "drive through" mode by entering the

starting station, picking an offset to follow (such as Center) and clicking the Green Arrow opposite the word Interval. This drives through the site at the selected interval, and you can watch

grades rise and fall, expand and contract. The Red Box stops the process.



Clicking OK on station 234.62 above would lead to the following stakeout screen, as seen in Plan View (default) and Section View (click Plan/Section in upper left of screen to switch between views). The button shows current view status.



In section view, if the vertical exaggeration is too large, tap the lower left icon (circled in red) and reduce the vertical exaggeration to 1 or 2, real-time, while in the process of staking the point. If the position is within tolerance settings under Equip menu for stakeout, the larger 'bullseve" will appear. Note also that using C for Configuration, you can go to the View tab and click on "Use CL for reference object". This means that whenever a horizontal alignment is involved, your instructions will be in the form of forward and back on the alignment, in and out from centerline.

Design File Example--Divided Highway: Divided highways with central ditches (sometimes called "depressed medians") can be defined as templates, starting from the center (ditch or low point) and entering each slope out to the cut and fill. In the example below, there is both an inside Page | 509



shoulder (4%) and outside shoulder (also 4%). The template is shown both inside the editor and through the command Draw Template.

😂 Input-Edit *.tp	l File		🛃 🧲		TPL VIEW	Ê → C
C:\Carlson Project GRADES:	<u> </u>	.tpl e Same as	Left	[3	
Left SURFACE		SURFACE		Ī		and particular
Distance Slope	ID 🔺 Dista	ance Slop	e I <u>I</u> ≜			\sim \sim
.2.000 -2.000%	EP2 24.0	00 6.000):1 M		੨∣੶	•
3.000 -4.000%	EP3 8.00)% <u>Ef</u>		ฉี	
4.000 -6.000:1	SHE 12.0			- P	K	
·		00 -2 00		Ī	<u>হ</u>	
Add Edit	Remove	Up	Down		Filž	
Cut/Fill	Super	Load	Save	L L	Template	e(Sc.Y=4.00): C:\Carcts\Data\Divided.tpl

In the Draw Template command, you can Green Arrow to the right and view all template files stored in the current directory of your data collector or PC. This is a way to visually "walk through" all your template files to confirm their appearance.

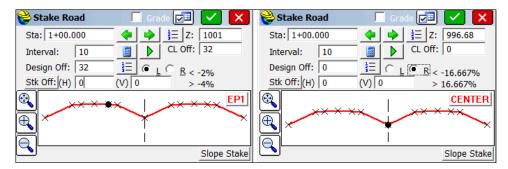
It is using divided highway style templates where use of the first settings button in Stake Road is so essential. In almost all cases, the ditch line is not the defined "grade point" of the road. The vertical alignment or profile is typically applied to the inside edge-of-pavement, in this case "EP1". This is accomplished by clicking Settings in the Design Files dialog (highlighted):

😂 Design Files 🛛 🗾 🔽 🔀	裬 Settings	🔍 or 🔍 of 🔽 🗙
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327 Profile C:\Carlson Projects\Data\Demo.pro Profile: 0+00.000 to 3+08.000 Template C:\Carlson Projects\Data\Divided.tpl Optional Files Superelevation None Tpl Transition	Apply Profile at Fix Offset Template ID Reference Alignm	CENTER CENTER MED EP1 LANE
Tpl Grade Table None Load Roading Files Save Roading Files	Vert Off of Profile:	EP2 EP3 SHD



Then, if a template ID is the grade point, you can choose it from a dropdown list. The profile grade can also be applied to a fixed offset (26 feet right for example) or to an entirely different reference alignment (selected as a .cl file). You can specify a vertical offset for the profile as well. So, if you defined your template as the subgrade slopes rather than surface slopes, your goal being to stake subgrade, you would need to reference the subgrade to the true profile of the road by entering a vertical offset. The use of the profile offset and reference itself can be turned on and off at the top of the screen. Until the Profile Setting is turned off, Stake Road always passes through the dialog above right to be sure you intend to use the current settings.

So, with this setting, and recognizing that the profile grade at station 100 is 1001.00, staking of the centerline ditch or depressed median will result in a recalculated center profile grade of 996.68.

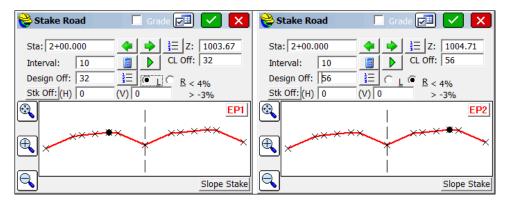


Divided Highways also offer challenges regarding superelevation. When in superelevation, only certain lanes respond and slopes such as shoulders and the inside ditch slopes remain constant. Within Input-Edit Template File, click on "Super" to set the controls for where superelevation applies:

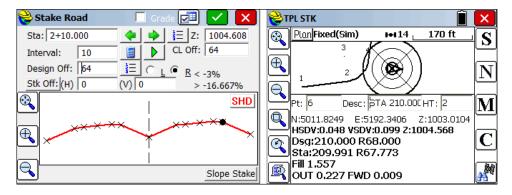
😂 Super Elevation Settings 🛛 🔽 🔀	😂 TPL VIEW 📋 🔁 🧲
Divided Road	<u>®</u>]
Transition from Normal to Super(Inside Edge)	
High Side PP: EP1 Low Side PP: EP1	
Transition from Normal to Super(Outside Edge)	
High Side PP: EP2 Low Side PP: EP2	
	<u></u> <u></u> →
Max Percent Slope Difference: 7%	1
Low Side Grades to Match Greater SUP Slope: 1	Template(Sc.Y=4.00): C:\Carcts\Data\Divided.tpl



With the above settings, even with superelevation applying to the 2-lane driving surfaces only, the outside and inside shoulders will change if the Maximum Algebraic Difference of the slope percentages are more than 7%. So, if the normal shoulder is 4%, and the road is in 4% super, then the uphill shoulder of the road at 4% downhill would result in an 8% algebraic difference. Thus, a 3% outside shoulder slope will be forced. This prevents "bottoming out" of vehicles as they drive outside the passing lane towards the shoulder in high-side superelevation. Here is an example of this applied in 4% superelevation. Note how the maximum 7% algebraic difference, forcing the shoulder to 3% from normal 4%, applies to both the inside and outside high side lanes.



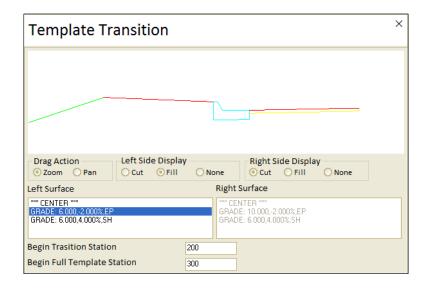
Shown below is a staking of a Horizontal Offset of 4 from the outside right shoulder, extending the shoulder slope to the right on station 210.





Design File Example with Reduced or Expanded Lane Dimensions using "Template Transition" (.tpt) File: Let's say that starting at station 200, the road shrinks from a width of 10 units on the left side to 6 at station 300. This can be accomplished, per above, by Template Series Files. But there is a file known as a Template Transition File and it is one of the only files requiring Carlson Civil, the Carlson office solution for road design, to make in advance. This is done using the command "Template Transition" under the Roads pulldown of Carlson Civil. The stations need to be entered in increasing order for start transition, Full Template (complete transition), and end Full Template and resume normal template. If there is no resumption of normal template, enter stations beyond the job range.

📚 Design Files 🛛 🗾 🔽 🗙	裬 Stake Road 👘	🔲 Grade 🗾 🗹 🗙
Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327 Profile C:\Carlson Projects\Data\Demo.pro Profile: 0+00.000 to 3+08.000 Template C:\Carlson Projects\Data\Divided.tpl Optional Files Superelevation None Tpl Transition C:\Carn Projects\Data\TEMP.tpt Tpl Grade Table None Load Roading Files Save Roading Files	Sta: 3+00.000 Interval: 5 Design Off: 6 Stk Off: (H) 0	↓ ↓ ↓ Z: 1003.88 ↓ CL Off: 6 ↓ CL Off: 6 ↓ CL Off: 6 ↓ CL Off: 9 ↓ CL
	<u>S</u>	Slope Stake



Note that at station 300, the full EP position is at Design Offset 6, based on the DEMO template transition file (DEMO.TPT). At station 250, the EP lane would be 8 units wide, halfway between



normal 10 at station 200 and the reduced with of 6 at station 300. The Template Transition File is a relatively crude method compared to others and can be considered a "legacy" feature reading Carlson Civil ".tpt" files. The expansion or contraction of road lanes, with the greater flexibility of both maintaining AND altering cross slopes, can be accomplished with Template Series Files (described in Superelevation example above) and with Template Grade Table Files, described next.

Design File Example with Template Grade Table File: The same example using Template Series File, where the Demo.tpl road is transitioned through 4% superelevation and a lane width change, left side from 10 to 8, can be accomplished identically using a Template Grade Table. The Template Grade Table takes a single template and associates specific lane width and slopes with any specified template ID point, left or right. This method has the ultimate flexibility for controlling road designs. Although described in the section on Road, Utilities, here is the above example accomplished using the Template Grade Table.

S	😂 Input-Edit *.tgt File 🛛 💽 🧲								8	Grade				🛃 🔽	X
	C:\Carlson Projects\Data\Demo.tgt Load TPL C:\Carlson Projects\Data\Demo1.tpl								ID: EP Station	Slope %	Distance		Side: Left		
	Left	SURFA	CE		Righ	t SURFA	ACE								
	ID	Table	Distance	Slo	ID	Table	Distance	Slc							
	EP	Yes	10.000	-4.0	EP	Yes	10.000	-4.(
	CB	No	0.010	2.00	CB	No	0.010	2.0							
	SH	No	6.000	4.00	SH	Yes	6.000	4.0							
										Station:	0+97.620		Slope:	-2.00%	
	•			Þ	•			•		Dist:	10.0000		L Sho	ow As Ratio	
	R	eport	Edit			EQ	Save	e		Show	Zeroes	Delete It	tem	Add Item	

You start by selecting the grade that will change. In this case, both the EP Left and the EP Right grades will be impacted by superelevation and lane width changes. So you can start by selecting EP Left. You next enter the station where the continuous transition from normal EP Left grade/slope to a different EP Left grade/slope occurs. The last station where 10 width at -2% occurs is reverse crown (2% all the way across) or 97.62. Enter that data and then click "Add Item". The next station controlling the transitional slopes on the left side would be full superelevation (-4%) at station 127.62. Continue entering the data as shown below left. The left EP lane holds -2% slope and 8 width through the end starting at 249.62, so no final station needs to be entered. For the left side, only 4 stations, as shown, control all the EP transitions.

裬 Grade			[I	X	Grade				L 🗸		X
ID: EP			Si	de: Lef	it	ID: EP			S	ide: Rig	ht	
Station 9	Slope %	Distance				Station	Slope %	Distan	ce]
0+97.62 -2	2.000	10.0000				0+37.620	-2.000	10.000	D			ī
1+27.62 -4	4.000	10.0000				1+27.620	4.000	10.0000	D			1
2+19.62 -4	4.000	10.0000				2+19.620	4.000	10.0000	D			
2+49.62 -2	2.000	8.0000				3+09.620	-2.000	10.000				
	2 +49.620 8.0000		Slope:	-2.00% w As Ra			3+09.620 10.0000		Slope:	-2.00% ow As Rat		
Show Z	Zeroes	Delete It	em	Add I	tem	Show 2	Zeroes I	Delete It	em	Add It	em	

Turning attention to the right side, or "high side" in the superelevation caused by a curve to the left, the transition out of normal crown begins at station 37.62. So this must be entered as the last "normal" width/slope station for the EP Right. Then the next controlling station is all the way to the full super at 127.62, since the rate of transition is consistent in this example (2% over each 30 length of road). The right side would have slope 0% at 67.62, +2% at 97.62 and +4% at 127.62 as shown, so only the latter, controlling station data needs to be entered. Complete the entire data for the right side EP as shown below left:

8	Grade		💽 🔽 🚺) In	put-Ed	it *.tgt Fi	le				-
	ID: EP		Side: Right	C:\(Carlson	Projects\Da	ata\D	emo	.tgt		
	Station	Slope %	Distance	Lo	ad TPL	C:\Carls	on Pr	oject	ts\Data\	DEMO.tpl	
	0+37.620	-2.000	10.0000	Left	SURFA	CE		Righ	t SURF/	\CE	
	1+27.620		10.0000	ID	Table	Distance	Slo	ID	Table	Distance	Slc
	2+19.620		10.0000	EP	Yes	10.000	-2.0	EP	Yes	10.000	-2.0
	3+09.620	-2.000	10.0000	SH	No	6.000	4.00	SH	Yes	6.000	4.0
		3 +09.620 10.0000 Zeroes [Slope: -2.00% Show As Ratio Delete Item Add Item	۲ R	eport	Edit	•	•	EQ	Save	•

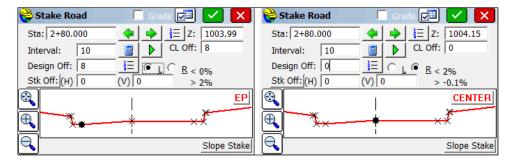
When both EP Left and Right sides are edited, they are marked "Yes" in the Template Grade Table dialog, indicating those template IDs have distinct grade tables. (If, for example, a shoulder dimension was expanded on the right side, it could have its own Grade Table). Note how different the left side EP data is from the right-side EP data--the pivot points for grade changes are different in each case, only identical at the shared full superelevation stations. If the station for the left EP lane width change was different than the precise "reverse crown" station, then a new and separate station would be entered controlling only that lane transition point. Template Grade Tables are ideal for transitioning road rehabilitation projects to existing, undisturbed, as-built road template dimensions and slopes.



Clicking Report in the Template Grade Table routine leads to the presentation at lower right. Now to apply the Demo.tgt Template Grade Table File, add it as an "optional" file in the Stake Road, Design File option. Click OK to proceed.

TPL Grade Table Report	🗧 📚 Design Files 🛛 🗔 🔽
Grade: SH Left	Centerline C:\Carlson Projects\Data\DEMO.cl Centerline: 0+00.000 to 3+08.327
Station Slope % Distance	Profile C:\Carlson Projects\Data\Demo.pro Profile: 0+00.000 to 3+08.000
Grade: EP Right	Template C:\Carlson Projects\Data\DEMO.tpl
Station Slope% Distance 0+37.620 -2.000% 10.000	Optional Files Superelevation None
1+27.620 4.000% 10.000 2+19.620 4.000% 10.000	Tpl Transition None
3+09.620 -2.000% 10.000	Tpl Grade Table C:\Car Projects\Data\Demo.tgt
, L	Load Roading Files Save Roading Files

Note 8 dimension of EP lane width on station 280 when EP Left is clicked on the screen, and when the Center point is clicked, the right lane appears in slope transition downward from full super (at 0.1% uphill grade, nearly flat). Experimenting with different stations or clicking the green arrow "drive through" button both help verify the accuracy of the Template Grade Table entries. It is important to point out that the Design File method allows templates to be adjusted 3 distinct ways: (1) acted on by superelevation (.sup) and lane transition (.tpt) files, (2) transitioned from one template to another with the Template Series File and (3) modified by a Template Grade Table file. The "Cut from Alignments" and Road Model options discussed below may be considered a fourth way, where template ID points can be assigned their own centerlines and profiles, as read from the drawing, directly assigned, or loaded from a LandXML file (Road Model method).





Section File Method

Section File Example with Multiple Sections and Longitudinal Pipes: For complicated roads, the cross-section data, provided at intervals and key stations on the alignment, is very often the "official" design data for purposes of construction. Staking out cross-sections according to the plans, therefore, is standard operating procedure in road construction stakeout. The challenge is often obtaining the cross-section data. Sometimes it is available in LandXML format, which SurvCE can read within Road, Utilities. It may also be available in a Columnar Text format, which SurvCE also reads. As a last resort, cross-section data can be hand entered to form the SurvCE ".sct" file, using the command Input-Edit Section File within Road, Utilities. There is a special format for Longitudinal Pipe Data that can be read automatically by SurvCE. This format, including the header line, is as follows (the "+" in the stationing is optional):

STA	Offset	FL Elev.	Link – ID	Link – Library Item	Туре
13+00.00	52.13	22.32	NP-26	18" RCP	Т
14+00.00	-47.61	22.08	NP-1	18" CMP	Т
14+00.00	49.63	22.02	NP-26	18" RCP	Т
15+00.00	-39.58	21.78	NP-1	18" CMP	Т

The 18" RCP (reinforced concrete pipe), for example, is found at station 13+00 at offset 52.13, flow line elevation (invert) of 22.32, Type 18" RCP and again at station 14+00, offset 49.63, flow line elevation of 22.02. The "Link-ID" column tracks the pipe ID from station to station, and the Link-Library Item is used to confirm the linked pipe and for purposes of display. The final column is used as a pipe designation and should be included. Longitudinal pipe data can also be entered directly within Input-Edit Section File as shown below. Note that the pipe size and name comes first in the description. When importing from an ASCII File, the Link - Library Item is found and sorted such that is goes first in the description field.

C	Edit Station:13+00.000									
	Offset	Elevation	Description							
	52.130	22.320	NP-26, 18"RCP, T							
		Edit Stati	on: 13+00	.000						
	A	dd	Edit	Remove						
	ι	Jp	Down	Clear						



Multiple cross-section files can be loaded by the option "Add Section" in the opening dialog of the Section option within Stake Road, Section File, Section Tab. You can Delete Sections from the list, and you can assign a Layer to the Sections.

📚 Stake Road 🛛 📰 🔽 🗙	😂 Stake Road 🛛 🔽 🗙
Definition Method Design Files Section File Cut Sections From Alignments Road Model File	Horizontal Vertical Section Other 1 Add Section 2 Delete Section 3 Layers Name Start Station End Station DEMO 0+50.000 3+00.000 SECTIONFILEMETHOD 13+00.000 13+00.000
Show Story Stake Report Load Road Net File None	

The Horizontal and Vertical Tabs are similar to those in Stake Line/Arc. The Horizontal Alignment (whether loaded as a ".cl" file or picked from the screen) MUST be selected. The +Vertical Alignment is optional, but for roads with high and low points, the vertical alignment is necessary to interpolate sections correctly when these high and low points or grade changes on the road profile, fall within the station interval. For example, if cross-sections were available at a 50-foot interval, but there was a high point at station 17+75, the vertical alignment would be critical for accurate interpolation of station 17+75. You have the option to apply the vertical alignment or work strictly with the cross-sections.

📚 PRO VIEW 📋 🧲	😂 Stake Road 🛛 🖌 🗙
	Horizontal Vertical Section Other
€ 1700 1750 1800	1 Profile File
	2 Select Polyline 5 Preview 6 Edit
	3 Define Point List 7 Save As
	Profile: C:\Surmo\Data\SCDOT\SC46RFP.pro
	Start Station: 1062.320 m
	Ending Station: 6254.154 ft
Profile(Sc.Y=50.00): C:\Surata\SCDOT\TN1.pro	Apply Vertical Alignment

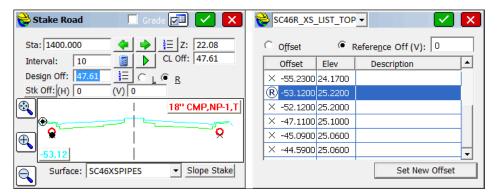
When you click OK (green check), you proceed to the Section Selection screen. Here you can select in the lower portion of the dialog which surface or sections to stake out. All break points on each selected surface appear. If a pipe is selected, its data appears in the upper right. If the cross-sections did not contain descriptions, then only the design offset appears in the dialog, along with the slopes left and right of the selected point. You can pick the points to stakeout graphically on the screen.



😂 Stake Road 🛛 🗌 Grade 📰 🖌 🗙	📚 Stake Road 🛛 🗌 Grade 📰 🔽 🗙
Sta: 1300.000 $\blacksquare \equiv Z$: 22.34 Interval: 10 $\blacksquare CL$ Off: 18.5 Design Off: 18.5 $\blacksquare CL$ Off: 18.5 Stk Off: (H) 0 (V) 0 > -2.034% Stk Off: (H) 0 (V) 0 > -2.069%	Sta: 1300.000 \blacksquare
Surface: SC46R_XS_LIST_SUE Slope Stake SC46R_SX_LIST_SUB SC46R_SX_LIST_TOP SC46XSPIPES	Surface: SC46R_XS_LIST_SUE Slope Stake

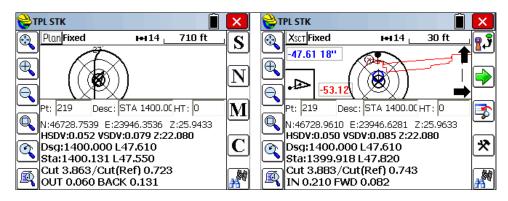
The selected or highlighted cross-section surface always appears red and bold for purposes of stakeout. The Settings button at the top of the screen leads to the standard Road Stakeout settings controls, also found in Job Settings, Stake tab.

Section File with Reference Point in Stake Road (For 2 Cut/Fill Results): The staking of pipes offers a convenient point to introduce the topic of the Road Stake Reference Point. If you click the "From List" button opposite the Design Offset within Stake Road, you are taken to a special list, that offers the ability not just to select the offset and elevation to stake, but to pick a section surface and a reference point on that section to use for stakeout. In this case, we selected the 2nd from left offset point, top of the fill slope, and then clicked "Set REF". This expands the information on the screen to include the reference point offset, to show that point as a black symbol with solid circle inside, along with the target point, in this case the 18" CMP pipe at station 1400.





Now when you click OK (green check) to proceed, additional information is presented on the screen during the stakeout process.



With reference points, the in-out and forward-back guidance is to the target point, but the cut and fill information is provided to both the target AND the reference point. Since the pipe target point is well below the top of bank reference point, cut to the reference in this example is just 0.7 approximately while cut to the pipe is 3.9 approximately. A single stake marking the pipe could show the cut to the shoulder as well. If the reference were reversed, you could stake the shoulder point and also reference the cut to the pipe as additional information to mark on the stake. Options to show North/East or Station/Offset are provided in the Stakeout Report.

😂 Stakeout Report	🗾 🔽	误 Stakeout Report		🔽 🔽
 Show North/East Northing Staked: 46728.842 Design: 46728.883 Move: North: 0.041 ft East: 0.030 ft VOff 1: Elev: VOff 2: Elev: HRMS: 0.009 VRM Store Point Point Point 	 Elevation 25.958 22.080 C(Ref) 0.738 DOP:3.200	C Show North/East Station Staked: 1400.042 Design: 1400.000 Move: BACK: 0.042 ft OUT: 0.029 ft VOff 1: Elev: VOff 2: Elev: HRMS:0.009 VRM Store Point Poi	Offset L42.581 L47.610 C 3.87 S:0.005 nt ID: 219	Station/Offset Elevation 25.958 22.080 78/C(Ref) 0.738 PDOP:3.200

Be sure to clear the Reference Point so it does not stay active.



Section File with Story Stake for ALL Cut/Fills to all Break Points: When staking out crosssections, it is beneficial to turn on "Show Story Stake Report". Whereas the Reference Point method outlined above provides 2 cut/fill values, the Story Stake provides All Cut/Fill values and is easy to use. The one advantage of the Reference Point method is that the reference can be on a different cross-section surface. Regarding the Story Stake, set it on in the opening screen. Then choose a point on a surface with many break points to stake out.

When the point is staked, the initial report screen shows the individual cut fill to the selected point:

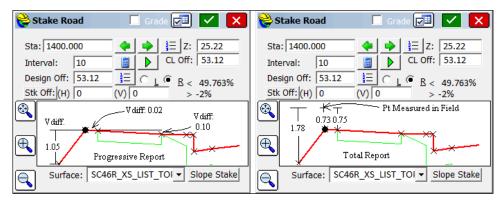
😂 Stakeout Report	X X							
C Show North/East @ Show	Station/Offset							
Station Offset	Elevation							
Staked: 1399.996 L53.122	25.954							
Design: 1400.000 L53.120	25.220							
Move: FWD: 0.004 ft IN: 0.002 ft Cut 0	Move. FWD: 0.004 ft							
VOff 1: Elev:								
VOff 2: Elev:								
HRMS:0.009 VRMS:0.005	PDOP:3.200							
Store Point ID: 219								
Point Description: TA 1400.000 L53.120 CUT0.								

When you click OK with Story Stake turned on, you obtain both Progressive and Total numbers for the entire list of offsets for the cross-section up to Center (entire left side in this case). And if you turned off "Report to Center", you would get a cut/fill report for all offsets on the entire cross-sections, from the single staked point.

😂 Offset Point	Report					\checkmark	Offset Poi	nt Rej	oort				\sim
Progressive C Total					Progressi								
Show Report	ort Up to	CENTER					Show Re	eport U	p to CEN	ITER			
Offset PT Sta:	Offset	:	Ele	evatio	n:		Offset PT Sta	a: O	ffset:		Elev	ation:	
1400.000	L53.12	2	25	.954			1400.000	L	53.122		25.9	954	
	HDIST	VDIST	SLOP	Έ		-		HD	IST VD	IST SI	OPE		•
55.23 to 53.12	2.11	1.05	FILL ·	49.8%	5 2.0:1		OFFSET to 5	5.23	2.11	1.78	CUT	84.6%	1.
55.23 to 52.12	1.00	0.02	CUT	2.0%	50.0::		OFFSET to 5	3.12	0.00	0.73	CUT	999.9%	6 C
55.23 to 47.11	5.01	0.10	CUT	2.0%	50.1:0		OFFSET to 5	2.12	1.00	0.75	CUT	75.2%	1.
55.23 to 45.09	2.02	0.04	CUT	2.0%	50.5::		OFFSET to 4	7.11	6.01	0.85	CUT	14.2%	7.1
55.23 to 44.59	0.50	0.00	FILL I	0.0%	999.9		OFFSET to 4	5.09	8.03	0.89	CUT	11.1%	9,1
55.23 to 44.51	0.08	0.50	CUT	625.0	% 0.2	+	OFFSET to 4	4.59	8.53	0.89	CUT	10.5%	9.1 🗸 📘
	4.40	<u> </u>			17 💽			4 - 4	0.64	100	out.	10.000	<u>آ</u>



Note that the Progressive Report shows the relative vertical distances between offset points, and does not utilize the field-staked elevation in the vertical calculation. But on the Total Report, the vertical difference is from the staked position to each of the offsets. Study the 4th column for the direction of the vertical difference as cut or fill.



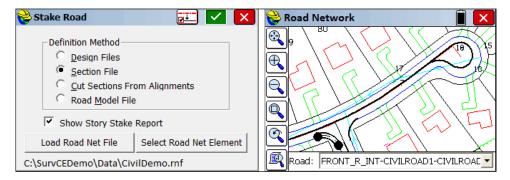
This report can also be saved to a user-formatted cutsheet file. Later in the Stake Road documentation, formatting of Story Stake cutsheets are discussed.

Section File Method using RNF Files from Carlson Civil, Road Network: Carlson Civil will output complete stakeout files in the form of "RNF" files as both Design Files and Section Files to stake all portions of road networks, including intersections and cul-de-sacs. Shown below is a road, viewed in 3D, designed in the Carlson Civil Road Networks command, including the option within Settings, Output Options tab, that produces the named ".rnf" file (Road Network File).

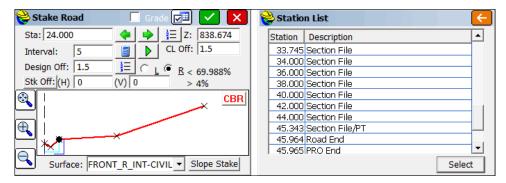
😻 Carlson 3D Viewer	Road Network Settings
	Process Options Output Options Report Options Display Options Transition Defaults
	Triangulate and Contour Setup
	Merge Road With Existing Set CivilHydro
	Wite SurvCE Stakeout Set CivilDemo
	Draw Template Polylines Draw Disturbed Area
	Draw Subgrade Polylines Subgrade IDs to Draw Select
	Draw Template Slopes Template IDs to Draw CENTER Select
	Draw Cross Section Slopes Template IDs to Draw TIE Select
	Draw Cross Section Polylines
	Draw Cut/Fill Arrows Arrow Size 5.0 Solid Cut Arrows
	Label Profile on Centerline Setup
	Output Coordinates Setup Output EOP Profiles Setup
	Elevate Pads Setup
	Set Layers Set Slopes Output File Defaults
	OK Cancel Help



It is recommended that the RNF files be staked out using the Sections options within Stake Roadsince all surfaces can be viewed and selected (e.g. surface of road, shoulder and cut/fill slopes, plus all subgrades). The Section Method offers the flexibility to select any desired Road Net Element for stakeout, as output in the form of the RNF file. To use the command, select the RNF file at the lower left of the opening dialog, then select the Road Net Element to stake, either graphically as shown or from the pulldown list. In the above road example, there are 6 elements, named according to the centerline files involved: (1) First Part Main Road (2) Second Part Main Road after Intersection, (3) Side Road, (4) First Curb Return Main Road to Side Road, (5) Second Curb Return Side Road back to Main Road and (6) the Cul-de-Sac.

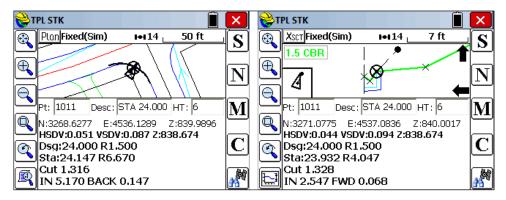


If is our goal to stake the back of curb on the first "Curb Return" as shown, then select it and choose the top surface and pick the back of curb point. If you pick "From List" for the Stations, you can review the entire station range for this small curb return, which in this case is 45.96 as shown below right. So, staking Station 24 on this special segment would be approximately halfway around the curb return. Note the "centerline" used for this is the edge-of-pavement or left-most point on the curb, so that the back of curb appears as CL Offset 1.5 (curb is 1.5 units wide).

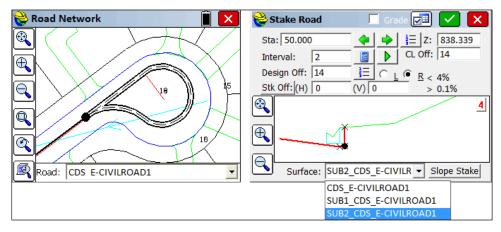




Note how any surface or subgrade point can be selected and staked out, at any distance along the special "centerline" for this curb return segment. The next procedure is to click OK to continue, to enter the stakeout screen, shown below in both plan view and cross-section view.



The process can be repeated for the cul-de-sac. Here we will stake out both the stone subgrade outside point and then we will slope stake the catch at a station approximately 1/4 of the distance around the cul-de-sac:



The cul-de-sac "centerline" is the outside edge-of-pavement facing the curb, and by clicking "From List" opposite Station, is seen to be just over 200 in total length in the screen below left. Staking out station 50 would be approximately 1/4 of the distance around the cul-de-sac.



Statio	n List	←	👌 TPL STK		×
Station	Description	_	Plan Fixed	₩14 <u>110 ft</u>	S
198.000	Section File		EV V	16 15	<u> </u>
200.000	Section File				N
202.000	Section File				LIN
204.000	Section File				
206.000	Section File		Pt: 1011	Desc: 5TA 50.000 HT: 6	ľм
208.000	Section File			J.	LAT V
210.000	Section File			5 E:4744.1779 Z:839.9935	
210.718	Road End			9 VSDV:0.070 Z:838.339	
210.719	PRO End		Dsg:50.00 Sta:50.72		Ľ
1					
		Select	Cut 1.655		
			14.965	BACK 0.720	a 1

The "catch" point at the top of cut can be staked out for station 50 by selecting the top surface outside shoulder point and then clicking the Slope Stake button in the lower right of the screen:

📚 Stake Road 🛛 🗌 Grade 🗾 🔽 🗙	😂 Slope Staking 🛛 🔽 🧲
Sta: 50.000 ▲ ▲ ▲	Slope: Define Slope by Next Section Poi \checkmark R \checkmark CUT: 4.00:1 FILL: 3.00:1 Ratio Mirror CP Pivot Point - Edge of Road > \checkmark Elev From Files Pivot Pt (Z/O/D): 839.756 R19.5 User(SH) Design Pt (Z/O): 839.756 R19.5 Stake Off (V/H): 0 Ref Off (V/Z): 0 N/A

Slope Staking takes you to a "parameter" dialog where you set the Pivot Point type (here it is "User Selection") and how the next slope is defined. By selecting "Define Slope by Next Section Point", the program detects that point is in cut, so calculates the cut upslope at 4:1 (matching the >25% at left) and ghosts the value so it cannot be changed. You can also change the selection type to "User Defined" and enter any cut upslope ratio you prefer. Then click the Green Check (OK) to continue:



X	💝 TPL STK	×
S	XSCT Fixed(Sim) I+I 14 10 ft	S
	-4.000;1	
\mathbf{N}		\mathbb{N}
WI	N:3386.8529 E:4746.4352 Z:841.4873	WI
	Coff:26.425 HSDV:0.050 VSDV:0.075	
Ľ	OUT 3.093 BACK 0.055	Ľ
	× S M C	S Xstr[Fixed(Sim) I+14 10 ft N -4.000;1 -4.000;1 -4.000;1 Pt: 1011 Desc: STA 50.055 HT: 4.5 M Pt: 1011 Desc: STA 50.055 HT: 4.5 N: 3386.8529 E:4746.4352 Z:841.4873 COff:26.425 HSDV:0.050 VSDV:0.075 Sta: 50.055 R23.331 OUT 3.093 BACK 0.055 Descign Cut 4 0001 from 920 756

Note that with a rod height of 4.5 in this simulated example above right, the ground catch position is projected at lower than the original estimate further to the right. This is often the case in slope staking--the ground has been altered since the design was conducted and you must react to actual field conditions. It should also be noted that the Slope Stake command "models" the existing ground real-time as you move, making the best estimate it can of the projected or interpolated catch point position. Since it works real time with GPS without taking a measurement (as required with a total station), it is best to keep the base of the pole close to the ground. Slope Staking leads to the Slope Reports shown below:

😂 Slope Staking Store	🔽 🔽	😝 TPL STK	X
Station Offset Pivot Pt: 50,000 R19,500	Elevation 839,756	RanFixed(Sim) ++14 7 ft	- S
Catch Pt: 50.000 R26.475	841.500		
Stake Pt: 50.028 R26.652 Stk-CP: IN 0.177 BACk	841.500 0.028	SurvCE	N
		Pt: 10 Stake Offset Point?	
Stk-PP: C1.744 @4.102:1 HD: 7	24.381%	Q N:338 Yes No 1998	_ <u>M</u>
✓ Store Data to Cutsheet File		Coff:200000000000000000000000000000000000	
VOff: Elv:		Sta:50.028 R26.652	
Point ID: 1011 Store Poin	t to CRD File	IN 0.177 BACK 0.028 Design Cut 4.000:1 from 839.756	
Desc: STA 50.028 1011 R26.65	2 ê =	Cut 1.744@4.102:1 for 7.152	*

It is recommended whenever doing Slope Staking to stake the first Offset Point, in case the actual catch point stake is knocked out during construction. Typically click Yes to the above prompt, "Stake Offset Point?" Use the "Delta Distance" option.



💝 First Offset 🛛 🔽 🗙	📚 TPL STK
Station: 50.000	Plan Fixed(Sim) HI14 30 ft S
Offset: 5	
, Offset Type	Pt; 1011 Desc; STA 49.982 HT; 4.5
C CL Offset Delta Distance from Catch Pt	N:3383.5117 E:4743.6356 Z:841.5090 H50V:0.041 V50V:0.096 Dsg:50.000 R31.475
	Sta:49.982 R27.688 OUT 3.787 FWD 0.018

When the offset stake is placed, you can do a second offset. This is sometimes beneficial in extremely small radius curves, such as a cul-de-sac, in order to have 2 stakes to point in the direction of the true catch point. But in most cases it is unnecessary. The slope stake report is shown below:

😂 Stakeo	ut Report		🗾 🔽 🗙	😂 Offse	et Point Re	port			
Current: Target:	Northing 3380.499 3380.503	Easting 4741.337 4741.335	Elevation 841.488	Sh			ER ^I	DFFSET ation: 488	•
						HDIS	T VDIST	SLOPE	
Difference	: 0.005			OFFSE	T to CATCH	5.00	0.01 FILL	0.2% <	423.5
	Store	Point to CRD	File		T to PIVOT	11.98	1.73 CUT	14.5%	6.9:
	Store	Data to Cuts	heet File	OFFSE	T to CBR	17.98	1.97 CUT	11.0%	9.1:
	,				T to CBR2	18.81	2.56 CUT		
Point ID:	1011			OFFSE	T to EP	19.48	2.31 CUT	11.8%	8.4:
Description	n: STA 50	0.002 1011 R31	.477 <u>Ê</u>						►

The "Combo" option shows a "progressive", incremental slope ratio for each segment (last column), combined with a total HDist and VDist measurement to each point. If you have named and defined a Slope Stake file in advance (File, Job Settings, Stake Tab), and clicked it on for storage, then the slope stake information will be stored in the slope stake file as shown below. The file formats of all of these "cutsheet" types are fully user configurable. A configurable Story Stake Report is outlined later in this chapter.

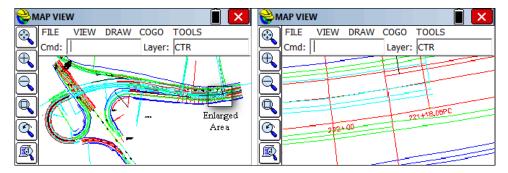


😂 Cutsheets		🗾 🔽 🔀	💝 E	dit CutSheet F	ile SubdivSi	ope.txt 🧲
Point Stakes	Format	Edit File	De	sign Sta	Pivot Off	Elev:PP/CP
Select File C:\Surv	CEDemo\Dat	ta\AR.txt	50.0	000	Right 19.500	841.500
Alignment Stakes	Format	Edit File	OFF	SET to CATCH	H 5.002	V 0.012
Select File C:\Surv	CEDemo\Dat Format	ta\Logging1.txt	OFF	SET to PIVOT	H 11.977	V 1.732
- Biope Branco	CEDemo\Dat		OFF	SET to CBR	H 17.977	V 1.972
Grade Stakes	Format	Edit File	OFF	SET to CBR2	H 18.810	V 2.555
Select File C:\Sur	.\Data\Subd	ivSlope.txt	OFF	ESET to EP	H 19.477	V 2.305 📃 💌
Story Stakes	Format	Edit File				F
Select File C:\Sur	\Data\mant	-STS.txt	Inse	ert Up Do	own Delete	Special

Cut from Alignments Method

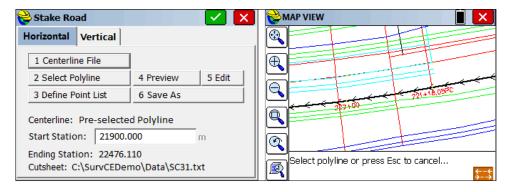
If a drawing or DXF file is loaded or created in SurvCE using CAD tools in the Map screen or by Field-to-Finish, 3D Polylines and 2D Polyline Contours can be used to extract cross-sections for stakeout. This is the "Cut from Alignments" option. The normal use of this command is to extract sections from a set of 3D Polylines representing pavement, shoulder, and ditch lines. However, it is possible to actually name the alignments by associating section descriptions with selected centerline (.cl) and profile (.pro) files. In normal use, when extracting sections from a drawing of 3D polylines, the layers of the polylines are used as the section point description. If several polylines are encountered with the same layer name, such as Ditch, then in the direction away from centerline, each subsequent common layer is given an appended number incremented by 1, as in Ditch, Ditch1, Ditch2, to create unique section point descriptions.

Consider the drawing of 3D polylines shown below. In close-up, stationing for the main horizontal alignment (centerline) appears, with a starting station computed to be 219+00.





So, within Stake Road, selected option 3, Cut Sections from Alignments. This leads to the standard alignment selection dialog, with tabs for Horizontal and Vertical Alignments. It is essential to set a Horizontal Alignment. Pick the main centerline (labeled with 221+18.05 PC above).



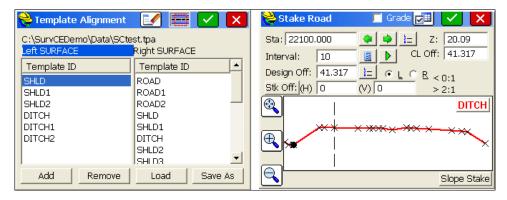
If you are unsure of the direction of the main centerline, pick the orange "Direction Reverse" button. If it was correct to begin with, you will need to reverse again to restore the original direction. It is important to point out that all polylines that will be selected for cross-sectioning need to be drawn in the same direction. So, prior to issuing the Cut from Alignments command, it is a good idea to go to the Map screen and study the polylines involved using the command Draw, Modify, Reverse Polyline. In the above example, all polylines for road, shoulder, ditch and other points need to be drawn and saved right to left, matching the main centerline. When selecting the main centerline, if it is 3D, you will be asked, Overwrite the Vertical Alignment? Answer with Yes. Set the correct Start Station, in this case, 21900 (verify same start station for vertical alignment). Then Ok (green check) to continue.

📚 Template Alignment 🛛 🛃 🚍 🔀	📚 MAP VIEW 📋 🗹
C:\SurvCEDemo\Data\SCtest.tpa Left SURFACE Right SURFACE	
Template ID Template ID	
	Select polylines or press Esc to cancel
Add Remove Load Save As	

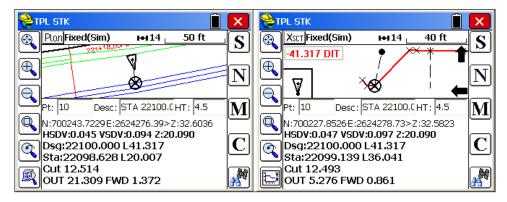
If there is previous data in the 2-column screen, use the Eraser Icon to delete all the data. Then rather then pick one polyline at a time, use the window/crossing selection icon circled in red above left. This leads immediately to a map screen as shown above right. In the lower portion of the dialog, click on "Allow Multiple Selection". Then do any combination of individual picks or window/crossing selections (lower left to upper right or lower right to upper left). A typical



selection is shown by the dashed rectangle above. Click OK to return to the Template Alignment dialog, which now has the data organized in 2 columns:

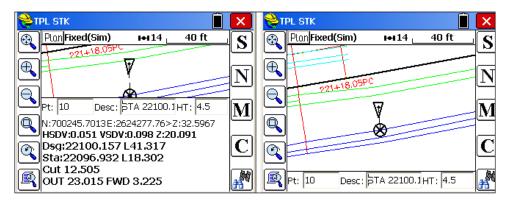


Note that when picking the first ditch point left side, that the layer is Ditch, and the next two are layered Ditch1 and Ditch2. Above the select Ditch point to the right is the third shoulder point on the left side, with SHLD2 as the ID. The next step is simply to click OK (green check) and start the normal stakeout process. Note also that you can Slope Stake (typically from the outer ditch point on the trapezoidal ditch, Ditch1 in this case).

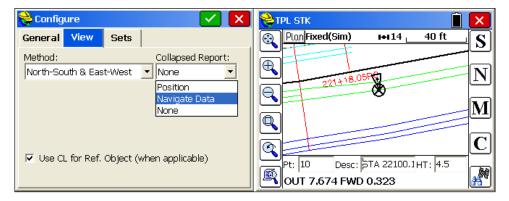


It should also be noted that on most data collectors with up and down - arrows, the 6 lines of cut and fill reporting can be reduced by using the down - arrow key. Tapping the up - arrow key restores the full 6-line display. (In PC Simulation, use F2 to minimize and F3 to restore the 6 lines). This works in both plan view and section view. You can also drag the graphic display down and back up with a press and hold on the lower graphic window border. This is a little more difficult as the selection of the press and hold must be relatively precise, since normal press, hold and move impressions in the graphic area are interpreted as the pan command.





The amount of reduction in text and expansion of graphics is dependent on View Settings. To shortcut to View Settings, tap C for Configuration (or the Tools icon for Configuration) and select the View tab shown below. The above right mode is Collapse Mode "None". Below, Collapse Mode "Navigate Data" is shown, which is 2 lines. The position mode is also 2 lines and shows the x,y,z coordinates of the triangle (your position in the field). The PCDemo version of SurvCE can be expanded and collapsed, according to the Collapsed Report setting, using F2 to shrink and F3 to expand.

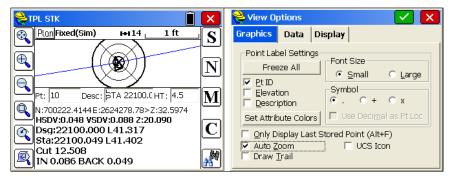


The Cut from Alignments method also allows use of the "Add" button to individually assign a centerline and profile to section points, but this method is tedious and rarely applies, compared to the method of selecting 3D polylines by pick and window/crossing selection from entities on the screen.



📚TPL STK	X	📚 View Options 🔽 🗙
Plan Fixed(Sim) ⊷14 410 ft	S	Graphics Data Display
		Point Label Settings
	N	Freeze All © Small © Large
Pt: 10 Desc: PTA 22100.CHT: 4.5	M	\Box Description \odot $O + O x$
N:700143.8470E:2624287.99>Z:32.5866 HSDV:0.054 VSDV:0.101 Z:20.090		Set Attribute Colors 🛛 🗖 Use Decimal as Pt Loc
Osg:22100.000 L41.317	\mathbf{C}	Only Display Last Stored Point (Alt+F)
Sta:22104.232 L120.383	هه	Auto Zoom 🔰 🔲 UCS Icon
IN 79.066 BACK 4.232	×	Draw <u>T</u> rail

When "Auto Zoom" is clicked on, the program zooms closely as the target is approached, leading to the bullseye (which appears whenever the target is within the Stakeout Tolerance set within Equip Menu, Tolerances.



The "Story Stake" information would appear as shown below (Progressive and Total options). By staking Section ID "Ditch", there are 2 Ditch ID points to the left and 2 shoulder and 1 Center point to the right, up to the selected centerline.



If "Show Report up to Center" is turned off (in effect, show ENTIRE report), then a much more complete report would appear providing offset information to all section points on both the left side and right side of the road.

≷ Offset Point Report 🛛 🗸					💝 Offset Point Report 🛛 🗸					\checkmark			
 Progressive Show Report U 	Progressive C Total Show Report Up to CENTER					○ Progressive							
Offset PT_Sta: O	Offset PT_Sta: Offset: Elevation:			Offset PT	Sta:	Off	fset:	E	levati	on:			
22100.000 L4	22100.000 L41.250 32.599				22100.00	0	L4:	1.250	3	2.599	1		
	HDIST	VDIST	SLO	PE					HDIST	VDIST	SLO	PE	
DITCH2 to DITCH1	3.88	1.94	CUT	50.0%	6 2.0:	OFFSET	to DIT	CH2	8.95	10.57	CUT	118.1	% O
DITCH1 to DITCH	5.00	0.00	FILL	0.0%	999.9	OFFSET	to DIT	CH1	5.07	12.51	CUT	246.9	% 0
DITCH to OFFSET	0.07	12.51	FILL	999.9	% O.C	OFFSET	to DIT	СН	0.07	12.51	CUT	999.9	% O
OFFSET to SHLD2	25.75	0.40	FILL	1.5%	64.6:	OFFSET	to SHL	D2	25.75	0.40	FILL	1.5%	64.E
SHLD2 to SHLD1	5.50	0.04	CUT	0.7%	139.ć	OFFSET	to SHL	D1	31.25	0.36	FILL	1.2%	86.9
SHLD1 to CENTER	10.00	0.07	CUT	0.7%	143.5	OFFSET	to CEN	ITER	41.25	0.29	FILL	0.7%	142.
•					▶	•							▶

Road Model

The LandXML Road Model, when loaded, requires selection of a main horizontal and vertical alignment. The routine then processes similar to Cut from Alignments, described above. The LandXML format for road design files is widely recognized around the world as the accepted form of file sharing. Carlson Software is the principle sponsor of LandXML.org beginning in 2014. In Scandinavia, for example, roads are often defined by a series of horizontal and vertical alignment "pairs" for each road breakline (edge-of-pavement, shoulder, etc.) and a single file can contain multiple roads, and all surfaces of each road (top, subgrade1, subgrade2, etc.). As an example, a portion of an actual LandXML file might appear as shown here, which includes the road name "316" in this case:

</Project>

<Alignmentsname="316">

```
<Alignmentname="316" length="971.597307" staStart="0.000000">
```

<CoordGeom>

```
<Linelength="27.309619" staStart="0.000000">
```

```
<Start>6581158.362094 151616.365550</Start>
```

```
<End>6581180.578173 151632.248280</End>
```

```
</Line>
```

```
<Spirallength="35.731361" staStart="27.309619" rot="ccw" spiType="clothoid"
```

```
radiusEnd="600.000000" radiusStart="INF" constant="146.420">
```

```
<Start>6581180.578173 151632.248280</Start>
```

<PI>6581199.957122 151646.102688</PI>

```
<End>6581209.848914 151652.738602</End>
```

Etc.

When the LandXML file is loaded, all the roads appear in a list, along with all subgrades.



😝 Select Main Road	X
114	*
-2.1 UK BÄRLAGER 1	
-2.1 UK BÄRLAGER 2	
-2.1 UK BINDLAGER 1	
-2.1 UK BINDLAGER 2	
-2.1 UK FÖRSTÄRKNING 1	
-2.1 UK FÖRSTÄRKNING 2	=
-2.1 UK SLITLAGER	
-2.1 V.VÄGREN 1	
316	· · ·

You then select any road to stake out, such as "316" in this example. Within the selected road, you can pick any surface (much like in the Cross-section method) and any point on the surface. If available, the description of the selected surface point is shown:

<mark>ề</mark> Stake Road	📃 Grade 🗾 🔽 🔀
Sta: 1+50.000	◆ ◆ <u></u> = Z: 16.125
Interval: 50) CL Off: 3.5
Design Off: 3. Stk Off: (H) 0	<u>L</u>
	(7) . 101170
<u> </u>	-1_1 K3 SÖDER
₽	
Surface:	FÄRDIG VÄG Slope Stake
	FÄRDIG VÄG
	UK BÄRLAGER 1
	UK BÄRLAGER 2
	UK BINDLAGER 1
	UK BINDLAGER 2
	UK FÖRSTÄR.ING 1
	UK FÖRSTÄR.ING 2
	UK SLITLAGER



Interpolation

If descriptions are provided, "intelligent" interpolation is performed between similar descriptions on slope transitions or widening lanes as well as vertical curves for all methods described above.

Stake Road Screen (Common to All Methods)

This screen is the heart of the program. Here is where you select the station and offset to stake out. You can even launch into a slope stake and then return to stake out other template points.

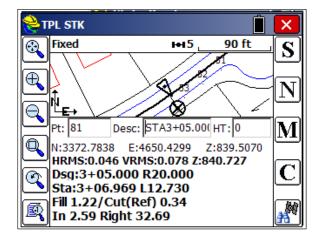
<mark>è</mark> Offset List			\checkmark	X
O Offset	• Reference	Off (V):	0	
Offset	Elev	Description		
× -10.0000	838.3869	L305_1		
R 0.0000	839.1669	CENTER		
imes 10.0000	839.9469	R305_1		
× 14.0000	840.2589	R305_2		
18.0000	840.5709	R305_3		
X 26.0000	837.9043	R305 4		
Set <u>R</u> EF		<u>C</u> lea	r REF	

- Settings: The "Additional Stake Stations" that appear in the List are set in the lower portion of the dialog. The Vertical Scale option will allow for "exaggeration" of the vertical on the template graphic. Though defaulting to 1, we can double the exaggeration by setting this to 2. In fact, an exaggeration of 5 works fine for the "demo.tpl" template file. The "Next Station Method" governs how "N" for next, from the stakeout graphic screen, moves you up. When set to "None", N for Next will stay put until you change your entries. But if set to "Next Offset (Left to Right)", Next will stay on the current station and move to the next offset. The "Next" in the dialog below, however, always increments the current station by the next station in the List. Don't confuse the Next button on this screen, with the N button on the graphic screen to follow, which is influenced by "Settings", and moves you along after you complete each point stakeout.
- **Station**: The value of the Station to Stake.
- **Interval**: The horizontal distance to increment the stationing when using the Next and Previous buttons.
- **Play/Pause**: This button allows the user to play through the road file like watching a drivethrough movie.
- List: Depending on the settings and specified interval, "List" will list the defined stations including intervals and critical stations.
- List Offsets: This dialog allows the user to pick from the known offsets by a list rather than using the graphic screen below. It also allows the user to select an optional second point of "Reference" for reporting cut/fill information while staking. So, you could stake the shoulder but also reference cut and fill to the centerline, as an option. With this option, the selected offset and the secondary reference offset will both be reported to.

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The resulting plan view in stakeout shows cut and fill to both the reference and the target point.

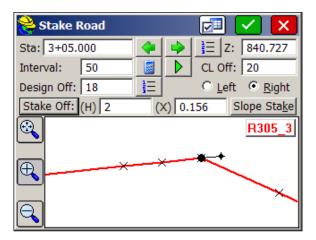


- **Design Offset**: Any offset can be entered, even if it is not a "break point" on the template. For example, an offset of Left 5 (-5) or Right 7.23 could be entered. For every design offset point selected, the elevation is calculated and presented. You can select the offset point from the offset list or literally pick it on the screen. The touchscreen is active in the graphic, so you can select the -12 (EP) just by picking it. Picking on the graphic screen will take you to the "Offset List" screen for verification, where you can confirm your pick by pressing Enter or selecting another offset.
- Stk Off(H): Horizontal offset from the design offset. If you enter an stake offset of 2 and the design offset point was at 12, then the stake would go in at offset 14 off of CL, but the cut/fill would refer to the elevation at the design offset location of 12. The stake offset and Off. to CL inter-react. A stake offset entry of 15 with a design offset of 12 left calculates to a setback of 3. If you click the "Stake Off" button, you can choose from a variety of methods to create an offset point, including extend current slope, apply next slope, vertical offset, or user-defined slope.



≷ Calculate Stake Offsets 🛛 🔽 🔀				
-Horizontal (Offset Distance	9		
Horizonta	al 🔿 Slope	Distance:	2	
Vertical Options				
Extend Curr	ent Slope		▼ R ▼	
Vert, Diff:	0.1560	Slope:	12.82:1	
Design Off:	R 18		<u>ب</u>	
Elevation:			┣╋╤╤┓║	
Stake Off:			· 🔨 🛛	
🗹 Display a	s Ratio	<u>v</u>		

Your offset is then computed and shown graphically:



Note that you can zoom and pan in the dialog above. Pan using your finger or stylus.

- Stake Off Button: This button allows the user to specify the horizontal and vertical offsets relative to the design offset. Various methods can be used for computing the offsets based on the template or section points and their elevations.
- Off to CL: This is the total distance that the stakeout position is from the defined road centerline.
- Vert. Off (V): Vertical offset from the design elevation.
- Elevation: Elevation to be staked. This value is based on the combined design elevation and vertical offset.
- **Run Slope Stake**: This feature allows for dynamic slope staking in the middle of the Stake Road routine. This option is very useful for road staging, and also for staking interior catch points like central median ditches. When the slope stake is completed, the program returns to



the main Stake Road dialog. Any point in the template or section can be used for running in a slope stake. You are asked to specify the desired cut-and-fill slope ratios. The slope can be auto-defined or user defined as follows:

<mark>ଚ୍ଚ</mark> Slope Staking	🔽 🧲
Slope:	
Slopes by Template	▼ L ▼
Pivot Point - User Selection	Elev From Files
	R24 User(L305_4)
Design Pt (Z/O): 835.763	L24
Stake Off (V/H): 0	LO
Ref Off (V/Z): 0	N/A

Define Slope by Next Section Point: This option allows you to select the edge of the road and use the proposed design catch point for auto-determining the slope rate.

Define Slope by Previous Section Point: This option allows you to select the proposed design catch point and then use the next point toward CL for auto-determining the slope rate.

Extend Current Slope: This option will allow you to pick the edge of the road or catch point and use the next point toward CL to end the slope between then away from CL.

User Defined Slope: Allows you to enter the slope ratio by hand for on-the-fly slope changes. **Slopes by Template**: This option extracts the slope definitions from the template file itself.

📚 Stake Road		
Sta: 3+05.000	🔶 🌩]∃ Z: 835.763
Interval: 50		CL Off: 24
Design Off: 24)=	● Left ○ Right
Stake Off: (H) 0	(V) 0	Slope Sta <u>k</u> e
		L305_4
E ×	- ×∦- 	

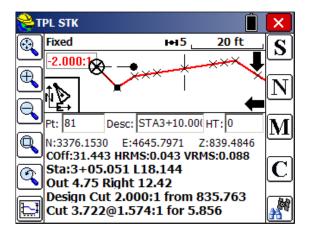
If you click Slope Stake, you can stake by the template slope for the ditch shown on the left side, or you can enter a user-defined slope to override what is in the template.

• **Pivot Point**: This option allows the user to perform on-the-fly offsets relative to the stakeout position.

Stakeout Views



Stake Road now allows you to navigate to the point in either plan view or cross-section view. Select the helmet icon and choose Section to see a section view and choose Plan to return to plan view.



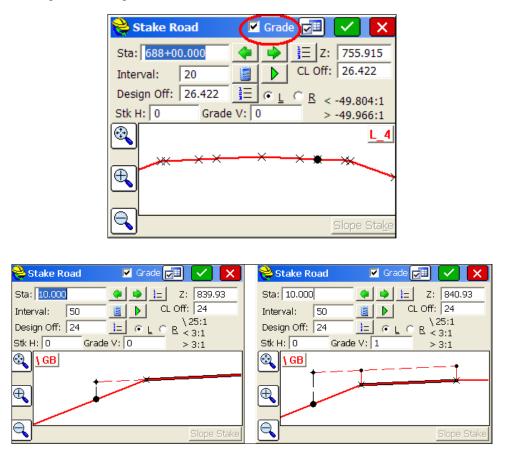
Cutsheets

Stake Road will produce Alignment-style cutsheets that include the option to report station and offset as well as the cut and fill to any point. These are fully described in Stake Line/Arc, Elevation Difference and in Job Settings, Stake Tab. If using Slope Stake within Stake Road, a slope stake report, including "progressive" and "total" distances to all template or section points, can be output. On the first screen of Stake Road, the "Store Stake" option can be selected, leading to "Story Stake" style Cutsheets (basically cut and fill reports on one side or both side of the cross-section at all break points). Using the Grade Stake Method (see below), special Grade Stake cutsheets can be produced.



Grade Stake Method

Regardless of the selection used to define the road (Design Files, Sections, Cut from Map Alignments or Road Model), the Grade Stake Method can be used for stakeout by clicking the "Grade" option at the top of the road stakeout screen, shown below:



This option is popular in places like Australia and the UK. When you enter an offset like 24 Left (shown above), you can then pick any grade on the selected side by tapping the screen, typically closer to centerline, and that grade will extend to the offset shown. The goal is to mark the grade stake with a line representing the extended slope. You can also add an offset to the vertical grade as shown at right. The process involves 3 quick steps: (1) click Grade at the top of screen, (2) select an offset, (3) pick a grade on the screen to extend and stake.

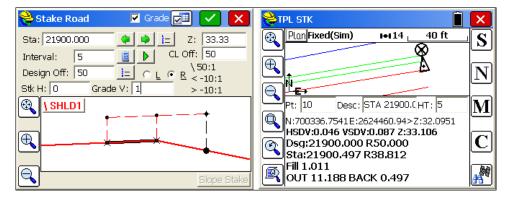
The grade stake can be placed anywhere. You can place the grade stake on the left side of the road and extend the grades on the right side of the road as shown below.



😂 Stake Road	🗹 Grade 🗾 🗸
Sta: 0+330.000	◆ → 三 Z: 683.907
Interval: 10	CL Off: 9.5
Design Off: 9.5	<u>Ξ</u> Θ L Ο <u>R</u> \50:1
Stake Off: (H) 0	(V) 0
<pre>@ offs=1m +C</pre>	2
offset=0	
	grade to
Surface: [EJE1_	067 Slope Stake

Point A is the position of the targeted grade stake, and the goal is to mark the stake by extending the slope of the selected grade (green one) where it intersects the vertical position of the stake (point B for vertical offset=0). You normally use a vertical offset when using grade stake (here shown as 1 meter) to find point C intersection. This methodology offers a handy way of checking a grade by placing the eye at the 0 offset of the grade and sighting down the grade, to verify if the slope is perfect, tangent to the line of sight.

When you click OK, you will be guided to set the Design Offset, the Grade Stake, and when on the point, you will obtain the cut or fill (typically fill value) to mark on the stake to match the extended grade (lower green line with zero offset, upper green line if a (V) or vertical offset is entered. You also have the option to position the stake anywhere on that station, since as you move in and out on the section, the program calculates the extended slope at your offset location. You could choose to place the stake at offset left 8.0 units, and you would get the cut/fill for that location. Cut and fill is computed from the bottom of the pole to the extended surface in green (either B, or C if an offset was used). If the pole is placed on top of the grade stake itself, then the cut/fill is to the top of the stake. In the graphic below, if you drove the stake at your current location, measuring up 1.01 would match the projected, extended grade, and the base of the pole is just 0.01 below the extended surface grade with no vertical offset.

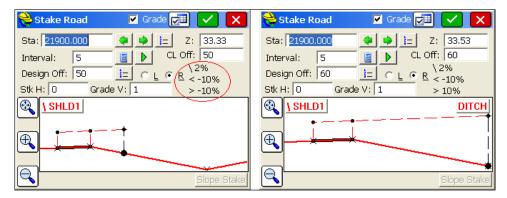




Opposite the "Design Offset" setting is a "From List" button, allowing you to pick the Design Offset to use. Click on this option and note that when using the Grade Stake Method, an extra "Grade" option appears for selecting and reviewing the offset segment in use.

😂 Stake Road 🛛 🗹 Grade 🗾 🖌 🗙	📚 Offset List 🛛 🔽 🗙
Sta: 21900.000	○ Offset ● Grade ○ Reference
Interval: 5 CL Off: 50	Offset Elev Desc
Design Off: 50 $(= C \subseteq O R < -10:1)$	✓ 36.0000 to 42.0000 32.0400 to 32.1700 ROAD
Stk H: 0 Grade V: 1 > -10:1	42.0000 to 46.0000 32.1700 to 32.2500 SHLD
🕄 <u>\ SHLD1</u>	✓ 46.0000 to 60.0000 32.2500 to 30.8500 SHLD
	✓ 60.0000 to 74.0000 30.8500 to 32.2500 DITC
	√ 74.0000 to 78.0000 32.2500 to 32.1700 SHLD _1
Slope Stake	Set New Grade

Note also that the grade segment slope is reported in the upper highlighted slope percent or ratio (as configured), and the slope at the design offset (50) or grade stake position is shown, both left and right of the selected position (in this case 10% or 10:1). Configuration of ratio vs slope can be set by clicking the Settings button at the top of the dialog, then going to the Road tab. The outer ID of the selected grade segment is presented in the upper left as "\SHLD1". The ID of the Design Offset to Stake is presented in the upper right of the graphic screen, as in "Ditch". When the selected Design Offset is not a section or template break point (e.g. 50 below), no ID is presented in the upper right.





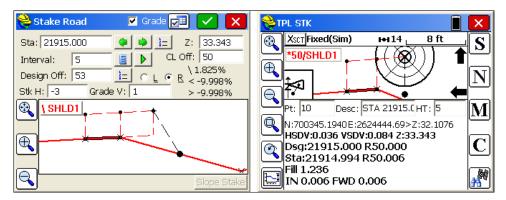
The Grade Stake method produces its own "Cutsheet" file or report of cut and fill. The Grade Stake report can be configured in Job Settings, Stake tab. Here is a report for stations 21900, 21905 and 21910, and shown in full below by using Excel to display the comma-delimited file, SC31GS.txt:

📚 Settings			×	1	<mark>è</mark> Edit CutSh	eet File SC310	GS.txt	
C:\SurvCEDemo\Da	ata\SC31	GS.txt			Design	Design Off	Fill	Grade Off
Item	On/Off	Header Label			21900.000	Right 50.000	1.233	Right 46.000
Grade Off	ON	Grade Off			21905.000	- Right 50.000	1.228	Right 46.086
Grade Width	ON	Grade Width			21903,000	Right 50,000	1.220	Right 40.080
Grade Slope Ratio	ON	Grade Slope Ratio			21910.000	Right 50.000	1.260	Right 46.172
Grade VOff	ON	Grade VOff						
Grade Elv1	ON	Grade Elv1						
Grade Elv2	ON	Grade Elv2						
Grade Design Elv	ON	Grade Design Elv	•					
Header Label: Gra	ade Off	Update Iter	n		•			Þ
Cutsheet from Raw On/Off Down Up Insert Up Do						Down Dele	te	Special

A	В	С	D	Е	F	G	Н		J	K	L	M
#Design Sta	Design Off	Design Elev	Stake Elev	Cut	Fill	Grade Off	Grade Width	Grade Slope Ratio	Grade VOff	Grade Elv1	Grade Elv2	Grade Design Elv
21900	Right 50.00	33.33	32.098		1.233	Right 46.000	4	50.000:1	1	32.25	32.17	33.331
21905	5 Right 50.00	33.334	32.106		1.228	Right 46.086	4	51.282:1	1	32.258	32.181	33.334
21910	Right 50.00	33.339	32.079		1.26	Right 46.172	4	53.333:1	1	32.267	32.192	33.339

It is worth noting that Slope Staking from the command Stake Road is disabled when in Grade Stake mode, since the two features are not related. Simply turn off Grade Stake method to reactivate the Slope Stake button.

Grade Stakes can even have a Horizontal Offset as shown below. On this right side of road Grade Stake example, a -3 horizontal offset tilts the stake point in towards centerline, to the left. The resulting station to stake is 21915. This is essentially the same as entering 21915 directly.





The circle with the X inside is the final target point, illustrating the effect of both a horizontal and vertical offset. That is where you would place the stake and mark the projected cut fill point on the stake or record it as text. Again, you don't need to set the stake at the target point--you know the cut and fill of the projected slope wherever you are, as long as you stay on the correct station. As you move left or right on the correct station, the design elevation is calculated at that offset (it appears to the right of the HRMS value above, as 33.343). Your actual pole reading is the Z:32.1076. So the fill here is 1.236, represented by the vertical black line from the solid circle (your current position) to the projected slope (shown in red). You can drive a stake there and mark a line 1.236 above the ground, to represent the projected slope at 1 vertical offset. But if you were at offset 45, the design elevation would be calculated at offset 45 and the fill would still be valid. If Fill is reported, you would drive the stake and measure up from the ground the fill distance, to mark the stake. Fill is from the desired red projected grade to your ground position. If Cut is reported, then you are above the projected slope, and you would need to simply note the cut on the stake, since the projected slope cannot be marked on the stake.

When Grade Stake is turned on, be aware that when returning to the Stake Road command, the "Grade" option will be default on. Turn it off to use Stake Road in the conventional way.

Story Stake Cutsheet Example

The Story Stake Cutsheet Report, is a report of cut and fill (see Job Settings, Stake tab, Cutsheets option). The term "Story Stake" means that the entire "story" of the cut and fill, across the entire cross-section (or up to centerline only if so configured) can be reported based on a single offset point staked on the road. The story stake report shown below will be created using cutsheet configuration tools.

<mark>ಜ</mark> Edit CutSheet File VA.txt 🧲						
Design Sta	Hub Offset	Hub Elev	Cut 🔺			
1+000.000	Right 4.986	28.404				
TIE	29.014		5.504			
DL	23.014		8.404			
SH	15.014		2.604			
EP	7.014		2.104			
CL 4.986 1.904 -						
Insert Up Down Delete Special						

In this report format, each station takes up a row including the actual point staked, which in this case is renamed "Hub Offset" and "Hub Elev". Then below this row, each offset description appears, including the offset distance and cut/fill from the field-staked point (note the centerline is the same distance as the Hub Offset).

This simple and useful format is configured as follows:

Referring to the opening screen of Stake Road, turn on "Show Story Stake Report". Prior to entering the Stake Road command, within Job Settings, Stake tab, Cutsheet option, under the



Story Stake option, choose Select File, enter a new file name (for the story stake "txt" file) and then update as shown below. Use the "Up" button to move up the fields needed for the report. The "Desc" field is optional, and the report shown above omits it. Note how the default "Staked Elv" is changed to "Hub Elev" using the "Update Item" option at the bottom of the dialog. Click "On/Off" to turn off all selected items below the "Fill" option. Target only 6 "On" items, or 5 if "Desc" is omitted.

1	<mark>è</mark> Settings		🗸 🔨					
	C:\SurvCEDe	mo\Data\	VA1.txt					
	Item	On/Off	Header Label 🔺					
	Design Sta	ON	Design Sta					
	Desc	ON	Desc					
	Staked Off	ON	Hub Offset 🚽					
	Stake Elv	ON	Staked Elv					
	Cut	ON	Cut					
	Fill	ON	Fill					
	Staked Sta	OFF	Staked Sta 🗾 👻					
	Header Label: Hub Elev Update Item							
	Cutsheet from Raw 🔽 On/Off Down Up							

The "Hub Offset" on the first line appears as "Right 4.986". This "Right" or "Left" (vs R or L) is configured by clicking Settings in the "Cutsheet" opening dialog within Job Settings, Stake tab. The "Store Grade ID Only" works very well within Stake Road, Cut from Alignments, since the Grade ID is captured from the layer name of the selected entities. Grade IDs can also be entered using Road, Utilities, Input-Edit Section File. These Grade IDs are then displayed beneath the Design Station, in the first column, based on this setting. Configure as shown below to obtain the above report:

😂 Cutsheet Settings 🛛 🕓	X									
Stored Story Stake Report										
Slope Stake: C Progressive 💿 Total C Combo										
OFFSE	OFFSET -									
Stake Road: 🔿 Progressive 💿 Total	Stake Road: 🔿 Progressive 💿 Total									
🔽 Store Grade ID Only 🔲 Add Off Val	ue									
Show Report Up to CENTER	Show Report Up to CENTER									
☑ Include Slope Stake Report as Notes										
Offset Prefix: Left: Left Right: F	light									



Slope Stake Cutsheet Example

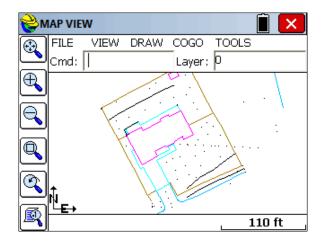
Slope Stake is an option within Stake Road. Using the same "Cutsheet Settings" shown above (in Job Settings, Stake Tab, Cutsheets option), as it applies to "Slope Stake", the "Store Grade ID Only" option, clicked on, leads to the slope stake report shown below. Note the key first 3 elements which need to be configured when creating the Slope Stake cutsheet file (Design Sta, Desc, Pivot Off). Just like with the Story Stake, the "Store Grade ID Only" places the section ID underneath the first column "Design Station" but goes further and places the Horizontal offset from the staked point under "Desc" and the vertical offset under "Pivot Offset", leading to a very simple and useful report. In this example, the catch point is a "top of slope" point above the ditch, which explains the positive vertical offsets to the ditch and even to the shoulder point.

📚 Cutsheet Settings 🛛 🖌 🗙								
Stored Story Stake Report								
Slope Stake: C Progressive I Total C Combo								
Stake Road: C Progressive C Total								
✓ Store Grade ID Only ☐ Add Off Value ☐ Show Report Up to CENTER								
☑ Include Slope Stake Report as Notes								
Offset Prefix: Left: Left Right: Right								



9 Map

This chapter describes the use of the MAP screen. The MAP screen commands are available in the pull-down menus or at the command prompt. The MAP screen is useful for drawing, COGO, creating points for stakeout, and for the import and export of DXF and shape files. No measurements are taken from the MAP screen.





9.1 Basics



The MAP screen is accessed by tapping the globe icon in the upper right of the main menu. The basic operations of the MAP screen are described here.

Map View Icons

The commands associated with the MAP View Icons are described in the figure below:

X	Zoom extents: Zooms to the extents of the map, showing all points and objects.
.	Zoom in: Zooms in 25%.
Q	Zoom out: Zooms out 25%
Q	Zoom window: Zooms into a rectangular area that you pick on the map screen.
Q	Zoom previous: Zooms to the previous view, SurvCE remembers up to 50 views.
	Opens the View Point Options dialog

The View Options button in the lower left opens up a 3-tab dialog with many additional settings for viewing points. For example, you can display just the Point ID, or you can turn on elevation and description display. With the elevation display on, you can even make the decimal place on the elevations be set as the point location, to save screen space.

By default, points are black, elevations blue and descriptions green, but these color assignments can be changed with the option "Set Attribute Colors". Point fonts can be made large and you can also show a Scale Bar in addition to the WCS Icon. If description is clicked on but there is no description, none will be displayed.



😝 View Options 🛛 🔽 🗙	📚 MAP VIEW 📋 🗙
Graphics Data Display	FILE VIEW DRAW COGO TOOLS
	Cmd: Layer: BUILDINGS
Point Label Settings	
Elevation Zeros	·839.31
Set Attribute Colors V Description	
Font Size Symbol	62
© Large Ó x € . C +	
Small Use Decimal as Pt Loc	
UCS Icon	
Scale Bar	

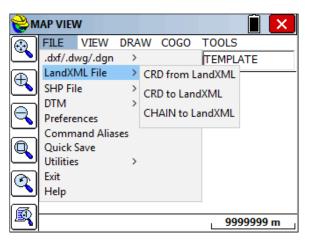
Clicking the Data tab brings up "Intelligent Zoom" and Traverse Defaults. Intelligent Zoom, if turned on, makes selection of points easier. If you are inversing between points or selecting points by clicking them on the screen, Intelligent Zoom detects distinct clusters of points and zooms to those clusters for easier selection, rather than bringing up a long list of points to choose from after clicking. Since this only applies to point selection, keeping Intelligent Zoom on is generally a good idea. Regarding Traverse Defaults, this option enables zenith angle prompting as you traverse or sideshot in the Map screen. It also sets whether hand-entered, Map screen traverse and sideshow entries are stored to the raw file.

The Display Tab allow for an option 'Use South as Reference', this will allow the user to use South as Reference. This option works in combination with Azimuth options-found under Job Settings. The Azimuth can range from 180 - 0 degrees.

Executing commands in Carlson MAP

The MAP screen defaults to a pull-down menu format containing over 90 additional commands, virtually doubling the number of commands found in the Menu Screens. Many of the commands in MAP offer CAD-like features such as layer freeze and thaw, predetermined area, polyline offsets and even contouring. One of the most important commands is Polyline to Points, which allows you to create points for reference or for stakeout (set out) from any selected polyline. The MAP screen also includes a command line format that can be set using Preferences. Several MAP screens pull - down menu commands involve "fly out" options, as shown below.





Alternatively, you can enter the command name, or command alias, at the command prompt and press ENTER. In many cases, the user can start a command while using another command. The newly started command is called a "transparent" command. Each command from the left-toolbar menu is a "transparent" command.

Usually, a command does not immediately execute. Carlson MAP either displays a dialog box or displays prompts at the command line requesting more information from the user. Typically, the user can select objects on the screen or enter data on the command line. Many commands consist of a series of options, structured as follows:

```
Cmd:Command name-Option1/oPtion2/opTion3/.../<default option>
```

To select one of the options, the user can enter the entire option name or only the capitalized letters, and then press ENTER. If available, the default option always appears in angle brackets (<>). To select the default option, just press ENTER. If no command is active, the user can repeat the previous command by pressing ENTER.

Panning the Screen

The user can move the drawing display (PAN) anytime. To use this command, the user must hold down and slide a finger — or the proper pointing device — on the screen. The drawing display is moved in the same direction as the pointing device. When you release the pointing device, the panning stops. Only the display moves and all objects retain their correct coordinates. Be careful to start the pan by picking in "empty" space. If you hold down on a point, you may obtain the "Point Details" screen, or you may see a list of points to select from (to see Point Details). If you hold down on a line, you may see the "Line Details" screen.



Point Details

Unless you are in the middle of a MAP screen command, you can click on a point and see a Point Details dialog. If you tap near several points, a list of nearby points will appear from which you can select the target point. Otherwise, you will go straight to Point Details, and see a screen that includes the option to delete or edit the point.

😝 Point Details	←
Point ID: 1	
Northing: 4959.8023m Easting: 4942.2812m Elevation: 0.0000m Description:	
Edit	Delete

If you are in total station mode, and actively surveying (with a setup and backsight specified), clicking on the setup or backsight point will lead to a special graphic, as shown here:

😝 Point Details	←	😝 Point Details	÷
Point ID: 1		Point ID: 2	
Northing: 4959.8023m Easting: 4942.2812m		Northing: 4976.6498m Easting: 5068.7853m	
Elevation: 0.0000m Description:		Elevation: 0.0000m Description:	
View Attributes		View Attributes	

If you have assigned attributes to the points (e.g. Description Pole, Type-Metal, Wires-4, etc.) by use of the Feature Code capabilities, these attributes can be reviewed. The Point Details option works both within the MAP screen (when you are not being prompted for entering points or selecting objects) and in all graphic screens within the Menu options. It is not as transparent and available as the dynamic pan option, but nearly so.



Line Details

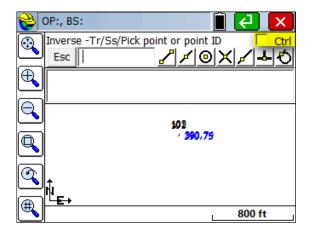
Unless you are in the middle of a Map screen command, you can also click on a line and see Line Details. Clicking the line at the lower edge of the drawing (a blue ditch line) leads to a simple Line Details display:

s N	IAP VIEW 📋 🗙	😝 Line Details	←
8	FILE VIEW DRAW COGO TOOLS Cmd: Layer: TEMPLATE	Source: Drawing	
R		2D Polyline	
	3 · 0.000		1
Q	11 2	Layer: CLINE	Change
0	12 1 -5.600 2 0.000	View Attributes	
R	"L <mark>E</mark> →90 m	Delete Line	

You have the option to delete the line or change its layer or View Attributes (if any). If the polyline (a line with 2 or more vertices) has different elevations on some of the vertices, then it is designated a "3D Polyline". A more advanced Line Details is provided when using Feature Codes within the Store Points command, allowing extension of lines and new lines from vertices on the polyline. The advanced Line Details is discussed under File, Feature Code List.

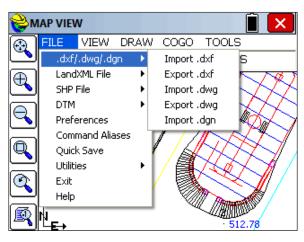
Control Points

Control points can be used in the Map Screen. To use control points, you must have the setting 'Use Ctrl Pts for Map Selection' enabled. Then, in the map screen, during any map command the option for Ctrl Points will be available to use in that map command.



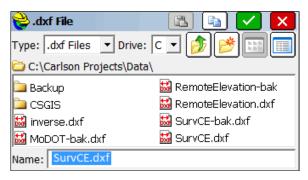






DXF File - Import DXF (IDXF)

Similar to the AutoCAD(r) DXFIN command, will bring in polylines from AutoCAD, Microstation, Terramodel and other products that can export data into a DXF file format. Text can be imported. Blocks under 256k are imported and can be selected or "snapped to" using the node or center snap (if a circle). For block or text importing to work, turn on "Allow Import .dxf/.dwg/Esri Options" within Job Settings, Options, in the File Menu. See discussion in Import DWG.





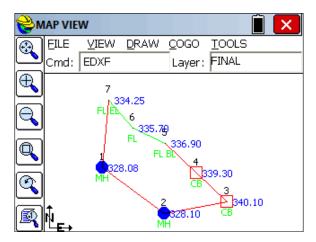
DXF File - Export DXF (EDXF):

The **EDXF** command is useful for exporting files to Microstation, Autocad, Intellicad, ESRI and virtually all other CAD drafting programs. It provides controls for displaying points and also for displaying GIS attributes associated with points and linework.

The **EDXF** command, similar to the AutoCAD(r) DXFOUT command, will export a DXF file. It captures not only 2D and 3D polylines and their layer names but also exports all visible (layer on) points from the CRD file into AutoCAD "Point" entities form (layer PNTS). All points and polylines that are visible (layers on) would be exported, not based on the current screen zoom, but based on the full extent of the drawing.

Automatic DXF Save / Export will automatically detect if the data loaded or created in the current job will not be acceptable by AutoDesk R12. If not acceptable, and AutoDesk 2000 DXF file will be created.

The **EDXF** command has many special features for displaying the points in the exported drawing. Consider the source drawing below:



When the Export DXF command is issued and a file name is entered, a dialog appears with options shown below. If you choose "Create block attribute on layer: 0", then all attributes such as point number, elevation and description take on the layer of the node. In this case, all point attributes inherit the fence line layer for the fence points and the utility layer for the catch basin and manhole points. If you do not put the attributes on layer 0, then they have distinct colors and layers for the number, elevation and description. In addition, if you click on "Save GIS Point Feature to Block", then if GIS attribute data is included, this data will appear beneath the description in a vertical, left-justified column (e.g. 5.4=depth, 2=number of inlets, Cast Concrete=type).



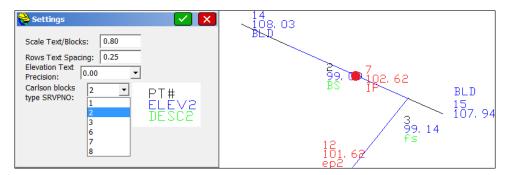
📚 Export .dxf Options 🛛 🔽 🗙	7 N 334,25
 Export linework Export points as: .dxf POINTs .dxf TEXT Carlson blocks Include Symbols Create block attribute on layer: 0 Save GIS Point Feature To Block Save GIS Line Feature To Block(Cente • • 	334.25 FL EL 335.70 S36.90 FL BL 339.30 State Cast Concrete S28.10 MH 328.085 S.4 Cast Concrete S28.10 MH 328.104 S.3 FL EL S340.10 Cast Cast Cast Cast Cast Cast

If the points are exported as Carlson blocks, then they will move as one object within CAD, when selected. Another option is to export the points as ".dxf text" in which case each distinct piece of text can be selected, moved and edited.

NAP VIEW	📚 Export .dxf Options 🛛 🗾 🔽 🗙
FILE VIEW DRAW COGO TOOLS Cmd: Layer: D	Export linework
14 U08.03 BLD	Export points as: C.dxf POINTs Carlson blocks
C 2 7 99.09 B5 99.09 IP 102.62 IS 107.94	Include Symbols Create block attribute on layer: 0 Save GIS Point Feature To Block Save GIS Line Feature To Block(Centre
12 ↓ 101.62	



Click the settings button at the top of the screen to change the text height and row spacing for the text. In the example below, we've moved the description of point 15 above point 15, since it can be selected and moved individually. Note that solid, circular point symbols import as basic circles. All points are imported with a node to snap to within CAD, even in "AutoCAD text" mode.



Other options in the command include drawing GIS line feature attributes and Saving Point Labels on separate layers. If "Save GIS Line Feature to Block (Center)" is clicked on, then attributes associated with a polyline will draw in the middle of the longest segment of the polyline. If "Save GIS Line Feature to Block" is clicked on, but the "Center" option is not clicked on, then the GIS attributes of the polyline draw on the second point of the line, below the other "standard" point attributes such as elevation and description. Shown below is the combination of normal point attributes (not placed on layer 0) and linework GIS feature plotting, shown associated with the second point in the polyline.

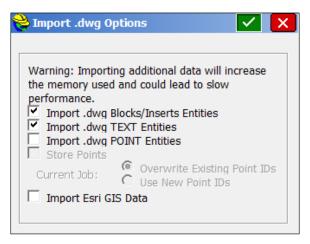
📚 Export .dxf Options 🛛 🗾 🔽 🗙	7 234,25	
 Export linework Export points as: .dxf POINTs .dxf TEXT Carlson blocks Save GIS Point Feature To Block Save GIS Line Feature To Block Save GIS Line Feature To Block Save Point Labels on Separate Layers • .dxf 	335.70 Chain Ling 56.90 Chain Ling 56.90 J28.08 State Concrete State Conc	10 336.90 Flacin Link Chain Link 11 336.89 Fl EL



The "Save Point Labels on Separate Layers" option places the exported points on the layers associated with the point descriptions, as defined in the Feature Code List. If "EP" points are defined as going on the "Road" layer, then when exported to CAD as a DXF file, these EP points will be on the Road layer, and BLD points associated with the "Building" layer will be on the "Building" layer in CAD. In this way, the exported points can be turned off an on by use of layer commands.

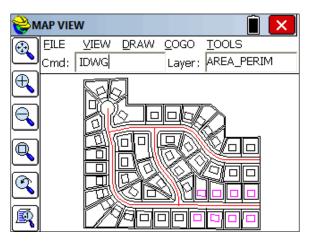
DWG File - Import .dwg (IDWG)

The IDWG command directly loads a ".dwg" file into SurvCE and all layer names are retained. Text and MText is imported but hatching is not imported. Only blocks under 256K, polylines and text will appear in SurvCE. Blocks such as symbols can be "snapped" to for stakeout using the node/center snap, which also serves as an insertion point snap. Text can be "snapped to" also using the node snap, in which case the text insertion point will be used. Be sure to go to File in the main menu, Job Settings, Options and turn on "Allow Import .dxf/.dwg/Esri Options". When these options are turned on, you obtain the following prompting when Importing:



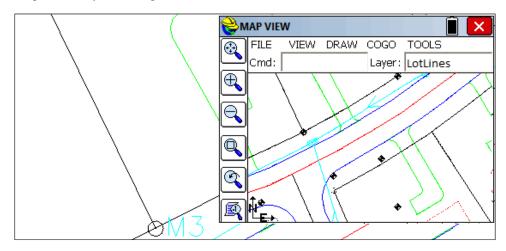
Note that Point Entities, points plotted in Autocad or in Carlson Survey and other Carlson products, can be imported and also stored as points within SurvCE.





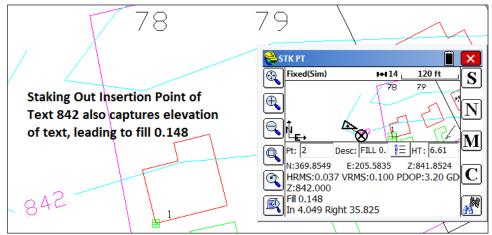
Importing Blocks and Importing Text in the DWG file

Blocks that are used in Autocad or Intellicad or other CAD packages using ".dwg" formats like Graebert and Bricsys can be imported into Carlson SurvCE. For block importing to work, set Process Block/Insert on within File, Preferences. In the example below, the storm sewer inlets are shown as a "grate" symbol, in various rotations. Note that these symbols import into SurvCE 3.0 and higher directly, including with rotation.





Note above that blocks with solid fill are imported as only the outline. Note also that the inlet grate near M3 in the .dwg file in CAD, at left, is imported with correct rotation. (Text was not imported in this example). All imported blocks can be staked out using the "cen" or "center" snap, which doubles as an "insertion point" snap. All forms of Text can be imported optionally with the exception of MText. Text created by the "Text" or "DText" commands import as shown below, using a single "Carlson" font style at present:



Note: If a .dwg file is exported from ArcMap 9.1, 10.0 and 10.1 using the command "Export to CAD", then this form of a .dwg will import in SurvCE with all associated ESRI attribute data captured. This data can then be edited, and new features and attributes can be added to the map. Then the EDWG (Export DWG) command in SurvCE will return the full drawing with associated attributes back to Esri ArcMap 9.1, 10.0 and 10.1, when imported.

DWG File - Export .dwg (EDWG)

The EDWG will export to ".dwg" format all linework appearing in the SurvCE Map screen, regardless of origin (imported, drawn in the MAP screen, created by Field Codes). Layers and even line thickness (as created by field codes) will be retained in the exported drawing. The controls for exporting DWG files are similar to those of exporting DXF files described above, with two added options: (1) to designate the DWG format as shown below, and (2) to export MSC (metadata) in the .dwg file for import by Esri ArcMap version 9.1, 10.0 and 10.1.

The command Import from CAD within Esri ArcMap (9.1 to 10.1) will efficiently import all screen entities and GIS attributes and store them in Esri format. Maps and data can complete the full cycle by being exported from Esri using the command "Export to Cad", editing and added to within SurvCE, then exported back to Esri for importing.



<mark> Export</mark> .dw	g Options				X
Export line	work				
Export poir	nts as:				
~	lwg POINTs arlson blocks	0	.dwg TE	XT	
Save GIS Line Feature To Block(Cente Save GIS Line Feature To Block ✓ Export Esri GIS Data Save Point Labels on Separate Layers ▼					
•					•
File Type:	2005-2009	•			
	2005-2009				
	2004				
	2000				
	R14				

DGN File - Import .dgn (IDGN):

Directly imports a Microstation .dgn file and stores the file in DXF format, the normal format of SurvCE.

LandXML - CRD from Land XML (XML2CRD):

This command allows you to import points from LandXML format to SurvCE.

LandXML - CRD to Land XML (CRD2XML):

This command allows you to export points from SurvCE to LandXML format.

😂 CRD Points to LandXML	
Current CRD File: C:\Carlson Projects\Data\Demo.crd	
Select File	
Current LandXML File: None	
Select File	



LandXML - Export Chain File to LandXML (CHAINXML):

This command allows you to export all the polylines from the current drawing created using Feature Codes, as LandXML chain objects into a LandXML file. For example, if you made strictly 3D polylines for break lines using descriptions such as EP for edge-of-pavement or DL for ditch line, then the 3D polylines can be exported as a LandXML chain file and used as break lines for contouring in other CAD programs. The combination of points and break lines can lead to optimal contouring. Most CAD packages will import linework using the DXF file approach, but many now recognize linework in LandXML "Chain" file format.

SHP File - Import Shape File (ISHP) (e.g. from ESRI):

This command allows you to import entities and also the associated attributes values from a SHP file. The routine displays "Import from SHP" dialog box. If the SHP file has POINT or POINTZ type, the entities will be stored into a CRD file. In the cases of an ARC, ARCZ, POLYGON or POLYGONZ SHP type, the entities will be stored into the current drawing. The attribute values will be stored into a *.vtt file. The routine requires a feature code name from the user, which will be used to store the name and the type of the attributes from the SHP file. SurvCE supports import of SHP ESRI basic files, including measure type, to the Feature Class Definition (POINTM, POLYGONM, ARCM).

SHP File - Quick Import SHP (QISHP):

This command allows you to import entities from SHP files (used by most programs produced by Esri). The routine displays the Import from SHP dialog shown below. POINT or POINTZ type entities will be stored in a CRD file. ARC, ARCZ, POLYGON, or POLYGONZ entities will be stored in the current drawing as POLYLINES.

😂 Import from SHP				
Current SHP:				
Select SHP Type:				
 Overwite Existing Point IDs Use New Point IDs 				
Attribute > Description : Layer :				
TEMPLATE	~			
Code Name:	~			



Current SHP: Displays the name of the SHP file that will be imported when this command is completed. Read-only, you must use the Select SHP button to specify the file name. **Select SHP**: Tap this button to select a SHP file name.

Current Job: Available when importing coordinate data. Specify whether to Overwrite Exiting Point Numbers or Use New Point Numbers.

Attribute used to fill Description: Available when importing coordinate data. Lists the attributes in the currently selected SHP file. Select which attribute to use to fill out the Description field in the CRD file.

Layer used to store new entities: Available when importing geometry. Select the layer to store the new entities.

Process: Tap the green checkmark to begin the import process. When complete, it will display, "Process done". Then click the orange back arrow to exit. If you are importing a large file, a progress bar at the bottom of the dialog will indicate the progress of the import.

SHP File - Export SHP File (ESHP):

This command allows you to export entities from the current drawing and also the associated attributes values, into a SHP file (or more accurately, multiple shape files). The routine will allow the user to select which entities will be exported, based on entity type and also based on the feature code name. The routine displays "Export to SHP" dialog box.

NAP VIEW	😂 Export to SHP 🛛 🖌 🧲
Warning Current Projection File is: C:\SurvCEDemo\Data\WGS 1984 UTM Zone 48S.prj Would you like to select a different Projection File?	Current SHP: Ascot1 Select New SHP Export All POINTS > 8 ARCS > 120 POLYGONS > 63
Press Cancel if you do not want any Projection File to be used!	Include attributes:Length, Area, Layer, Pt ID, Northing, Easting, Elevation, Description Remove Arcs Include: ✓ Z Coordinates (offset cutoff): ✓ Slope if 3D Line 0.1
]0.1



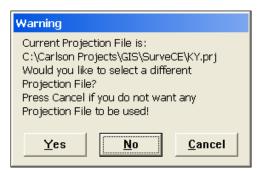
Click on Export All and include special attributes and optionally the Z coordinates. If you have point, arcs (non-closed polylines in Esri terminology) and polygons (closed polylines), all with one attribute, you will obtain up to nine files as shown below:

Ascotl_11.dbf Ascotl_11.shp Ascotl_11.shx Ascotl_13.dbf Ascotl_13.shp Ascotl_13.shx Ascotl_15.dbf Ascotl_15.shp Ascotl_15.shx

The selection of the Z coordinate places the 1 after the underline character. Otherwise, the file form would be, for example, Ascotl_1.shx (special attributes only). The "1" group represent points, the "3" group represent arcs (unclosed polylines) and the "5" group represent polygons (closed polylines). Within Export Shape file, the field name in the dbf file is expanded to handle up to 254 characters.

SHP File - Quick Export SHP (QESHP):

This command allows you to export polylines and/or points to an SHP file. When first entering the command, you may be prompted for a "projection file", a .prj file, that allows the export to overlay on grid coordinates. The ".prj" file itself is made within Esri products. You can choose to use the current ".prj" file, use another, or cancel any use of a projection file, as shown below:



Then proceed to a dialog that displays the following options:



😂 Quick Export 1	to SHP			
Current SHP: A	ceSite			
Select New SHP 🔽 Do not export points				
Export entities from	m selected Lay	ers:		
AREATXT BREAK			Select All	
BRGTXT		✓	Clear All	
Remove Arcs (offset cutoff): 0.1	Include:	Z Cool Slope	rdinates if 3D Line	

Current SHP: Displays the name of the SHP file that will be created when this command is completed. Read-only, you must use the Select new SHP button to specify the file name. **Select new SHP**: Tap this button to select a SHP file name.

Do not export points: When this option is checked, only polylines are exported to the SHP file. Export entities from selected Layers: Lists the layers in the current map. You may select certain layers for export.

Select All: Selects all layers in the list.

Clear All: Clears all selected layers in the list.

Remove Arcs (offset cutoff): Specifies the maximum distance that a vertex on a polyline segment will deviate from the original arc.

Include Z Coordinates: When this option is checked, elevation data (or Z coordinates) will be included in the SHP file.

Slope if 3D Line: If distinct, different vertice elevations are detected, you have the option to retain the starting elevation for all vertices or export the vertices with their distinct elevations. **Process**: Tap the green checkmark to begin the export process. When complete, it displays, "Process Done". Then tap the orange back arrow to exit. If you are exporting a large file, a progress bar at the bottom of the dialog will indicate the progress of the export.

Export ASCII w/GIS:

Allows exporting of points with attribute data in the form Pt ID, Northing, Easting, Elevation, Description, Attribute1, Attribute2, etc.



DTM Import - DTM from DXF (TDXF):

Allows you to import 3DFACE entities from a DXF File and save them as a triangulation (TIN) file and also draw them as 3D faces.

😂 Import 3DFACE from .dxt	f 🛛 🗸 🧲
DTM (*.tin;*.flt): None	
Draw 3DFace entities Select layer:	Select New DTM File
0	ON 🔨
CLINE	ON
DEMO	ON
DISTXT	ON
EXISTING	ON 🗸
Layer name: TRI_FACE	

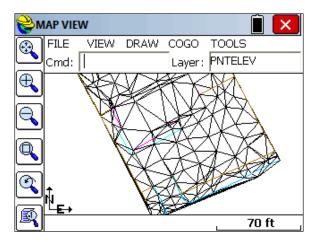
DTM Import - DTM from Land XML (TXML):

Allows you to import 3DFACE entities from an XML File and save them as a triangulation (TIN) file and also draw them as 3D faces.

😂 Import 3DFACE from .dxf 🛛 🛛 🧹				
DTM (*.tin;*.flt):	None			
Draw 3DFace Select layer:	entities	Select New	w DTM File	
0		ON	~	
CLINE		ON		
DEMO		ON		
DISTXT		ON		
EXISTING		ON	~	
Layer name:	TRI_FACE	<u></u>		



The DTM file is stored in SurvCE as a TIN file and can be used for commands such as Elevation Difference (obtaining cut/fill by comparing field measurements to the DTM).



The 3DFaces are placed on a layer (TRI_FACE by default), and that layer can be turned off and removed from view. If you choose E for Erase, you can pick the 3D Face entities and erase them on command. There is no particular value to seeing the 3D Faces, so it is not recommended that they be drawn. The main value is to capture the TIN (triangulation) file for use in Elevation Difference.

DTM Export - DTM to LandXML:

Load a .TIN or .FLT file and export to LandXML format. The process typically takes place in less than 1 second. Click the back arrow to return to the Map screen.

DTM Import - DTM from Ispol:

Allows you to import a TIN file from the Ispol format, commonly used in Spain.

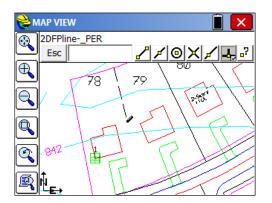


Preferences (SETT):

This allows the user to turn on/off the pull-down MAP menus. Menus Off is rarely used, provides more graphic space, but forces users to enter commands at the command line by typing them in (such as E for Erase). The graphic screen style of normal or reverse (solid dark) background is set here. Preferences also includes the setting "Sketch Option" which removes the "tangent" snap from the available snaps for selecting points on lines and objects and substitutes a "?" snap for sketched or randomly picked points on the screen, adding a new command "2D Sketch" under the Map Screen, Draw, Polyline options.

When the 2D Sketch is selected, then there is a snap option to pick in blank space on the screen, the snap to the right, seen as a "?". Any polyline drawn with the sketch "?" snap can be used for stakeout using conventional snaps. So, you could draw a new 2D Polyline to divide lots 78 and 79 by snapping to the back property line (Nearest), picking a "?" sketch snap in the middle and ending with a perpendicular snap to the lower property line, as shown below. Then you could stake out the sketched point (pencil below) using the endpoint snap.

😂 Preferences 🛛 🗾 🔽 🗙	DRAW COGO TOOLS
Command Bar style: Menus ON Menus OFF	Polyline > 2D
Command but styles in Menus Orr	Circle 2D (Road)
	Erase 3D
	Layer > 2D (Sketch)
	Extend >
Graphic Screen style: Normal Reverse One Tap Zoom	Offset >
	Modify >
	Place GRID
	Align Pline/Bldg >
Start \	Transform >





Command Aliases (AL):

Brings up a list of commands in the MAP mode for which the user can substitute an alias. If you would prefer to type A for Area rather than AR, you can substitute "A" as an alias for AR. Three commands will not accept substitutes: Inverse, Traverse and Sideshot (I, T and S). In addition to commands, you can toggle over to the "Linework special code" option, and substitute aliases codes for the default special codes such as PC, PT and END (used to control linework using feature codes). As an example, you could choose the "X" or ".." to End a line, or use "CS" for curve start instead of PC. A list of MAP commands is shown below:

B	Command	Aliases	🗾 🔽 🔀		
	MAP Com	nmands	C Linework codes		
	Command	Alias	<u> </u>		
	2DPLINE	2DP	L		
	2DFPLINE	2DFP			
	3DIST	3D			
	3DP2PRO	3D2P			
	3DPLINE	3DP			
	ALIASES	AL			
	ALIGNB	AB			
	2D Pline(Road)				
			Alias: 2DP Accept		



Commond	A 1:	Description
Command	Alias	Description
2DPLINE	2DP	2D Polyline
3DIST	3D	Bearing and 3D Distance
3DP2PRO	3D2P	3D Polyline to Profile (.pro)
3DPLINE	3DP	3D Polyline
ALIASES	AL	Aliases
ALIGNB	AB	Align Building 1-Segment
ALIGNBC	ABC	Align Building 2-Segment
ALIGNBSET	ABSET	Align Building Settings
APERTURE	AP	Aperture Size
AREA	AR	Compute Area
CHAINXML	CHAINXML	Chain of Polylines to LandXML
CHANGE	CHG	Change Layer
CIRCLE	CR	Draw Circle
CL2PLINE	CL2P	Centerline (.CL) to Polyline
CONV2D	C2D	Converts 3D to 2D
COPY	COP	Copy Entities
COPYGIS	CGIS	Copy GIS Data
CRD2XML	CRD2XML	CRD Points to LandXML
CURVCALC	CC	Curve Calculator
DELLAYER	DL	Delete layer
DRAWBLDG	DB	Line or L-Figure to Building
DRAWLP	DLP	Draw / Locate Points
DRAWMOSS	DMOSS	Draw / Import Moss File
DRAWPLN	DPLN	Draw / Import PLN File
EDITPL	DDP	Edit Polyline
ERASE	E	Erase Entity
EXIT	Х	Exit
EXPSHP	ESHP	Export Shapefile
QEXPSHP	QESHP	Quick Export Shapfile
EXPDWG	EDWG	Export .dwg File
EXPDXF	EDXF	Export .dxf File
FLD2FIN	F2F	Reprocess Field to Finish
FILLET	F	Fillet 2 Lines – Create Curve
FIND	FND	Find Point
Help	H or ?	Help
HINGEDA	HA	Hinged Area
DXF2FLT	TDXF	Import DTM from DXF
IMPSHP	ISHP	Import Shapefile
QIMPSHP	QISHP	Quick Import Shapefile
XML2CRD	XML2CRD	Import LandXML to CRD
IMPDGN	IDGN	Import .dgn File
IMPDWG	IDWG	Import .dwg File
IMPDXF	IDXF	Import .dxf File
EDITGIS	EGIS	Edit GIS Data
INVERSE	I	Inverse (Distance)
ISOLAYER	IL	Isolate Layer
ISOLATE	ISO	Isolate Points
ISSMOOTH	ISSMO	Report Deflection in Plines



JOIN	JN	Join Polyline Segments
LIST	LI	List Entity / Report Layer
LISTELEV	LELV	List Elevation
LAYER	LA	View Layers
MIRROR	MIR	Mirror Entity
MOVE	MOV	Move Entity
NGSQUERY	NSGQUERY	NGS Query for Control Points
OFFSET	OF	Offset Type
OFFSET2D	O2	Offset 2D
OFFSET 3D	03	Offset 3D
OFFSETB	OBUF	Buffer Offset
OFFBYSEG	OSEG	Segment Offset
TRDEF	TD	Traverse Defaults
POLYLINE	PL	2D Polyline
PLINE2CL	P2CL	Polyline to Centerline File
PL2PNTS	P2P	Polyline to Points
QSAVE	QS	Ouick Save
REMARCS	RMA	Remove Arcs
REVPLINE	RV	Reverse Polyline Direction
ROTATE	ROT	Rotate Entity
SAVEASCRD	SCRD	Copy CRD File
SCALE	SCL	Scale Entities
SCALEBAR	SB	Scale Bar On / Top / Off
SIDESHOT	S or SS	Sideshot
SLIDINGA	SA	Sliding Side Area
SLPREP	SR	Slope Report
TRAVERSE	T or TR	Traverse
TRGCALC	TC	Triangle Calculator
TRGCNT	TRGC	Triangulate and Contour
TRIM	TM	Trim
UCS	UCS	UCS Icon On / Off
VIEWOPT	VO	View Options
ZOOM	Z	Zoom
SETTINGS	SETT	Settings (Preferences)
DIVSEG	DVS	Divide Polyline by Segments
DIVINT	DVI	Divide Polyline by Interval
FLT2XML	T2XML	Export DTM to LandXML
XML2FLT	TXML	Import LandXML to DTM
WORLDIMG	WORLDIMG	Image Overlay
GIS2TXT	GIS2TXT	Export GIS to ASCII Text
DRAWGRID	DG	Draw Grid
TPP2FLT	TTTP	Import DTM from ISPOL Files
XBYDIST	XDST	Extend by Distance
XBYEDGE	XEDG	Extend by Distance Extend to Edge
VOLUME	VOL	Volume Report
* OLUME	VOL	volume Report

Linework and special "field-to-finish" codes are shown below:



<mark>è</mark> Spec	ial Codes 🛛 🗾 🗸	X	
О ма	P Commands 🔎 Linework codes		
Code	Action		
Space	Code Separator		
None	String Designator		
ST	Begin Line		
EL	End Line		
PC	Arc PC		
PT	Arc PT		
CLO	Close Figure		
SMO Smooth Line			
Carlson Code: Accept			

Code	Action
Space	Code Separator
None	String Designator
ST	Begin Line
EL	End Line
PC	ARC PC
PT	Arc PT
CLO	Close Figure
SMO	Smooth Line
JPN	Join Point
RECT	Close Rectangular
OH	Offset Horizontal
OV	Offset Vertical
NE	No Elevation
JOG	Extend by Distance
ZO	Elevation Only
AFIT	Arc Fit by Second Point
CIR	Close Circular
BFIT	Best Fit Line
BPRJ	Best Fit Line

The Settings button at the top of the screen applies to field-to-finish coding and is covered in the Feature Code List feature within the File menu.

Quick Save (QS): Saves the current DXF file without prompting for the file name.



Save As(CRD):

Saves the current coordinate file to the location you choose as a backup copy.

Warning			
Do you want to make a copy of the current CRD file? File name: Demo.crd Location: C:\Carlson Projects\Data\			
Yes	No		

Draw MOSS File (DRAWMOSS):

This will import and draw a MOSS ".inp" file.

Draw PLN File (DRAWPLN):

This will import and draw a Carlson PLN file, which is a file of polylines and converted text, created in Carlson Survey or the Carlson Civil Suite.

Exit (X):

This exits the MAP and CAD session and brings you back to the Menu screen.

Help (H):

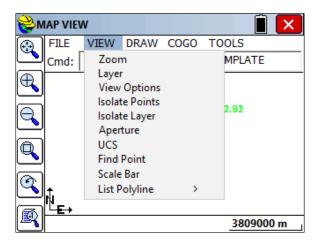
Launches the interactive Help screen describing various MAP screen commands. Scroll up and down to review. With wireless on, includes access to Internet Explorer, by tapping the icon at the top of the Help screen. The Help screen is an HTML file which will appear if loaded on the data collector.



9.3 View



The View menu is found next to the File menu in MAP view. Below you will find each feature described.



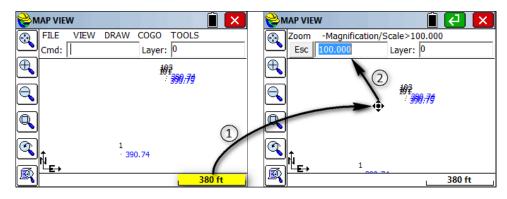
Zoom (Z):

Increase or decrease the apparent size of polylines and distances between points, in drawing area. The specific options in the command are N (Zoom to Point ID/Number, enter zoom magnification), I (Zoom In), O (Zoom Out), W (Zoom Window), P (Previous) and E (Extents). The Zoom command options can also be accessed using the first 5 buttons from left-toolbar menu. The order of buttons, starting with the first top button, is: Extents, In, Out, Window, Previous. Zoom Previous will "nest" which means that if you Zoom In or Zoom Window 3 times, each Zoom Previous takes you back one step and 3 Zoom Previous commands would return to your original view.



Fast Scale / Magnification

The map can be scaled quickly by clicking on the lower-left Scale. The user can then Select the new center (by point number or Map location) of the Map and type in the preferred scale for the Map View.



Layer (LA):

This command manages layers and layer properties.

👌 Layer Manager 🛛 🧲			
0 CLINE		ON ON	^
DEMO		ON	
DISTXT		ON	
EXISTING		ON	
FINAL		ON	~
Current Layer: TEMPLATE		0.1	Color:
New Layer:			
On all		Of	ffall
	Delete	On/Off	Current
-			- <u> </u>

Add a new layer: Type in a new name into the New Layer edit box. The New button will appear at the bottom. Tap this button. If you type in a new layer name and the New button does not appear, then the layer name you entered contains invalid characters.

Set a layer current: Highlight the layer name in the list and then tap the Current button. You cannot set a layer current if that layer is turned Off. Turn the layer On first and then set it current. **Delete a layer**: Highlight the layer name in the list and tap the Delete button. You cannot delete layers that contain objects. If you select a layer and the Delete button is not visible, then this layer contains objects.

Turn a layer On/Off: Highlight the layer name and tap the On/Off button. Objects on layers that are On will be visible, objects on layers that are Off are not visible.

On all: This button will turn all layers on



Off all: This button will turn all layers except the current layer off. **Color**: Clicking on the color bar will bring up the color palette allowing you to set or change the layer color of the highlighted layer.

One of the main purposes of the Layer command is to permit the import, by DXF, of a drawing containing all possible polyline work to stake out (set out). Then you can reduce clutter on the drawing by turning layers off, leaving only the layers you want. You can stake any endpoint, intersection, or other location on the polylines using "snaps" without creating point numbers. You can also do the MAP command Cogo, Interpolate Points, Polylines to Points and make point numbers out of all vertices (corners) of polylines where you need to set stakes. Then proceed with Stakeout by Points.

View Options (VO):

This command controls the appearance of point objects on screen. This is exactly the same as touching the lower left graphic icon. The routine displays the View Point Options dialog. Pt#, Description and Elevation toggles control whether these attributes are labeled with the points. If Freeze All is on, the points are placed on the map, without attributes. Available point symbols are: ".", "+", "x". The "Decimal is point location" toggle determines if the decimal point used in the display of elevations represents simultaneously the point location and symbol. This slightly reduces screen clutter. Turning on the WCS Icon and Scale Bar would show the north direction and graphic scale at all time in the MAP view. Turning them off also reduces screen clutter.

Small and Large toggles determine the size of font used to display the point object on screen. Set Color Attributes brings up the color palette (available only on color CE devices). This lets you choose the color of the point symbol, elevation and description text. Traverse Defaults is found under the Data tab, which also includes the "Intelligent Zoom" toggle ("on" setting recommended). The Traverse Defaults button brings up a dialog that has the settings for prompting each time for instrument and rod height and the vertical angle. This applies to the T for Traverse and SS for Sideshot commands that allow point calculation within the MAP Screen. For Cogo work, turn off Instrument/Rod Height and Vertical Angle prompting. For manual entry of actual field measurements, turn them back on.



💝 View Options 🛛 🔽 🗙	😂 MAP VIEW 📋 🗙
Graphics Data Display	FILE VIEW DRAW COGO TOOLS Cmd: Layer: BUILDINGS
Point Label Settings Freeze All ♥ Pt ID Set Attribute Colors ♥ Description Font Size Symbol C Large Small ♥ UCS Icon ♥ UCS Icon ♥ Scale Bar	

	🔍 Color Point A	Attribute 🔽 🔀		
	Current Job	O New Job		
	Pt ID:			
	Elevation:			
	Description:			
😂 View Options	X	💝 Traverse Defaults 🛛 🔽 🗙		
Graphics Data Display		Prompt for: Instrument & Rod Height Vertical Angle Prompt:		
GIS Inspector		<u>N</u> one <u>0</u> Degrees Level <u>90</u> Degrees Level <u>E</u> levation Difference		
Traverse Defaults		Raw File:		

GIS Inspector: The option allows for creating and viewing points with attributes directly from the map screen. Once enabled, simply click on any point in the map screen to view / edit the GIS Attributes. This will also prompt the user to add attributes when adding any new point using CAD commands.

Note: to View or Edit attributes of a polygon, click anywhere inside the polygon.

The Display tab is covered in the Map-Basics section of the manual and allows for rotation of the map screen to any cardinal direction (N, S, E, W) and also allows mirroring of the screen. These screen views carry forward into all survey and stakeout screens involving graphics.



Isolate Points (ISO):

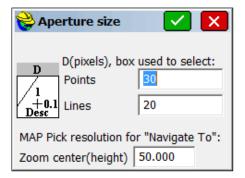
This is another useful command to reduce screen clutter. If you have 500 points on the screen, you can isolate to only those points you wish to see, by entering a distinct point range, in the form 1-10, 22, 25-30, or a certain description. This would isolate to points 1 through 10, point 22 and points 25 to 30, and other points are "frozen". You can also isolate to descriptions (D for Descriptions) by entering a description such as "EG" for Existing Ground or a wildcard description using an "*" such as "IP*" for any description beginning with IP (IP, IPF, IPS, etc.). Repeat the ISO command and enter the full point file range (or "all") to restore all points.

Isolate Layer (IL):

Select any polyline layer and isolate it to keep that layer. Other polyline layers are turned off (frozen), but point layers are retained. Use the Layer command to turn layers back on as needed (On All).

Aperture (AP):

Controls the size of the rectangle area used to select points or polylines from screen. Initially, the size in pixels is 20 units for points selection and 10 units for polylines selection. You can change it as shown. The routine displays the Aperture size dialog.



UCS (UCS) User Coordinate System Indicator:

This will toggle the visibility of the UCS icon shown in the MAP screen. This can also can be done in the View Options command or through lower left icon in Map screen.





Find Point (FND):

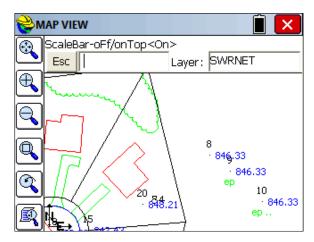
This command allows you to find a point on the MAP screen. Enter the point you want to find and a zoom height. If you enter a point that is not on the map, the dialog will warn you and allow you to enter another point number.

😂 Find point bas	ed on		🛛 🔠 🧲
Pt ID:	Desc:		
Zoom center(heig	ght):	50.000	
Pt ID Desc			
I			

Click Find and the SurvCE zooms to the selected point at the entered scale.

Scale Bar (SB):

This will toggle the visibility of scale bar on or off. The scale bar is normally shown at the bottom of the MAP screen. The "onTop" option places the icon on top of the Map View saving maximum space for the graphics:





List Polyline (LI):

Applying to line work entities only, this lists the layer, 2D or 3D status, Closed or Open status, perimeter (length), and area or projected area (if not closed). The coordinates of the polyline are shown including the elevation:

💝 Polyline list 🛛 🛛 🔹	÷
	_
LAYER: CLINE	^
2D Polyline, Open	
Color: bylayer	
PERIMETER: 308.3272 m	
AREA: 12007.2720SQ. METERS	
1.2007HECTARES	
2.9670ACRES	
129244.6827SQ. FEET	
129245.1996SQ. INT'L FEET	
0.0046SQ. MILES	
14360.5149SQ. YARDS	
	5
	Ť



9.4 Draw



The Draw menu is found next to the View menu in MAP view. Each feature is described below.

8 €∾		w				Ê 🗙
\odot	FILE	VIEW	DRAW	COGO	TOO	LS
<u> </u>	Cmd:		Polyl	ine	>	2D
(\oplus)			Circl	e		2D (Road)
			Erase	2		3D
			Laye	r	>	2D (Sketch)
			Exter	Extend >		
Q			Offset >		>	
			Mod	ify	>	
I C	+	11 12 ₁ -5.6	Place	e GRID		
	nh E→	-5 69 0	Aligr	n Pline/B	ldg >	
R			Trans	sform	>	

Draw - Polyline (All options):

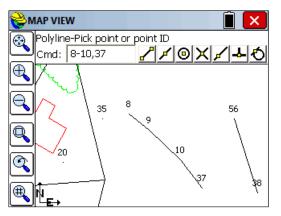
This set of commands have been updated for the 6.0 Release with Direction and Distance functionality. Now, when a user initiates one of these commands, the 'Len', or length, option provides the user with options for Direction and Distance of the line to be drawn.

		Î 🔁 🗙
\bigcirc	Polyline-aZi/Brg/Ang/	′L/R/toPoint/ <len></len>
Ľ	Esc	▞/◎≍/ᆇ�
B		
Q	3 328.08	2
	4 328.08	328.08
Q		1 · 328.07
	n) NJ -==→	Point 1



2D Polyline (PL) (AutoCAD style):

This command allows you to pick points from the screen or type in point numbers or snap to line segments. The snaps appear as icons (see below) and include, in order, left to right: "Endpoint," "Midpoint," ""Center of Arc or Radius Point/Block Insertion," "Intersection," "Nearest," "Perpendicular," and "Tangent to Arc." The "Nearest" snap will simply pick a point on any line or arc you select, at the nearest point to where you pick. First, pick your starting point then you have several options on the command line. You can also draw by point number and even use ranges, as in 8-10,37 which would draw sequentially from 8 through 10 then to 37, as shown below.



Points can be entered or picked from the screen. The default option is to keep picking points and the other options are described below.

Cmd:Polyline-Arc/Close/Undo/<End>

A: Starts an arc segment. See below for details.

C: Closes the polyline (you must have at least two polyline segments drawn before you can close)

U: Will undo the last segment drawn (you can Undo again and remove multiple segments)

E: Will end the Polyline command. Since it is the default, Enter will also end the polyline.

ESC: This will cancel drawing of the polyline.

Constructing an arc segment

After choosing A, the command line will change to:

Cmd: Polyline-Arc CEn/Len/Sec/<Rad>

You have various options for constructing an arc as part of your polyline.

CEn: Allows you to specify the center point (or radius point) for the arc. After picking the center point, you must specify the arc end point and then the arc direction.

LEn: Allows you to specify the arc length. First you pick the arc end point and then you can enter the arc length. The minimum arc length is given to you.

SEc: Allows you to specify the second point and end point to define the arc.

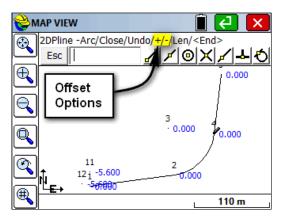
Rad: Allows you to specify a radius length. First you pick the arc end point and then you can enter the radius length. The minimum radius length is given to you.

2D Polyline (Road):



This command allows you to draw a 2D Polyline. You can draw by point number, with ranges as in 8-12, or by picking on the screen using snaps or picked points. This command is similar to the polyline command described above with the following additions:

+/-: The +/- options activate an additional prompt that allows you to plot line segments at a 90degree deflection angle from the last line. [+] is a right deflection and [-] is a left deflection. Len: This option prompts you for the length of a line segment. Enter the length and a line segment will be drawn that length using the same bearing as the previous line segment. If the previous segment is an arc, then the new segment will be tangent to that arc.



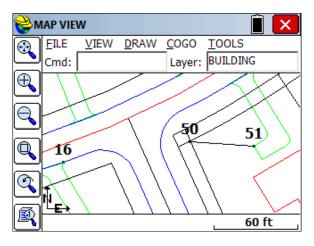
3D Polyline (3DP):

The 3D Polyline command is similar to the 2D polyline command. It will even draw arcs but will create a polyline on the screen with many vertices at different Z elevations which are linearly interpolated around the arc. If the start of the arc is point 17 at elevation 842.246 and the end of the arc is point 9 at elevation 839, then using View, List, you would see intermediate vertices (note that the segment length between vertices is about 0.12 units in this case).

💝 Polyline list	←
DINT: Y = 3382.9571, X = 4664.9588, Z = 842.2464	^
DINT: Y = 3382.9819, X = 4665.0741, Z = 842.2431	
DINT: Y = 3383.0068, X = 4665.1895, Z = 842.2399	
DINT: Y = 3383.0317, X = 4665.3048, Z = 842.2366	× .



Using the snaps to draw lines can accomplish advanced coordinate geometry calculations. The same snaps are available in the Store Point screens to aid in point storage efficiency as well. For example, if you offset two polylines and wanted to determine the point where the offset lines intersect as well as the corner of the driveway, you could draw a line from intersect to endpoint and do the command Polylines to Points (COGO, Create Points), which would create points 50 and 51. Polylines to Points will not find intersects, so it is more direct to simply do Draw Locate Points and use the intersect snap to create point 50 (COGO, Create Points). These procedures avoid complicated COGO involving curve-line intersects at offset. If your goal is to stake out points, you do not even need to create Point IDs, since the command Stake Points will locate points by snap, directly from the drawing.



Circle (CR):

This command draws a circle entity, based on diameter defined by two points or based on a center point and a radius. You can select and erase the circle with the command E for Erase. The circle is considered a polyline.

Erase (E):

Erases all selected polylines. It will not erase points. Note that you can erase an entire area by selecting a Window through the polylines (picking first a lower left point in "blank space", then picking an upper right point). If you even contact or enclose any polylines with this window selection, they will be erased. So, the "window" erase procedure mimics the "crossing" selection method of AutoCAD (r). If you enter "All" at the Cmd prompt, you will erase all linework. There is no Undo, so this would be permanent for that Job. However, you can redraw any linework created by Feature Codes, using MAP \rightarrow Tools \rightarrow Field to Finish.



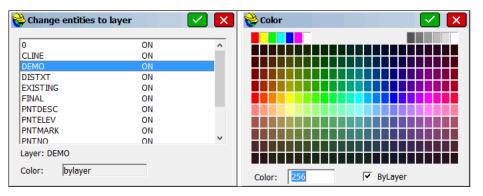
Delete Layer (DL):

Select from a list one or more layers, or select "From Screen", then the routine will delete all the polylines on those layers. If you entered C* at the lower line, the entities on all layers starting with the letter C would be erased.

癸 Erase by Layer		
Select Layers: By Name:	Clear all	From Screen
0 CLINE		^
DEMO		
DISTXT EXISTING		
FINAL		
PNTDESC		~
Layers of Entities to E	Erase:	
,		

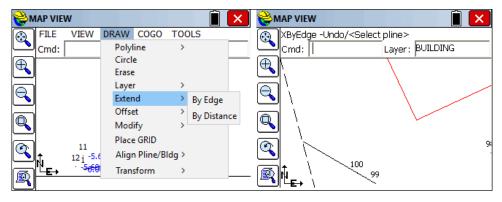
Change Layer (CHG):

This changes the layer of the selected polylines. One form of selection is to type L and press Enter in order to select last created polyline from the drawing. The routine displays the "Change entities to layer" dialog box. When the dialog appears on the screen, the selection in the layer list will be set to the current layer. Pick another layer to change layer. Clicking the color bar (where it shows "bylayer") brings up the color palette, letting you change the color by picking or ByLayer. So you can change the layer of a selected polyline or you can keep its layer and just change its color.





Extend - By Edge (XBYEDGE): First select the line to extend to, then the line you wish to lengthen and extend. In the example below, pick the line at left first, then the short line to extend second, and you obtain the result. There is a U for Undo option if you do not want to keep the extended line.



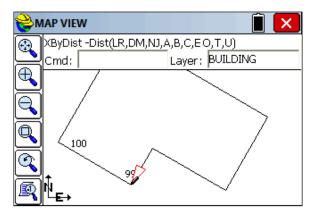
Extend - By Distance (XBYDIST): This powerful command allows you to create figures such as buildings, walls and other linear features that can then be staked out or used simply as a graphical reference or for additional CAD operations like offsets. If the distance from 99 to 100 is 7.07 feet, and you wish to make an L-shaped building that continues past point 100 for a total distance of 10 feet then goes 15' right, 20' right, 10' right, 10' right and closes, this is done with the following entries:

XBYDisT-Last/Points/<Select Polyline>: Press Enter to Select a Polyline and then pick, towards point 100, the starting line segment. The arrow will appear towards the picked end. If you get Point Details, you have not pressed Enter to "Select Polyline".

s N	IAP VIE	w			X
\odot	XByDis	t -Dist(LR,DN	1,NJ,A,B,C,E	<u>,,,,U)</u>	
P	Cmd:		Layer:	BUILDING	
B					
Q					
Ā		100			
Q		× ×	9 9		
	nu E→		\sim		



Then enter T for Total Distance (program displays current distance of 7.07), then 10 (the additional 2.93 feet is drawn), then R for Right. The arrow then turns to the right. Then enter 15 then R, then 20, R, 10, R, 10, then C to close.



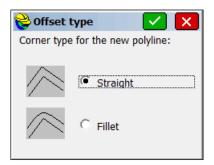
The full list of options are:

Abbrev.	Command	Description
L / R	Left / Right	Two L's or two R's would reverse the direction of the line
Μ	Move	Moves without drawing. Acts lie a 'pen up'. You can then enter left and right distances
D	Draw	Draws after a Move. Acts like a 'pen down' Distances entered will draw.
Ν	Number	Creates point numbers at the vertices and numbers from the end of the job file.
J	Jog	Turns off point numbering and goes back to simple 'jobs' of line segments. This is the default condition.
Α	Arc	Draws arcs based on radius point and end point or radius length and end point.
В	Bearing	(-aZi / Brg / ToPoint / <ang>) Entering 45 turns an angle of 45 degrees. B for Bearing allows bearing entry in all modes accepted by SurvCE, such as N34.15E. you can also draw by azimuth or to a point ID.</ang>
С	Close	Used in the example above to close to point 99, the starting point.
Ε	Extend	Will extend the line to any selected polyline.
0	New Polyline	Starts a new polyline and creates a separate entity, even though the figure will appear continuous.
Т	Total Distance	Total Distance
U	Undo	Undo
Esc	Esc	Will exit the command at any point.

Offset Settings (OF):

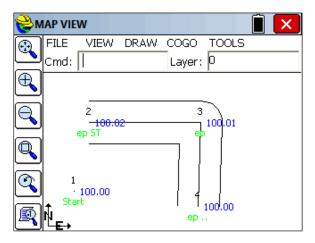
This command allows you to set the type of corner that SurvCE should create when offsetting entities.





Offset - 2D (O2):

Mimics the AutoCAD (r) Offset command, and only works with 2D polylines. Enter the offset distance and pick the left or right offset amount. The building pad at left in the graphic associated with Segment Offset was offset 10 units in the outer direction, for example. The 2D and 3D offset commands have the option to fillet the corner (create arcs of radius equal to the offset distance) on exterior offsets based on Offset Settings under the Tools pulldown menu. This exterior offset with arc is sometimes referred to as a "buffer" offset, in that all points on the exterior offset are exactly the same distance from the source polyline. Buffer offsets are sometimes used for easements or GIS applications. Offsets to the interior will not create arc segments.





Offset - 3D (O3):

This offsets 3D polylines both horizontally and vertically. It is great in combination with road/utility centerlines to create offset polylines to stake. It can be used for ditch lines, curbs, walls and many other applications. The standard offset method is "Interval". In the case below, a 3D polyline for edge-of-pavement (EP) was offset Horizontally 0.2 then Vertically 0.5 for top of curb, then offset again 4.5H and 0V for outer edge of sidewalk. These three 3D polylines can then be selected in Stake Road, option "Cut from Alignments" and then with the outer sidewalk edge selected as the "centerline", the stakeout screen would appear as shown below (exaggeration 4x):

📚 Stake Road 🛛 🗖 Grade 🗾 🔽 🗙
Sta: 10.000
Interval: Image: Second
Stk Off: (H) 0 (V) 0 CENTER
Slope Stake

Using the "Interval" method (normal method), vertical offsets can be by elevation difference (default), or by slope percent or ratio. The default "Continuous" option keeps the offset 3D Polyline as a single entity. If you do the "Segment" option approach, only the segments of the 3D polyline will offset (leaving gaps), and you have the option to create Point IDs on the offset vertices.

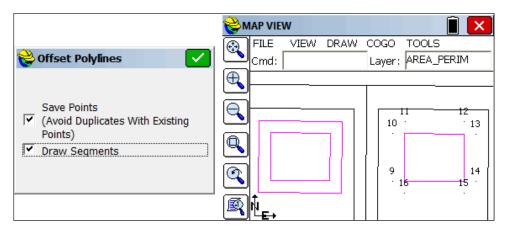
📚 MAP VIEW 📋 🔁 🔀	😂 MAP VIEW 📋 🗙
OffRevSee-Select polyline	DrawLP -Coords/ <pick> OSNAP point Esc</pick>
P00	
Save Points (Avoid Duplicates With Existing	23
Points) Points) Draw Segments Points	



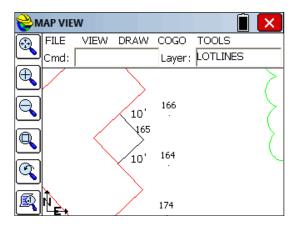
The "Constant" option takes a 3D polyline and offsets it to a constant elevation for all vertices. So, if you measured the base of a retaining wall that sloped downhill, but the top of the wall was a constant elevation, you could offset a fixed horizontal distance to that single elevation.

Offset - By Segment (OSEG):

This will offset all vertices of each segment of the polyline in a 90-degree offset and will draw line segments or optionally create points at the offsets. This is shown at right (in contrast to the parallel line offset at left) in the graphic below. You begin by entering the offset amount (e.g. 10). Then a dialog appears with options to Avoid Duplicates and "Draw Segments", which, if unchecked, removes the line segments and leaves only the points.



For L-shaped buildings or figures with angles, an additional interior offset point is calculated at the intersect of the parallel offset lines based on the entered offset distance, such as 10 (see point 165 below--the lines to 165 are drawn only to illustrate the 10' offset):

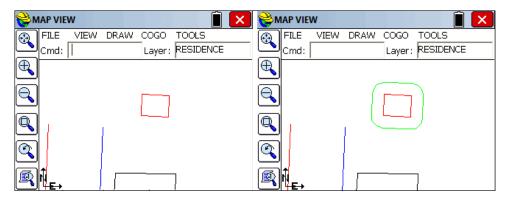


For L-shaped figures, offsets are also projected through to the other side, so that the offset for point 174 appears across the building, for purposes of pulling a stringline.



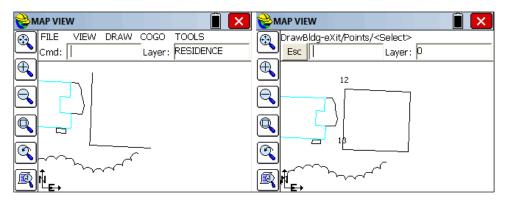
Offset - Buffer Offset (Offsetb):

Pick any closed figure or multi-sided figure and you can offset, typically to the outside, using a rounded radius corner, such that all points on the offset line have the same distance from the nearest point on the figure. An offset of 2 units was used below on the closed polyline shown, using Buffer Offset.



Offset - 4-Sided Building (DrawBldg):

Sometimes it is possibly only to measure 3 points on a rectangular building. If you connect the 2 sides with a 3-point polyline, you can click on the building using the command Offset, 4 Sided Building, and create the missing 2 sides.

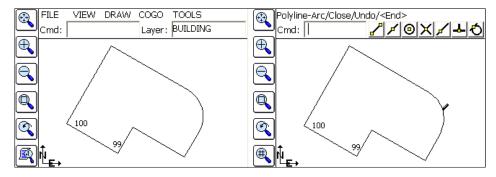


You can select by tapping the building or choose "Points" to enter point 12, 13 and snap the endpoint of the 3rd side, for example. If you have only measured 2 points for a rectangular object, the command will still work--it will prompt for the offset distance (positive is to the right, negative is to the left) and create the 4-sided building or object. You will get a warning if a picked polyline has more than 3 vertices--in that scenario, use the "Points" object to pick the 3 corners of the building.



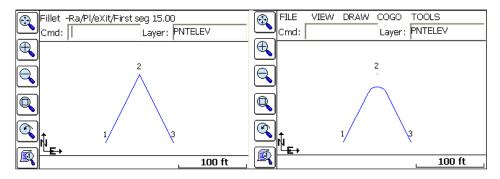
Modify - Remove Arcs (RMA):

Pick any polyline with an arc, specify the "offset cutoff" spacing, and turn the arc into chords. Offset cutoff refers to the maximum separation between the chord and the original arc. If you enter a small cutoff distance of 0.1, then at no point do the chord segments differ from the arc than 0.1. Be careful with this command – there is no "Undo" to restore the arcs (though you can immediately start a new job and "re-load" the last, saved DXF file of the drawing). After removing arcs, you can draw a polyline from points on the arc, after creating small chords, using the "endpoint" snap (first snap on the left in the list of snaps).



Modify - Fillet (F):

Similar to AutoCAD's Fillet command. It prompts: Cmd: Fillet -Ra/PI/eXit/First seg 25.00. If you are trying to inscribe a curve at the corner of a polyline, you enter the desired radius first by selecting R for Radius (at the above prompt). Then you choose the P option. This leads to the prompt, Cmd: Fillet -Ra/PI/eXit/Select pl 25.00. Select the polyline near the vertex where you want the curve to go. This completes the process. If you wish to change the radius, enter R. If you want to fillet the corner of 2 distinct polylines, then just pick them as prompted (do not do the P for Polyline option). This command will only work with 2D polylines, completed with the command 2DP, or imported from a DXF file as 2D polylines, or converted from 3D using the command C2D which changes the vertice elevations to zero.

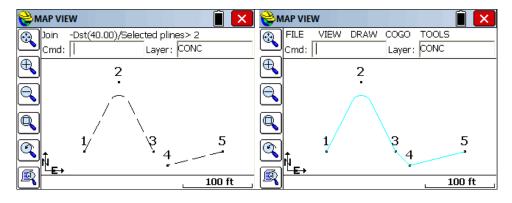




See the previous two figures. Because in the Left figure, from 1 to 2 to 3 was one continuous polyline, after the radius was set at 15, P was entered to set up the one-pick approach for polylines, leading to the completed fillet command and the result as shown in the Right figure. Now you can do Cogo, Interpolate Points, Polylines to Points (P2P) and solve for the points for the beginning of the arc, radius and end of arc, for purposes of stakeout (set out).

Modify - Join (JN):

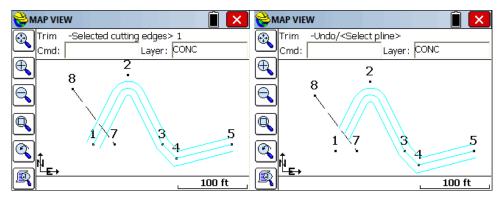
This command allows you to join polylines. Enter D to specify a new maximum separation distance, then select the polylines on the MAP screen. If you use 0 for Distance, then the polyline to join must be separate polylines connecting to common points. The advantage of joining polylines is that they can then be offset as a unit, and the vertices of the offset polylines can be turned into points for stake out. The offset command, in effect, does all the complicated bearing-bearing intersects for you. For example, if the resulting polyline were a pipeline with a 20-meter total right-of-way, then to stake the right-of-way points, you would offset the polyline 10 units left, then 10 units right, then turn both offset polylines into points, or directly stake by snapping to the offset polylines using endpoint and nearest snaps.





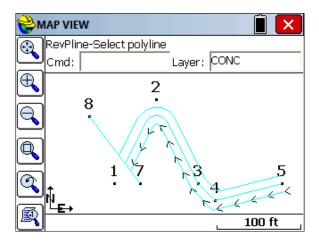
Modify - Trim (TM):

This allows you to trim polylines to the edge of other polylines just like in AutoCAD (r). Then the command Polyline to Points (P2P) will turn all vertices, including the trimmed end points, into points for stakeout.



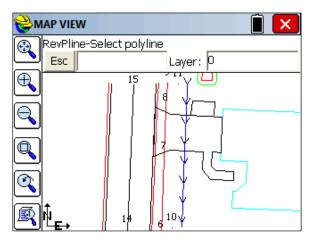
Modify - Reverse Polyline (RV):

When you turn a polyline into points, it will start the point numbering at the beginning of the polyline. Thus, it may be useful to control the direction of the polylines for purposes of stationing and staking. This is done with the command Reverse Polyline. Each time you pick a polyline using this command, you reverse its direction, and little temporary arrows are displayed along the polyline indicating the current direction. If it is not the direction you want, reverse again.





This command is useful to prepare for Stake Road using Cut from Alignments. The polylines for the various road breaks in grade need to be drawn in the same direction for "Cut from Alignments" (screen selection of 3D polylines) to work effectively. So, in the instance below, if the alignment goes south to north (point 14 to point 15) and the ditchline polyline shown is drawn in the wrong direction, use Reverse Polyline to get its direction matching that of the main centerline. In this case, pick it one more time to reverse it so it goes south to north.



Place (Draw) GRID (DG):

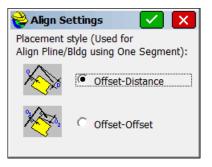
This command toggles a horizontal and vertical grid display over your drawing, allowing you to set the grid resolution in drawing units. These grid lines are for reference only and are not part of the stored drawing associated with the job. To turn off, repeat the command and enter Off.

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	Cmd:			I	Layer:	PR-RD	-STAN	И
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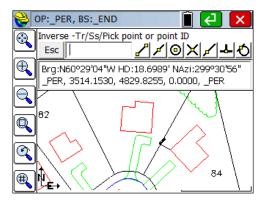
Align Settings (ABSET):

This command allows you to select between two methods of aligning buildings using the Align Building One Segment command under Draw, Align Pline/Building. The first method (offsetdistance) aligns buildings parallel to the sideline based on a sideline offset and a distance offset along the sideline to the front of the building. The second method (offset-offset) holds the building parallel to the sideline but ensures that the frontage offset to the selected corner of the building matches the second offset value.



Align Pline/Building One Segment (AlignB), Offset-Distance Method:

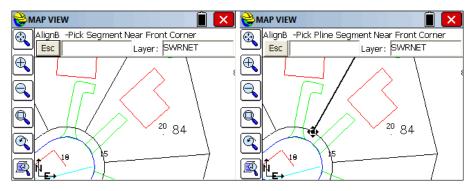
This is a building application allowing adjustment of the building pad location in the field. If you import a map of a subdvision or building project containing a building pad, side lot lines and a frontage line, you can reset the building pad to a new, specific offset from the frontage and also force the building pad to be parallel to a selected side lot line, at a specific offset to the lot line. Refer first to the graphic below which shows an existing building on lot 84. Using the I for Inverse command in the MAP screen, you can obtain the distance from the end point of the building and then select the perpendicular snap on the lot line. The distance is 18.7 feet. Similarly, the distance from the building to the arc of the frontage line can be computed at approximately 58 feet.



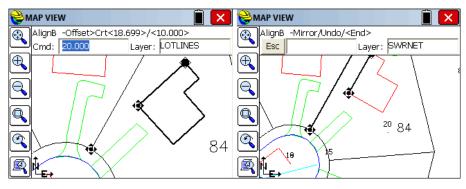


There are 2 methods of Building Align, which are set under Tools, Align Settings. The first method is to align the building parallel to a lot line at a certain offset from the frontage, measured along the lot line. This is the Offset-Distance setting for Building Align. To illustrate this method, assume the goal is to place the building parallel to the side lot line at 20 feet offset, and offset from the frontage at 65 feet as measured along the lot line. Here are the prompts for the Align Building command:

Pick Lot Segment Near Front Corner (of lot line): Pick the line shown below near where it contacts the right-of-way, near the front. The building setback offset will be calculated from the front end of the lot line.



Pick Pline (Building) Segment Near Front, Lot Side: Pick the same lower left building corner as shown above, but along the side facing the adjoining lot line. This leads to the graphic below. The correct side line is highlighted.



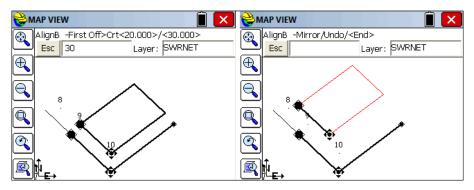
Offset>Crt<18.699>/<10.000>: Enter the desired side line offset (20).

Distance>Crd<57.919>/<10.000>: Enter the desired frontage offset (65), as measured along the selected side line. The building redraws as shown. You can Undo or enter M for Mirror, which mirrors the building around the highlighted building line (and in this case would force the building across the lot line. Even after you experiment with Mirror, you can Mirror again or Undo the entire process.

Align Pline/Building One Segment (AlignB), Offset-Offset Method: If the Align Settings under Tools is set to Offset-Offset, then two offsets will apply using the One Segment command: (1) to the side line and (2) to the front line. This method requires that the lot line be a continuous



polyline for both the side and front portions of the lot, allowing just one pick, hence "One Segment" method. Also, both lines need to be straight--this option will not handle a curving front line. It is best illustrated in the simple example below:



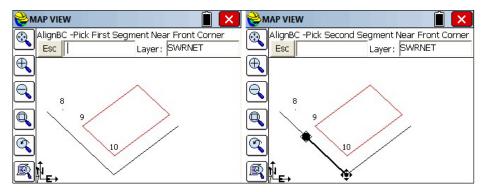
Pick Lot Segment Near Front Corner (of lot line): Do the same pick as before on the side lot line opposite the building, near the frontage portion of the lot line.

Pick Pline (Building) Segment Near Front, Lot Side: Then pick the building also on the side facing the side lot line, between points 9 and 10 but closer to point 10. Then enter the side offset first (30 in this case) and then enter the frontage setback offset next (50 in this case). This results in the new position for the building as shown, 50 units from the frontage line and 30 units offset from the side line, ready for stakeout. Stake out the new building by snapping to the endpoints in the command Stake Points or follow with Offset by Segment to stake offset points.



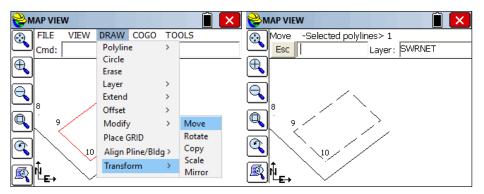
Align Pline/Building Two Segment (AlignBC):

This option is almost identical to Align Building One Segment, Offset-Offset method covered immediately above. The only difference is that the frontage line can be a separate line, allowing for 2 picks to identify the side line first and the frontage line second. And similarly, both side line and frontage line must be straight. The command does not handle arc segments. The command differs from the Offset-Offset, One Segment method only by asking for separate picks for the side lot line (first) and the frontage lot line (second), as shown below. In fact, you can pick a continuous lot line in 2 picks, so it works with continuous or distinct, separate lot lines identically. For this reason, it is recommended just to keep the Align Building setting on Offset-Distance, and use the 2-pick approach for the double offset method.



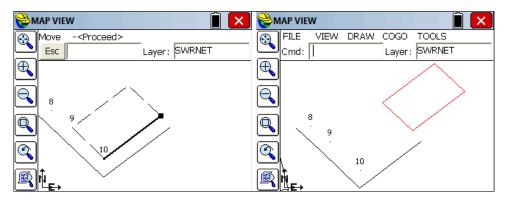
Transform (MOV, ROT, COP, SCL, MIR):

This command allows you to reposition polylines in the drawing to new locations based on your point geometry. The transformation options are Move, Rotate, Copy, Scale, Mirror. These work much like they do in AutoCAD, with input being the base or source point, and the destination or target point, rotation or scale. In the case of Rotate, the base point is the rotation pivot point and then you enter a rotation angle.



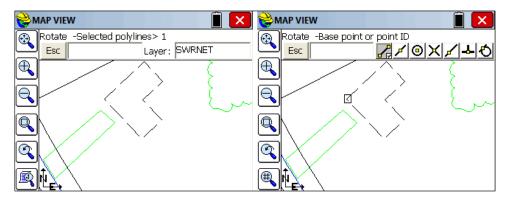


The **Move** command is shown above. One or more polylines can be selected. Then the move must be defined as the relative distance between two selected positions. If the first "Source Point" is point 10 (entered as 10) and the second "Target" position is the right corner of the selected polyline (snap to endpoint), the end result would be as shown below:



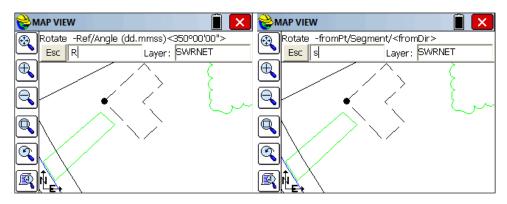
The polylines can be returned to their original position by just reversing the order of the selected Source Point and Target Point. The Copy command may also be used as a Move command, since it has the advantage of showing the new copy and keeping the original, in case you wish to erase the new version and repeat for better results. The Mirror command includes the option to delete the source or retain the source entities. Note: These commands only move selected linework and do NOT reposition the corresponding points in the drawing.

The **Rotate** command has the following prompting:

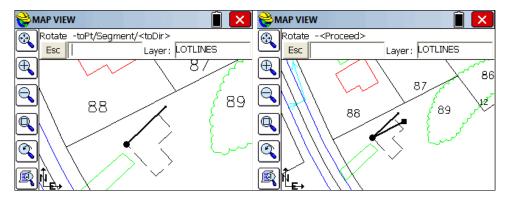


First you select the polylines to rotate. Press Enter when there are no more selections. Then choose your Base Point for rotation. Here, we use the Endpoint snap and select the corner of the building shown.



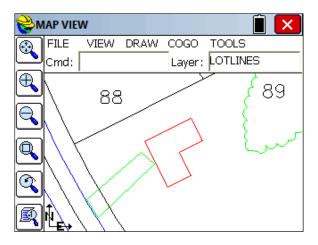


Select the pivot point first. If you want to make it parallel to an existing line, choose R then S for Segment, then pick the segment on the figure you wish to reference first. Then after that, the next pick, also by S for Segment, will be for the property line (e.g. the line to the north) you wish to match.

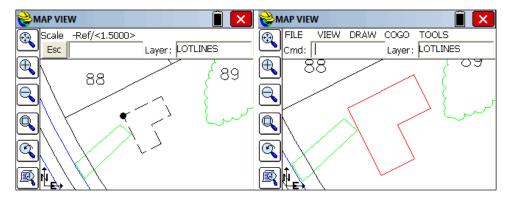




After the rotation is confirmed, you obtain the final results shown below. The simplest rotation, of course, is just by angle, where 10 degrees would rotate 10 degrees clockwise from the pivot point.



The **Scale** command operates much like the others by first requesting a base point for scaling, and then a scale factor: R for Ref is similar to rotate, where you specify the segment on the object that you are referencing and then the segment on another object you wish to match, for scaling.





9.5 Cogo

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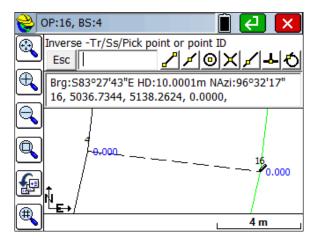
The COGO menu is found next to the Draw menu in MAP view. Below you will find each feature described.

s 🗳		w				
\odot	FILE	VIEW	DRAW	COGO	TOOLS	
	Cmd:			Inv/Tra	v/SideS	>
₽				Create	Points	>
				Calcula	tor	>
				Area		>
M				Slope R	eport	
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Inverse (I):

Inverse command Inverses and presents the bearing and distance between point numbers. It has the added benefit that the previous point inversed becomes the backsight, and the current point inversed becomes the occupied point, allowing you to sequence directly into the Traverse or Sideshot commands. (Use angle code 7 to turn an angle right from the backsight to the foresight.) The "snaps" are available in inverse, so you can calculate the distance from a point to a line by "snapping" to endpoint, intersect, perpendicular (as shown below) or nearest.



Traverse (T) (also TR):

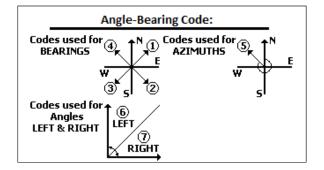
Similar to the Sideshot command, the Traverse command will "move up" to the last point traversed, holding the previous occupied points as the backsight. Exit with Esc.

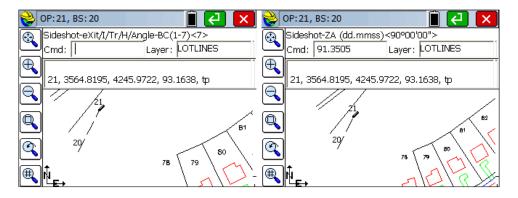


Sideshot (SS) (also S):

This allows for sideshots from any point that is "occupied" by use of the inverse command. For example, if you inverse from 126 to 150, you are "on" 150 and backsighting 126. Then at the prompt "Cmd: Inverse – Tr/Ss/Pick point or point No:", you can enter S for Sideshot. The first prompt is the Angle-Bearing Code: Sideshot-eXit/I/Tr/H/Angle-BC(1-7)<7>, which can be any of the following:

- 1-NE (0 through 90 if degrees, 0 through 100 if gons/grads)
- 2-SE (same as above)
- 3-SW (same as above)
- 4-NW (same as above)
- 5-Azimuth (360 circle if degrees, 400 circle if gons/grads)
- 6-Angle Left (degrees or gons)
- 7-Angle Right (degrees or gons)







Note that at the Angle/Bearing prompt, you can transition back to inverse (from your occupied point) or to traverse, which would move you up to the next traversed point. Code 7 turns angle right. In the standard MAP screen prior to selecting T or SS, if you click the lower left View Options button, and then select the Data tab and choose Traverse Defaults, you can turn on the Zenith Angle or Elevation Difference prompts. Then sideshot and traverse entries can be used for hand-entry of field data. Within Sideshot, you stay on your current point, holding the backsight, and foresighting (calculating) as many points as desired. X returns to the MAP screen as does Esc.

After the angle code, the remaining prompts are the angle itself (as in 85.3522, DDD.MMSS), zenith angle, slope distance, description and point ID. Exit with Esc anytime. In gons/grads, angles are also in decimal form, and angles such as 397.9871 are valid. The lower left icon within the sideshot/traverse routine, as shown above, leads to a "Find Point" option.

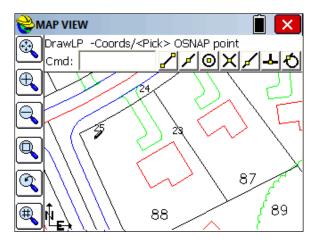
Create Points - Draw Locate Points (DrawLP):

This command creates points at endpoints and intersections of polylines, based on use of the

"snaps". In the example below, point 23 was created at the northeast endpoint 🗹 of the

building on lot 88, point 24 was created at the intersect X of the driveway and the lot frontage

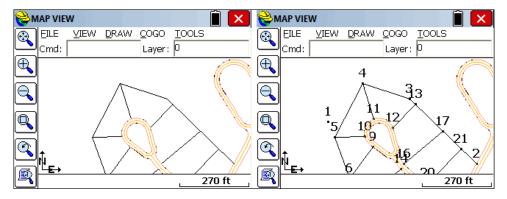
line and point 25 was created at the center of the arc of the pavement line. The "snaps" from left to right are endpoint, mid-point, arc center/insertion, intersection, nearest, perpendicular and tangent.





Create Points - Polyline to Points (P2P):

This command converts any selected polylines into points. It is useful in capturing points for stakeout from polylines created as offsets or brought in from DXF files. This allows you to react to circumstances in the field by creating points from polylines, when and where needed. For example, if you wanted to make point numbers out of the lot corners below on the SW lot, Select Cogo, Create Points, Polylines to Points (or more simply enter P2P at the command line). Then pick each desired polyline. The program will avoid making duplicated points on vertices that already have point IDs.



The new points are shown in "large" format, for emphasis.

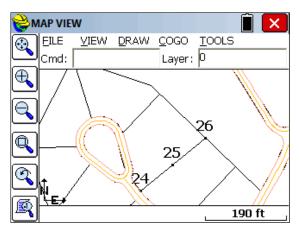
Create Points - Divide Along Entity (DVS):

This divides a polyline into the number of segments entered. A dialog will allow you enter in the number of segments. There are settings to prompt for descriptions and elevations and to create points at the end points of the polyline.

😂 Divide Along Entity		
Starting Point ID:	19	
Point Prompt Settings	,	
Prompt for Descriptions	Elevations	
Create Points At Endpoints		
Number of Segments		
2	_	



The command will create new vertices along the polyline, but can also create point numbers starting at the entered Point ID, and you can elect to be prompted for descriptions and/or elevations at each new point. If a property line were divided into two segments, you would create three new points, if Create Points at Endpoints is clicked on. Otherwise, division of a line into two segments would create only 1 new point ID, in the middle of the line or polyline.



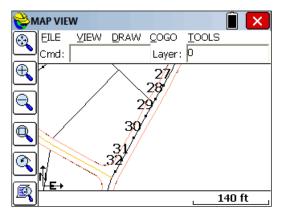
Create Points - Interval Along Entity (DVI):

This divides a polyline by the distance entered. Curves can have a different interval. There are settings to prompt for descriptions and elevations and to create points at the end points of the polyline.

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Elevations
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50.0000



This command is often used for creating points on centerlines. Note the program resets the interval at break points like PI's and PC's. Note that you can choose to create more points at a smaller interval going around curves.



Triangle Calculator (TC):

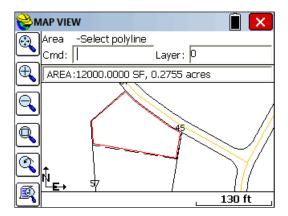
Goes directly from the MAP view to the Triangle calculator. See COGO - Calculator for detail.

Curve Calculator (CC):

Shortcut to the curve calculator, then returns to MAP. See COGO - Calculator for detail.

Area (AR):

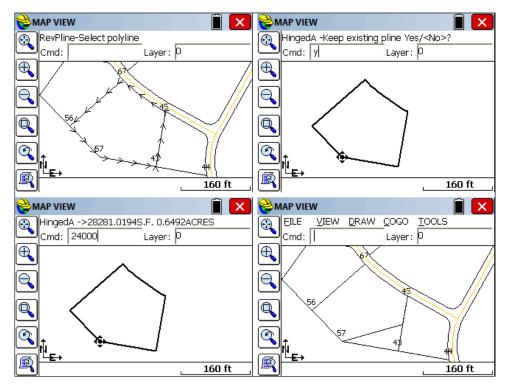
This will report the area of any picked polyline. If you pick an unclosed polyline, the program will draw a temporary line for the closing segment and report the area.





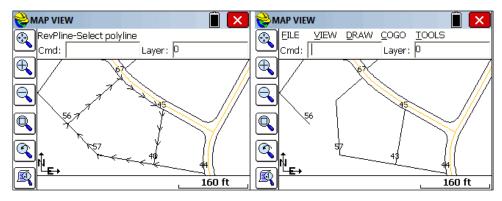
Hinged Area (HA):

This command can be used to determine the dimensions of a figure when the area is fixed and three or more sides are known. The figure must be defined by a closed polyline. After executing the command, select the polyline. Next, select the hinge point. The polyline segment clockwise from your hinge point will be the segment to move. SurvCE will then ask you if you want to keep the existing polyline. If you answer Yes, a new polyline with the desired area is created, if you answer No, the polyline you pick is modified. Next, the current area of the polyline is shown. At this point, enter the new area in the units specified under Job Settings. (If your units are set to feet, the area will be specified in square feet). See the top-left figure below.



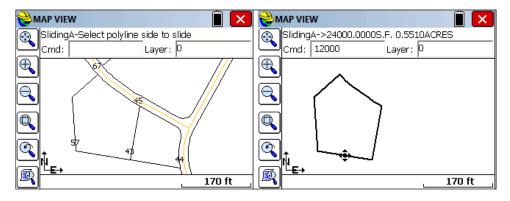


Note how the hinged side occurred on the clockwise side of the polygon perimeter (side 57 to 43). If we erase the new polyline, reverse the original polyline (RV) and repeat the command, this time answering "No" to "Keep existing" and again targeting 24000 s.f. area, we get the following:

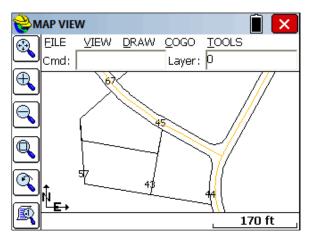


Sliding Area (SA):

This command adjusts one side of a polyline to meet a specified area. You must specify the new area in the same units as specified under Job Settings. The area to adjust must be a closed polyline. After executing the command, select the polyline. SurvCE will then ask you if you want to keep the existing polyline. If you answer Yes, a new polyline with the desired area is created, if you answer No, the polyline you pick is modified. Next, the current area of the polyline is shown. At this point, enter the new area in the units specified under Job Settings. (If your units are set to feet, the area will be specified in square feet). Let's choose to divide our new parcel into two equal areas of 12,000 square feet each.







Slope Report (SR):

This command reports the horizontal area along with the slope area of a figure defined by a range of points. The command actually executes the TRIANGULATION command to compute the slopes within the defined area. There are options to include breaklines, use a predefined TIN model, and prompt for inclusion/exclusion areas. If you use a TIN model, you should click on "Prompt for Inclusion/Exclusion" and then pick perimeters where the calculation will be applied.

Consider the figure defined by points numbered 570, 97, 569, 584, 585, 75, and back to 570 as shown below. From the COGO AREA command, we see that the horizontal area of the enclosing polygon is 11,653.4122 Sq Ft. Performing the SLOPE REPORT yields the same horizontal results, but also reports the slope area, and the maximum, minimum, and average elevations and the average slope within the area.

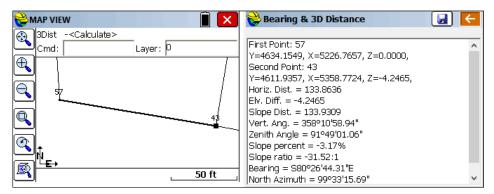
😂 MAP VIEW 📋 🔀	📚 Triangulate & Contour 🛛 🔽 🔀
Area -Select polyline Cmd: Layer: 0 AREA:11653.4122 SF, 0.2675 acres 98 97 95 95 570 569 568	✓ Points Range of Points: 570, 97, 569, 584, 585, 75 Wildcard descriptions: <u> <u> </u></u>
	Include: 🗹 Breaklines 🔽 Contours
Ses 584 583 100 ft	Select File None Prompt for inclusions/exclusions



裬 Slope Report	
Horizontal Area: 11653.4122SQ. FEET 11653.4588SQ. INT'L FEET 1294.8223SQ. YARDS 0.0004SQ. MILES 1082.6411SQ. METERS 0.2675ACRES 0.1083HECTARES Slope Area: 16140.2722SQ. FEET 16140.3368SQ. INT'L FEET 1793.3618SQ. YARDS 0.0006SQ. MILES 1499.4854SQ. METERS 0.3705ACRES 0.1499HECTARES AVERAGE ELEVATION: 511.4906 AVERAGE SLOPE: 62.2649 MAXIMUM ELEVATION: 520.0000 MINIMUM ELEVATION: 440.9770	*
	*

Bearing & 3D Distance (3D):

This command reports the horizontal distance, elevation difference, slope distance, vertical angle, percent slope, slope ratio, bearing and azimuth between two 3D points. The user can pick or enter the number of two points, select a polyline segment or pick two points on any polylines from MAP using the "snaps". Within the report screen, clicking the disk icon on top will create a Txt file of the inverse for export.





9.6 Tools



The Tools menu is found next to the COGO menu in MAP view. Below you will find each feature described.

		P VIEW			Ê	×	
\bigcirc	FILE	VIEW	DRAW	COGO	TOOLS		
P	Cmd:				terline Pline to PRO		
€					Pline Profile		
H				Con	Convert Polylines to 2D		
				Edit		,	
M				Trav	Traverse Defaults		
Ľ				Surf	ace		
P				Field	d to Finish		
				Ima	Image Overlays		
[🚳]				Wel	Web Map Overlays		
Ľ	й _е ,			NGS	Survey Mai	rk Query	



Centerline - Polyline to CL (P2CL):

Converts any polyline into a centerline file for use in the Roading commands and in Centerline, Curve and Offset Stakeout. You will be prompted for starting station and the name of the centerline (horizontal alignment) file, and you will obtain a centerline report. To station the polyline in the opposite direction, use Reverse Polyline (RV), or select Draw, Modify, Reverse Polyline to change the direction of the polyline prior to issuing the command. If we choose the existing polyline as shown, we obtain the following CL file report:

😂 CL file report 🛛 🗧 🧲
Warning:
Polyline should have been drawn in direction of increas
Station North(y)
0+00.000018551.220014632.33
1+50.000018538.418314781.78 Radius: 684.9315, Length: 479.4176, Delta: 40°06'15"
6+29.417618340.305515207.64 Radius: 603.5534, Length: 474.0297, Delta: 45°00'00"
11+03.447318163.528815634.42
12+53.447318163.528815784.42

Draw CL to Map (CL2P):

This command draws a POLYLINE entity using the data from a centerline file. You can practice this command by selecting the file Demo.cl, provided with the program. It draws in the current layer set within the View pulldown, Layer command.



Polyline Smooth Test (IsSmooth):

Select a polyline to verify smoothing. A polyline with tangent curves would report "Smooth Polyline: No deflection angles greater than 0 degrees detected." A polyline such as a right-of-way line or top-of-bank line in a roadway design (see below) would report all angled points of intersections (PI's). The purpose of the command is to detect alignments that have non-tangent curves or PI points without curves. It is also useful to verify whether alignments such as right-of-ways have perfect 90 degree, right-angle deflections. The centerline with tangent curves in the graphic below, for example, reports "Smooth Polyline", while the top-of-bank polyline (see arrow) reports the information at right.

📚 MAP VIEW 📋 🔁 🗙	📚 Polyline not Smooth:
FILE VIEW DRAW COGO TOOLS	
Cmd: Layer: ROAD_BREAK	1º09'20" at: 1.636!
	2º28'42" at: 12.390!
	1º06'29" at: 23.141!
	1º06'29" at: 33.894!
	1º06'29" at: 44.647!
	1º06'26" at: 55.399!
	1º01'10" at: 66.152!
	0°58'30" at: 76.903!
	0°58'30" at: 87.654!
	0°58'30" at: 98.404!
	0°58'30" at: 109.153!
	3°31'26" at: 119.901!
	1025'24" at: 130.6571

3D Pline to PRO (3DP2Pro):

Pick any 3D polyline and create a profile. If you pick a polyline at 0 elevation, the program will warn, "Cannot create PRO file. Not a 3D Pline! Please select another Polyline." If you pick a polyline that has vertices with elevations, a profile or vertical alignment file (.pro extension) will be created and can be reviewed and edited within the Roads Menu command, option Profile Editor. You can set the starting station. Keep in mind that for alignments with curves, 3D polylines must use chords with many vertices since the program cannot present 3D polyline arcs. Because chords reduce the distance around arcs, stationing may not match the true 2D alignment. This would not impact straight alignments or deflection-type alignments such as for electric, telephone and water lines or sewer lines running between manholes.



Convert Polylines to 2D (C2D):

Pick any 3D polyline or contour polyline at uniform elevation and convert it to 2D (elevations of vertices are set to 0). Helpful when doing the Fillet command, for example, which requires a 2D polyline.

Edit - Polyline (EDP):

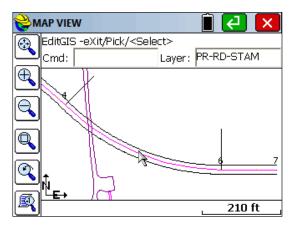
Remove vertices, insert vertices and update (alter) the coordinates of any vertex. For example, if we pick the centerline that was used above, we obtain the edit dialog, with options to add or remove segments or arcs, edit curve information, etc. Saving changes updates the graphics on the screen. Double-clicking any line is equivalent to tapping Update.

e	À Edit	: Polyli	ine		←		
	Polyline(2D)-List of Vertices:						
	No	Pt ID		Easting			
	۹ 1		4959.8023	4942.2812			
	€ ? 2		4976.6498	5068.7853			
	٩ 3		5037.8730	5128.3273			
	<u> </u>		5125.9457	5138.9099			
	I	nsert	E	Edit Arc	Update		
É	<u>ð</u>		F	Remove	Save		



Edit - Input-Edit GIS Data (EGIS):

This command allows you to input or edit GIS attributes associated with an entity. Select the entity from the screen or for the case of a closed polyline, pick inside the area defined by that entity.



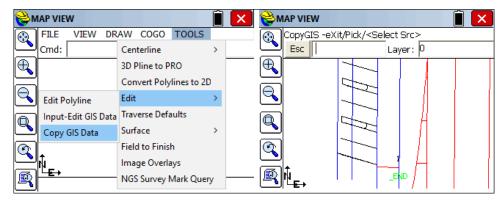
Only polylines (open or closed) can be selected. This command does not apply to attributes associated with points (use List Points to edit point attributes). Attributes are associated with points, polylines and polygons (closed polylines) either through use of feature codes or by importing shape files or dwg files exported from ESRI products. If a polyline is closed, you can use the Pick option and simply pick inside its interior. This "ROAD" description included a "SURFACE MATERIAL" attribute, which now can be edited. Drawings that are exported using "Export to CAD" from ArcMap 9.1, 10.0 or 10.1, when imported within SurvCE, will include many GIS feature options that can be selected in the top pulldown and assigned to the selected polyline, with corresponding attributes. The "Recall" button will display the last attribute values chosen for any feature such as "BLD" (for buildings in this case) or "SW" (e.g. for sidewalks). GIS attributes can be exported to ESRI using the commands Export Shape Files or Export .dwg.

😂 Add GIS Data	BLD 🔹	←
1487628464	BLD	les
(Char) How many Stories	MH	
3	SW WV	•
Del Recall	Next Prev Save	



Copy GIS Data (CGIS):

Select a source entity to extract GIS data from and then apply it to a destination entity. So, if one building has GIS data that applies to another building, you pick the source building and then select the destination building and it then shares the same GIS data.



<Select Src> is the prompt to pick the source entity with existing GIS data, following by <Select Dst> which prompts to select the destination entity to apply the GIS data to. The program warns if the source entity has no GIS data. You have the option to edit the destination data, so if you copy the GIS attribute "Number of Stories" for a building, you can edit the destination data, for example, from 3 stories to 2 stories, within this copy procedure.



Traverse Defaults (TD):

This sets the elevation prompting (none, vertical, zenith, elevation difference), within the Traverse and Sideshot commands within the MAP view. Also enables a prompt for Instrument and Rod Height. Default setting is no instrument or rod heights and no vertical angle prompting, so inputs are simplified as angle/bearing code, angle/bearing, distance, description, point number. Traverse and Sideshot entries within the MAP screen are stored to the RW5 file unless this option is clicked off at the bottom of the dialog.

Note: 3D MODE must be enabled in **Equip/Configure** for this dialog to become active. Otherwise, choices are "grayed out."

ờ Traverse Defaults 🛛 🔽 🚺	
Prompt for:	
Vertical Angle Prompt:	
<u>N</u> one	
O Degrees Level	
C <u>9</u> 0 Degrees Level C <u>E</u> levation Difference	
Raw File:	
○ On ● Off	

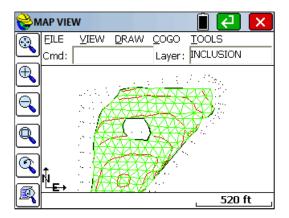


Triangulate & Contour (TRGC):

Triangulate and Contour can create a final contour map based on user given data: points, polylines. This function has many options which are specified in its dialog box. The routine will prompt also for inclusion and exclusion polylines. You can use exclusion polylines to avoid contouring within buildings, for example. If you have no exclusion polyline (or no inclusion polyline), press Enter to continue. To delete entities drawn with this command, turn off all of the drawing options and reprocess or use the View pulldown menu and isolate to the layers involved then erase all objects.

ł	Triangulate & Conto	our 🔽 🔀				
	Points -					
	Range of Points:	ALL				
	Wildcard descriptions:	Ê				
	Draw Contours Cor					
	Include: 🔽 Breaklines 🔽 Contours					
	Erase Previous Contour Entities					
	Save Triangulation t	o File 🔲 Draw Triangulation				
	Select File None					
	Prompt for inclusions/exclusions					

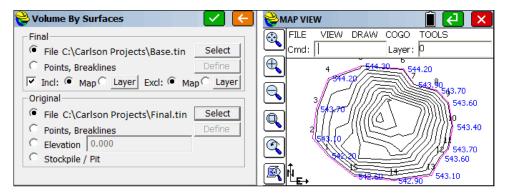
If "Prompt for inclusions/exclusions" is turned on, then the first selection is for the inclusion and optional exclusion polylines. If a ".tin" is saved, it can be recalled in commands such as Elevation Difference and used for stakeout and determination of cut and fill. If "Draw Triangulation" is turned on, the triangulation lines will be drawn. When selecting entities for contouring and triangulation, there are 3 types of entities that can be selected: Points, Breaklines and Contours. Points would be point IDs, breaklines would be 3D polylines and contours would be 2D polylines at non-zero elevation.





Volume (VOL):

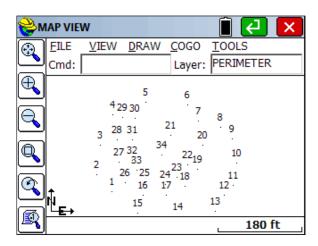
Volumes can be computed by several methods, using surface files (e.g. ".tin" files), point ranges and/or layers to define existing and final surfaces. Perimeters can be used to further limit the area of the volume calculation.



😝 Volume By Surfaces	
Final ○ File None ● Points, Breaklines ▼ Incl: ● Map ○ Layer Excl: ● M	Select Define ap C Layer
Original O File None	Select
Points, Breaklines Elevation 0.000	Define
C Stockpile / Pit	

In the example above left, two tin files are used to define the surfaces for volume calculation, as enclosed by an inclusion perimeter. In the example above right, the base surface might be defined by points 1 to 15 and the final surface defined by the contour and perimeter layers. Referring to the graphic below, which illustrates the same stockpile as above, the "Final" point range could be defined as ALL points, and the "Original" point range could be defined as the base points of the stockpile or points 1-15. Use the "Define" button to specify the desired layers and point ranges to include in the calculation for original and final surfaces.





So, using the settings above in the Volume routine, you would verify your two point ranges, then click OK. For example, the "Original" surface point range would be set as follows using the "Define" button for "Original" prior to clicking OK.

📚 Select Entities			X
Points	🗌 Save	e Surface to File	
Range: Wildcard Descriptions	1-15		
Available Layers:		Layers Used:	
106 PERIMETER	_>>		
PNTNO	>		
	<		
	_<<		

Clicking OK moves forward to a shrink and swell factor screen. Only if you are set to English units do you get the option for tons based on a density factor. In metric units, the volume is presented in cubic meters. You can create a new surface TIN file that merges the original surface with the final surface within the selected or assumed perimeter. If you do not have an inclusion perimeter, then the largest "convex" figure defined by all final surface points and entities becomes the default perimeter.



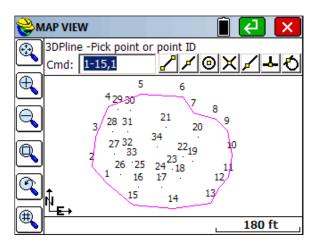
裬 Volume Report	Options
Cut Swell Factor:	1.00
Fill Shrink Factor:	1.00
Report Tons	
Density(g/cm^3);	1.300
Save Merged S	urface to File

Clicking OK continues to the Volume Report.

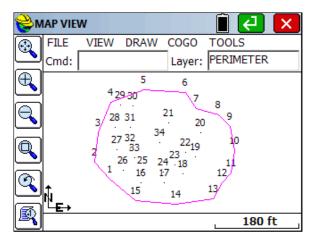
Volume Report	←			
Area in Cut: 0.0 S.F., 0.00 acres	_			
Area in Fill: 58,791.6 S.F., 1.35 acres				
Area exactly in daylight: 761.6 S.F., 0.02 acres				
Average fill depth: 21.22 ft				
Total inclusion area: 59,553.2 S.F., 1.37 acres				
Cut volume: 0.0 C.F., 0.00 C.Y.				
Fill volume: 1,247,273.4 C.F., 46,195.31 C.Y.				
Cut to Fill ratio: 0.00				
Cut (C.Y.) / Area (acres): 0.00				
Fill (C.Y.) / Area (acres): 33789.43				
	Ţ			
ŀ	<u> </u>			

The report can be saved to a text file using the "Save to Disk" icon at the top of the screen within "Volume Report". Click the "Return" arrow to continue back to the Map screen. If you draw a 3D polyline perimeter connecting points with elevation representing the outer limits of the volume calculation (using Draw, Polyline, 3D), then you can click on Inclusion and use the polyline as an inclusion perimeter. You can also use drawn elements on different layers as part of the volume calculation, if they are 3D, by moving them over to the right-column using the "Define" button. Volumes can also be conducted between "File" surfaces, TIN files made with Triangulate & Contour or within the Volume command itself using the option "Save Merged Surface to File."





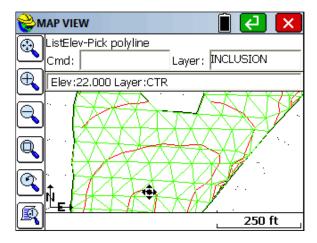
Finally, if you are doing a stockpile and make the effort to put this outer perimeter in the "Perimeter" layer, then you can select the "Stockpile" option within Volume, define the final surface appropriately, and click OK. You don't need any other definition for the original surface. This is because the Perimeter layer will define both the inclusion perimeter and the original surface in this case.





List Elevation (LELV):

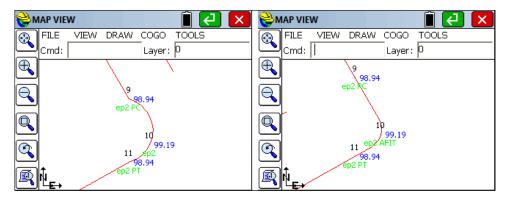
This command allows the user to pick on an entity and retrieve the elevation of that point. If you pick on a 3D polyline, you will get an interpolated elevation at the picked point.

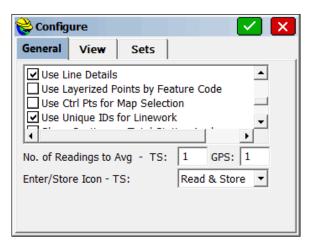




Field to Finish (F2F):

This command will redraw the linework created with Feature Codes based on the current coordinates of the points. So, if a GPS file was "processed" using a new localization, or a total station survey was adjusted, the existing linework made by use of Feature Codes will erase and redraw by connecting to the adjusted coordinates. In this way, polylines on the MAP screen created by field surveying will be redrawn to recapture their association with the adjusted point coordinates. Note that linework created by Feature Codes will redraw automatically in all graphic screens after coordinate positions or descriptions are edited within File \rightarrow Points. The F2F command will restore linework to point-based positions after erasing or moving linework on the screen.







In the example above, a field survey of a curve through points 9, 10 and 11 created a bulging curve due to erroneous measurement(s) of the true PC of the 3-point arc. If point 10 is clicked and edited with the field code EP2 AFIT, the AFIT (or as user-defined in the Special Codes within Feature Codes) on the middle curve point will force a tangent arc and adjust the true PC and PT points, keeping the field-measured points on the tangent. Then if Field-to-Finish is selected within the Tools menu, the curve will redraw. Note also that within Equip, Configure, if "Use Line Details" is clicked on, this setting has the effect of automatically re-drawing the linework upon any edits, without selection of Tools, Field to Finish.

When using Field to Finish, any line that is not ended with an "end" or "close" code will be detected and presented. These are very common when using the "counter" or appended number method of coding. This refers to coding a first EP as EP1, EP1, EP1, and a second EP as EP2, EP2, EP2. In this case, no end code is used--the suffix on the EP indicates which line is being coded and drawn. When these types of codes are selected (versus EP, EP, EP End or EP ST, EP, EP) then you may be prompted as shown below. Typically, choose the option "End All". This same screen is obtained by choosing the option "V" for Review (versus Redraw) when first selecting the command. Update and Redraw accomplish the same thing

<mark> Active</mark>	Linework		
EP			
EP1			
EP2			
EP3			
EP4			
EP5			
EP6			
EP7			
EP8			
WALL			
WALL1			
End	End All	Clear	Clear All



Image Overlay:

This command will attach an image database to the SurvCE drawing. Image databases are georeferenced aerial photography or image maps. These image databases can contain multiple large images that have been processed for quick display in SurvCE. The boundary for the image-set is shown by a dashed line. Images are inserted in coordinate system and units of the image. Image databases are processed with the Image X-Port utility of Carlson X-Port and take the form of IMD or IDB files. Only using SurvPC, can images be directly imported as jpg, tiff and other formats. The option to Save Image Boundary Points creates points at the 4 corners of the image, allowing you to zoom to those points. However, Zoom Extents (upper left icon in MAP screen) will zoom to the extents of the image if no points exist in the file.

<mark>8</mark> ₿₩	IAP VIE	N				Î 🗙			癸 Attach/Detach World Image 🛛 🛛 🔀
3	FILE	VIEW	DRAW	_	TOOLS]		Display Ima 🗌 Save Image Boundary Poin
	Cmd:	And in Mile		Layer:	TEMPLA		terline	>	Current Image Database:
E	14	No. of Contraction	3	a (Pline to PRO		None
Q				47	1100	Con Edit	vert Polylines to 2D		Change Image
	- 14			E.F.	1 12 I		erse Defaults		
Q	1				120	Surf		>	
6			that			Field	d to Finish		Run Image Set Manager
			a fil			Imag	ge Overlays		
R	1		UN			NGS	Survey Mark Query		

Images that do not have any georeferenced information built into them (or available in a separate jpw or tfw file) must be calibrated within Carlson X-Port, the office software companion to SurvCE, using the Image Manager. GeoPDF format is supported.





Web Map Overlays:

This command will allow for online maps to be applied to the background of the map screen. Current options are Google and OpenStreetMaps. For this option to function properly, the data collector needs to be connected to the internet.

Web Map Overlays	
Provider:	Google 🛛 🛃
Layer:	Satellite 💽 📯
Dimension:	512x512
Image Format:	PNG 💽
Use Reverse Graphic S	creen style
Terms o	/Google Earth Additional f Service n/help/terms_maps.html)

Active: This allows for the user to activate the web map overlay (if checked).

Provider: This allows the selection of the web map overlay source (Currently OpenStreetMap or Google).

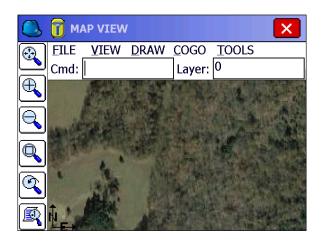
Dimension: This allows for selecting the size of the web map overlay. Options here are:

- 256x256
- 512x512
- 1024x1024
- 2048x2048

Note that smaller resolutions will use less data and load more quickly.

Image Format: This allows for selection of the web map overlay format (either JPEG or PNG). Once the preferred selections are completed, the web map overlay will show in the Map screen.





NGS Survey Mark Query:

This command will search the published NGS database for all recorded monuments or control points stored on the NGS website, within a specified radius of the current position. It requires an internet connection by cell phone or wireless.

s N	IAP VIEW						😂 NGS Survey Mark Qu	iery 🧲
•	FILE VIEW	DRAW	_	TOOLS			Projection: UTM/WGS 84//	Automatic Zone Selection
<u> </u>	Cmd:		Layer:	TEMPLA	Centerline	>	North	C South
(₽,			18 0.00		3D Pline to PRO		Lat(dd.mmssss):	N 0°02'44.379661"
				~	Convert Polylines to 2D		C East	West
					Edit	>	Lon(ddd.mmssss):	W 85°26'33.979522"
					Traverse Defaults		Search Radius (Miles):	0.25
۳					Surface	>		
\bigcirc					Field to Finish		Search N	GS Datasheets
<u> </u>	ŵ		1 0.000.	000	Image Overlays		Se	lect File
	└ €→			/3	NGS Survey Mark Query			

😂 NGS Survey Mark Query						
Search request has been sent						
0%						
Cancel						

The default Search Radius is the area shown within the current Map Screen view. The latitude and longitude are calculated from the map coordinates and current projection.

Since this is a NGS (US only feature) the search radius is in decimal miles. Search NGS Datasheets will get all the datasheets for this search radius. You can expand the Search Radius further as desired. The program sends a request to the NGS web site. Please be patient while the data is being recalled--it may take several seconds. This will download a new search a copy it to a folder NGS_Control_jobname. The default name for the file is gis.xml. The information in these folders can be recalled (without internet connection) using Select File.



The points will appear in a list, as shown below, whether based on a fresh search or if recalled using Select File.

NGS Sea	arch Results		(ờ NGS Sea	rch Result	's		+	裬 Review	File	
On/Off	Point ID	Name	•	On/Off	Point ID	Nam	e :	•		DESIGNATION - MAYSV	ILLE LEWIS AND 🗠
	HY1984	D 34			HY1984	D 34			DH4416		
	HY2046	D 55			HY2046	D 55	5			STATE/COUNTY- KY/MA	SON
	HY2507	FERNLEAF			HY2507	FEDNIE	AF		DH4416	COUNTRY - US	
	HY2486	MAYSVILLE 1954			H		E 1954			USGS QUAD - MAYSVII	LLE WEST (1993)
	HY2488	MAYSVILLE AZ MK	_		H D	ownloading DH4416	AZ MK	- 1	DH4416		
	HY2494	MAYSVILLE FIRST PRESB CI			н		RESB CI		DH4416	*CURREN	IT SURVEY CONTI
	DH4416	MAYSVILLE LEWIS AND CLARK			D		CLARK		DH4416		
	HY2485	MAYSVILLE RADIO STA WET			HY2485	MAYSVILLE RADIO S	TA WFT		DH4416*	NAD 83(2011) POSITION	N- 38 38 51.72845
	HY2484	MAYSVILLE REYNOLDS TOB	-1		HY2484	MAYSVILLE REYNOL	DS TOB	-1.	DH4416*	NAD 83(2011) ELLIP HT	 121.092 (mete
J.T.	INCOLOC	MINEDUA DECET	•	17	INVALOC			•		NAD 83(2011) EPOCH	
•		,		•			•		DH4416*		

By default, all the recalled monuments are unselected (Off). You can select individually or Select All. If you highlight a point, you can study its full information by clicking Data Sheet. The button Map Points stores all selected points to the coordinate file, and they will display on the screen. If combined with an Image Overlay, points can be easily located for reference, usable as GPS control points or as control for total station measurement.



10 Tutorials

10.1 Tutorial 1: Calculating a Traverse (By Hand) with SurvCE

In order to do a hand traverse with SurvCE, go to the **MAP** screen by clicking the icon in the upper right corner (appearing as a globe). While in the map screen, select the **Map Settings** icon to set your Traverse Defaults



Traverse Steps:

- 1. To begin, you must key in the command for inverse by typing "I". This will establish your occupied and backsight points. The command prompt will display the following:
- 2. Cmd:Inverse Tr/Ss/Pick point or point No
- 3. Key in the backsight point number followed by the [ENTER] key.
- 4. Key in the occupied point number followed by the [ENTER] key.
- 5. Key "T" for Traverse or "S" for Sideshot followed by the [ENTER] key.
- 6. If you keyed in "**T**" for traverse, the command prompt will be waiting for an angle code by displaying the following:
- 7. Cmd:Traverse eXit/I/Ss/Angle-BC(1-7)<7>
- 8. If you keyed in "S" for sideshot, the command prompt will also be waiting for an angle code by displaying the following:
- 9. Cmd:Sideshot eXit/I/Tr/Angle-BC(1-7)<7>
- 10. The code choices you can key in are as follows:
- 11. 1 Northeast Bearing
- 12. 2 Southeast Bearing
- 13. 3 Southwest Bearing
- 14. 4 Northwest Bearing
- 15. Azimuth
- 16. Angle Left
- 17. Angle Right
- 18. Key in the angle code of choice followed by the [ENTER] key
- 19. Key in the angular value in the dd.mmss format followed by the [ENTER] key.
- 20. If you selected a vertical prompt under **Traverse Defaults**, then key in the appropriate value followed by the **[ENTER]** key.
- 21. Key in the slope distance followed by the [ENTER] key.
- 22. Key in the point description followed by the [ENTER] key.
- 23. Press the [ENTER] key to accept the next available point number or key in a new point number followed by the [ENTER] key.
- 24. If you traversed, then you are now occupying the new point and are backsighting the previous point of occupation. If you sideshot the new point, then you are still at the previous setup and ready to compute the next point.
- 25. Options at the command prompt when presented with the messages listed in step 5 are as follows:
- X Exit
- I Inverse



S - Sideshot

T - **Traverse** *Note: in order to establish new occupied and backsight point information, you must use the "I" (Inverse) command and define the backsight point first and the occupied point second.*

10.2 Tutorial 2: Performing Math Functions in Carlson SurvCE Input Boxes

Many input boxes in SurvCE allow the user to calculate math functions "on-the-fly". To enter rod heights while in a GNSS setup screen that is not in your current units (e.g. you're using a 2 meter pole but working in U.S. feet), key in the following:

The Rod Height followed by "m" for Meters, "ft" for Feet and "ift" for International Feet followed by the [ENTER] key will convert the measurement into your current units (e.g. 2m = 6.5617). To compute the azimuth from one point to another to automatically enter in the azimuth while using the **Point by Direction** option in **Point Store**, key in the following:

Point ID, Point ID (e.g. "1,2")

To add or subtract a value from the computed azimuth, key in the following: **Point ID,PointID+Angle** (e.g. "**1,2+90**")

Or

Point ID,Point ID-Angle (e.g. "1,2-90")



10.3 Tutorial 3: Defining Field Codes, Line/Layer Properties & GIS Prompting

SurvCE can have one pre-defined FCL (Feature Code List) file loaded with the job coordinate CRD file.

The Feature Code List file stores pre-defined field codes that define Line/Layer drawing properties and optionally GIS prompting. (More than one FCL file can exist but only one can be loaded at a time per job coordinate CRD file.)

The operator builds this FCL file using option 5 "Feature Code List" in the File main menu. See the figure below.

JOB:VA_Beach					
File Equip Su	ırv COGO Road				
1 Job	6 Data Transfer				
2 Job Settings	7 Import/Export ASCII				
3 List Points	8 Delete File				
4 Configure Reading	9 Add Job Notes				
5 Feature Code List	0 Exit				

After you select 5 Feature Code List, the following Code List pop-up box is displayed. See the figure below.

Code Li	Code List: VA_BeachClose								
Code	Code Linework Line Type Layer Nam								
•				►					
Add		<u>E</u> dit	Re	move					
Loa	ad	<u>S</u> ave As	Speci	al codes					



FCL (Feature Code List) files can be created, edited or reviewed on a PC using Carlson X-Port or any Carlson Surveying office software. (SurvCE's FCL file is equivalent to Carlson's Field-to-Finish FLD Table used in their PC office software. Transfer all PC Field-to-finish FLD table files using SurveyCOM or Carlson Export. Select the Field Code Table option to upload the FLD file to SurvCE as a FLC file.)

Defining Field Code Line/Layer Properties

To define codes with line/layer drawn features and, optionally, GIS prompting, select in the Code List pop-up box "Add" (as shown in the previous figure). The following Add Code pop-up box allows the operator to define Field Code Line/Layer drawing properties.

Add Code	<u>0</u> K	<u>C</u> ancel
Code:	er name:	
Full Text:		
	olyline is 30):
YES 🔽 Y	ES	•
New Attribut	es	

- Code: Input one-word Field Code
- Layer Name: Defines the layer the linework 2D & 3D will draw in using Store Points
- Full Text: User defined full text description for code
- Polyline On: Yes or No defines to draw or not to draw between similar codes e.g. EP, EP1
- Polyline is 3D: Yes or No Yes draws in 3D, No in 2D
- New Attributes: This highlights after inputting all the Line/Layer drawing properties

The following EP code has been input in the FCL file. When Surveying using Store Points in the Survey menu, inputting field codes EP, EP1, EP2 and so on will draw 3D Polylines between these similar codes in the EOP layer. A 3D Polyline will be drawn in real-time when collecting data and inputting EP or EP# codes in Surveyed points descriptions.

As mentioned above, "New Attributes" becomes highlighted after inputting all the Line/Layer drawing properties. GIS prompting information can be added for this field code. If no GIS prompting is applicable for this field code, simply pick OK and create another field code, or exit and store the FCL file.



Add Code		<u>о</u> к	<u>C</u> ancel			
Code: [EP EOP	er name:				
Full Text:	Edge of pavement	:				
Polyline On: YES		olyline is 30 ES); •			
New Attributes						

Defining Field Code GIS Prompting

To add GIS prompting to a defined Line/Layer code, select "New Attributes". This button can be seen in the above figure at the bottom of the dialog. The following GIS Feature pop-up box is displayed. See the next figure below. To define GIS prompting for the EP field code, select "Add" in the Feature dialog shown below. The next pop-up box that appears, titled New attribute, is then displayed (shown below, underneath the Feature dialog). The New attribute dialog creates GIS prompting.

Feature			<u>C</u> lose	New attr	ibute			Cancel
Name: EP				Name:				Codes
Attribute		Туре	Req.	Prompt:				
				Default Va	ilue:			Set
				List Value:	s: Type:	Char	💌 Req.:	No 💌
•			Þ					
Load	Edit	Add	<u>R</u> emove					
Up	<u>D</u> own	<u>S</u> ave		Add	Remove	Up	Down	ОК



Load will load any existing Field Code GIS prompting for reuse. Edit reviews or revises existing GIS prompting. Add creates individual GIS prompting, as shown in the figure immediately above (New attribute dialog). Remove deletes any highlighted GIS attribute. Up and Down reorders the sequence of GIS attribute prompting. Save stores input or edited GIS prompting and exits to Line/Layer drawing properties.

Defining GIS Prompting

- Feature Code Name: No spaces GIS title for database
- Codes: Special codes, e.g. Date, Time, Lat, Long.
- GIS Prompt: Including spaces full name for GIS
- Default Value: Most common GIS value/default value
- Set: Lets the operator highlight and select the default value if there is a List of attribute Values.
- **Type**: Offers 4 options CHAR, INT, REAL and Code. Code Type will default to character type corresponding to special Codes. Codes can be Char, Int. or Real automatically.
- **Req**: Requisite/required entry. Operator cannot leave any GIS prompt empty when this field is set to Yes.

To add GIS attribute prompting for List Values, select the "Add" button within the New attribute dialog, as shown immediately below. The figure below that shows the New value pop-up box. The operator inputs, after selecting Add again, for each possible material (e.g. macadam, concrete, brick, stone cobbles and so on).

New attri	bute	Cancel	New value	Cancel
Name:	MATERIAL	Codes		
Prompt:	Road Surface			
Default Val	lue:	Set	MATERIAL	
List Values	: Type: Char 💌 Req.:	No 💌	Macadam	OK
Add	Remove Up Down	ОК		

The data input for all GIS List Values is shown in following figure below. Note that Macadam is highlighted and will be the default value. If there are more than six attribute List Values, scroll bars will appear. This defines only one GIS entry Material for the EP field code. Each GIS prompt for the field code EP (e.g. Material, Location, Condition, Width, Slope and so on) will require being created using Add in the Feature pop-up box, as shown earlier in this tutorial.



New attri	Cancel						
Name:	MATERIAL			Codes			
Prompt:	Prompt: Road Surface						
Default Va	Default Value: Macadam Set						
List Values: Type: Char 🔽 Req.: No 💌							
Macadam							
Concrete							
Brick							
Cobbled Stones							
Add	Remove	Up	Down	OK			

Add, Remove, Up and Down pertain to GIS List Values prompting. Add and Remove create or delete List Values entries. Up or Down reorders the highlighted List Value up or down. OK exits the GIS prompting screen retaining the GIS prompting entries and Cancel exits and discards all new inputs. The completed GIS field code for EP is shown below in the Feature dialog.

Feature				<u>C</u> lose
Name: EP				
Attribute			Туре	Req.
MATERIAL			Char	No
LOCATION			Char	Yes
CONDITION			Char	Yes
WIDTH			Char	Yes
SLOPE			Char	No
 				
Load	<u>E</u> dit	<u>A</u> dd	E	<u>R</u> emove
<u>U</u> р	<u>D</u> own		<u>S</u> ave	

With all of the GIS Features input – Material, Location, Condition, Width and Slope – the operator can now select Save to store the GIS prompting for the field code EP. When storing points in the Survey menu in Store Points with EP or EP#, 3D linework when ended will prompt for EP GIS data as defined here. If 2D or 3D linework is created the GIS data will be attached to the linework. Note that Location, Condition and Width are required input GIS fields. Load allows selecting any existing field codes GIS prompting for reuse. Edit reviews or revises existing GIS prompting. Remove deletes highlighted GIS attribute prompting. The Up and Down buttons will reorder GIS attribute prompting. Save stores and exits.

Importing & Exporting GIS Information from SurvCE



SurvCE imports and exports ESRI SHP files. SurvCE solely uses ESRI SHP files to interface with all GIS programs. ESRI SHP files are open architecture and are a widely used and accepted GIS format for most common GIS packages. To import or export GIS data to or from SurvCE, select in MAP – File – SHP File – Import or Export SHP File (Quick Import or Export only reads and writes the drawing entities and doesn't include the GIS info). There are two figures later in this tutorial that depict this.

SurvCE Creates Three ESRI GIS Drawing Objects: Points, Arcs (Polylines) and Polygons (Closed Polylines)

There are only three types of drawing entries in ESRI SHP files points, arcs (open 2D or 3D Polylines) and polygons (closed 2D or 3D Polylines). The EP field code creates points and arcs and/or polygons. GIS information is stored only to the arcs or polygons and not the EP points. All GIS information for EP will be attached to the 3D Polylines. The second Field Code UP in the FCL job file creates points only with no linework. The UP field code attaches GIS information to the UP points. See the next two figures below.

Feature				<u>C</u> lose	Add Code		<u>0</u> K	<u>C</u> ancel
Name: ep						Lave	r name:	
Attribute		Т	уре	Req.	Code:			
UP_NO		C	Char	Yes	1	1		
HGT CONDITION		Ċ	Char Char	No Yes	Full Text:	Utility Pole		
COMMENTS	i	C	Char	No	Polyline C			
_					NO	-		
◀				►				
Load	<u>E</u> dit	Add	E	emove		New Attribut	∋s	
<u>U</u> p	<u>D</u> own	9	<u>ave</u>					



Save Feature Code List File

With two field codes (EP and UP) with GIS information input and stored, using option 5 "Feature Code List" (in the File main menu), let's collect some Survey data in Store Points with GIS information. First, Save As these two codes into a Feature Code List file, as shown below.

I	Code L	ist: VA_B	each		<u>C</u> lose		Feature Code List	<u>O</u> K <u>C</u> ancel
	Code	Linework	Line Type	Layer Na	Full Tex		Type: FCL Files	
	EP UP	Yes No	3D 3D	EP UTILITY	Edge of Utility Po		🔄 \SystemCF\Data\	
	0	140	50	OTHERT	O diney i t		🗀 Backup	☑ VA_Beach.fcl
						Ш	🗀 CSGIS	
						Ш	NY_DOT.fcl	
						Ш	🖻 test.fcl	
	•						🖻 tpk.fcl	
	A	∖dd	<u>E</u> dit	<u>R</u> ei	move			
	Ŀ	oad	<u>S</u> ave As	Specia	al codes		Name: VA_Beach.fc	

The Add and Edit buttons create or revise Line/Layer drawing properties and GIS prompting. Remove deletes field codes highlighted. Load unloads the current FCL file and loads another existing FCL Field Code List.

Collecting & Storing GIS information in SurvCE

To demonstrate collecting Survey data with GIS information, SurvCE is set to either Manual Total Station or GNSS Simulation.

For Manual Total Station, go to the menu Survey – Store Points (see the next two figures). Follow the figures for Manual Total Station. It is important, in the main menu, that File – Configure Reading – HGT/Desc Prompt on Save is toggled ON!

JOB:VA_Beach		JOB:VA_	Beach		@ [MAP
File Equip Su	rv COGO Road	File	Equip	Surv	COGO	Road
Instrument	1 Sideshot/Traverse 6 Building Face S				ce Survey	
	<u>OK</u> Cancel	2 Stakeo	ut Points	7 R	emote Ele	evation
Instrument: Manual Tota	I Station	3 Stakeo	ut Line/Ar	'C 8 R	esection	
4 Receiver Utilities	9 Peripherals	4 Offset	4 Offset Stakeout		9 Set Collection	
5 Localization	0 About SurvCE	5 Elevatio	on Differe	nce 0 S	et Review	,

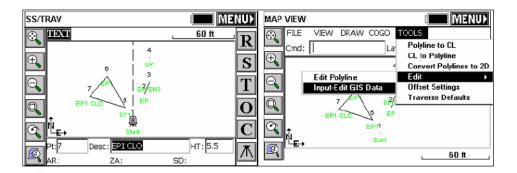


For GNSS Simulation, go to the menu Survey – Store Point (see the next two figures) and follow figures for GNSS Simulation.

JOB:VA_Beach		כ	OB:VA_	Beach]	MAP
File Equip Su	rv COGO Road		File	Equip	Su	rv	COGO	Road
Instrument	OK <u>C</u> ancel		1 Store F	Points		6 A	uto by Ir	nterval
			2 Stakeout Points 7			7 La	7 Log Static Data	
Instrument: GPS Simulat	ion 🔽		3 Stakeo	ut Line/Ar	c			
4 Receiver Utilities 9 Peripherals			4 Offset Stakeout					
5 Localization	0 About SurvCE		5 Elevatio	on Differe	nce			

See these Manual Total Station example screen captures, shown here in the next four figures.

Store Point		<u>OK</u> ancel	UP Cancel
	arget Height: 0.000		Add(ID:4)>Utility Pole (Char) UTILITY POLE NUMBER
AR : 15°00'00" N :5062.2643 Point Description :	ZA:92°00'00" E:5016.6837	SD:64.5000 Z:497.7490	(Char) HEIGHT 35.5'
Point Description.	EP UP		(Char) cond
			(Char) Comments JSC Survey Manual Total Station
			Next Previous Delete OK





GNSS Simulation screen capture examples are shown in these next four figures.

Store Point		<u>D</u> K	<u>C</u> ancel	Store Point		<u>OK</u> <u>C</u> ancel
	arget Height: 3.281			Point Number : 3	Target Height: 3.281	
N:5073.2243 HRMS:0.045	E:5030.9588 VRMS:0.087		5.7679 P:3.200	N:5073.2243 HRM5:0.045	E:5030.9588 VRMS:0.087	Z:96.7679 PDOP:3.200
Point Description:				Point Description	EP END	
	EP				EP	
	UP				UP	

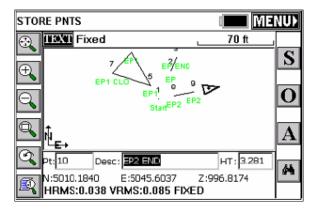
EP Cancel	EP Cancel
Add(ID:1036452394)>Edge of pavement	Add(ID:1036452394)>Edge of pavement
(Char) Road Surface	(Char) Road Surface
Macadam	Macadam 💌
(Char) Location - Street Numbers Name	(Char) Location - Street Numbers Name
	115 to 175 Robin Road
(Char) Condition	(Char) Condition
Good	50% Good 25% Bad 25% Fair 🔽
(Char) Measured Width	Excellent
	Good
	Fair
Next Previous Delete OK	Bad

The sequence of shoots started with GNSS Simulation storing points 2 and 3 as EP codes. Point 3 was stored as EP END. A 3D Polyline was drawn between 2 to 3 and GIS prompting popped-up after point 3 was stored shown above. Note in the Condition field the operator input data not found in the default settings. Point 4 was stored using manual total station as a UP point code. Point 4's UP GIS prompting appeared after point 4 was stored. Points 5 through 7 were stored as a closed polygon. This was done by storing point 7 as EP1 CLO to close back to the start point 5 of the EP1 3D Polyline. The GIS prompting appeared for EP1 (not shown) and entered. The last sequence above was to exit Store Points and select MAP.



Editing GIS Information on Arcs and Polygons – Input-Edit GIS Data

To edit existing GIS information stored on Arcs (2D/3D Polylines) or Polygons (closed 2D/3D Polylines) in the MAP pop-up box, select Tools – Edit – Input/Edit GIS Data, and pick any polyline or polygon. There are two figures below. The top figure shows how the closed 3D Polyline between points 5, 6 and 7 was selected using this command. GIS data for the closed 3D Polygon is shown in the second figure.



The above figure displays the next EP code EP2 stored using GNSS Simulation. When ended with a END or CLO description after EP2 SurvCE will prompt for EP GIS data to attach to the polyline as defined above.

+ EP			▼ Close
	152395)>Edge	e of pavement	
(Char) Road	Surface		
Concrete			•
<u> </u>	ion - Street Ni	umbers Nam	е
115 BOND S	STREET		
(Char) Condi	tion		
Good			▼
(Char) Meas	ured Width		
15'			
Next	Previous	Delete	Save

The figure above displays the ease of reviewing, creating or editing GIS data using Input-Edit GIS Data. From the MAP screen Input-Edit GIS Data was selected and the closed 3D Polyline picked on the screen. The GIS data stored prior was displayed for review or editing. Any data point, polyline or closed polyline could be selected using the Input-Edit GIS Data command in MAP and new GIS attached to this entity or existing GIS data reviewed and edited.

Editing GIS Information on Points using List Points

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Input-Edit GIS Data only works creating, reviewing or editing GIS information on Arcs or Polygons. To create, review or edit GIS information on points use List Points shown below under File -3 List Points.

JOB:VA_Beach	MAP MAP MAP MAP MAP M	Pts: 9	Highest: 9			Settings	⊆lose
		Pt ID	Northing	Easting	Elevation	Descripti	on 🛛 Pt IE
File Equip Su	ırv COGO Road	1	5000.00	5000.00	500.000	Start	1
1 Job	6 Data Transfer	2	5026.71 5038.22	5011.29 5016.16	996.722 996.817	ep Ep end	2 3
		4	5062.26	5016.68	497.749	UP	4
2 Job Settings	7 Import/Export ASCII	5	5012.99 5043.29	4992.50 4975.00	105.000 104.127	EP1 EP1	5
		1 17	5024.50	4957.57	104.145	EP1 CLD	7
3 List Points	8 Delete File	8	5002.85	5014.01	996.801	EPZ	8
[]		9	5006.51	5032.35	996.807	EP2	9
4 Configure Reading	9 Add Job Notes						
5 Feature Code List	0 Exit	•					
		Ed	it	<u>A</u> dd	Eind	i	De <u>l</u> ete

Highlight point 4 and select Edit (see figure immediately above). Point 4 is the only Surveyed number with GIS data stored to the point. The Edit Point pop-up box appears, and can be seen in the next figure below. To create, review or edit GIS information select Input/Edit Attributes (See Figure 9-32).

Note: At the +UP box on top the down - arrow can be selected and one or more GIS field codes could attach GIS data to this same point. Points, Arcs or Polygons can all have one or more GIS field codes attached to these entities.

Edit Point		<u>D</u> K	<u>C</u> ancel	+ UP Close
Point ID:	4		Edit Notes	Edit(ID:4)>Utility Pole (Char) UTILITY POLE NUMBER 101A
Northing:	5062.2643	ft		(Char) HEIGHT
Easting:	5016.6837	ft		35.5'
Elevation:	497.7491	ft		(Char) cond Good
Description:	UP			(Char) Comments
I	nput/Edit Attrib	utes		JSC Survey Manual Total Station Next Previous Delete Save



Exporting SurvCE GIS Data as ESRI SHP files

MAP VIEW MENUX	Export to SHP Close
ELE VIEW DRAW COGO IOCLS DXF File LandXML File LandXML File	Current SHP: VA_Beach Select New SHP V Export All
SHP File Import SHP File FLT from DXF Quick Import SHP Preferences Export SHP File Quick Save Quick Save	POINTS > 9 ARCS > 2 POLYGONS > 1 Implude special attributes
Exit 4,15 EP/9690-72 Help EP / 500/9800-81 EP / 500/9800-81 StatP2EP 2 StatP2EP 2 90 ft	Remove Arcs (offset cutoff): 0.1 Include Z Coordinates Process

These final two figures, above, display the exporting of our VA_Beach MAP and GIS data. The ESRI SHP file consists of 9 points, 2 arcs and 1 polygon (closed polyline). Only one point, point 4, has UP GIS data. Two arc polylines and one polygon have EP GIS information attached. Note that Include special attributes is checked. This adds to polyline arcs and closed polygons the polylines length and area to the GIS data automatically. Process with Export All checked stores the VA_Beach three SHP files automatically to a user defined subdirectory and a fourth SHP file with 8 points without GIS data.



10.4 Tutorial 4: Standard Procedures for Conducting GNSS Localizations

This tutorial is intended to assist users with the recommended localization method for SurvCE. Other methods can be used and it is up to the individual users to determine which is best for them.

File Extensions

Localization File: *.dat Geoid Model File: *.gsf Coordinate File: *.crd Raw Data File: *.rw5

Projections

It is essential that the proper plane coordinate projection is selected prior to creating a localization file. This should be the first step performed during the creation of the job file and be performed easily through File \Box Job Settings \Box GNSS.

Geoid Model

An important item to note is if the user intends to use a geoid model (typical for localizations that contain less that 3 control points), the geoid model must be applied prior to the creation of the localization file.

A local portion of the geoid grid must be extracted from the Carlson Geoid Model using Carlson X-Port, SurvCOM, Survey or Civil/SurvCADD, and the geoid model file must be installed prior to the creation of the local geoid file. It is also highly recommended that the local geoid file grid size does not exceed 100 miles.

Web Link to the Geoid Files

http://update.carlsonsw.com/public/CarlsonGeoidGrids.exe

Transfer or Enter the Known (local) Points

It's a good idea to simplify the process by transferring the known (local) points to the data collector prior to going to the field. Conversely, the user can keyboard enter the known coordinates for these points into the CRD file, one at a time, using File \Box List Points \Box Add. It is not recommended that the user keys in the local coordinates from within the localization process as transpositions can occur easily. However, this can be done as well.

Collect the GNSS Locations with Averaging

Using the Survey/Store Points routine, specify your point ID. It is good to use something that will relate to the original known point. Example, if the known point for the first control point is 1, then you may want to collect the measured location as 1001.

Use the average reading icon <A> to collect several epochs of data at each point. Typically, when using a 1 Hz receiver, 10 to 30 readings will be collected to ensure that the RTK solution is consistently reporting the same position for 10 to 30 seconds. On a 5 Hz receiver, the user may want to collect 50 or more readings as 50 readings would be 10 seconds.

Create the Localization File

Once the data collector has points that represent the known (local) coordinates and the measured data for these points, the localization file can be created.

Select Equip \rightarrow Localization \rightarrow Add to enter each point into the localization file.



Local Point

The first dialog presented to the user will be the Local Point dialog shown below. Enter the known (local) coordinate point ID or coordinates. If the point does not exist in the CRD file and coordinates are entered into this dialog, do not enter a point ID. Select OK when the known (local) position has been defined.

Local Point	
	OK Cancel
Please enter local coordinate values. You may use a point number from the current or control job.	
Point From File:	1
Local Northing:	5000
Local Easting:	5000
Local Elevation:	100

Figure 11: GNSS Coordinates

The next dialog presented will be the GNSS Coordinates dialog shown below. Since the measured locations for each point has already been recorded, the user will want to use the option From Raw File in this dialog. Select OK to continue.



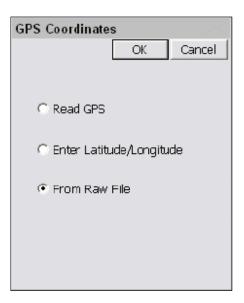


Figure 12: Surveyed Point

Next, the user will be presented with the Surveyed Point dialog shown below (top image). This dialog allows the user to select or enter the GNSS measured point that represents the known (local) point. If the user selects the GNSS measured point using the list icon, they should ignore the current coordinates displayed in the List Points dialog shown below (bottom image), as they only reflect the non-localized position at this point. The important thing to remember is that if the local point was 1, and the GNSS measured point was 1001, the user must enter 1001 in this dialog.



Surveyed Point	List Points	3		
OK Cancel	Settings	Eind Ot	< <u>C</u> lose	
Please enter a point number from the	PtID	Northing	Easting	Elevati
current or control job for which raw	* 1	5000.0000	5000.0000	100.00
data exists.	₩ 1001	5017.9607	5007.5937	93.479
Point From File: 1001	<	Ш		>

Save the Localization File

Once all of the points have been added to the localization dialog, save the localization file before exiting using the Save button.

Reprocess Raw File and Update Coordinates

At this point, all of the coordinates in the CRD file that represent the measured positions need to be updated to reflect the newly created localization. To do this, select COGO \Box Process Raw File and process the raw file through the localization file. This will update the previously measured GNSS points. Verify that the positions look valid by viewing the points in File \Box List Points. You should be able to compare the known and measured positions to see if they look right. Depending on the localization method, the measured values may not be exactly the same as the original known positions due to error that may have existed in the original positions.

Additional GNSS Measurements

Once the localization is defined, all of the GNSS points measured after its creation will be recorded to the CRD file based on this localization.

Changing the Localization

If the user determines that they want to redefine the current localization during a job, they must reprocess the entire raw file after making any changes to the localization file. It may be prudent to simply define a new localization file from scratch, leaving the original intact, and reprocess the raw file through this new localization file. Just remember that the last localization loaded, will be the current localization.

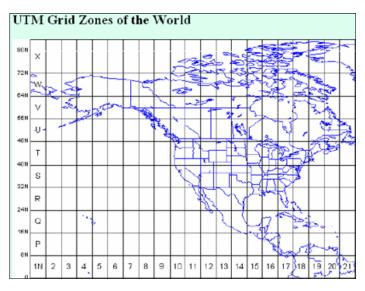


Selecting Projections for use in Localization

Whenever you select a projection or coordinate system, you can place it in a "most used" list of coordinate systems to choose from under the GNSS tab in Job Settings. This list can contain one projection system or many different systems the user selects.

Job Settings		OK	Cancel	
Options Units N	ew Job	GPS	Stakeou	t
Projection:	E	Edit Proje	ction List	
UTM/WGS 84/U	TM zone	16N		•
UTM/WGS 84/U		16N		
MUSA/NAD27/KY1		1 105		
SWITZERLAND/CH1903+/LV95				
One Point Localization Azimuth:				
State Plane Grid 🔹				

This is a special list of either predefined (e.g. KY North NAD83) or user-defined coordinates systems. To get the list started or add to the list, select Edit Projection List and click Add Predefined. In the U.S., for example, surveyors might want to keep the UTM (WGS84) system plus the NAD83 and NAD27 "state plane" zones in the list for quick access, covering the region of your work. European and other worldwide zones can be added. When setting up a UTM selection, you can choose your zone, referencing the graphic below for the US:



You can see a map of the UTM zones online at: <u>http://www.dmap.co.uk/utmworld.htm</u>



To edit the list of saved projections, click on Edit Projection List. Here we select a user-defined UTM system from the list to Delete or Edit.

Coordinate Projection Done					
Selection List:					
	H1903+/LV95				
UTM					
<					
Delete Add Predefined					
Edit Add User Defined					
	ielection List: UTM/WGS 84/UTI USA/NAD83/KY N USA/NAD27/KY N SWITZERLAND/CI UK/ED50/TM 0 N UTM	election List: UTM/WGS 84/UTM zone 16N USA/NAD83/KY North USA/NAD27/KY North SWITZERLAND/CH1903+/LV95 UK/ED50/TM 0 N UTM eleteAdd Predefire			

Choosing Edit will bring you to the screen below:

Edit/View Sy	stem		<u>0</u> K	<u>C</u> ancel
System: USA/NAD83/MA Mainland				
Projection: 📕	ambert_Con	forma	al_Conic_2	SP 🔽
Datum: N	4D83			
Edit/ <u>V</u> iew I	Datum		New <u>D</u> at	um
N. Parallel:	42.683333	3333	False No	rthing:
S. Parallel:	41.716666	6666	750000 m	
C. Meridian: -71.5			False Ea	sting:
Lat. of Origin :	41		200000	m

/



From this screen, you can select the Projection calculation method as well as calculation parameters. Projections include:

- Lambert Conformal_Conic_2SP,
- Transverse_Mercator,
- Oblique_Sterographic (Double),
- Lambert_Conformal_Conic_1SP,
- Oblique_Mercator_83,
- Stereographic, Oblique_Mercator_27,
- Transverse_Mercator_OSTN02,
- Oblique_Stereographic_RD2000,
- Oblique_Mercator,
- Cassini Soldner,
- Transverse_Mercator_27,
- Lambert_Conformal_Conic_27,
- Transverse_Mercator_Alaska_27
- Transverse_Mercator_34

You may also use the buttons on this screen to edit the existing datum or create a new datum definition.

Define Coordinate System			<u>O</u> K	<u>C</u> ancel
Name: WGS84				
Ellipsoid:	Ellipsoid: WGS84~1			
a: 6378137		т	Scale (pp	om):
1/f: 298.257223	5627	76	D	
dx: 5	m	rot X:	D	· ·
dY: 0	m	rot Y:	D	1
dz: 0	m	rot Z:	D	
🗵 GSF File is rela	ative	to WGS8	4	

The Datum definition screen is where you select the ellipsoid and Helmert parameters to apply. If you select Add User Defined within the Coordinate Projection List screen, you proceed to the screen below:



New System			<u>0</u> K	<u>C</u> ancel	
System:	MyNewSys	MyNewSystem			
Projection:	Transverse	e_Merca	tor	-	
Datum:					
Load File			New <u>D</u> atum		
Scale Factor	: 1		False No	rthing:	
C. Meridian:	0		0	m	
Zone Width:	6		False Ea	sting:	
Lat. of Origin	I: 0		0	m	

Here you enter the name of the new system and select the projection type and parameters, or you can "Load File" to load a pre-defined system stored earlier (in the form *.sys or *.csl).

Coordinate Projection	<u>O</u> K	<u>C</u> ancel
Type: SYS Files 🔹	filt	
L D:\EMULATORW32\survce\Re	elease\data	\
AGD84HIGGINS.sys		
AGD84HIGGINS2.sys		
AGD84HIGGINS3.sys		
🗩 alaska1.sys		
AlaskaNAD83_1.sys		
		<u> </u>
Name:		

If you select "Add Predefined" to create a new, stored projection system, you will be presented with this screen:



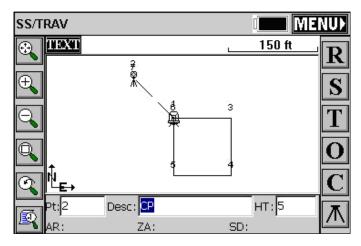
Coordinate Projection		<u>o</u> k	<u>C</u> ancel
Country: AL East AL West AK I AK II AK II AK IV AK V AK VI AK VI	USA/NAD83 USA/NAD23 USA/NAD27 AUSTRALIA AUSTRIA BELGIUM CANADA		

Here you can select the country and then the corresponding system for your area. There is a very extensive list of European and Asian systems including in the list. The "quick-access" short list of most used projections enhances job efficiency.



10.5 Tutorial 5: Performing a Compass Rule Adjustment

In the example below, as shown in the next figure, the traverse was performed by occupying point 1 located at the NW corner of the block. The initial backsight was established by azimuth, measured and stored as point 2 shown NW along the hanging le.g. Angles and distances were measured in a clockwise direction. Point numbers 6 and 1 are at the same location and point numbers 7 and 2 are at the same location. This method allows for the closing of the angles and the measurement of all traverse legs.



Process Raw File

Select "Process Raw File" from the "COGO" tab, as shown below in this figure.

JOB:Coelss Rule Examp	👷 🛄 MAP)		
File Equip Surv	COGO Road		
1 Keyboard Input	6 Station Store		
2 Inverse	7 Transformation		
3 Areas	8 Calculator		
4 Intersections	9 Process Ra w File		
5 Point Projection	0 Point in Direction		



Select Raw File

The next figure below shows the standard Windows file selection dialog. Select the RW5 file you want to process followed by the "OK" button.

Raw File	OK	Cancel
Type: RW5 Files 💌	Ðď	
🖾 C : \SurvCEDemo \Data \		
🗀 Backup		
CSGIS		
🖻 Compass Rule Example.rw5		
SurvCE_Demo.rw5		
Name: Compass Rule Example.rw5		

Select "Compass" from the adjustment options dialog box as shown in this figure below.

Process Raw File	Cancel
No Adjust	Crandall
Angle Balance	Direct-Reverse Report
Transit	Draw Traverse Lines
Compass	Review RW5 File



Reference Closing Point

Key in the initial occupied point number for the "Reference Closing Point #:" and toggle on the "Apply Angle Balance" option, followed by the "OK" button, as shown in the next figure below.

Process Raw Data Options			OK	Cancel
Referen	ce Closing P	oint #:	1	
North:	10000	Apply Ar	ngle Balanc	e
East:	20000	🔽 Vertical	Error Adju	stment
Elv:	100	Report P	Point Adjus	tments
		🔽 Report U	Jnadjusted	Points
		🔽 Report 9	Sideshots	

Closed Traverse

In a closed traverse scenario, the reference closing point will always be your initial occupied point name.

Note that you will need two known points, or one point and a known azimuth, for a closed traverse. The angle balance point will be the same location as the original backsight and will not be adjusted.

Open Traverse

In an open traverse scenario, the reference closing point will be a stored point name or coordinates that represents the known values for the last occupied point in the traverse.

Note that you will need two known points, or one point and a known azimuth, at the beginning and at the end of an open traverse; one point at the end will be used to close on and other will be used for angle balance (when Angle Balance is applied). The angle balance point will be the same as the last foresight point in the traverse and will not be adjusted.



Traverse Points

You'll notice in the Angle Balance Measurement figure below, since you keyed in the data yourself, that the number of traverse points in this survey is 7. Since point 7 was only measured to avoid and record the closing angle balance measurement by hand, in this example the traverse is only from points 1 through 6. Replace the 7 in the "Ending Point Number" input box with a 6, as shown in this next figure immediately below, followed by the "OK" button. Note that point 6 should be the same location as point number 1 in a closed traverse.

Traverse Points	OK	Cancel
Starting Point Number:	1	
Ending Point Number:	6	

Angle Balance

Select the foresight shot from the last occupied point to the original backsight location. In this example, we would select the leg measured from point 6 to point 7, since point 7 was our foresight angle balance shot to point 2. Press the "OK" button. In an open traverse, this would be the measured leg that represents the known azimuth or bearing at the end of the traverse.

Angle E	Balan	ce Measurem	ent	OK	Cancel
Select	the Ar	ngle Balance Sl	not:		
Occup	y Pt	Foresight Pt			
1		2			
1		-3			
3		4			
4		5			
		6			
		/			



Reference Closing Angle

Finally, we need to provide the reference closing angle (record). This is the original backsight azimuth. Key in point 1 and point 2, or key in the known azimuth or bearing, followed by the "OK" button.

In an open traverse, key in the stored point numbers that represent the values for the known control points at the end of the traverse, or key in the known azimuth or bearing.

The adjustment report should be presented, and the adjustment should be complete. The angle balance point number 7 will not be adjusted to fit point number 2, and can be discarded.

Reference Closing Angle	OK	Cancel
Measured Closing Bearing:	N45°00'08	"W
Measured Closing Azimuth:	314°59'52'	u
Angular Error : -0.000800000	1	
From Point: 1 To Po	oint: 2	
Reference Closing Angle (dd.mn	nss): 45	.0000
Format		O AZ
	· 1400	~~~



10.6 Tutorial 6: Advanced Reporting with GIS Attributes

Advanced Reporting with GIS Attributes is a powerful SurvPC feature and can be used in a variety of useful ways.

For example, say a user is inspecting welded seams. The user has been tasked to create an inspection report in Excel showing all the inspected welded seams. This can be setup and executed within SurvPC.

This will be setup using Feature Codes within SurvPC. A feature code will be created with various attributes assigned to it. In our example, the feature code 'Weld' will be created with the following attributes:

- Point ID
- Defect Code
- Defect Location Seam#
- Northing
- Easting
- Repair Date
- Repair Time
- Repair Type
- Approximate Size
- Machine ID
- Repair Tech Initials
- Vacuum Test: Pass or Fail
- Vacuum Test Date
- Vacuum Test Technician

Each attribute can be setup specifically to assist the user to create the most efficient workflow. In our example, we will setup each attribute as follows:

Attribute	Туре	Required	Editable	Select-Only
Point ID	Char	Yes	Read-Only	Yes
Defect Code	Char	Yes	Allow	No
Defect Location	Char	No	Allow	No
Northing	Real	Yes	Read-Only	Yes
Easting	Real	Yes	Read-Only	Yes
Repair Date	Char	No	Allow	No
Repair Time	Char	No	Allow	No
Repair Type	Char	No	Allow	No
Approximate Size	Char	No	Allow	No
Machine ID	Char	No	Allow	No
Repair Tech Initials	Char	No	Allow	No
Vacuum Test Pass Fail	Char	No	Allow	No
Vacuum Test Date	Char	No	Allow	No
Vacuum Test Technician	Char	No	Allow	No

Table 1: Attribute Table - Advanced Reporting with GIS Attributes



An attribute table, such as shown above, should be setup regarding any reporting required. The user has many degrees of freedom setting up the attributes for a feature code. Each attribute can have list values. For instance, we set our attribute 'Repair Type' to have list values of P, BT, and C to indicate specific repair types. Attributes can have values that are times, such as our attribute 'Repair Time'. Attributes can be automatically filled out if set to Read-Only. For instance, we set our attributes 'Point ID', 'Northing', and 'Easting' to Read-Only. This means that when a point is stored, these values will be automatically entered in the attribute table.



Creating a Feature Code

In our example, we want to create a new feature code 'Weld'. This is done from the File-Feature Code command. This will present the user with the Code List screen. Click on the 'Add' button to create a new feature code. This will bring up the Add Code screen, where we type in the new feature code 'Weld' in the Code dialog box.

😂 Add Code	🗾 🗹 🔀
Code: weld Category: NO CATEGORY v Set Symbol Name: POINT\spt6. Layer: WELD Full Text:	bmp Select Color:
Entity Type:	Edit Feature
Point 2D Polyline 3D Polyline	Notes

We want this the be in no category and setup a symbol of a blue square 'point\spt6.bmb'. The 'No Category' option is default whereas the symbol is selected using the 'Set Symbol' button and browsing to the square icon. The color of the symbol is setup by clicking on the white dialog box and selecting a blue color. We select the entity type as a point and continue by selecting the 'New Feature' button.

Creating an Attribute Table

The attribute table shown above can be created within SurvPC by using the Add button for each attribute. For example, to add the 'Northing' attribute, we click on Add, select the name as 'Northing' click on the 'Codes' button to use the default 'Northing' option, set the prompt (here, we use 'Location Northing'), and select the type. With the Northing attribute complete, we click on the green check. Following this workflow for each attribute, we continue adding attributes until our attribute table is completed.



Feature					n Use (
Set W	/ELD				
Attribute			Туре	Req.	Editab 📤
POINTID			Char	Yes	Read-
DEFECT_COL	DE		Char	Yes	Allow
REPAIR_TIM	REPAIR TIME			No	Allow
APPROXIMATE SIZE			Char	Yes	Allow
REPAIR_TEC	IR_TECH_INITIALS			Yes	Allow
	CT DACC E	ΛTI	Char	Mo	
Point 🔻	Edit		Up		Down
Load	Remove	Add Save		Save	

The Prompt used for each attribute will be the column header in the Excel (.csv) report.

An attribute that is a function of time is defaulted to 'HH:MM:SS' format, but is user selectable for 'HH:MM' eliminating the seconds, if preferred. This option is accessed via the Settings Icon found in the Special Codes screen.

Storing Points with Feature Code 'weld'

With our attribute table completed, we can store points in the field. We are storing point numbers with the format 'R1, R2, ..., R5' and using the code 'weld' to initiate our Feature Code attribute prompts. Once a point is stored, the attribute list is shown for us to fill out. We have stored 5 points with the following attribute data.

· *	D4	DA	D 4	D (D.
Point ID	R1	R2	R3	R4	R5
Defect Code	BO	BO	AT	DS	Т
Repair Time	10:41	10:42	10:54	10:44	11:00
Approximate Size	2x3	2x3	2x3	3x3	2x3
Repair Tech Initials	GGG	GGG	GGG	GGG	GGG
Vacuum Test Pass Fail	Р	Р	Р	Р	Р
Vacuum Test Date	8/21/17	8/21/17	8/21/17	8/21/17	8/21/17
Vacuum Test Technician	AAA	AAA	AAA	AAA	AAA
Repair Type	С	Р	BT	С	Р
Defect Location	S9	S12	S13	S7	S2
Northing	127606.6173	127620.4441	127620.6660	127619.7337	127598.0587
Easting	542492.6815	542497.1847	542491.4401	542489.862	542453.1694
Repair Date	9/21/17	9/21/17	9/21/17	9/21/17	9/21/17



Times entered/edited can be of the format '1020' for'10:20' – eliminating the need to type the colon while in the field.

😂 Add GIS Data	WELD		-	X
2	[Point]	Sav	e <u>V</u> alu	es
(Char) Pointid:<<.PointID.>>				
2				
(Char) Defect Code				
BO				•
(Char) Repair Time				
10:20				
(Char) Approximate Size				
2x3				-
Del	Prev	Vext	Save	

(Char) Repair Time	(Char) Repair Time
1020	10:20



Export ASCII – Attributes only (.csv)

Now we have stored our 5 points: R1, R2, R3, R4, R5, we can export the attribute data to Excel for reporting purposes. This is accomplished via the File - Import / Export – Export ASCII command.

• Select 'Custom' for the Coordinate Order and click on the Config button. Within the Config button, click on the left arrow a few times to clear out the dialog box under Used. Green check when complete.

😂 Custom	X
Preview:	
l Available:	Used:
ID NORTHING EASTING ELEVATION DESCRIPTION LATITUDE	 > < <
Write "DESCR	IPTION" Up Down C Right C Left

• Select Comma for the Delimiter selection, 'R1-R5' for the Range selection, and the check box for Attributes. We will now click the Settings Icon to select our Export Ascii Preferences.

误 Export Ase	Settings Icon
File Type: Coordinate Or	User Defined 💌
Custom	✓ Config
Delimiter-	
Comma	○ Space ○ Tab ○ Other
Range:	Export Point Notes
Precision: 0	.0000 Cher: Point Info Attributes
Format	Geodetic



• Enable checkboxes 'Include Header', 'Only GIS', and 'Skip Attribute Names'. Green check when complete.

💝 Preferences 🛛 🔽 🗙
Export Other Delimiter: Comma C Tab C Space C Other , Counter: 1
Add Prefix to DESC:
Export Attributes:
Only GIS:
 ✓ Skip Attribute Names ☐ Include Code Type ☐ Include Connection Code ☐ Export Partner Software (XML) Files

• Click on the green check to open the 'Ascii File to Write' screen. In the Type dropdown list, select 'CSV Files' and type in a filename in the bottom dialog box. Click the green check when complete.

Open .csv in Excel

With the .csv document successfully exported, it can be viewed in Excel.

	Α	В	С	D	E	F	G	Н	1	J	К	L	М
		Defect	Repair	Approximate	Repair Tech	Vacuum Test	Vacuum Test Date	Vacuum Test	Repair	Defect	Location		
1	PointID	Code	Time	Size	Initials	Pass Fail	(format 7/27/17)	Technician	Туре	Location	Northing	Easting:	Repair Date
2	R1	BO	10:41	2x3	GGG	Ρ	8/21/2017	AAA	С	S 9	127606.6173	542492.6815	9/21/2017
3	R2	BO	10:42	2x3	GGG	Р	8/21/2017	AAA	P	S12	127620.4441	542497.1847	9/21/2017
4	R3	AT	10:54	2x3	GGG	Ρ	8/21/2017	AAA	BT	S13	127620.666	542491.4401	9/21/2017
5	R4	DS	10:44	3x3	GGG	Ρ	8/21/2017	AAA	С	S7	127619.7337	542489.862	9/21/2017
6	R5	т	11:00	2x3	GGG	P	8/21/2017	GGG	Р	S2	127598.0587	542453.1694	9/21/2017

The exported GIS attribute data can be used for reporting purposes. Notice the Headers are what we originally typed in the Attribute's Prompt dialog box. The times are reported with colons in HH:MM format without the need to type colons in the field (as shown above). Any point attributes deemed important can be setup in this manner for easy data downloading and reporting.



11 Troubleshooting

11.1 GPS Heights

SurvCE records GPS heights as the ellipsoid height, expressed in meters, at either the phase center or the ARP of the antenna, depending on the GPS manufacturer. If the position is recorded to the ARP, then the LS record (antenna height) will only reflect the user-entered value. If the position is recorded to the phase center, then the LS record (antenna height) will reflect the user-entered value plus the phase center offset.

SurvCE records the ARP position for the following GPS manufacturers:

- Leica
- Geodetics

11.2 Handheld Hardware

How do I reset the computer after a lock up?

Ranger

Hold down the power button until the computer resets or instructs you to hold it for 5 more seconds to reset.

Allegro

Hold down the power button until the computer resets.

Why can't I load the software?

The computer may disconnect from ActiveSync when there is not enough memory allocated to "Storage Memory". In the control panel, select the "System" icon followed by the Memory tab. Position the slider so that there is 5mb (5120 kb) allocated and not in use (i.e. if the "In Use" value says 1024 kb then add 1024 & 5120 to determine what the "Allocated" value should be).

How do I clear the RAM backup and why?

Clearing the RAM backup seems to improve performance on the Ranger platform after new programs have been installed or removed. Make sure that all software applications are closed and select the "RAM Backup" icon from the control panel. Select the **Delete** button and answer **Yes** to the three resulting message boxes.



Why can't I communicate through the COM port?

If you cannot communicate with the instrument, verify all COM settings in SurvCE and make sure that they match the COM settings on the instrument. If communication has previously been working and the COM settings have not been altered, try one of the following to clear up the COM port:

- Exit SurvCE, turn off the computer, Restart the computer and re-enter SurvCE.
- Exit SurvCE and perform a soft reset on the device (Verify that all applications have been closed).
- Exit SurvCE and perform a hard reset on the device (Verify that all applications have been closed).

How do I set the CAPS LOCK status?

Ranger

1) Hold down the yellow shift button [$^$] and the [ALT] buttons, then press and release the power button.

2) A small keyboard should be showing. On the small keyboard, press the [CAPS] button then repeat step 1 to dismiss the keyboard.

Allegro

Press and release the blue function button followed by the CapLk/Shift button located at the lower left side of the keyboard.

How frequently should I charge the device?

We recommend starting every day with a fully-charged battery. Refer to your hardware manual for specifics on charging your battery.

How do I calibrate the touch screen?

In the control panel of the CE device, select the "Stylus" icon to configure the "Double Tab" and "Calibration" of the touch screen.

How do I turn on/off the back light?

Ranger

Hold down the shift button [$^{\ }$] and then press and release the power button.

Allegro

Press and release the yellow function button followed by the F3/F8 button located at the top center of the keyboard.

How can I speed up the Allegro performance?

In the control panel of the Allegro, select the "System" icon and then the "Memory" tab. Set your "Storage Memory" allocation to 8000 KB or 8 MB +/-. This should provide more RAM to the system for operating the programs and increase performance.



How can I Recover the SurvCE Icon if it Disappears?

It may be possible to lose the SurvCE Icon off the desktop if, for example, the power drains out of the CE device. There are safeguards against this, but if it happens, follow these steps to restore the icon:

- 1. Select **Start** (lower left on most CE devices, Ctrl Esc on the Ranger) and choose **Windows Explorer** under **Programs**.
- 2. Navigate to the SurvStar directory (the directory containing SurvCE), which on some devices is \Disk\SurvStar.
- 3. Look for the SurvCE Shortcut and highlight it.
- 4. Choose the Edit pull down in Windows Explorer and choose Copy.
- 5. Then return to the desktop where the icons are visible and press **ALT** then tap into blank space on the screen (sometimes referred to as ALT-Click).
- 6. Choose Paste Shortcut. That should restore it.

If the icon disappears, this indicates some problem in the original installation of SurvCE, since a process occurs to make the icon permanent. You can help ensure that your restored icon is permanent by going to Start, Settings, Control Panel and choosing Perform Ram Backup. Select Backup Now, as prompted. This should make the SurvCE icon remain even after full loss of battery.

Can I lose data or get bad data if I Re-Boot my CE device?

If you re-boot your Allegro or Carlson Explorer or Ipaq or any other CE device you are using, you can lose your antenna height or prism height information, because SurvCE does not store to memory changes in antenna height or prism height, except in the following scenarios:

The hard save of antenna/prism heights is done when you exit the program, when you save a configuration from the instrument icon at the top of the screen, when you say OK to Configure Rover, Configure Base or Equip/Settings (for TS), when you change jobs, and when you enter Equip/Comm Settings. Prior to release 1.50.007, in November, 2004, even Configure Rover did not save the height information "to disk".

Therefore, if you re-boot, perform a hard reset, or otherwise exit the program by any method other than the normal File, Exit method, recent changes to the prism height or antenna height may not be saved. On re-entering the program, the X,Y position for GPS work, for example, will very likely be correct, but elevations may have been lost. When using GPS, it is recommended, after a re-boot, that you do the command Configure Rover to re-establish the correct elevations, and in all cases (GPS and Total Station) it is recommended that you double-check your antenna or prism heights before proceeding.



11.3 Miscellaneous Instrument Configuration

Leica Robotic - Do I need to be in RCS (Remote Control) mode?

You must verify that you are NOT in RCS mode when using SurvCE with Leica robotic equipment. It will appear as though you are not communicating with the instrument if this mode is active. Refer to the Leica documentation for how to exit RCS mode.

Leica GPS - What firmware will allow radio channel changing?

Firmware version 3.52 or later is required for SurvCE to have radio channel changing functionality.

Geodimeter 600 - What firmware version is required?

Firmware version 696-03.xx or later is required for SurvCE to operate with this instrument. To check the firmware on the instrument, follow the key strokes: Menu, 5, 4, 1. The Geodimeter 640, for example, does not take measurements in reverse face. Therefore, when doing D&R, set reverse face to angle only.

Sokkia GSR 2700 IS - What do I do when I get the Bluetooth pass key prompt?

This receiver does not require a pass key. If you are prompted for one, do a factory reset on the receiver by holding the power key down until the message displayed is Factory Reset. Then turn the device off and back on again. In Carlson SurvCE, clear the receiver from the Bluetooth connections list and add it back in.



11.4 Supported File Formats

What file types does SurvCE use or convert?

- ALI ISPOL Centerline File (Spain)
- ALN TerraModel Road Alignment File
- ALZ Form of CLIP Vertical Alignment File (Spain)
- ASC ASCII text file for point imports or Inroads Centerline File
- CL Carlson Horizontal Road Alignment File
- CR5 TDS Binary Coordinate File
- **CRD** Carlson coordinate file in binary form.
- DAT Carlson Localization File
- **DXF** Drawing file format that can be used for exchanging drawings.
- EGM Carlson EGM Geoid File
- FCL Carlson Field Code Library file.
- **FFF** Older form of Caice Cross-section File
- FLT Carlson Triangulation Mesh File
- **G99** Carlson Geoid99 File
- GRD Carlson Grid File
- **GSI** Leica file extension for Raw files, Roading files, etc.
- INF Carlson User Preferences Settings File
- **INP** MOSS Roading Files (Horizontal and Vertical Alignment)
- LIS Form of IGRDS Cross-section File
- **NOT** Carlson Note File
- OBS Geodimeter Coordinate File
- **OSD** A form of Geopak Centerline File
- PLT Horizontal Alignment Report file from CLIP (Spain)
- **POS** Sokkia or Trimble Coordinate File
- PRO Carlson Vertical Road Alignment File
- **RAS** ISPOL Vertical Road Alignment File (Spain)
- RD5 TDS Road Alignment File
- RDS IGRDS Cross-section File
- REF Carlson Base Station Reference File
- **RLN** TerraModel Road Alignment File
- **RW5** Carlson Raw Data File, TDS Raw Data File
- SC1 ISPOL Cross-section File (Spain)
- SCT Carlson Cross-section File
- SDR Sokkia file extension for Raw Files, Roading files, etc.
- SHP ESRI Shape File
- SUP Carlson Road Superelevation File
- TPL Carlson Road Template File
- TPT Carlson Road Template Transition File
- **TRV** Traverse PC Coordinate File and CLIP Format for Sections (Spain)
- XML LandXML File may contain a variety of file types (e.g. Roading/DTM)
- XRS Form of Geopak Cross-section File



12 Raw Data

12.1 File Format

Carlson SurvCE RW5 Format

This section outlines the Carlson SurvCE RW5 format in detail. The format is a comma delimited ASCII file containing record types, headers, recorded data and comments.

The format is based on the RW5 raw data specification, with the exception of angle sets. Angle sets are recorded as BD, BR, FD and FR records to allow reduction of all possible data that can be recorded by Carlson SurvCE using the **Set Collection** routine. Essentially, these records are identical to a sideshot record.

With the exception of the aforementioned angle set records, if the RW5 specification is modified to provide enhanced functionality, the added or modified data will reside in comment records to avoid incompatibility with existing software. SurvCE writes latency in the GPS notes record of the RW5 file.

Backsight Record

Record type: BK	
Field Header	Description
OP	Occupy Point
BP	Back Point
BS	Backsight
BC	Back Circle

Example:

BK, OP1, BP2, BS315.0000, BC0.0044

Job Record

Record type: JB

Field Header	Description
NM	Job Name
DT	Date
TM	Time

Example:

JB,NMSAMPLE,DT06-27-2003,TM14:21:53



Line of Sight Record

Record type:	LS

Field Header	Description
HI	Height of Instrument
HR	Height of Rod*

*GPS heights may be recorded to phase center or ARP depending on GPS make.

Example(s): LS,H15.000000,HR6.000000 LS,HR4.000000

Mode Setup Record

The mode setup will be recorded at the beginning of the raw data file. Record type: MO

Field Header	Description
AD	Azimuth direction (0 for North, 1 for South)
UN	Distance unit (0 for Feet, 1 for Meter)
SF	Scale Factor
EC	Earth Curvature (0 for OFF, 1 for ON)
EO	EDM Offset (Inch)

Example:

MO, AD0, UN0, SF1.00000000, EC1, EO0.0, AU0

Occupy Record

Record type: OC

Field Header	Description
OP	Point Name
Ν	Northing (the header is N space)
E	Easting (the header is E space)
EL	Elevation
	Note

Example:

OC,OP1,N 5000.00000,E 5000.00000,EL100.000,--CP



Off Center Shot Record

Record type: OF

Field Header	Description
AR	Angle Right
ZE	Zenith (actual)
SD	Slope Distance

Example(s):

OF,*AR*90.3333,*ZE*90.0000,*SD*25.550000 *OF*,*ZE*90.3333,--*Vert Angle Offset*

Store Point Record

Record type: SP

Field Header	Description
PN	Point Name
N	Northing
Е	Easting
EL	Elevation
	Note

Example:

SP,PN100,N 5002.0000,E 5000.0000,EL100.0000,--PP



Traverse / Sideshot Record / Backsight Direct / Backsight Reverse / Foresight Direct / Foresight Reverse

Record type: TR / SS / BD / BR / FD / FR

	Field Header	Description
	OP	Occupy Point
	FP	Foresight Point
One of the following:		
	AZ	Azimuth
	BR	Bearing
	AR	Angle-Right
	AL	Angle-Left
	DR	Deflection-Right
	DL	Deflection-Left
One of the following:		
	ZE	Zenith
	VA	Vertical Angle
	CE	Change Elevation
One of the following		
	SD	Slope Distance
	HD	Horizontal Distance
		Note

Example (s):

TR,OP1,FP4,AR90.3333,ZE90.3333,SD25.550000,--CP SS,OP1,FP2,AR0.0044,ZE86.0133,SD10.313750,--CP BD,OP1,FP2,AR0.0055,ZE86.0126,SD10.320000,--CP BR,OP1,FP2,AR180.0037,ZE273.5826,SD10.315000,--CP FD,OP1,FP3,AR57.1630,ZE89.4305,SD7.393000,--CP FR,OP1,FP3,AR237.1612,ZE270.1548,SD7.395000,--CP



GPS

Record type: GPS

Field Header	Description
PN	Point Name
LA	Latitude (WGS84)
LN	Longitude (WGS84, Negative for West)
EL	Ellipsoid elevation (in meters)
	Note

*GPS heights may be recorded to APC or ARP depending on GPS make.

Example(s): GPS,PN701,LA42.214630920,LN-71.081409184,EL-21.8459,--CP /Brass Disk

Alphabetical listing of Record Types

- BD Backsight Direct
- **BK** Backsight
- BR Backsight Reverse
- FD Foresight Direct
- FR Foresight Reverse
- GPS GPS Position in Lat (dd.mmss) Lon (dd.mmss) and WGS84 Ellipsoid Elevation in meters
- JB Job
- LS Line of Sight
- MO Mode Setup
- OC Occupy
- OF Off Center Shot
- SP Store Point
- SS Side Shot
- TR Traverse
- -- Note Record



Alphabetical listing of Field Headers

- **AD** Azimuth Direction (0 for North, 1 for South)
- AL Angle-Left
- AR Angle-Right
- AZ Azimuth
- BC Back Circle
- **BP** Back Point
- **BR** Bearing (this field will be recorded as N123.4500W)
- **BS** Backsight (when back point is not defined)
- **CE** Change Elevation
- DL Deflection-Left
- **DR** Deflection-Right
- **DT** Local Date (MM-DD-YYYY)
- **E** Easting (the header is E space)
- **EC** Earth Curvature (0 for off, 1 for on)
- EL Elevation (GPS value is ellipsoid elevation in meters)
- EO EDM Offset
- **FE** Foresight Elevation
- FP Foresight Point
- HD Horizontal Distance
- **HI** Height of Instrument
- **HR** Height of Rod
- LA Latitude
- LN Longitude
- **N** Northing (the header is N space)
- **OC** Occupy Point Coordinates
- **OP** Occupy Point
- **PN** Point Name
- **SD** Slope Distance
- SF Scale Factor
- **TM** Local Time (HH:MM:SS)
- UN Distance Unit (0 for feet, 1 for meter, 2 for US feet)
- VA Vertical Angle
- **ZE** Zenith
- -- Note



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